



## Why

We generalize the notion of a point in  $\mathbf{R}$ , a line in  $\mathbf{R}^2$  and a plane in  $\mathbf{R}^3$ .

## Definition

A *hyperplane* is a  $(n - 1)$ -dimensional affine set in  $\mathbf{R}^n$ .

## Discussion

Since the  $n - 1$ -dimensional subspaces are the orthogonal complements of the one-dimensional subspaces, they are the sets which can be specified by

$$\{x \in \mathbf{R}^n \mid x \perp b\} + a$$

for  $a, b \in \mathbf{R}^n$ . The hyperplanes are translates of these,

$$\begin{aligned} \{x \in \mathbf{R}^n \mid x \perp b\} + a &= \{x + a \mid \langle x, b \rangle = 0\} \\ &= \{y \mid \langle y - a, b \rangle = 0\} = \{y \mid \langle y, b \rangle = \beta\}, \end{aligned}$$

where  $\beta = \langle a, b \rangle$ .

## Characterization

**Proposition 1.**  *$H \subset \mathbf{R}^n$  is a hyperplane if and only if there exists  $\beta \in \mathbf{R}$  and nonzero  $b \in \mathbf{R}^n$  so that*

$$H = \{x \in \mathbf{R}^n \mid \langle x, b \rangle = \beta\}.$$

**Remark 1.**  *$b$  and  $\beta$  are unique up to a common nonzero multiple. For example,  $b, \beta$  and  $2b, 2\beta$  give the same hyperplane.*

**Remark 2.** *Any such vector  $b$  is called a normal (or normal vector) to the hyperplane.*

**Remark 3.** *If  $H$  is a hyperplane not containing the origin, then there is a unique unit vector  $u$  and  $\alpha > 0$  so that*

$$H = \{x \in \mathbf{R}^n \mid \langle x, u \rangle = \alpha\}$$



