



### Why

We can cast various common probabilistic regression models into the probabilistic errors linear model by mentioning the input space and feature maps. This unifies our analysis.

### Definition

A *line fit model* has input space  $\mathbf{R}$  and output space  $\mathbf{R}$ . We use a regression function  $\phi : \mathbf{R} \rightarrow \mathbf{R}^2$  defined by  $\phi(t) = (1, t)^\top$ .

We think of  $t \in T \subset \mathbf{R}$  as a “dose level” ( $T$  is an interval). Given dose levels  $t_1, \dots, t_\ell$  and repetitions  $n_1, \dots, n_\ell$  we obtain the design matrix. Here the regression function generates a line segment embedded in the plane  $\mathbf{R}^2$ . We call the parameters the *intercept parameter* and *slope parameter*.

A *parabola fit model* has input space  $\mathbf{R}$  and output space  $\mathbf{R}$ . We use a regression function  $\phi : \mathbf{R} \rightarrow \mathbf{R}^3$  defined by  $\phi(t) = (1, t, t^2)^\top$ . Here the regression space is a segment of a parabola embedded in space  $\mathbf{R}^3$  (since  $t \in T$  an interval).

These two are instance of *polynomial fit models* of degree  $d \geq 1$ , in which the regression function becomes  $\phi : \mathbf{R} \rightarrow \mathbf{R}^{d+1}$  defined by  $\phi(t) = (1, t, t^2, \dots, t^d)^\top$ . In this case, the regression range  $\phi(T)$  is a one-dimensional curve embedded in  $\mathbf{R}^{d+1}$ . In cases in which it is clear that the input space is a single real variable  $t$ , a linear model for a line fit (parabola fit, polynomial fit of degree  $d$ ) is called a *first-degree model* (*second-degree model*, *dth degree model*).

### $m$ -way models

We can generalize to *m-way dth degree polynomial fit models* in which the input space is  $X \subset \mathbf{R}^m$  and the regression function  $\phi : \mathbf{R}^m \rightarrow \mathbf{R}^k$  ( $k$  is  $d + m$  choose  $d$ ) is the vector of all monomials of degree  $d$  in  $m$  variables.

For example, a two-way third-degree model has a regression function

$$\phi(t_1, t_2) = \begin{bmatrix} 1 & t_1 & t_2 & t_1^2 & t_1 t_2 & t_2^2 & t_1^3 & t_1^2 t_2 & t_1 t_2^2 & t_2^3 \end{bmatrix}^\top.$$

Or consider a three way second-degree model with regression function

$$\phi(t_1, t_2, t_3) = \begin{bmatrix} 1 & t_1 & t_2 & t_3 & t_1^2 & t_1 t_2 & t_1 t_3 & t_2^2 & t_2 t_3 & t_3^2 \end{bmatrix}^\top.$$

Both models will result in parameter vectors of size ten. We call these models *saturated* because they have every possible  $d$ th degree power or cross product of variables. In generally, a  $m$ -way  $d$ th degree model has  $d + m$  choose  $d$  mean parameters.

In contrast to saturated models we can talk about *nonsaturated* models. For example, a nonsaturated two-way second-degree model has  $\phi : \mathbf{R}^2 \rightarrow \mathbf{R}^4$  where  $\phi(t_1, t_2) = (1, t_1, t_2, t_1^2)^\top$ .

