

## TREE DISTRIBUTION APPROXIMATORS

## Why

We approximate a distribution with a distribution that factors according to a given tree. Such a distribution requires tabulating fewer numbers to express the probability of outcome.

## **Definition**

We will use the relative entropy as a criterion of approximation. Given a distribution over a product of finite sets and a tree, we want to find the optimal approximator among distributions which factor according to the tree. We call such a distribution a tree distribution approximator or tree approximator of the given distribution for the tree. We call the tree the approximator tree.

## Result

**Prop.** 1. Let  $A_1, \ldots, A_n$  be finite non-empty sets. Define  $A = \prod_{i=1}^n A_i$ . Let  $q: A \to [0,1]$  a distribution and T a tree on  $\{1,\ldots,n\}$ . The distribution  $p_T^*: A \to [0,1]$  defined by

$$p_T^* = q_1 \prod_{i 
eq 1} q_{i|\mathrm{pa}\,i}$$

minimizes the relative entropy with q among all distributions on A which factor according to T.

*Proof.* Let  $p:A\to [0,1]$  be a distribution which factors ac-

cording to T. First, express

$$p = p_1 \prod_{i \neq i} p_{i|\text{pa}\,i}$$

where pa i is the parent of vertex i in T rooted at vertex 1 (i = 2, ..., n).

Second, recall that the relative entropy of q with p is H(q, p) - H(q). Since H(q) does not depend on p, p is a minimizer of the relative of q with p if and only if p is a minimizer of H(q, p).

Third, express

$$H(q, p) = -\sum_{a \in A} q(a) \log p(a)$$

$$= -\sum_{a \in A} q(a) \left( \log p_1(a_1) + \sum_{i \neq 1} \log p_{i|pai}(a_i, a_{pai}) \right)$$

$$= H(q_1, p_1) + \sum_{i \neq 1} \sum_{a_{pai} \in A_{pai}} q_{pai}(a_{pai}) H(q_{i|pai}(\cdot, a_{pai}), p_{i|pai}(\cdot, a_{pai}))$$

which separates across  $p_1$  an  $p_{i|pai}(\cdot, a_{pai})$  for i = 2, ..., n and  $a_{pai} \in A_{pai}$ .

Fourth, recall  $H(\cdot,\cdot) \geq 0$  and is zero on repeated pairs. By this, we mean, for example,  $H(p_1, p_1) = 0$ . So  $p_1 = q_1$  and  $p_{i|\text{pa}\,i} = q_{i|\text{pa}\,i}$  are solutions.

Proposition 1 states the form of an optimal approximator given a tree. A natural next question is to select the tree.

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