

## RANGE SPACES OF LINEAR TRANSFORMATIONS

## Why

When is a linear transformation *onto*? In other words, when is the range the whole space? This question is a bit more invovled, but we will start with observing in this sheet that the range of a linear map happens to be a subspace.

## Definition

For a linear transformation  $T \in \mathcal{L}(V, W)$ , we refer to range(T) as the range space (or image space) of T.

**Proposition 1.** Suppose  $T \in \mathcal{L}(V, W)$ . Then range T is a subspace of W.

*Proof.* We verify that range(T) contains 0 and is closed under vector addition and scalar multiplication. Clearly T(0) = 0, so  $0 \in \text{range } T$ . Next, suppose  $w_1, w_2 \in \text{range } T \subset W$  So there exists  $v_1, v_2 \in V$  so that

$$Tv_1 = w_1$$
 and  $Tv_2 = w_2$ 

We conclude  $w_1 + w_2 = Tv_1 + Tv_2 = T(v_1 + v_2)$ . So  $w_1 + w_2 \in \text{range } T$ . Likewise, if  $w \in \text{range } T$ , then there exists  $v \in V$  such that w = Tv. So then  $\lambda w = \lambda Tv = T(\lambda v)$ , and so  $\lambda w \in \text{range } T$ .

## **Examples**

To come.

