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1 Sets

1.1 Why

We speak of a collection of objects, pre-specified or possessing a similar property.

1.2 Definition

A **set** is a collection of objects. We use **object** as usual in the English language. So a set is an object with the property that it contains other objects.

In thinking of a set, then, we regularly consider the objects it contains. We call the objects contained in a set the **members** or **elements** of the set. So we say that an object contained in a set is a **member of** or an **element of** the set.

1.2.1 Notation

We denote sets by upper case latin letters: for example, A , B , and C . We denote elements of sets by lower case latin letters: for example, a , b , and c . We denote that an object a is an element of a set A by $a \in A$. We read the notation $a \in A$ aloud as “a

in A .” The \in is a stylized ϵ , a mnemonic for “element of”. We write $a \notin A$, read aloud as “a not in A ,” if a is not an element of A .

If we can write down the elements of A , we do so using brace notation. For example, if the set A is such that it contains only the elements a, b, c , we denote A by $\{a, b, c\}$. If the elements of a set are well-known, then we introduce the set in English and name it; often we select the name mnemonically. For example, let L be the set of latin letters.

If the elements of a set satisfy some common condition, then we use the braces and include the condition. For example, let V be the set of vowels. We can denote V by $\{l \in L \mid l \text{ is a vowel}\}$. We read the symbol \mid aloud as “such that.” We read the whole notation aloud as “l in L such that l is a vowel.” We call the notation **set-builder notation**. Set-builder notation is indispensable for sets defined implicitly by some condition. Here we could have alternatively denoted V by $\{“a”, “e”, “i”, “o”, “u”\}$. We prefer the former, slightly more concise notation.

1.3 Two Sets

Let A a set. A **subset** of A is a set whose elements are also contained in A . A **superset** if A is a set which contains all the elements of A . Two sets are **equal** if they contain the same elements; equivalently if they are each subsets of each other.

The **power set** of A is the set of subsets of A . The **empty set** is the set containing no elements. The empty set is subset

of every set.

1.3.1 Notation

Let A and B be sets. We denote that A is a subset of B by $A \subset B$. We read the notation $A \subset B$ aloud as “A subset B”. We denote that A is equal to B by $A = B$. We read the notation $A = B$ aloud as “A equals B”. We denote the empty set by \emptyset , read aloud as “empty.” We denote the power set of A by 2^A , read aloud as “two to the A.”



2 Ordered Pairs

2.1 Why

We speak of objects composed of elements from different sets.

2.2 Definition

Let A and B be non-empty sets. Let $a \in A$ and $b \in B$. An **ordered pair** is the set $\{\{a\}, \{a, b\}\}$. The **cartesian product** of A and B is the set of all ordered pairs. The **first element** of $\{\{a\}, \{a, b\}\}$ is a and the **second element** is b .

We observe that two pairs are equal if they have equal elements in the same order. If $A \neq B$, the ordering causes the cartesian product of A and B to differ from the cartesian product of B with A . If $A = B$, however, the symmetry holds.

2.2.1 Notation

We denote the ordered pair $\{\{a\}, \{a, b\}\}$ by (a, b) . We denote the cartesian product of A with B by $A \times B$, read aloud as “A cross B.” In this notation, if $A \neq B$, then $A \times B \neq B \times A$.



3 Relations

3.1 Why

We want to relate elements of two sets.

3.2 Definition

A **relation** between two non-empty sets A and B is a subset of $A \times B$. A relation on a single set C is a subset of $C \times C$.

3.2.1 Notation

We denote relations with upper case capital latin letters because they are sets. Let R be a relation on A and B . We denote that $(a, b) \in R$ by aRb , read aloud as “a in relation R to b.”

Often, instead of latin letters we use other symbols. For example, \sim , $=$, $<$, \leq , \prec , and \preceq .

3.3 Properties

Let R be a relation on a non-empty set A . R is **reflexive** if

$$(a, a) \in R$$

for all $a \in A$. R is **transitive** if

$$(a, b) \in R \wedge (b, c) \in R \implies (a, c) \in R$$

for all $a, b, c \in A$. R is **symmetric** if

$$(a, b) \in R \implies (b, a) \in R$$

for all $a, b \in A$. R is **anti-symmetric** if

$$(a, b) \in R \implies (b, a) \notin R$$

for all $a, b \in A$.



4 Functions

4.1 Why

We want a notion for a correspondence between two sets.

4.2 Definition

A **functional** relation on two sets relates each element of the first set with a unique element of the second set. A **function** is a functional relation.

The **domain** of the function is the first set and **codomain** of the function is the second set. The function **maps** elements **from** the domain **to** the codomain. We call the codomain element associated with the domain element the **result of applying** the function to the domain element.

4.2.1 Notation

Let A and B be sets. If A is the domain and B the codomain, we denote the set of functions from A to B by $A \rightarrow B$, read aloud as “A to B”.

A function is an element of the set $A \rightarrow B$, so we denote them

by lower case latin letters, especially f , g , and h . Of course, f is a mnemonic for function; g and h follow f in the alphabet. We denote that $f \in A \rightarrow B$, by $f : A \rightarrow B$, read aloud as “f from A to B”.

Let $f : A \rightarrow B$. For each element $a \in A$, we denote the result of applying f to a by $f(a)$, read aloud “f of a.” We sometimes drop the parentheses, and write the result as f_a , read aloud as “f sub a.”

Let $g : A \times B \rightarrow C$. We often write $g(a, b)$ or g_{ab} instead of $g((a, b))$. We read $g(a, b)$ aloud as “g of a and b”. We read g_{ab} aloud as “g sub a b.”

4.3 Properties

Let $f : A \rightarrow B$. The **image** of a set $C \subset A$ is the set $\{f(c) \in B \mid c \in C\}$. The **range** of f is the image of the domain. The **inverse image** of a set $D \subset B$ is the set $\{a \in A \mid f(a) \in D\}$.

The range need not equal the codomain; though it, like every other image, is a subset of the codomain. The function maps to domain **on** to the codomain if the range and codomain are equal; in this case we call the function **onto**. This language suggests that every element of the codomain is used by f . It means that for each element b of the codomain, we can find an element a of the domain so that $f(a) = b$.

An element of the codomain may be the result of several elements of the domain. This overlapping, using an element of the

codomain more than once, is a regular occurrence. If a function is a unique correspondence in that every domain element has a different result, we call it **one-to-one**. This language is meant to suggest that each element of the domain corresponds to one and exactly one element of the codomain, and vice versa.

4.3.1 Notation

Let $f : A \rightarrow B$. We denote the image of $C \subset A$ by $f(C)$, read aloud as “f of C.” This notation is overloaded: for $c \in C$, $f(c) \in B$, whereas $f(C) \subset B$. Read aloud, the two are indistinguishable, so we must be careful to specify whether we mean an element c or a set C . The property that f is onto can be written succinctly as $f(A) = B$. We denote the inverse image of $D \subset B$ by $f^{-1}(D)$, read aloud as “f inverse D.”



5 Natural Numbers

5.1 Why

We want to count, forever.

5.2 Definition

We define the set of **natural numbers** implicitly. There is an element of the set which we call **one**. Then we say that for each element n of the set, there is a unique corresponding element called the **successor** of n which is also in the set. The **successor function** is the implicitly defined a function from the set into itself associating elements with their successors. We call the elements **numbers** and the refer to the set itself as the **naturals**.

To recap, we start by knowing that one is in the set, and the successor of one is in the set. We call the successor of one **two**. We call the successor of two **three**. And so on using the English language in the usual manner. We are saying, in the language of sets, that the essence of counting is starting with one and adding one repeatedly.

5.2.1 Notation

We denote the set of natural numbers by N , a mnemonic for natural. We often denote elements of N by n , a mnemonic for number, or m , a letter close to n . We denote the element called one by 1.

5.3 Induction

We assert two additional self-evident and indispensable properties of these natural numbers. First, one is the successor of no other element. Second, if we have a subset of the naturals containing one with the property that it contains successors of its elements, then that set is equal to the natural numbers. We call this second property the **principle of mathematical induction**.

These two properties, along with the existence and uniqueness of successors are together called **Peano's axioms** for the natural numbers. When in familiar company, we freely assume Peano's axioms.

5.4 Notation

As an exercise in the notation assumed so far, we can write Peano's axioms: N is a set along with a function $s : N \rightarrow N$ such that

1. $s(n)$ is the successor of n for all $n \in N$.

2. s is one-to-one; $s(n) = s(m) \implies m = n$ for all $m, n \in N$.
3. There does not exist $n \in N$ such that $s(n) = 1$.
4. If $T \subset N$, $1 \in T$, and $s(n) \in T$ for all $n \in T$, then $T = N$.



6 Graphs

6.1 Why

We want to visualize relations.

6.2 Definition

A **graph** is a set and a relation on the set. The graph is **undirected** if the relation is symmetric; otherwise the graph is **directed**.

A **vertex** of the graph is an element of the set. The set is called the **vertex set**. An **edge** of the graph is an element of the relation. The relation is called the **edge set**.

6.2.1 Notation

We denote the vertex set by V , a mnemonic for vertex. We denote the edge set by E , a mnemonic for edge. We denote a graph by (V, E) . If the vertex set is assumed we can unambiguously refer to the graph by E .

6.2.2 Visualization

We visualize the graph by drawing a point for each vertex. If two vertices u and v are in relation, we draw a line from the point corresponding to u to the point corresponding to v with an arrow at the point corresponding to v . If the graph is undirected, we omit arrows.

6.3 Paths

A path in a relation is a sequence of elements in which consecutive elements are related. A path **cycles** if an element appears more than once. A path is **finite** if the sequence is finite. A finite path is a **loop** if it cycles once.



7 Trees

7.1 Why

Tree branches split and do not recombine. We formalize this property in the language of graphs.

7.2 Definition

A **tree** is a connected acyclic graph.

7.2.1 Notation

Let (V, E) be a tree. When the vertex set is clear from context, we use T , a mnemonic for “tree,” to denote the edge set. We denote the set of trees on the vertex set V by $T(V)$.

7.3 Properties

Proposition 1. *In any tree, there is only one path between any two vertices.*



8 Graph Cliques

8.1 Why

We speak of the complete subgraphs of a graph.

8.2 Definition

A **complete** graph is one for which an edge exists between any two nodes.

A **subgraph** of a given graph is a graph whose vertex set is a subset of the given vertex set and whose edge set is the subset of given edges connecting vertices in the vertex subset. With reference to the underlying graph, then, a subgraph can be specified completely by its vertex set.

A **clique** of a given graph is a complete subgraph of that graph. When speaking of the cliques of a given graph, we identify the cliques with their vertex set. The relation contained in gives a partial order on cliques. A clique is **maximal** if it maximal with respect to this relation; i.e., it is contained in no other clique. As a convention, we include \emptyset as a clique.

8.2.1 Notation

Let (V, E) a graph. We denote a clique by $C \subset V$, a mnemonic for clique.



9 Function Composition

9.1 Why

We want a notion for applying two functions one after the other.
We apply a first function then a second function.

9.2 Definition

Consider two functions for which the codomain of the first function is the domain of the second function.

The **composition** of the second function with the first function is the function which associates each element in the first's domain with the element in the second's codomain that the second function associates with the result of the first function.

The idea is that we take an element in the first domain. We apply the first function to it. We obtain an element in the first's codomain. This result is an element of the second's domain. We apply the second function to this result. We obtain an element in the second's codomain. The composition of the second function with the first is the function so constructed.

9.2.1 Notation

Let A, B, C be non-empty sets. Let $f : A \rightarrow B$ and $g : B \rightarrow C$. We denote the composition of g with f by $g \circ f$ read aloud as “ g composed with f .” To make clear the domain and codomain, we denote the composition $g \circ f : A \rightarrow C$.

In previously introduced notation, $g \circ f$ satisfies

$$(g \circ f)(a) = g(f(a))$$

for all $a \in A$.

9.3 Inverses

The **identity function** on a set is a function which associates each element with itself. A function

A second function is an **inverse function** of a first function if the domain of the first function is the codomain of the second function, the domain of the second function is the codomain of the first function, and the composition of the first function with the second is the identity function on the first domain and the composition of the second function on the first is the identity function on the second domain.



10 Function Inverses

10.1 Why

We want a notion of reversing functions.

10.2 Definition

An **identity function** is a relation on a set which is functional and reflexive. It associates each element in the set with itself. There is only one identity function associated to each set.

Consider two functions for which the codomain of the first function is the domain of the second function and the codomain of the second function is the domain of the first function. These functions are **inverse functions** if the composition of the second with the first is the identity function on the first's domain and the composition of the first with the second is the identity function on the second's domain.

In this case we say that the second function is an **inverse** of the first, and vice versa. When an inverse exists, it is unique, so we refer to the **inverse** of a function.

10.2.1 Notation

Let A a non-empty set. We denote the identity function on A by id_A , read aloud as “identity on A .” id_A maps A onto A .

Let A, B be non-empty sets. Let $f : A \rightarrow B$ and $g : B \rightarrow A$ be functions. f and g are inverse functions if $g \circ f = \text{id}_A$ and $f \circ g = \text{id}_B$.

10.3 The Inverse

We discuss existence and uniqueness of an inverse.

Proposition 2. *Let $f : A \rightarrow B$, $g : B \rightarrow A$, and $h : B \rightarrow A$.*

If g and h are both inverse functions of f , then $g = h$.

Proof.

□

Proposition 3. *If a function is one-to-one and onto, it has an inverse.*

Proof.

□



11 Order Relations

11.1 Why

We want to handle elements of a set in a particular order.

11.2 Definition

Let R be a relation on a non-empty set A . R is a **partial order** if it is reflexive, transitive, and anti-symmetric.

A **partially ordered set** is a set and a partial order. The language partial is meant to suggest that two elements need not be comparable. For example, suppose R is $\{(a, a) \mid a \in A\}$; we may justifiably call this no order at all and call A totally unordered, but it is a partial order by our definition.

Often we want all elements of the set A to be comparable. We call R **connexive** if for all $a, b \in A$, $(a, b) \in R$ or $(b, a) \in R$. If R is a partial order and connexive, we call it a **total order**.

A **totally ordered set** is a set together with a total order. The language is a faithful guide: we can compare any two elements. Still, we prefer one word to three, and so we will use the shorter term **chain** for a totally ordered set; other terms include **simply ordered set** and **linearly ordered set**.

11.2.1 Notation

We denote total and partial orders on a set A by \preceq . We read \preceq aloud as “precedes or equal to” and so read $a \preceq b$ aloud as “a precedes or is equal to b.” If $a \preceq b$ but $a \neq b$, we write $a \prec b$, read aloud as “a precedes b.”



12 Algebra

12.1 Why

We want to combine set elements to get other set elements.

12.2 Basics

An **operation** on a set is a function from ordered pairs of elements in the set to the same set. We use operations to combine the elements. We operate on pairs. An **algebra** is a set and an operation. We call the set the **ground set**.

12.2.1 Notation

Let A a set and $g : A \times A \rightarrow A$. We commonly forego the notation $g(a, b)$ and instead write $a g b$. We call this style **infix notation**.

Using lower case latin letters for every the elements and for the operation is confusing, but we often have special symbols for particular operations. Examples of such symbols include $+$, $-$, \cdot , \circ , and \star .

If we had a set A and an operation $+$: $A \times A \rightarrow A$, we would

write $a + b$ for the result of applying $+$ to (a, b) . In denoting the algebra, we would say let $(A, +)$ be an algebra.

12.3 Operation Properties

An operation **commutes** if the result of two elements is the same regardless of their order; we call the operation **commutative**

An operation **associates** if given any three elements in order it doesn't matter whether we first operate on the first two and then with the result of the first two the third, or the second two and with the result of the second two the first.

A first operation over a set **distributes** over a second operation over the same set if the result of applying the first operation to an element and a result of the second operation is the same as applying the second operation to the results of the first operation with the arguments of the second operation.

12.3.1 Notation

Let $(A, +)$ an algebra.

We denote that $+$ commutes by asserting

$$a + b = b + a$$

for all $a, b \in A$. We denote that $+$ associates by asserting

$$(a + b) + c = (a + b) + c$$

for all $a, b, c \in A$. Let (A, \cdot) a second algebra over the same set. We denote that \cdot distributes over $+$ by

$$a \cdot (b + c) = (a \cdot b) + (a \cdot c)$$

for all $a, b, c \in A$.

12.4 Identity Elements

We call $e \in A$ an **identity element** if (1) $e + a = e$ and (2) $a + e = e$ for all $a \in A$. If only (1) holds, we call e a **left identity**. If only (2) holds, we call e a **right identity**.

12.5 Inverse Elements

We call $b \in A$ an **inverse element** of $a \in A$ if (1) $b + a = e$ and (2) $a + b = e$. If only (1) holds, we call e a **left inverse**. If only (2) holds, we call e a **right inverse**.



13 Set Operations

13.1 Why

We want to consider the elements of two sets together at once, and other sets created from two sets.

13.2 Definitions

Let A and B be two sets.

The **union** of A with B is the set whose elements are in either A *or* B *or* both. The key word in the definition is *or*.

The **intersection** of A with B is the set whose elements are in both A *and* B . The keyword in the definition is *and*.

Viewed as operations, both union and intersection commute; this property justifies the language “with.” The intersection is a subset of A , of B , and of the union of A with B .

The **symmetric difference** of A and B is the set whose elements are in the union but not in the intersection. The symmetric difference commutes because both union and intersection commute; this property justifies the language “and.” The symmetric difference is a subset of the union.

Let C be a set containing A . The **complement** of A in C is the symmetric difference of A and C . Since $A \subset C$, the union is C and the intersection is A . So the complement is the “left-over” elements of B after removing the elements of A .

We call these four operations **set-algebraic operations**.

13.2.1 Notation

Let A, B be sets. We denote the union of A with B by $A \cup B$, read aloud as “A union B.” \cup is a stylized U. We denote the intersection of A with B by $A \cap B$, read aloud as “A intersect B.” We denote the symmetric difference of A and B by $A \Delta B$, read aloud as “A symdiff B.” “Delta” is a mnemonic for difference.

Let C be a set containing A . We denote the complement of A in C by $C - A$, read aloud as “C minus A.”

13.2.2 Results

Proposition 4. *For all sets A and B the operations \cup , \cap , and Δ commute.*

Proposition 5. *Let S a set. For all sets $A, B \subset S$,*

$$(1) \quad S - (A \cup B) = (S - A) \cap (S - B)$$

$$(2) \quad S - (A \cap B) = (S - A) \cup (S - B).$$

Proposition 6. *Let S a set. For all sets $A, B \subset S$,*

$$A \Delta B = (A \cup B) \cap C_S(A \cap B)$$

TODO : notation



14 Arithmetic

14.1 Why

Counting one by one is slow so we define an algebra on the naturals.

14.2 Sums and Addition

Let m and n be two natural numbers. If we apply the successor function to m n times we obtain a number. If we apply the successor function to n m times we obtain a number. Indeed, we obtain the same number in both cases. We call this number the **sum** of m and n . We say we **add** m to n , or vice versa. We call this symmetric operation mapping (m, n) to their sum **addition**.

14.2.1 Notation

We denote the operation of addition by $+$ and so denote the sum of the naturals m and n by $m + n$.

14.3 Products and Multiplication

Let m and n naturals. If we add n copies of m we obtain a number. If we add m copies of n we obtain a number. Indeed, we obtain the same number in both cases. We call this number the **product** of m and n . We say we **multiply** m to n , or vice versa. We call this symmetric operation mapping (m, n) to their product **multiplication**.

14.3.1 Notation

We denote the operation of multiplication by \cdot and so denote the product of the naturals m and n by $m \cdot n$.



15 Equivalence Relations

15.1 Why

We want to handle at once all elements which are indistinguishable or equivalent in some aspect.

15.2 Definition

A relation R on a set A is an **equivalence relation** if it is reflexive, symmetric, and transitive.

For an element $a \in A$, we call the set of elements in relation R to a the **equivalence class** of a . The key observation, recorded and proven below, is that the equivalence classes partition the set A . A frequent technique is to define an appropriate equivalence relation on a large set A and then to work with the set of equivalence classes of A .

We call the set of equivalence classes the **quotient set** of A under R . An equally good name is the divided set of A under R , but this terminology is not standard. The language in both cases reminds us that \sim partitions the set A into equivalence classes.

15.2.1 Notation

If R is an equivalence relation on a set A , we use the symbol \sim . When alone, \sim is read aloud as “sim,” but we still read $a \sim b$ aloud as “a equivalent to b.” We denote the quotient set of A under \sim by A/\sim , read aloud as “A quotient sim”.

15.2.2 Results

TODO



16 Families

16.1 Why

We want to generalize operations beyond two objects.

16.2 Definition

Let A, B be non-empty sets. A **family** of elements of a first set **indexed** by elements of a second set is the range of a function from the second set to the first set. We call second set the **index set**.

If the index set is a finite set, we call the family a **finite family**. If the index set is a countable set, we call the family a **countable family**. If the index set is an uncountable set, we call the family a **uncountable family**.

If the codomain is a set of sets, we call the family a **family of sets**. We often use a subset of the whole natural numbers as the index set. In this case, and for other indexed sets with orders, we call the family an **ordered family**.

16.2.1 Notation

Let A be a non-empty set. We denote the index set by I , a mnemonic for index. For $i \in I$, let a_i denote the result of applying the function to i ; the notation evokes function notation but avoids naming the function.

We denote the family of a_α indexed with I by $\{a_\alpha\}_{\alpha \in I}$, which is short-hand for set-builder notation. We read this notation “a sub-alpha, alpha in I.”

16.3 Operations

The **pairwise extension** of a commutative operation is the function from finite families of the ground set to the ground set obtained by applying the operation pairwise to elements.

The **ordered pairwise extension** of an operation is the function from finite families ground set to the ground set obtained by applying the operation pairwise to elements in order.

16.3.1 Notation

Let $(A, +)$ be an algebra and $\{A_i\}_{i=1}^n$ a finite family of elements of A . We denote the pairwise extension by

$$\bigoplus_{i=1}^n A_i$$

16.4 Family Set Algebra

We define the set whose elements are the objects which are contained in at least one family member the **family union**. We define the set whose elements are the objects which are contained in all of the family members the **family intersection**.

16.4.1 Notation

We denote the family union by $\cup_{\alpha \in I} A_\alpha$. We read this notation as “union over alpha in I of A sub-alpha.” We denote family intersection by $\cap_{\alpha \in I} A_\alpha$. We read this notation as “intersection over alpha in I of A sub-alpha.”

16.4.2 Results

Proposition 7. *For an indexed family $\{A_\alpha\}_{\alpha \in I}$ in S , if $I = \{i, j\}$ then*

$$\cup_{\alpha \in I} A_\alpha = A_i \cup A_j$$

and

$$\cap_{\alpha \in I} A_\alpha = A_i \cap A_j.$$

Proposition 8. *For an indexed family $\{A_\alpha\}_{\alpha \in I}$ in S , if $I = \emptyset$, then*

$$\cup_{\alpha \in I} A_\alpha = \emptyset$$

and

$$\cap_{\alpha \in I} A_\alpha = S.$$

Proposition 9. *For an indexed family $\{A_\alpha\}_{\alpha \in I}$ in S .*

$$C_S(\cup_{\alpha \in I} A_\alpha) = \cap_{\alpha \in I} C_S(A_\alpha)$$

and

$$C_S(\cap_{\alpha \in I} A_\alpha) = \cup_{\alpha \in I} C_S(A_\alpha).$$



17 Partitions

17.1 Why

We divide a set into disjoint subsets whose union is the whole set. In this way we can handle each subset of the main set individually, and so handle the entire set piece by piece.

17.2 Definition

A **disjoint family** of sets is a family for which the intersection of any two member sets is empty. A **partition** of a set is a disjoint family of subsets of the set whose union is the set. A **piece** of a partition is an element of the family.

17.2.1 Notation

No new notation for partitions. Instead, we record the properties of partitions in previously introduced notation.

Let A be a set and $\{A_\alpha\}_{\alpha \in I}$ a family of subsets of A . We denote the condition that the family is disjoint by $A_\alpha \cap A_\beta = \emptyset$, for all $\alpha, \beta \in I$. We denote the condition that the family union is A by $\cup_{\alpha \in I} A_\alpha = A$.



18 Direct Products

18.1 Why

We can profitably generalize the notion of cartesian product to families of sets indexed by the natural numbers.

18.2 Direct Products

The **direct product** of family indexed by a subset of the naturals is the set whose elements are ordered sequences of elements from each set in the family. The ordering on the sequences comes from the natural ordering on N . If the index set is finite, we call the elements of the direct product **n -tuples**. If the index set is the natural numbers, and every set in the family is the same set A , we call the elements of the direct product the **sequences** in A .

18.2.1 Notation

For a family $\{A_\alpha\}_{\alpha \in I}$ of S with $I = \{1, \dots, n\}$, we denote the direct product by

$$\prod_{i=1}^n A_i.$$

We read this notation as “product over alpha in I of A sub-alpha.” We denote an element of $\prod_{i=1}^n A_i$ by (a_1, a_2, \dots, a_n) with the understanding that $a_1 \in A_1, a_2 \in A_2, \dots, a_n \in A_n$.

If I is the set of natural numbers we denote the direct product by

$$\prod_{i=1}^{\infty} A_i.$$

We denote an element of $\prod_{i=1}^{\infty} A_i$ by (a_i) with the understanding that $a_i \in A_i$ for all $i = 1, 2, 3, \dots$. If $A_i = A$ for all $i = 1, 2, 3, \dots$, then (a_i) is a sequence in A .



19 Sequences

19.1 Why

We introduce language for the steps of an infinite process.

19.2 Definition

A **sequence** is a function from the natural numbers to a set.

Equivalently, a sequence is an element of a direct product of a family of sets for which each set in the family is identical and the index set is the natural numbers.

19.2.1 Notation



20 Monotone Sequences

20.1 Why

If the base set of a sequence has a partial order, then we can discuss its relation to the order of sequence.

20.2 Definition

A sequence on a partially ordered set is **non-decreasing** if whenever a first index precedes a second index the element associated with the first index precedes the element associated with the second element. A sequence on a partially ordered set is **increasing** if it is non-decreasing and no two elements are the same. An increasing sequence is non-decreasing.

A sequence on a partially ordered set is **non-increasing** if whenever a first index precedes a second index the element associated with the first index succeeds the element associated with the second element. A sequence on a partially ordered set is **decreasing** if it is non-increasing and no two elements are the same. A decreasing sequence is non-increasing.

A sequence on a partially ordered set is **monotone** if it is non-decreasing, or non-increasing. A sequence on a partially or-

dered set is **strictly monotone** if it is decreasing, or increasing.

20.2.1 Notation

Let A a non-empty set with partial order \preceq . Let $\{a_n\}_n$ a sequence in A .

The sequence is non-decreasing if $n \leq m \implies a_n \preceq a_m$, and increasing if $n < m \implies a_n \prec a_m$. The sequence is non-increasing if $n \leq m \implies a_n \succeq a_m$, and decreasing if $n < m \implies a_n \succ a_m$.

20.3 Examples

Example 10. Let A a non-empty set and $\{A_n\}_n$ a sequence of sets in 2^A . Partially order elements of 2^A by the relation contained in.



21 Nets

21.1 Why

We generalize the notion of sequence to index sets beyond the naturals.

21.2 Definition

A sequence is a function on the natural numbers; this set has two important properties: (a) we can order the natural numbers and (b) we can always go “further out.”

To elaborate on property (b): if handed two natural numbers m and n , we can always find another, for example $\max\{m, n\} + 1$, larger than m and n . We might think of larger as “further out” from the first natural number: 1.

Combining these two observations, we define a directed set:

Definition 11. A **directed set** is a set D with a partial order \preceq satisfying one additional property: for all $a, b \in D$, there exists $c \in D$ such that $a \preceq c$ and $b \preceq c$.

Definition 12. A **net** is a function on a directed set.

A sequence, then, is a net. The directed set is the set of natural numbers and the partial order is $m \preceq n$ if $m \leq n$.

21.2.1 Notation

Directed sets involve a set and a partial order. We commonly assume the partial order, and just denote the set. We use the letter D as a mnemonic for directed.

For nets, we use function notation and generalize sequence notation. We denote the net $x : D \rightarrow A$ by $\{a_\alpha\}$, emulating notation for sequences. The use of α rather than n reminds us that D need not be the set of natural numbers.



22 Categories

22.1 Why

We generalize the notion of sets and functions.

22.2 Definition

A **category** is a collection of objects together with a set of **category maps** for each ordered pair of objects. The set of maps has a binary operation called **category composition**, whose induced algebra is associative and contains identities.

As the fundamental example, consider the category whose objects are sets and whose maps are functions. The sets are the objects of the category. The functions are the maps. The rule of composition is ordinary function composition. The map identities are the identity functions. We call this category the **category of sets**.

22.2.1 Notation

Our notation for categories is guided by our generalizing the notions of set and functions.

We denote categories with upper-case latin letters in script; for example, \mathcal{C} . We read \mathcal{C} aloud as “script C.” Upper case latin letters remind that the category is a set of objects. The script form reminds that these objects may themselves be sets.

We denote the objects of a category by upper-case latin letters, for example A, B, C ; an allusion to the idea that these generalize sets. We denote the set of maps for an ordered pair of objects (A, B) by $A \rightarrow B$; an allusion to the function notation. We denote members of $A \rightarrow B$ using lower case latin letters, for example f, g, h ; an allusion to our function notation.



23 Groups

23.1 Why

We generalize the algebraic structure of addition over the integers.

23.2 Definition

A **group** is an algebra with: (1) an associative operation, (2) an identity element, and (3) an inverse for each element. We call the operation of the algebra **group addition**. A **commutative group** is a group whose operation commutes.

23.2.1 Notation

TODO



24 Rings

24.1 Why

We generalize the algebraic structure of addition and multiplication over the integers.

24.2 Definition

A **ring** is two algebras over the same ground set with: (1) the first algebra a commutative group (2) an identity element in the second algebra, and (3) the operation of the second algebra distributes over the operation of the first algebra.

We call the operation of the first algebra **ring addition**. We call the operation of the second algebra **ring multiplication**.

24.2.1 Notation

TODO



25 Fields

25.1 Why

We generalize the algebraic structure of addition and multiplication over the rationals.

25.2 Definition

A **field** is two algebras over the same ground set with: (1) both algebras are commutative groups (2) the operation of the second algebra distributes over the operation of the first algebra.

We call the operation of the first algebra **field addition**. We call the operation of the second algebra **field multiplication**.

25.2.1 Notation

TODO



26 Vectors

26.1 Why

We speak of objects which we can add and scale.

26.2 Definition

26.2.1 Notation



27 Homomorphism

27.1 Why

We name a function which preserves group structure.

27.2 Definition

A **homomorphism** from group $(A, +)$ to group $(B, \tilde{+})$ is a function $f : A \rightarrow B$ such that $f(e_A) = f(e_B)$ for identities $e_A \in A$ and $e_B \in B$ and $f(a + a') = f(a) \tilde{+} f(a')$ for all $a, a' \in A$.

27.2.1 Notation

TODO



28 Cardinality

28.1 Why

We want to speak of the number of elements of a set. Subtlety arises when we can not finish counting the set's elements.

28.2 Finite Definition

If a set A is contained in a set B and not equal to B , we say that B is a **larger set** than A . Conversely, we say that A is a **smaller set** than B . We reason that we could pair the elements of B with themselves in A and still have some elements of B left over.

A **finite set** is one whose elements we can count and the process terminates. For example, $\{1, 2, 3\}$ or $\{a, b, c, d\}$. The **cardinality** of a finite set is the number of elements it contains. The cardinality of $\{1, 2, 3\}$ is 3 and the cardinality of $\{a, b, c, d\}$ is 4.

28.2.1 Notation

Let A be a non-empty set. We denote the cardinality of A by $|A|$.

28.3 Infinite Definition

Suppose we know that the counting process could never terminate. This situation superficially seems bizarre, but is in fact built in to some of our fundamental notions: namely, the natural numbers. We defined the natural numbers in a manner which made them not finite.

If we had a bag of natural numbers, we could use the total order to find the largest, and then use the existence of a successor to add a new largest number. Therefore, bizarrely, the process of counting the natural numbers can not terminate.

An **infinite set** is a non-empty set which is not finite. So the natural numbers are an infinite set. Alternatively we say that there are **infinitely many** natural numbers. The negating prefix “in” emphasizes that we have defined the nature of the size of the naturals indirectly: their size is not something we understand from the simple intuition of counting, but in contrast to the simple intuition of counting.

Still, we imagine that if we could go on forever, we could count the natural numbers; so in an infinite sense, they are countable. A **countable** set is one which is either (a) finite or (b) one for which there exists a one-to-one function mapping the natural numbers onto the set.

The natural numbers are countable: we exhibit the identity function. Less obviously the integer numbers and rational numbers are countable. Even more bizarre, the real numbers are not countable. An **uncountable** set is one which is not countable.

28.3.1 Notation

We denote the cardinality of the natural numbers by \aleph_0 .



29 Subset System

29.1 Why

We speak of a set and a set of its subsets satisfying properties. The utility of this abstract concept is proved by its examples, in future sheets.

29.2 Definition

A **subset system** is a pair of sets: the second set contains subsets of the first.

We call the first set the **base set**. If the base set is finite, we call the subset system a **finite subset system**. A **distinguished subset** is an element of the second set. An **undistinguished subset** is a subset of the first set which is not distinguished.

29.2.1 Notation

Let A be a set and $\mathcal{A} \subset 2^A$. We denote the subset system of A and \mathcal{A} by (A, \mathcal{A}) , read aloud as “A, script A.”

29.3 Example

Example 13. *Let A be a nonempty set. Let \mathcal{A} be 2^A . Then (A, \mathcal{A}) is a subset system.*



30 Topological Space

30.1 Why

We want to generalize the notion of continuity.

30.2 Definition

A **topological space** is a subset system for which: (1) the empty set and the base set are distinguished, (2) the intersection of a finite family of distinguished subsets is distinguished, and (3) the union of a family of distinguished subsets is distinguished. We call the set of distinguished subsets the **topology**. We call the distinguished subsets the **open sets**.

30.2.1 Notation

Let A be a non-empty set. For the set of distinguished sets, we use \mathcal{T} , a mnemonic for topology, read aloud as “script T”. We denote elements of \mathcal{T} by O , a mnemonic for open. We denote the topological space with base set A and topology \mathcal{T} by (A, \mathcal{T}) . We denote the properties satisfied by elements of \mathcal{T} :

1. $X, \emptyset \in \mathcal{T}$

$$2. \{O_i\}_{i=1}^n \subset \mathcal{T} \implies \bigcap_{i=1}^n O_i \in \mathcal{T}$$

$$3. \{O_\alpha\}_{\alpha \in I} \subset \mathcal{T} \implies \bigcup_{\alpha \in I} O_\alpha \in \mathcal{T}$$



31 Monotone Classes

31.1 Why

31.2 Definition

The **limit** of an increasing sequence of sets is the family union of the sequence. The **limit** of a decreasing sequence of sets is the family intersection of the sequence.

A **monotone limit** of an sequence of sets is the limit of a monotone sequence.

A **monotone space** is a subset space in which monotone limits of monotone sequences of distinguished sets are distinguished. We call the distinguished sets a **monotone class**.

31.2.1 Notation

Let A a non-empty set with partial order \preceq . Let (A, \mathcal{A}) be a subset space on A .

Let $\{A_n\}_n$ be an increasing or decreasing sequence in \mathcal{A} . We denote the limit of $\{A_n\}_n$ by $\lim_n A_n$.

If $\{A_n\}_n$ is increasing, $\lim_n A_n = \cup_n A_n$. If $\{A_n\}_n$ is decreasing, $\lim_n A_n = \cap_n A_n$.

If (A, \mathcal{A}) is a monotone space, then for all monotone $\{A_n\}_n$ in \mathcal{A} , $\lim_n A_n \in \mathcal{A}$. In this case, \mathcal{A} is a montone class.



32 Subset Algebra

32.1 Why

We speak of a subset space with set-algebraic properties.

32.2 Definition

A **subset algebra** is a subset space for which (1) the base set is distinguished (2) the complement of a distinguished set is distinguished (3) the union of two distinguished sets is distinguished.

We call the set of distinguished sets an **algebra** on the the base set. We justify this language by showing that the standard set operations applied to distinguished sets result in distinguished sets.

If a set of subsets is closed under complements it contains the base set if and only if it contains the empty set. So we can replace condition (1) by insisting that the algebra contain the empty set. Similarly, if a non-empty set of subsets is closed under complements and unions then it contains the base set: the union of a distinguished set and its complement. Thus we can replace condition (1) by insisting that the algebra be non-empty.

32.2.1 Notation

The notation follows that of a subset space. Let (A, \mathcal{A}) be a subset algebra. We also say “let \mathcal{A} be an algebra on A .” Moreover, since the largest element of the algebra is the base set, we can say without ambiguity: “let \mathcal{A} be an algebra.”

32.3 Properties

Proposition 14. *For any subset algebra, \emptyset is distinguished.*

Proposition 15. *For any subset algebra, for any distinguished sets, (a) the intersection is distinguished and (b) their symmetric difference is distinguished. So, if one contains the other, the complement of the smaller in the larger is distinguished.*

Proposition 16. *For any subset algebra, for any finite family of distinguished sets, (a) the finite family union and (b) the finite family intersection are both distinguished.*

So we could have defined an algebra by insisting it be closed under finite intersections.

32.4 Examples

Example 17. *For any set A , $(A, 2^A)$ is a subset algebra.*

Example 18. *For any set A , $(A, \{A, \emptyset\})$ is a subset algebra.*

Example 19. For any infinite set A , let \mathcal{A} be the set

$$\{B \subset A \mid |B| < \aleph_0 \vee |C_A(B)| < \aleph_0\}.$$

\mathcal{A} is an algebra; the **finite/co-finite algebra**.

Example 20. For any infinite set A , let \mathcal{A} be the set

$$\{B \subset A \mid |B| \leq \aleph_0 \vee |C_A(B)| \leq \aleph_0\}.$$

\mathcal{A} is an algebra; the **countable/co-countable algebra**.

Example 21. For any infinite set A , let \mathcal{A} be the set

$$\{B \subset A \mid |B| \leq \aleph_0\}.$$

\mathcal{A} is not an algebra.

Example 22. Let A be an uncountable set. Let \mathcal{A} be the collection of all countable subsets of A . \mathcal{A} is not a sigma algebra.



33 Monotone Algebra

33.1 Why

Closure under monotone limits is a weaker condition than that included in the definition of sigma algebras, but is sufficient if the set is also an algebra. TODO: why

33.2 Result

If a subset algebra is a monotone space, then it is a countably summable subset algebra.

Proposition 23. *A subset algebra is a countably summable if either:*

- 1. the limit of a nondecreasing sequence of distinguished sets is distinguished*
- 2. the limit of a nonincreasing sequence of distinguished sets is distinguished.*

Proof. TODO

□



34 Monotone Class Theorem

34.1 Why

TODO

34.2 Result

Proposition 24. *The sigma algebra generated by an algebra of sets is the same as the monotone class generated by the algebra.*

Proof. TODO

□



35 Rational Numbers

35.1 Why

35.2 Definition



36 Real Numbers

36.1 Why

36.2 Definition



37 Real Intervals

37.1 Why

We use frequently subsets of the real numbers which correspond to segments of the line.

37.2 Definition

Take two real numbers, with the first less than the second.

An **interval** is one of four sets:

1. the set of real numbers larger than the first number and smaller than the second; we call the interval **open**.
2. the set of real numbers larger than or equal to the first number and smaller than or equal to the second number; we call the interval **closed**.
3. the set of real numbers larger than the first number and smaller than or equal to the second; we call the interval **open on the left** and **closed on the right**.
4. the set of real numbers larger than or equal to the first number and smaller than the second; we call the interval **closed on the left** and **open on the right**.

If an interval is neither open nor closed we call it **half-open** or **half-closed**

We call the two numbers the **endpoints** of the interval. An open interval does not contain its endpoints. A closed interval contains its endpoints. A half-open/half-closed interval contains only one of its endpoints.

37.2.1 Notation

Denote the set of real numbers by R . Let $a, b \in R$ with $a < b$.

We denote the open interval from a to b by (a, b) . This notation, although standard, is the same as that for ordered pairs; no confusion arises with adequate context.

We denote the closed interval from a to b by $[a, b]$. We record the fact $(a, b) \subset [a, b]$ in our new notation.

We denote the half-open interval from a to b , closed on the right, by $(a, b]$ and the half-open interval from a to b , closed on the left, by $[a, b)$.



38 Real Functions

38.1 Why

We define functions mapping real numbers to real numbers.

38.2 Definition

A **real function** is a function from subset of the real numbers into a subset of the real numbers. When clear from context, we call a real function a function.

Often, the domain is an interval. In this case, we say that the function is defined on a closed interval of the real line. We usually leave the codomain as the set of real numbers, unless we wish to speak of the function being onto.

38.2.1 Notation

Let R denote the set of real numbers. Let $f : R \rightarrow R$. Then f is a real function.

Let $a, b \in R$. Let $[a, b] \subset R$ a closed interval of real numbers. Let $f : [a, b] \rightarrow R$. Then f is a real function defined on a closed interval.

We regularly declare the interval and the function in one pass: Let $f : [a, b] \rightarrow R$, read aloud as “ f from closed a b to R .”



39 Interval Partitions

39.1 Why

We partition a real interval into interval pieces.

39.2 Definition

An **interval partition** is a finite partition of a closed real interval. An interval partition is **regular** if all pieces except the largest are closed on the left and open on the right and the largest is closed.

Any regular interval partition with $n - 1$ elements can be represented by $n + 1$ real numbers: the endpoints of each interval. We call these the **cut points** of the interval partition.

39.2.1 Notation

Let R denote the set of real numbers. Let $[a, b]$ a closed interval in R with endpoints $a, b \in R$.

Consider a regular partition. of $[a, b]$ with $n - 1$ pieces. We can identify its cut points:

$$a = a_1 < a_2 < \dots a_{n-1} < a_n = b.$$

The pieces of the partition are:

$$[a_1, a_2), [a_2, a_3), \dots, [a_{n-2}, a_{n-1}) [a_{n-1}, a_n].$$



40 Length

40.1 Why

We want to define the length of a subset of real numbers.

40.2 Common Notions

We take two common notions:

1. The length of the whole is the sum of the length of the parts; the **additivity principle**.
2. If one whole contains another, the first's length at least as large as the second's length; the **containment principle**.

The task is to make precise the use of “whole,” “parts,” and “contains.” We start with intervals.

40.3 Definition

The **length** of an interval is the difference of its endpoints: the larger minus the smaller.

Two intervals are **non-overlapping** if their intersection is a single point or empty. The **length** of the union of two non-overlapping intervals is the sum of their lengths.

A **simple** subset of the real numbers is a finite union of non-overlapping intervals. The length of a simple subset is the sum of the lengths of its family.

A **countably simple** subset of the real numbers is a countable union of non-overlapping intervals. The length of a countably simple subset is the limit of the sum of the lengths of its family; as we have defined it, length is positive, so this series is either bounded and increasing and so converges, or is infinite, and so converges to $+\infty$.

At this point, we must confront the obvious question: are all subsets of the real numbers countably simple? Answer: no. So, what can we say?

A **cover** of a set A of real numbers is a family whose union is a contains A . Since a cover always contains the set A , it's length, which we understand, must be larger (containment principles) than A . So what if we declare that the length of an arbitrary set A be the greatest lower bound of the lengths of all sequences of intervals covering A . Will this work?

40.3.1 Cuts

If a, b are real numbers and $a < b$, then we **cut** an interval with a and b as its endpoints by selecting c such that $a < c$ and $c < b$. We obtain two intervals, one with endpoints a, c and one with

endpoints c, b ; we call these two the **cut pieces**.

Given an interval, the length of the interval is the sum of any two cut pieces, because the pieces are non-overlapping.

40.4 All sets

Proposition 25. *Not all subsets of real numbers are simple.*

Exhibit: \mathbb{R} is not finite.

Proposition 26. *Not all subsets of real numbers are countably simple.*

Exhibit: the rationals.

Here's the great insight: approximate a set by a countable family of intervals.

40.4.1 Notation



41 Absolute Value

41.1 Why

We want a notion of distance between elements of the real line.

41.2 Definition

We define a function mapping a real number to its length from zero.



42 Characteristic Functions

42.1 Why

We represent rectangles by functions.

42.2 Definition

The **characteristic function** of a subset of some base set is the function from the base set to the real numbers which maps elements contained in the subset to value one and maps all other elements to zero. The range of the function is the set consisting of the real numbers one and zero.

If the base set is the real numbers and the subset is an interval, then the characteristic function is a rectangle with height one and the width of the interval.

42.2.1 Notation

Let A be a non-empty set and $B \subset A$. We denote the characteristic function of B in A by $\chi_B : A \rightarrow R$. The Greek letter χ is a mnemonic for “characteristic”.

The subscript indicates the set on which the function is one.
In other words, for all $B \subset A$, $\chi_B^{-1}(\{1\}) = B$.

If B is an interval and α is a real number then $\alpha\chi_B$ is a rectangle with height α .



43 Simple Functions

43.1 Why

We want to define area under a real function. We define functions for which this notion is clear.

43.2 Definition

A **simple function** is a function whose range is a finite set.

Partition the range into the finite family of one-element sets. The family whose members consist of the inverse images of these sets is a partition of the domain. We call this the **simple partition** of the function.

A **real simple function** is a simple function whose codomain is real. In this case, we can write the simple function as a sum of the characteristic functions of the inverse images elements.

43.2.1 Notation

Let A and B be non-empty sets. We denote the set of simple functions from A to B by $\mathcal{SF}(A, B)$.

We denote the set of simple real functions with domain A by $\mathcal{SF}(A)$. We denote subset of non-negative simple real functions with domain A by $\mathcal{SF}_+(A)$.

Let $f \in \mathcal{SF}(A)$. Order the members of the range of f from 1 to n as r_1, \dots, r_n . Define $A_i = f^{-1}(\{r_i\})$. Then $f = \sum_{i=1}^n r_i \chi_{A_i}$.



44 Real Limits

44.1 Why

We want to speak of an infinite process which, although never arrives, does terminate.

44.2 Definition

A **limit** of a sequence of real numbers is a real number for which we can always find a final part of the sequence wholly contained in an interval around the limit, no matter how small the interval.

You propose a limit for a sequence. To test this proposal, I specify some small positive real number. Then we look for a final part wholly contained in the interval of that width. If we can always find the final part, no matter how small the positive number I specified, then the proposed limit is true.

44.2.1 Existence

Some sequences have no limits. Consider the sequence which alternates between the $+1$ and -1 . To show that the limit does not exist, we argue indirectly. We take any real number and test

it with the interval length one. No matter which real number we have selected, $+1$ and -1 are a distance two apart, and so can not both be contained in an interval of width one.

44.2.2 Uniqueness

If a sequence has a limit, it has only one limit. So, from here on, we will speak of **the limit** of the sequence.

To see this uniqueness, suppose that two real numbers satisfy the limiting property. We now argue indirectly: suppose also that they are not equal. Denote the distance between them by x . Then ask for final parts in intervals of width $x/2$ for both limits.

44.2.3 Approximation

We use limits to speak about the terminating behavior of infinite processes. We think about the sequence as approximating the limit. The sequence may never actually take the value of its limit, so the limit need be in the set of terms of the sequence, but it does get close.

The definition, moreover, ensures that the sequence will get arbitrarily close. We can operationalize this property, by taking the first element of that final part after which all elements are close to the limit. This element is an element of the sequence approximates the limit value well.

44.2.4 Notation

Let $\{a_n\}_n$ be a sequence of real numbers. Let a be a real number. We denote that a is the limit of $\{a_n\}_n$ by

$$a = \lim_{n \rightarrow \infty} a_n.$$

We read this statement aloud as “ a is the limit of a_n .” The above statement asserts two facts: (1) the sequence $\{a_n\}_n$ has a limit and (2) the limit is the real number a . We sometimes abbreviate the by writing $a = \lim_n a_n$.



45 Real Limiting Bounds

45.1 Why

We can think of a limit as existing when the limit of upper bounds and lower bounds on final parts of the sequence coincide.

45.2 Definition

The **limit superior** of a sequence of real numbers is the limit of the sequence of suprema of final parts of the sequence. Similarly, the **limit inferior** of a sequence of real numbers is the limit of the sequence of infima of final parts of the sequence.

The limit of the sequence exists if and only if the If the limit superior and the limit inferior coincide, then the sequence has a limit which is defined to be the limiting value of each of those two sequences.

$$\liminf_n f_n$$

$$\liminf_n f_n$$



46 Extended Real Numbers

46.1 Why

That some limits grow without bound leads us to add two elements to the set of real numbers.

46.2 Definition

The set of **extended real numbers** is the union of the set of real numbers with a set containing two distinct elements: one which we call **positive infinity** and one which we call **negative infinity**.

46.3 Intervals

We



47 Real Length Impossible

47.1 Why

Given a subset of the real line, what is its length?

47.2 Background

Let $a, b \in R$ with $a \leq b$. The **length** of the closed interval of the real numbers $[a, b]$ is $b - a$. The length is non-negative.

A family $\{A_\alpha\}_{\alpha \in I}$ is **disjoint** if for $\alpha, \beta \in I$, $\alpha \neq \beta$, then $A_\alpha \cap A_\beta = \emptyset$. A set A can be **partitioned** into a family if there exists a disjoint family whose union is A . A set $A \subset R$ is **simple** if it can be partitioned into a countable family whose members are closed intervals. The above discussion suggests that we should define the length of a simple set as the sum of the lengths of sets which partition it.

The above discussion suggests that if we wish to define a function $\text{length} : 2^R \rightarrow R \cup \{-\infty, \infty\}$, we should ask that (1) $\text{length}(A) \geq 0$, (2) $\text{length}([a, b]) = b - a$, (3) for disjoint closed intervals $\{A_n\}_{n \in N}$, $\text{length}(A_i) = \sum_i \text{length}(A_i)$, and (4) for all $A \subset R$ and $a \in R$, $\text{length}(A + x) = \text{length}(A)$.

47.3 Converse

Define the equivalence relation \sim on R by $x \sim y$ if $x \sim y \in Q$

47.3.1 Notation

Let A be a set and $\mathcal{A} \subset 2^A$. We denote the subset algebra of A and \mathcal{A} by (A, \mathcal{A}) , read aloud as “ A , script A .”

47.4 Properties

Proposition 27. *For any set A , 2^A is a sigma algebra.*

Proposition 28. *The intersection of a family of sigma algebras is a sigma algebra.*

47.5 Generation

Proposition 29. *Let A a set and \mathcal{B} a set of subsets. There is a unique smallest sigma algebra (A, \mathcal{A}) with $\mathcal{B} \subset \mathcal{A}$.*

We call the unique smallest sigma algebra containing B the **generated sigma algebra** of B .



48 Sigma Algebra

48.1 Why

For general measure theory, we need an algebra of sets closed under countable unions; we define such an object (TODO).

48.2 Definition

A **countably summable subset algebra** is a subset space for which (1) the base set is distinguished (2) the complement of a distinguished set is distinguished (3) the union of a sequence of distinguished sets is distinguished.

The name is justified, as each countably summable subset algebra is a subset algebra, because the union of A_1, \dots, A_n coincides with the union of $A_1, \dots, A_n, A_n, A_n, \dots$.

We say that the set of distinguished sets a **sigma algebra** on the base set; we justify this language, as for an algebra, by the closure properties under standard set operations.

48.2.1 Notation

The notation follows that of a subset space. Let (A, \mathcal{A}) be a countably summable subset algebra. We also say “let \mathcal{A} be a sigma algebra on A .” Moreover, since the largest element of the sigma algebra is the base set, we can say without ambiguity: “let \mathcal{A} be a sigma algebra.”

48.3 Examples

Example 30. *For any set A , 2^A is a sigma algebra.*

Example 31. *For any set A , $\{A, \emptyset\}$ is a sigma algebra.*

Example 32. *Let A be an infinite set. Let \mathcal{A} the collection of finite subsets of A . \mathcal{A} is not a sigma algebra.*

Example 33. *Let A be an infinite set. Let \mathcal{A} be the collection subsets of A such that the set or its complement is finite. \mathcal{A} is not a sigma algebra.*

Proposition 34. *The intersection of a family of sigma algebras is a sigma algebra.*

Example 35. *For any infinite set A , let \mathcal{A} be the set*

$$\{B \subset A \mid |B| \leq \aleph_0 \vee |C_A(B)| \leq \aleph_0\}.$$

*\mathcal{A} is an algebra; the **countable/co-countable algebra**.*

TOOD : cleanuexamples



49 Generated Sigma Algebra

49.1 Why

A simple way to obtain a sigma algebra, is to ask it to obtain some sets, and then to ask it to contain all the sets it needs to fulfill the properties.

49.2 Definition

The **generated sigma algebra** for a set of subsets is the smallest sigma algebra containing the set of subsets. We must prove the existence and uniqueness of this sigma algebra.

Proposition 36. *The intersection of a non-empty set of sigma algebras on the same base set is a sigma algebra.*

Proof. Let $\{(\mathcal{A}, \mathcal{A}_\alpha)\}_{\alpha \in I}$ a family of sigma algebras on the same base set. Define \mathcal{A} as $\cap_{\alpha \in I} \mathcal{A}_\alpha$.

1. For all $\alpha \in I$, $A \in \mathcal{A}_\alpha$, thus $A \in \mathcal{A}$; condition (a).
2. For all $B \in \mathcal{A}$, for all $\alpha \in I$, $B \in \mathcal{A}_\alpha$. Thus, for all $\alpha \in I$, $C_A(B) \in \mathcal{A}_\alpha$. And so $C_A(B) \in \mathcal{A}$; condition (b).

3. For all sequences $\{B_n\} \subset \mathcal{A}$, $\{B_n\} \subset \mathcal{A}_\alpha$ for all α . Thus $\cup_n B_n \in \mathcal{A}_\alpha$ for all α and so $\cup_n B_n \in \mathcal{A}$; condition (c).

□

On the other hand, the union of a set of sigma algebras can fail to be a sigma algebra.

Proposition 37. *If A is a set and $\mathcal{A} \subset 2^A$, then there is a unique a smallest sigma algebra containing \mathcal{A} .*

Proof. We know of one sigma algebra containing \mathcal{A} : the power set of A . Thus, the set of sigma algebras containing \mathcal{A} is not empty. Proposition 36 implies the intersection of all such sigma algebras (containing \mathcal{A}) is a sigma algebra. The intersection contains \mathcal{A} , and is contained in all other sigma algebras with this property, so is a smallest sigma algebra containing \mathcal{A} . If \mathcal{B}, \mathcal{C} were two smallest sigma algebras, then $\mathcal{B} \subset \mathcal{C}$ and $\mathcal{C} \subset \mathcal{B}$, but then $\mathcal{B} = \mathcal{C}$; thus the smallest sigma algebra is unique. □

49.3 Notation

Let A be a set and $\mathcal{A} \subset 2^A$. We denote the sigma algebra generated by \mathcal{A} by $\sigma(\mathcal{A})$.



50 Topological Sigma Algebra

50.1 Why

We often take the a the topology of a topological space as the generating set for the sigma algebra.

50.2 Definition

Given a topological space, the **topological sigma algebra** is the sigma algebra generated by the topology.

50.3 Notation

Let (A, \mathcal{T}) be a topological space. We denote the topological sigma algebra by $\sigma(\mathcal{T})$.



51 Borel Sigma Algebra

51.1 Why

We name and discuss the topological sigma algebra on the real numbers; the language and results generalize to finite direct products of the real numbers.

51.2 Definition

The **Borel sigma algebra** is the topological sigma algebra for the real numbers with the usual topology; we call its members the **Borel sets**.

51.3 Notation

Throughout this sheet we denote the real numbers by R . As usual, then, we denote the d -dimensional direct product of R by R^d . We denote the Borel sigma algebra on R^d by $\mathcal{B}(R^d)$. We denote $\mathcal{B}(R^1)$ by $\mathcal{B}(R)$.

51.4 Alternate Generations

The Borel sigma algebra is useful because it contains interesting sets besides the open sets. To make precise this statement, we show that the Borel sigma algebra is generated by, and therefore contains, other common subsets of R .

Proposition 38. *If a sigma algebra \mathcal{A} includes a particular set of subsets \mathcal{B} , then \mathcal{A} includes $\sigma(\mathcal{B})$.*

Proposition 39. *Each of*

- (a) the collection of all closed subsets of R ,*
- (b) the collection of all subintervals of R of the form $(-\infty, b]$,*
- (c) the collection of all subintervals of R of the form $(a, b]$,*

generate $\mathcal{B}(R)$.

Proof. Denote the sigma algebra which corresponds to (a) by \mathcal{B}_1 , that which corresponds to (b) by \mathcal{B}_2 , and that which corresponds to (c) by \mathcal{B}_3 . It suffices to establish $\mathcal{B}(R) \subset \mathcal{B}_3 \subset \mathcal{B}_2 \subset \mathcal{B}_1 \subset \mathcal{B}(R)$.

Start with \mathcal{B}_1 . Closed sets are the complement of open sets. Thus $\mathcal{B}(R)$ contains all closed sets and so contains the sigma algebra generated by all closed sets, namely \mathcal{B}_1 .

Next, \mathcal{B}_2 . The intervals $(-\infty, b]$ are closed. Thus \mathcal{B}_1 contains all such intervals, and so contains the sigma algebra generated by such intervals, namely \mathcal{B}_2 .

Next, \mathcal{B}_3 . An interval $(a, b]$ is $(-\infty, b) \cap C_R((-\infty, a])$. Thus, all such intervals are contained in \mathcal{B}_2 , and so \mathcal{B}_2 contains the sigma algebra generated by all such intervals, namely, \mathcal{B}_3 .

Each open interval of R is the union of a sequence of sets $(a, b]$; namely $(a, b - 1/n]$. So \mathcal{B}_3 contains all open intervals (a, b) . Each open set of R can be written as a countable union of open intervals (proof: TODO). Thus, \mathcal{B}_3 contains all open sets, and therefore contains the sigma algebra generated by the open subsets, namely $\mathcal{B}(R)$. \square

Proposition 40. *Each of:*

- (a) *the collection of all closed subsets of R^d ,*
- (b) *the collection of all closed half-spaces of R^d of the form*

$$\{(x_1, \dots, x_d) \mid x_i \leq b_i\}$$

for some index i and some b in R , and

- (c) *the collection of all rectangles of R^d of the form*

$$\{(x_1, \dots, x_d) \mid a_i < x_i \leq b_i\}$$

generate $\mathcal{B}(R^d)$.

Proof. Follow the proof of Proposition 39.

The complement of open sets are closed. Closed half spaces are closed. A strip of the form $\{(x_1, \dots, x_d) \mid a_i < x_i \leq b_i\}$ is the intersection of two half-spaces in (b). Each rectangle in (c) is the union of d such strips.

TODO: two step last piece, open rectangles are unions of rectangles in (c) and open sets are union of open rectangles.

□



52 Measures

52.1 Why

We want to generalize the notion of length, area, volume beyond the Lebesgue measure on the product spaces of real numbers.

52.2 Definition

An extended-real-valued non-negative function on an algebra is **finitely additive** if the result of the function applied to the union of a disjoint finite family of distinguished sets is the sum of the results of the function applied to each of the sets individually.

An extended-real-valued non-negative function on a sigma algebra is **countably additive** if the result of the function applied to the union of a disjoint countable family of distinguished sets is the limit of the partial sums of the results of the function applied to each of the sets individually.

A **finitely additive measure** is an extended-real-valued non-negative finitely additive function which associates the empty set with the real number 0. A **countably additive measure** is an extended-real-valued non-negative countably additive function which associates the empty set with the real number 0. We

call countably additive measures **measures**, for short.

Every countably additive measure is finitely additive. On the other hand, there exist finitely additive measures which are not countable additive.

In the context of measure, we call a countably untable subset algebra a **measurable space**. We call the distinguished sets **measurable** sets. A **measure space** is triple. As a pair, the first two objects are a measurable space. The third object is a measure defined on the sigma algebra of the measurable space.

52.3 Notation

Let A a set. Let \mathcal{A} a sigma algebra on A . The pair (A, \mathcal{A}) is a measurable space.

Let $\mu : \mathcal{A} \rightarrow [0, \infty]$ a measure; thus: (a) $\mu(\emptyset) = 0$ and (b) for disjoint $\{A_n\} \subset \mathcal{A}$, $\mu(\cup_{n=1}^{\infty} A_n) = \sum_{n=1}^{\infty} \mu(A_n)$. The triple (A, \mathcal{A}, μ) is a measure space.

We use μ since it is a mnemonic for “measure”. We often also use ν to denote measures, since it is after μ in the Greek alphabet, and λ , since it is before μ in the Greek alphabet.

52.4 Examples

Example 41. Let (A, \mathcal{A}) a measurable space. Let $\mu : \mathcal{A} \rightarrow [0, +\infty]$ such that $\mu(A)$ is $|A|$ if A is finite and $\mu(A)$ is $+\infty$ otherwise. Then μ is a measure. We call μ the **counting mea-**

sure.

Example 42. Let (A, \mathcal{A}) measurable. Fix $a \in A$. Let $\mu : \mathcal{A} \rightarrow [0, +\infty]$ such that $\mu(A)$ is 1 if $a \in A$ and $\mu(A)$ is 0 otherwise. Then μ is a measure. We call μ the **point mass** concentrated at a .

Example 43. Let R denote the real numbers. The Lebesgue measure on the measurable space $(R, \mathcal{B}(R))$ is a measure.

Example 44. Let N be the natural numbers. Let \mathcal{A} the finite co-finite algebra on N . Let $\mu : \mathcal{A} \rightarrow [0, +\infty]$ be such that $\mu(A)$ is 1 if A is infinite or 0 otherwise. Then μ is a finitely additive measure. However it is impossible to extend μ to be a countably additive measure. Observe that if $A_n = \{n\}$ the $\mu(\cup_n A_n) = 1$ but $\sum_n \mu(A_n) = 0$.

Example 45. Let (A, \mathcal{A}) a measurable space. Let $\mu : \mathcal{A} \rightarrow [0, +\infty]$ be 0 if $A = \emptyset$ and $\mu(A)$ is $+\infty$ otherwise. Then μ is a measure.

Example 46. Let A be set with at least two elements ($|A| \geq 2$). Let $\mathcal{A} = 2^A$. Let $\mu : \mathcal{A} \rightarrow [0, +\infty]$ such that $\mu(A)$ is 0 if $A = \emptyset$ and $\mu(A) = 1$ otherwise. Then μ is not a measure, nor is μ finitely additive.

Proof. Let $B, C \in \mathcal{A}$, $B \cap C = \emptyset$ then using finite additivity we obtain a contradiction $1 = \mu(B \cup C) = \mu(B) + \mu(C) = 2$. \square



53 Finite Measures

53.1 Why

Sometimes we want finite measures.

53.2 Definition

A measurable set is **finite** if its measure is a real number. The measure space itself is **finite** if the base set is finite.

A measurable set is **sigma-finite** if there exists a sequence of finite measurable sets whose union is the set. The measure space itself is **sigma-finite** if the base set is sigma finite.

53.2.1 Notation

We denote that a measure space is finite by saying “Let (A, \mathcal{A}, μ) and $\mu(A) < +\infty$.”

Example 47. *Let (A, \mathcal{A}) be a measurable space.*

The counting measure on (A, \mathcal{A}) is finite if and only if the base set is finite. It is sigma finite if and only if the base set is a union of a sequence of finite sets.

If $\mathcal{A} = 2^A$, then the counting measure is sigma finite if and only if A is countable.

Example 48. *A point mass measure is finite.*

Example 49. *Let R be the set of real numbers. The Lebesgue measure on $(R, \mathcal{B}(R))$ is sigma finite.*



54 Measure Properties

54.1 Why

We expect measure to have the common sense properties we stated when trying to define a notion of length for the real line.

54.2 Monotonicity

An extended-real-valued function on an algebra is **monotone** if, given a first distinguished set contained in a distinguished second set, the result of the first is no greater than the result of the second.

Proposition 50. *All measures are monotone.*

Proof. Let (A, \mathcal{A}, μ) be a measure space. Let $A, B \in \mathcal{A}$ and $A \subset B$. Then $B = A \cup (B - A)$, a disjoint union. So

$$\mu(B) = \mu(A \cup (B - A)) = \mu(A) + \mu(B - A),$$

by the additivity of μ . Since $\mu(B - A) \geq 0$, we conclude $\mu(A) \leq \mu(B)$. \square

Proposition 51. $A \subset B$ and B finite means $\mu(B - A) = \mu(B) - \mu(A)$. TODO

54.3 Subadditivity

Monotonicity along with additivity of measures give us one other convenient property: subadditivity.

An extended-real-valued function on an algebra is **subadditive** if, given a sequence of distinguished sets, the result of union of the sequence is no greater than the limit of the partial sums of the results on each element of the sequence.

Proposition 52. *All measures are subadditive.*

Proof. Let (A, \mathcal{A}, μ) be a measure space.

Let $\{A_n\} \subset \mathcal{A}$. Define $\{B_n\} \subset \mathcal{A}$ with $B_n := A_n - \cup_{i=1}^{n-1} A_i$. Then $\cup_n A_n = \cup_n B_n$, $\{B_n\}$ is a disjoint sequence, and $B_n \subset A_n$ for each n . So

$$\mu(\cup_n A_n) = \mu(\cup_n B_n) = \sum_{i=1}^{\infty} \mu(B_n) \leq \sum_{i=1}^{\infty} \mu(A_n),$$

by additivity and then monotonicity of measure. \square

54.4 Limits

Measures also behave well under limits.

An extended-real-valued function on an algebra **resolves under increasing limits** if the result of the union of an increasing sequence of distinguished sets coincides with the limit of the sequence of results on the individual sets. An extended-real-valued function on an algebra **resolves under decreasing**

limits if the result of the intersection of a decreasing sequence of distinguished sets coincides with the limit of the sequence of results on the individual sets.

Proposition 53. *Measures resolve under increasing limits.*

Proof. Let (A, \mathcal{A}, μ) be a measure space. Let $\{A_n\}$ be an increasing sequence in \mathcal{A} . Then we want to show: $\mu(\cup_n A_n) = \lim_{n \rightarrow \infty} \mu(A_n)$.

Define $\{B_n\}$ such that $B_n := A_n - \cup_{i=1}^{n-1} A_i$. Then $\{B_n\}$ is disjoint, $A_n = \cup_{i=1}^n B_i$ for each n , $\cup_n A_n = \cup_n B_n$, and $\mu(\cup_{i=1}^n B_i) = \sum_{i=1}^n \mu(B_i)$, by additivity. So

$$\begin{aligned} \mu(\cup_n A_n) &= \mu(\cup_n B_n) \\ &= \lim_{n \rightarrow \infty} \sum_{i=1}^n \mu(B_i) \\ &= \lim_{n \rightarrow \infty} \mu(\cup_{i=1}^n B_i) \\ &= \lim_{n \rightarrow \infty} \mu(A_n). \end{aligned}$$

□

Proposition 54. *Measures resolve under decreasing limits if there is a finite set in the decreasing sequence.*

Proof. Let (A, \mathcal{A}, μ) be a measure space. Let $\{A_n\}$ be a decreasing sequence in \mathcal{A} with one element finite. Then we want to show: $\mu(\cap_n A_n) = \lim_{n \rightarrow \infty} \mu(A_n)$.

On one hand, let n_0 be the index of the first finite element of the sequence. Then for all $n \geq n_0$, the sequence is finite

because of the monotonicity of measure. Denote this decreasing finite subsequence of sets by $\{B_n\}$. Then $\cap_n A_n = \cap_n B_n$ and $\lim_n A_n = \lim_n B_n$.

On the other hand, the sequence $\{B_1 - B_n\}$ is an increasing sequence in \mathcal{A} . Also $\cap_n B_n = B_1 - \cup_n (B_1 - B_n)$. So

$$\begin{aligned}
\mu(\cap_n B_n) &= \mu(B_1 - \cup_n (B_1 - B_n)) \\
&= \mu(B_1) - \mu(\cup_n (B_1 - B_n)) \\
&= \mu(B_1) - \lim_n \mu(B_1 - B_n) \\
&= \mu(B_1) - \left(\lim_n \mu(B_1) - \mu(B_n) \right) \\
&= \lim_n \mu(B_n).
\end{aligned}$$

□



55 Measure Space

55.1 Why

We want to generalize the notions of length, area, and volume.

55.2 Definition

A **measurable space** is a sigma algebra. We call the distinguished subsets the **measurable sets**.

A **measure** on a measurable space is a function from the sigma algebra to the positive extended reals. A **measure space** is a measurable space and a measure.

55.2.1 Notation

55.2.2 Properties

Proposition 55. *Let (A, \mathcal{A}) be a measurable space and $m : \mathcal{A} \rightarrow [0, \infty]$ be a measure.*

*If $B \subset C \subset A$, then $m(B) \leq m(C)$. We call this property the of measures **monotonicity of measure**.*

Proposition 56. *For a measure space (A, \mathcal{A}, m) .*

If $B \subset C \subset A$, then $m(B) \leq m(C)$.

We call this property the **monotonicity of measure**.

Proposition 57. For a measure space (A, \mathcal{A}, m) .

If $\{A_n\} \subset \mathcal{A}$ a countable family, then $m(\cup A_n) \leq \sum_i m(A_i)$.

We call this property the **sub-additivity of measure**.

Proposition 58. For a measure space (A, \mathcal{A}, m) .

If $\{A_n\} \subset \mathcal{A}$ a countable family, then $m(\cup A_n) \leq \sum_i m(A_i)$.

We call this property the **sub-additivity of measure**.

Proposition 59. For a measure space (A, \mathcal{A}, m) .

$$m(\cup_{n=1}^{\infty} A_i) = \lim_{n \rightarrow \infty} m(A_i)$$

Proposition 60. For a measure space (A, \mathcal{A}, m) .

$$m(\cap_{n=1}^{\infty} A_i) = \lim_{n \rightarrow \infty} m(A_i)$$

55.2.3 Examples

Example 61. *counting measure*



56 Measurable Functions

56.1 Why

We define integrals using an infinite process; in order for each step of the process to make sense, need functions to be measurable. Maybe: point to simple functions so that the why is clear.

56.2 Definition

A function between the base sets of two measurable spaces is **measurable** with respect to the distinguished sets of the two spaces if the inverse image of every distinguished subset of the codomain is a distinguished subset of the domain.

56.2.1 Notation

Let (X, \mathcal{A}) and (Y, \mathcal{B}) be measurable spaces. Then a function $f : X \rightarrow Y$ is measurable if $B \in \mathcal{B}$ implies $f^{-1}(B) \in \mathcal{A}$. We say that f is measurable with respect to \mathcal{A} and \mathcal{B} .

In this case, we sometimes say f is a measurable function from (X, \mathcal{A}) to (Y, \mathcal{B}) . We say, $f : (X, \mathcal{A}) \rightarrow (Y, \mathcal{B})$ is measurable, read aloud as “f from X, A to Y, B is measurable.”



57 Measurable Function Operations

57.1 Why

Under which operations is the set of measurable functions closed?

57.2 Overview

Measurable functions are closed under composition and concatenation. Taking these facts together with the observation that continuous functions are measurable, we conclude that measurable functions are closed under addition, multiplication, and (with suitable nonzero assumptions) division.

57.3 Results

Proposition 62. *The composition of two measurable functions is measurable.*

Proof. Let (X, \mathcal{A}) , (Y, \mathcal{B}) , (Z, \mathcal{C}) be measurable spaces. Let $f : X \rightarrow Y$ and $g : Y \rightarrow Z$ be measurable functions. Define $h = g \circ f$.

Let $C \in \mathcal{C}$. Measurability of g implies $g^{-1}(C) \in \mathcal{B}$. This fact, together with measurability of f , implies $f^{-1}(g^{-1}(C)) \in \mathcal{A}$. Since $h^{-1} = f^{-1} \circ g^{-1}$, we conclude that h is measurable. \square

Proposition 63. *A continuous function between topological spaces is measurable with respect to the topological sigma algebras.*

Proposition 64. *The concatenation of two measurable functions is measurable.*

Proof. Let (X, \mathcal{A}) , (Y, \mathcal{B}) and (Z, \mathcal{C}) be measurable spaces. Let $f : X \rightarrow Y$ and $g : X \rightarrow Z$ be measurable. Define $h : X \rightarrow Y \times Z$ by $h(x) = (f(x), g(x))$. \square

Proposition 65. *Let (X, \mathcal{A}) be a measurable space and let R denote the real numbers. Let $f, g : X \rightarrow R$ be measurable.*

Then, $f + g$ and fg are measurable.



58 Almost Everywhere

58.1 Why

We treat properties failing on a set of measure zero as though they occur everywhere; especially in discussions of convergence.

58.2 Definition

A subset of the base set of a measure space is **negligible** if there exists a measurable set with measure zero containing the subset. Negligible sets need not be measurable.

A property holds **almost everywhere** with respect to a measure on a measure space if the set of elements of the base set on which the property does not hold is negligible.

If the property holds everywhere, it holds almost everywhere. In this sense we call the almost everywhere sense “weaker” than the everywhere sense.

58.2.1 Notation

Let (X, \mathcal{A}, μ) be a measure space. A set $N \subset X$ is negligible if there exists $A \in \mathcal{A}$ with $N \subset A$ and $\mu(A) = 0$.

We abbreviate almost everywhere as “a.e.,” read “almost everywhere”. We say that a property “holds a.e.” If the measure μ is not clear from context, we say that the property holds almost everywhere $[\mu]$ or μ -a.e., read “mu almost everywhere.”

58.3 Examples

Let (X, \mathcal{A}, μ) be a measure space and let R be the real numbers.

58.3.1 Function Comparisons

Let $f, g : X \rightarrow R$ be two functions on X , not necessarily measurable. Then $f = g$ almost everywhere if the set of points at which the functions disagree is μ -negligible. Similarly, $f \geq g$ almost everywhere if the set of points where f is less than g is μ -negligible. If f and g are \mathcal{A} -measurable, then the sets

$$\{x \in X \mid f(x) \neq g(x)\} \text{ and } \{x \in X \mid f(x) < g(x)\}$$

are measurable; but they need not be measurable otherwise.

58.3.2 Function Limits

Let $f_n : X \rightarrow R$ for each natural number n and let $f : X \rightarrow R$ be a function. The sequence $\{f_n\}_n$ **converges to f almost everywhere** if

$$\left\{x \in X \mid \lim_n f_n \text{ does not exist, or } f(x) \neq \lim_n f_n\right\}$$

is μ -negligible. In this case, we write “ $f = \lim_n f_n$ almost everywhere.”



59 Almost Everywhere Measurability

59.1 Why

Does convergence almost everywhere of a sequence of measurable functions guarantee measurability of the limit function? It does on complete measure spaces, and we can use this result to “weaken” the hypotheses of many theorems.

59.2 Results

A measure is **complete** if every subset of a measurable set of measure zero is measurable. If the measure is complete, then every negligible set must be measurable.

We begin with a transitivity property: almost everywhere equality of two functions allows us to infer measurability of one from the other.

Proposition 66. *Let (X, \mathcal{A}, μ) be a measure space. Let $f, g : X \rightarrow [-\infty, \infty]$ with $f = g$ almost everywhere. If μ is complete and f is \mathcal{A} -measurable, then g is \mathcal{A} -measurable.*

Proof.

□

Proposition 67. *Let (X, \mathcal{A}, μ) be a measure space. Let $f_n : X \rightarrow [-\infty, \infty]$ for all natural numbers n and $f : X \rightarrow [-\infty, \infty]$ with $\{f_n\}_n$ converging to f almost everywhere. If μ is complete and f_n is measurable for each n , then f is \mathcal{A} -measurable.*

Proof.

□



60 Matroids

60.1 Why

We generalize the notion of linear dependence.

60.2 Definition

A **matroid** is a finite subset algebra satisfying:

1. The subset of a distinguished set is distinguished.
2. For two distinguished subsets of nonequal cardinality, there is an element of the base set in the complement of the smaller set in the bigger set whose singleton union with the smaller set is a distinguished set.

An **independent subset** of a matroid is a distinguished subset. A **depenedent subset** of a matroid is an undistinguished subset.

60.2.1 Notation

We follow the notation of subset algebras, but use M for the base set, a mnemonic for matroid, and \mathcal{I} for the distinguished sets, a mnemonic for independent.

Let (M, \mathcal{I}) a matroid. We denote the properties by

1. $A \in \mathcal{I} \wedge B \subset A \implies B \in \mathcal{I}.$

2. $A, B \in \mathcal{I} \wedge |A| < |B| \implies \exists x \in M : (A \cup \{x\}) \in \mathcal{I}$



61 Simple Integrals

61.1 Why

We want to define area under a real function. We begin with functions whose area under the curve is self-evident.

61.2 Definition

Consider a measure space. The characteristic function of any measurable set is measurable. A simple function is measurable if and only if each element of its simple partition is measurable.

The **integral** of a measurable non-negative simple function is the sum of the products of the measure of each piece with the value of the function on that piece. For example, the integral of a measurable characteristic function of a subset is the measure of that subset.

The **integral operator** is the real-valued function which associates each measurable non-negative simple function with its integral. The simple integral is non-negative, so the integral operator is a non-negative function.

61.2.1 Notation

Let (X, \mathcal{A}, μ) be a measure space. Let R be the set of real numbers.

Let $f : X \rightarrow R$ be a measurable simple function. So there exist $A_1, \dots, A_n \in \mathcal{A}$ and $a_1, \dots, a_n \in R$ with:

$$f = \sum_{i=1}^n a_i \chi_{A_i}.$$

We denote the integral of f with respect to measure μ by $\int f d\mu$. We defined:

$$\int f d\mu = \sum_{i=1}^n a_i \mu(A_i).$$



62 Non-negative Integrals

62.1 Why

We want to define area under an extended real function. We use the infinite process to approximate the area under a non-negative extended real function using simple functions.

62.2 Definition

Consider a measure space.

The **integral** of a measurable nonnegative function is the supremum of integrals over non-negative simple functions pointwise less than or equal to the function.

62.2.1 Notation

Let (X, \mathcal{A}, μ) be a measure space. Let $f : X \rightarrow [0, \infty]$ be measurable. We denote the integral of f with respect to the measure μ by $\int f d\mu$. We defined:

$$\int f d\mu = \sup \left\{ \int g d\mu \mid g \in \mathcal{SF}_+(X) \text{ and } g \leq f \right\}.$$



63 Real Integrals

63.1 Why

We define the area under an extended real function.

63.2 Definition

The **positive part** of an extended-real-valued function is the function mapping each element to the maximum of the function's result and zero. The **negative part** of an extended-real-valued function is the function mapping each element to the maximum of the negative of function's result and zero.

We decompose an extended-real-valued function as the difference of its positive part and its negative part. Both the positive and negative parts are non-negative extended-real-valued functions.

Consider a measure space. An **integrable** function is a measurable extended real function for which the non-negative integral of the positive part and the non-negative integral of the negative part of the function are finite.

The **integral** of an integrable function is the difference of the non-negative integral of the positive part and the non-

negative integral of the negative part.

If one but not both of the parts of the function are finite, we say that the integral **exists** and again define it as before. in this way we avoid arithmetic between two infinities.

63.2.1 Notation

Let A a non-empty set. Let $g : A \rightarrow [-\infty, \infty]$. We denote the positive part of g by g^+ and the negative part of g by g^- :

$$g^+(x) = \max\{g(x), 0\} \quad \text{and} \quad g^-(x) = \max\{-g(x), 0\}.$$

Moreover, we decompose g as $g = g^+ - g^-$. We observed that $g^+(x) \geq 0$ and $g^-(x) \geq 0$ for all $x \in X$.

Let (X, \mathcal{A}, μ) be a measure space. Let $f : X \rightarrow [-\infty, +\infty]$ measurable and one of $\int f^+ d\mu$ or $\int f^- d\mu$ is finite (if both are finite, f is integrable).

We denote the integral of f with respect to the measure μ by $\int f d\mu$. We defined:

$$\int f d\mu = \left(\int f^+ d\mu \right) - \left(\int f^- d\mu \right).$$



64 Simple Integral Homogeneity

64.1 Why

If we stack a rectangle on top of itself we have a rectangle twice the height. The additivity principle says that the area of the so-formed rectangle is the sum of the areas of the stacked rectangles. Our definition of integral for simple functions has this property.

64.2 Result

Proposition 68. *The simple non-negative integral operator is homogenous over non-negative real values.*

Proof. Let (X, \mathcal{A}, μ) be a measure space. Let $\mathcal{SF}_+(X)$ denote the non-negative real-valued simple functions on X . Define $s : \mathcal{SF}_+(X) \rightarrow [0, \infty]$ by $s(f) = \int f d\mu$ for $f \in \mathcal{SF}_+(X)$.

In this notation, we want to show that $s(\alpha f) = \alpha s(f)$ for all $\alpha \in [0, \infty)$ and $f \in \mathcal{SF}_+(X)$. Toward this end, let $f \in \mathcal{SF}_+(X)$ with the simple partition $\{A_n\} \subset \mathcal{A}$ and $\{a_n\} \subset [0, \infty]$.

First, let $\alpha \in (0, \infty)$. Then $\alpha f \in \mathcal{SF}_+(X)$, with the simple

partition $\{A_n\} \subset \mathcal{A}$ and $\{\alpha a_n\} \subset [0, \infty]$.

$$s(\alpha f) = \sum_{i=1}^n \alpha a_n \mu(A_i) = \alpha \sum_{i=1}^n a_n \mu(A_i) = \alpha s(f).$$

If $\alpha = 0$, then αf is uniformly zero; it is the non-negative simple with partition $\{X\}$ and $\{0\}$. Regardless of the measure of X , this non-negative simple function is zero. Recall that we define $0 \cdot \infty = \infty \cdot 0 = 0$. \square



65 Simple Integral Additivity

65.1 Why

If we stack a two rectangles, with equal base lengths but different heights, on top of each other, the additivity principle says that the area of the so-formed rectangle is the sum of the areas of the stacked rectangles. Our definition of integral for simple functions has this property.

65.2 Result

Proposition 69. *The simple non-negative integral operator is additive.*

Proof. Let (X, \mathcal{A}, μ) be a measure space. Let $\mathcal{SF}_+(X)$ denote the non-negative real-valued simple functions on X . Define $s : \mathcal{SF}_+(X) \rightarrow [0, \infty]$ by $s(f) = \int f d\mu$ for $f \in \mathcal{SF}_+(X)$.

In this notation, we want to show that $s(f+g) = s(f) + s(g)$ for all $f, g \in \mathcal{SF}_+(X)$. Toward this end, let $f, g \in \mathcal{SF}_+(X)$ with the simple partitions:

$$\{A_i\}_{i=1}^m, \{B_j\}_{j=1}^n \subset \mathcal{A} \quad \text{and} \quad \{a_i\}_{i=1}^m, \{b_j\}_{j=1}^n \subset [0, \infty].$$

We consider the refinement of the two partitions. TODO:
 this is why you don't do the unique maximal partition business.
 $\{A_i \cap B_j\}_{i,j=1}^{i=m, j=n}$.

First, let $\alpha \in (0, \infty)$. Then $\alpha f \in \mathcal{SF}_+(X)$, with the simple partition $\{A_n\} \subset \mathcal{A}$ and $\{\alpha a_n\} \subset [0, \infty]$.

$$s(\alpha f) = \sum_{i=1}^n \alpha a_n \mu(A_i) = \alpha \sum_{i=1}^n a_n \mu(A_i) = \alpha s(f).$$

If $\alpha = 0$, then αf is uniformly zero; it is the non-negative simple with partition $\{X\}$ and $\{0\}$. Regardless of the measure of X , this non-negative simple function is zero Recall that we define $0 \cdot \infty = \infty \cdot 0 = 0$. \square



66 Simple Integral Monotonicity

66.1 Why

If one rectangle contains another rectangle, the area of the first should be larger than the area of the second. Our definition of integral for simple functions carries this property. TODO: area sheet.

66.2 Result

Proposition 70. *The simple non-negative integral operator is monotone.*

Proof. Let (X, \mathcal{A}, μ) be a measure space. Let $f, g \in \mathcal{SF}_+(X)$ with $f \leq g$. Then $f - g \in \mathcal{SF}_+(X)$, so

$$\begin{aligned} \int g d\mu &= \int (f + (g - f)) d\mu \\ &\stackrel{(a)}{=} \int f d\mu + \int (g - f) d\mu \\ &\stackrel{(b)}{\geq} \int f d\mu \end{aligned}$$

where (a) follows from linearity and (b) follows from non-negativity; properties of the non-negative simple integral operator.

□



67 Real Integral Monotone Convergence

67.1 Why

An integral is a limit. When can we exchange this limit with another? We give a first result in the search for sufficient conditions to do so.

67.2 Result

When context is clear, we refer to the following proposition as the **monotone convergence theorem**.

Proposition 71. *The integral of the almost everywhere limit of an almost-everywhere nondecreasing sequence of measurable, nonnegative, extended-real-valued functions is the limit of the sequence of integrals of the functions.*

Proof. Let (X, \mathcal{A}, μ) be a measure space, and let $f_n : X \rightarrow [-\infty, \infty]$ be a \mathcal{A} -measurable function for every natural number n and let $f : X \rightarrow [-\infty, \infty]$ be a \mathcal{A} -measurable function. We want to show that if

$$f_n(x) \leq f_{n+1}(x) \quad \text{and} \quad f(x) = \lim_n f_n(x)$$

hold for all natural n and almost every x in X , then

$$\int f d\mu = \lim_n \int f_n d\mu.$$

□



68 Real Integral Series Convergence

68.1 Why

Sums of non-negative functions are increasing, and workable with the monotone convergence theorem.

68.2 Result

Proposition 72. *The integral of the limit of the partial sums of a sequence of measurable, nonnegative, extended-real-valued functions is the limit of the partial sums of the integrals.*

Proof. Let (X, \mathcal{A}, μ) be a measure space, and let $f_n : \rightarrow [0, \infty]$ a \mathcal{A} -measurable function for every natural number n . We want to show that:

$$\int \sum_{k=1}^{\infty} f_k d\mu = \sum_{k=1}^{\infty} \int f_k d\mu.$$

We apply the monotone convergence theorem to the sequence $\{\sum_{i=1}^n f_i\}_n$. This sequence is nondecreasing because $f_n \geq 0$ for all n . \square



69 Real Integral Limit Inferior Bound

69.1 Why

TODO

69.2 Result

Proposition 73. *The integral of the limit inferior of a sequence of measurable, nonnegative, extended-real-valued functions is no larger than the limit inferior of the sequence of integrals.*

Proof. Let (X, \mathcal{A}, μ) be a measure space, and let $f_n : \rightarrow [0, \infty]$ a \mathcal{A} -measurable function for every natural number n . We want to show that if

$$\int \liminf_n f_n d\mu \leq \liminf_n \int f_n d\mu.$$

□



70 Real Integral Dominated Convergence

70.1 Why

An integral is a limit. When can we exchange this limit with another? We give a first result in the search for sufficient conditions to do so.

70.2 Result

When context is clear, we refer to the following proposition as the **dominated convergence theorem**.

Proposition 74. *The integral of the almost everywhere limit of a sequence of measurable, extended-real-valued, almost-everywhere bounded functions is the limit of the sequence of integrals of the functions.*

Proof. Let (X, \mathcal{A}, μ) be a measure space. Let $f : X \rightarrow [-\infty, \infty]$ be a \mathcal{A} -measurable function. Let $f_n : X \rightarrow [-\infty, \infty]$ a \mathcal{A} -measurable function for every natural number n so that $\{f_n\}_n$ converges almost everywhere to f . Let $g : X \rightarrow [0, \infty]$ be an integrable

function which dominates f_n almost everywhere for each n . We want to show that:

$$\int f d\mu = \lim_n \int f_n d\mu.$$

□



71 Real Integral Limit Theorems

71.1 Why

A vista sheet on exchanging integrals and limits.

71.2 Discussion

The monotone convergence theorem and the dominated convergence theorem give conditions under which we can exchange a limit with an integral. Since an integral is a limit, these theorems give conditions under which we can exchange limits.

We remember in exchanging these limits that we are really exchanging infinite processes. It is no surprise that this exchange does not always make sense. Nonetheless, the dominated convergence theorem gives a simple criteria which is easy and guarantees the desired exchange is valid.

TODO: Structure of the theory. Building from the monotone convergence for simple functions through to the dominated convergence.



72 Image Measures

72.1 Why

A measurable function from a measure space to a measurable space induces a measure on the measurable space.

72.2 Definition

Consider two measurable spaces and a measurable function between them. The **image measure** of a measure on the first space under the measurable function is the measure on the second space which assigns to each measurable set the measure of the inverse image of that measurable set.

72.2.1 Notation

Let (X, \mathcal{A}) and (Y, \mathcal{B}) be two measurable spaces. Let $f : X \rightarrow Y$ be a measurable function. Let $\mu : \mathcal{A} \rightarrow [0, \infty]$ be a measure. We denote the image measure of μ under f by $\mu \circ f^{-1}$. The measure $\mu \circ f^{-1}$ satisfies

$$\mu \circ f^{-1}(B) = \mu(f^{-1}(B))$$

for every $B \in \mathcal{B}$.

72.3 Change of Variables

The main property we would like to hold is that integration on the new measure space is the same as integration on the old.

Proposition 75. *Let (X, \mathcal{A}) and (Y, \mathcal{B}) be measurable spaces and let R denote the real numbers. Let $f : X \rightarrow Y$ be a measurable function and let $\mu : \mathcal{A} \rightarrow [0, \infty]$ be a measure.*

Then $g : Y \rightarrow R$ is integrable with respect to $\mu \circ f^{-1}$ if and only if $g \circ f$ is integrable with respect to μ . In this case,

$$\int g d(\mu \circ f^{-1}) = \int g \circ f d\mu.$$

Proof.

□



73 Functionals

73.1 Why

We speak of maps from a vector space to a field of scalars.

73.2 Definition

A **functional** is a function from a set of vectors to a field. It is natural, and common, for the field of scalars to be the base field.

A real-valued functional is **non-negative** if its range is a subset of the non-negative real numbers. A real-valued functional is **definite** if the only it maps to zero is the zero element of the vector space.

A real-valued functional on a real or complex vector space is **absolutely homogeneous** if the result of a scaled vector is the same as the result of the vector scaled by the absolute value of the scalar.



74 Signed Measures

74.1 Why

We allow measures to take negative values. We want a vector space of finite measures. TODO

74.2 Definition

An extended-real-valued function on a sigma algebra is **countably additive** if the result of the function applied to the union of a disjoint countable family of distinguished sets is the limit of the partial sums of the results of the function applied to each of the sets individually. The limit of the partial sums must exist irregardless of the summand order.

A **signed measure** is an extended-real-valued function on a sigma algebra that is (1) zero on the empty set and (2) countably additive. We call the result of the function applied to a set in the sigma algebra the **signed measure** (or when no ambiguity arises, the **measure**) of the set.

A **finite** signed measure is one for which the measure of every set is finite. This condition is equivalent to the base set having finite measure (see below).

74.2.1 Notation

We denote signed measures by μ a mnemonic for “measure.” Let (X, \mathcal{A}) be a measurable space and let $\mu : \mathcal{A} \rightarrow [-\infty, \infty]$. Then μ is a signed measure if

1. $\mu(\emptyset) = 0$ and
2. $\mu(\cup_i A_i) = \lim_{n \rightarrow \infty} \sum_{k=1}^n \mu(A_k)$ for all disjoint families $\{A_n\}_n$.

74.3 Infinite Exclusivity

Proposition 76. *A signed measure is finite if and only if it is finite on the base set.*

Proof. Let (X, \mathcal{A}) be a measurable space. Let $\mu : \mathcal{A} \rightarrow [-\infty, \infty]$ be a signed measure. (\Rightarrow) If μ is finite, then $\mu(X)$ is finite since $X \in \mathcal{A}$. (\Leftarrow) Next, suppose $\mu(X)$ is finite. Let $A \in \mathcal{A}$. Then $X = A \cup (X - A)$, with these sets disjoint, so by countable additivity of μ , $\mu(X) = \mu(A) + \mu(X - A)$. Since $\mu(X)$ finite, $\mu(A)$ and $\mu(X - A)$ are both finite. \square

Proposition 77. *A signed measure never takes both positive infinity and negative infinity.*

Proof. Let (X, \mathcal{A}) be a measurable space. Let $\mu : \mathcal{A} \rightarrow [-\infty, \infty]$ be a signed measure. First, suppose $\mu(X)$ is finite, Then by Proposition 76 μ is finite for each $A \in \mathcal{A}$.

Suppose $\mu(X) = \infty$. Let $A \in \mathcal{A}$. As before, $\mu(X) = \mu(A) + \mu(X - A)$. Since $\mu(X) = +\infty$, then both of $\mu(A)$ and $\mu(X - A)$

A) must be either finite or $+\infty$. Argue similarly for $\mu(X) = -\infty$. \square



75 Product Sigma Algebras

75.1 Why

We want to generalize the construction of cover area as generated as a product of two cover lengths, and more generally for arbitrary measure spaces. TODO

75.2 Definition

Consider two measurable spaces. The **product base set** is the cartesian product of the first base set with the second base set. A first distinguished set is a distinguished set of the first measurable space, and likewise for a second distinguished set.

A **rectangle with measurable sides** is a set in product base set which is a product of a first distinguished set with a second distinguished set. The **product sigma algebra** is the sigma algebra generated by the rectangles with measurable sides.

The **product measurable space** is the measurable space whose base set is the product base set and whose sigma algebra is the product sigma algebra.

75.2.1 Notation

Let (X, \mathcal{A}) and (Y, \mathcal{B}) be measurable spaces. The product base set is $X \times Y$. A set $R \in X \times Y$ is a rectangle with measurable sides if $R = A \times B$ for $A \in \mathcal{A}$ and $B \in \mathcal{B}$. We denote the product sigma algebra of \mathcal{A} and \mathcal{B} by $\mathcal{A} \times \mathcal{B}$. $(X \times Y, \mathcal{A} \times \mathcal{B})$ is the product measurable space.



76 Product Sections

76.1 Why

Toward a theory of iterated integrals, we need to generalize rectangular strips to arbitrary products.

76.2 Definition

Consider the product of two non-empty sets.

First, consider a subset of this product. For a specified element in the first set, the **set section** of the subset with respect to that element is the set of elements in the second set for which the ordered pair of the specified element and that element is in the subset; the section is a subset of the second set. For elements of the second set, we define sections similarly.

Second, consider a function on the product. For a specified element in the first set, the **function section** of the function for that element is the function from the second set to the codomain of the function which maps elements of the second set to the result of the function applied to the ordered pair of the specified element and the element of the second set. For elements of the second set, we define sections similarly.

76.2.1 Notation

Let X, Y be non-empty sets.

Let $E \subset X \times Y$. For $x \in X$, we denote the section of E with respect to x by E_x . For $y \in Y$, we denote the section of E with respect to y by E^y . For every $x \in X$ and $y \in Y$,

$$E_x = \{y \in Y \mid (x, y) \in E\} \quad \text{and} \quad E^y = \{x \in X \mid (x, y) \in E\}.$$

$$E_x \subset Y \text{ and } E^y \subset X.$$

Let $f : X \times Y \rightarrow Z$. For $x \in X$, we denote the section of f with respect to x by $f_x : Y \rightarrow Z$. For $y \in Y$, we denote the section of f with respect to y by $f^y : X \rightarrow Z$. For every $x \in X$ and $y \in Y$,

$$f_x(y) = f(x, y) \quad \text{and} \quad f^y(x) = f(x, y).$$



77 Measurable Sections

77.1 Why

Toward a theory of iterated integrals, we need to know that set and function sections are measurable.

77.2 Results

Proposition 78. *Let (X, \mathcal{A}) and (Y, \mathcal{B}) be measurable spaces. For any $E \in \mathcal{A} \times \mathcal{B}$, the sections E_x and E^y are measurable for any $x \in X$ and $y \in Y$.*

Proof. TODO

□

Proposition 79. *Let (X, \mathcal{A}) and (Y, \mathcal{B}) be measurable spaces. Let $f : X \times Y \rightarrow F$, where F is the extended real numbers or the complex numbers, and f is measurable (using the appropriate sigma algebra of the codomain). The sections $f_x : Y \rightarrow F$ and $f^y : X \rightarrow F$ are measurable for each $x \in X$ and $y \in Y$.*

Proof. TODO

□



78 Sections Measures

78.1 Why

Toward a theory of iterated integrals, we need to know the function measuring a section is integrable.

78.2 Results

Proposition 80. *Let (X, \mathcal{A}, μ) and (Y, \mathcal{B}, ν) be sigma-finite measurable spaces. Let $E \in \mathcal{A} \times \mathcal{B}$. The function $x \mapsto \nu(E_x)$ is \mathcal{A} -measurable and the function $y \mapsto \mu(E^y)$ is \mathcal{B} -measurable.*

Proof. TODO

□



79 Product Measures

79.1 Why

We want to generalize the construction of cover area as generated as a product of two cover lengths, and more generally for arbitrary measure spaces. TODO

79.2 Definition

The **product measure** of the measures of two sigma finite measure spaces is the unique measure which assigns to every rectangle with measurable sides the product of the measures of the sides. We prove that such a measure exists, and is unique.

79.2.1 Defining Result

Proposition 81. *Let (X, \mathcal{A}, μ) and (Y, \mathcal{B}, ν) be sigma-finite measurable spaces. There is a unique measure π on $\mathcal{A} \times \mathcal{B}$ such that*

$$\pi(A \times B) = \mu(A) \times \nu(B)$$

for all $A \in \mathcal{A}$ and $B \in \mathcal{B}$. Furthermore, for any $E \in \mathcal{A} \times \mathcal{B}$.

$$\pi(E) = \int_X \nu(E_x) d\mu(x) = \int_Y \mu(E^y) d\nu(y).$$

Proof. TODO

□

79.2.2 Notation

Let (X, \mathcal{A}, μ) and (Y, \mathcal{B}, ν) be sigma-finite measurable spaces. We denote the product measure by $\mu \times \nu$. For all $A \in \mathcal{A}$ and $B \in \mathcal{B}$,

$$(\mu \times \nu)(A \times B) = \mu(A) \times \nu(B).$$



80 Norms

80.1 Why

We want to measure the size of an element in a vector space.

80.2 Definition

A **norm** is a real-valued functional that is (a) non-negative, (b) definite, (c) absolutely homogeneous, (d) and satisfies a triangle inequality. The triangle inequality property requires that the norm applied to the sum of any two vectors is less than the sum of the norms.

80.2.1 Examples

Example 82. *The absolute value function is a norm on the vector space of real numbers.*

Example 83. *The Euclidean distance is a norm on the various real spaces.*

80.2.2 Notation

Let (X, F) be a vector space where F is the field of real numbers or the field of complex numbers. Let R denote the set of real numbers. Let $f : X \rightarrow R$. The functional f is a norm if

1. $f(v) \geq 0$ for all $x \in V$
2. $f(v) = 0$ if and only if $x = 0 \in X$.
3. $f(\alpha x) = |\alpha|f(x)$ for all $\alpha \in F, x \in X$
4. $f(x + y) \leq f(x) + f(y)$ for all $x, y \in X$.

In this case, for $x \in X$, we denote $f(x)$ by $|x|$, read aloud “norm x”. The notation follows the notation of absolute value as a norm. When we wish to distinguish the norm from the absolute value function, we may write $\|x\|$. In some cases, we go further, and for a norm indexed by some parameter α or set A we write $\|x\|_\alpha$ or $\|x\|_A$.