

## FEATURIZED PROBABILISTIC LINEAR MODELS

# Why

It is natural to embed a dataset.

### Definition

Let  $(x : \Omega \to \mathbb{R}^d, A \in \mathbb{R}^{n \times d}, e : \Omega \to \mathbb{R}^n)$  be a probabilistic linear model over the probability space  $(\Omega, \mathcal{A}, \mathbf{P})$ . Let  $\phi : \mathbb{R}^d \to \mathbb{R}^{d'}$  be a feature map. Then  $(x, A, e, \phi)$  is an featurized probabilistic linear model (also embedded probabilistic linear model). We are modeling the function  $h : \Omega \to (\mathbb{R}^d \to \mathbb{R})$  as linear in the features

$$h_{\omega}(a) = \phi(a)^{\top} x(\omega).$$

## Correspondence to linear model

Denote the data matrix of the embedded feature vectors by  $\phi(A)$ . Then, of course, the embedded linear model  $(x, A, e, \phi)$  corresponds to the linear model  $(x, \phi(A), e)$ .

#### Normal case

In the normal (Gaussian) case, the parameter posterior  $g_{x|y}(\cdot, \gamma)$  is a normal density with mean

$$\Sigma_x \phi(A)^{\top} \left( \phi(A) \Sigma_x \phi(A)^{\top} + \Sigma_e \right)^{-1} \gamma$$

and covariance

$$\left(\Sigma_x^{-1} + \phi(A)^{\top} \Sigma_e^{-1} \phi(A)\right)^{-1}$$
.

The predictive density for a point  $a \in \mathbb{R}^d$  is normal with mean

$$(\phi(a)^{\top}\Sigma_x\phi(A)^{\top} + \Sigma_{fe})\left(\phi(A)\Sigma_x\phi(A)^{\top} + \Sigma_e\right)^{-1}\gamma.$$

