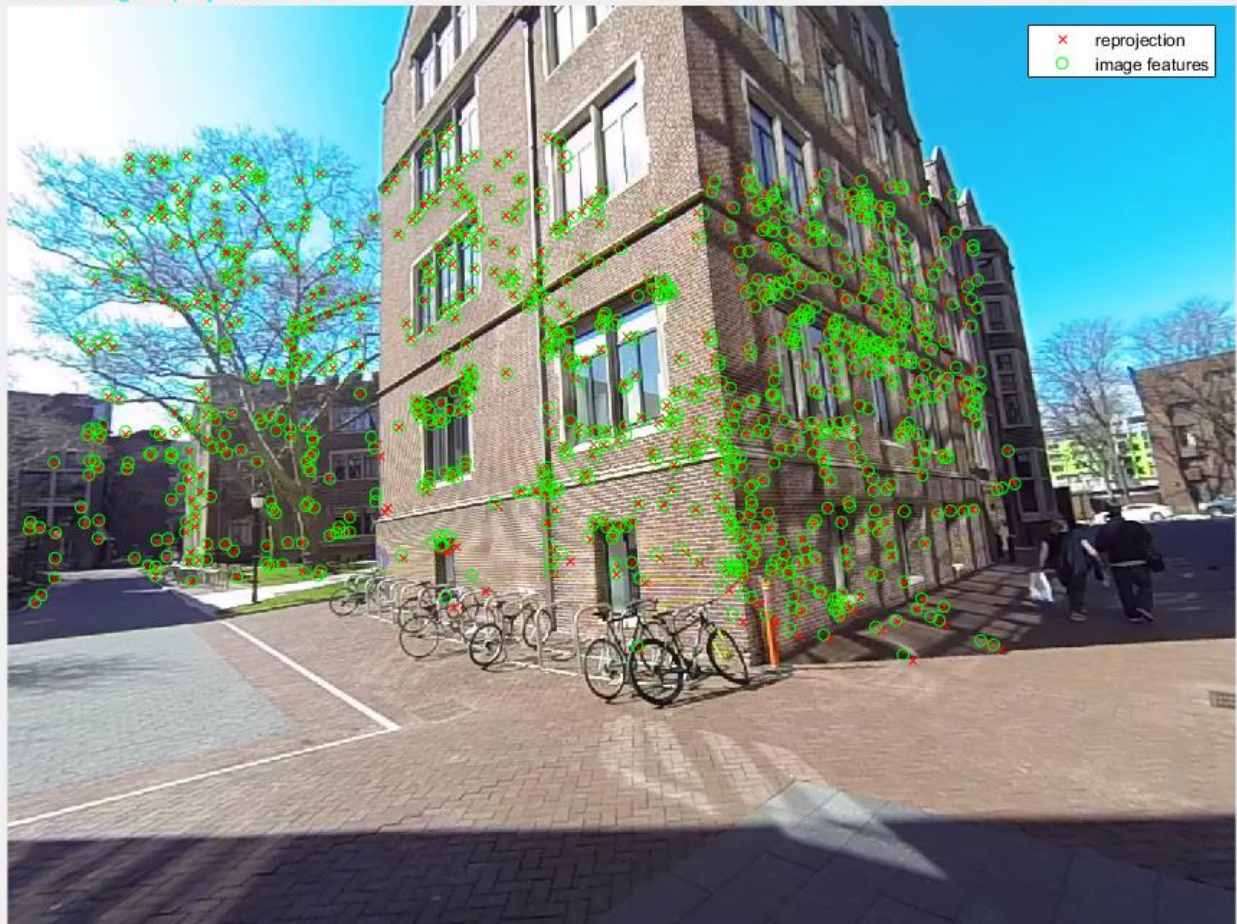


## Visualization of feature matching after outlier rejection

The average reprojection error is: 3.2864



Visualization of the all camera pose and 3D points cloud

