

#### DISTRIBUTION EXPECTATION

## Why

If we model some measured value as a random variable with induced distribution  $p:V\to \mathbb{R}$ , then one interpretation of p(v) for  $v\in V$  is the *proportion* of times in a large number of trials that we *expect* to measure the value v.

### **Definition**

Given a distribution  $p: \Omega \to \mathbf{R}$  and a real-valued outcome variable  $x: \Omega \to \mathbf{R}$ , the expectation (or mean) of x under p is  $\sum_{\omega \in \Omega} p(\omega) x(\omega)$ .

#### Notation

We denote the expectation of x under p by  $\mathbf{E}(x)$ . When there is no chance of ambiguity, we write  $\mathbf{E}(x)$ .

# **Properties**

Let  $x, y : \Omega \to \mathbb{R}$  be two outcome variables and  $p : \Omega \to \mathbb{R}$  a distribution. Let  $\alpha, \beta \in \mathbb{R}$ . Define  $z = \alpha x + \beta y$  by  $z(\omega) = \alpha x(\omega) + \beta y(\omega)$ . Then  $\mathbf{E}(z) = \alpha \mathbf{E}(x) + \beta \mathbf{E}(z)$ .

# **Example:** expectation

Suppose  $\Omega = \{1, 2, 3, 4, 5\}$  with p(1) = 0.1, p(2) = 0.15, p(3) = 0.1, p(5) = 0.25 and p(5) = 0.4. Define  $x : \Omega \to \mathbb{R}$  by

$$x(a) = \begin{cases} -1 & \text{if } a = 1 \text{ or } a = 2, \\ 1 & \text{if } a = 3 \text{ or } a = 4, \\ 2 & \text{if } a = 5. \end{cases}$$

The expectation of x under p is

$$\mathsf{E}x = -1 - 0.15 + 0.1 + 0.25 + 2(0.4) = 0.9.$$

### Two routes for computation

Denote by  $p_x: V \to \mathbf{R}$  the induced distribution of  $x: \Omega \to V$  (where  $V \subset \mathbf{R}$ ). Then  $\mathbf{E}(x) = \sum_{v \in V} p_x(v)v$  since

$$\sum_{\omega \in \Omega} p(\omega) x(\omega) = \sum_{v \in V} \sum_{\omega \in x^{-1}(v)} x(\omega) p(\omega)$$
$$= \sum_{v \in V} v \sum_{\omega \in x^{-1}(v)} p(\omega)$$
$$= \sum_{v \in V} x(v) p_x(v).$$

# Interpretations

We interpret the mean as the center of mass of the induced distribution.

