

## **ORDINARY ROW REDUCTIONS**

## Why

When does the technique of row reductions prevail?

## Multivariable row reductions

Let  $S = (A \in \mathbb{R}^{m \times m}, b \in \mathbb{R}^m)$  be a linear system with  $A_{kk} \neq 0$ . The *kth row reduction* of S is the linear system (C, d) with  $C_{st} = A_{st} - (A_{sk}/A_{kk})A_{kt}$  if  $i < s \le m$  and  $C_{st} = A_{st}$  otherwise.

The idea, as in the example in Linear System Row Reductions, is to eliminate variable k from equations  $k+1,\ldots,m$ . We are taking the kth column of A from

$$\begin{bmatrix} A_{1k} \\ \vdots \\ A_{kk} \\ A_{k+1,k} \\ \vdots \\ A_{mk} \end{bmatrix} \quad \text{to} \quad \begin{bmatrix} A_{1k} \\ \vdots \\ A_{kk} \\ 0 \\ \vdots \\ 0 \end{bmatrix}.$$

We interpret the *i*th row reduction as subtracting equations of the system or reducing rows of the array A. If  $a^i, c^i \in \mathbb{R}^n$  denote the *i*th rows of A and C,  $c^i = a^i - (A_{ik}/A_{kk})a^k$  for  $k < i \le m$ , In other words, we obtain the *i*th row of matrix C by subtracting a multiple of the kth row of matrix A from the *i*th row of matrix A, for  $k < i \le m$ . The following is an immediate consequence of real arithmetic.

**Proposition 1.** Let  $(A \in \mathbb{R}^{m \times n}, b \in \mathbb{R}^n)$  be a linear system

which row reduces to (C,d). Then  $x \in \mathbb{R}^n$  is a solution of (A,b) if and only if it is a solution of (C,d).

## Ordinary reductions

We call the system S ordinarily reducible if there exists a sequence of systems  $S_1, \ldots, S_{m-1}$  so that  $S_1$  is the 11-reduction of S and  $S_i$  is the ii-reduction of  $S_{i-1}$  for  $i = 1, \ldots, n-1$ . In this case, we call  $S_{n-1}$  the final ordinary reduction (or just ordinary reduction) of S. The following is an immediate consequence of Proposition 1.

**Proposition 2.** Let S' be the (final) ordinary reduction of S. Then S and S' have equivalent solution sets.

This process of constructing the ordinary reduction is called Gauss elimination or Gaussian elimination. We call the kkth entry of system  $S_{k-1}$  the pivot. In an ordinarily reducible system, the pivots are nonzero.

The idea is that a system is ordinarily reducible if we can take row reductions in sequence an end up with a system that is easy to back-substitute and solve. The difficulty is that this need not be the case. For example, consider the following obvious difficulty. The system (A, b) in which

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 2 \end{bmatrix} \text{ and } \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

is not ordinarily reducible, but clearly solvable.

