





Bayesian Learning via Stochastic Gradient Langevin Dynamics

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Introduction

Introduction

Large scale datasets limits.

- o MCMC: each iteration requires computations over the whole dataset.
- o SGD: does not capture parameter uncertainty and can potentially overfit data.
- o Idea: algorithm that overcomes MCMC and SGD issues.

Optimization.

- The first phase of MCMC is optimization ("burn-in").
- o Idea: algorithm that naturally transitions between optimization and sampling.

Noise generalizes well.

- o Neural network.
- o Idea: add noise into the algorithm for better generalization.

Stochastic Gradient Langevin

Dynamics

- Key motivation. Combine SGD and MCMC to benefit from the advantages of both methods.
- o Idea. Algorithm with the proposed update :

$$\Delta\theta_{t} = \frac{\epsilon_{t}}{2} \left(\nabla \log p(\theta_{t}) + \frac{N}{n} \sum_{i=1}^{n} \nabla \log p(x_{ti} \mid \theta_{t}) \right) + \eta_{t}; \quad \eta_{t} \sim N(0, \epsilon_{t}I)$$

- o Initial phase: imitates an efficient SGD.
- Transition: smooth transition from the burn-in optimisation phase into the posterior sampling phase.
- Second phase: the injected noise dominates and the algorithm approximates MCMC.
- Advantage. Efficient use of large datasets while allowing for parameter uncertainty to be captured in a Bayesian manner.

SGLD: Application

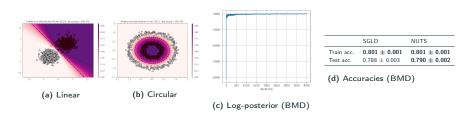
o Setting. Bayesian logistic regression model with a Gaussian prior:

$$\theta \sim \mathcal{N}(0, I); \quad y_i \underset{iid}{\sim} \mathcal{B}(\sigma(y_i x_i^T \theta)), \quad \forall i \in \{1, \dots, N\}$$

 \circ Gradient update. $\epsilon_t = a(b+t)^{-\gamma}, \ \eta_t \sim \mathcal{N}(O, \epsilon_t I)$

$$\theta_{t+1} = \theta_t + \frac{\epsilon_t}{2} \left[-\frac{1}{\sigma^2} \theta + \frac{N}{n} \sum_{i=1}^{n} (1 - \sigma(y_i x_i^T \theta)) y_i x_i \right] + \eta_t$$

- o Application to linear and circular synthetic dataset.
- Application to the Bank Marketing Dataset¹(BMD).



https://www.kaggle.com/datasets/janiobachmann/bank-marketing-dataset

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SGLD: Strengths and weaknesses

Strengths. SGLD combines:

- o Bayesian framework for uncertainty quantification and model regularisation.
- o Gradient updates by mini-batches to reduce computation time.

Weaknesses.

- o Need to tune the step size parameters a,b,γ to control the chaotic behaviour of convergence.
- o Poor mixing during the posterior sampling phase.

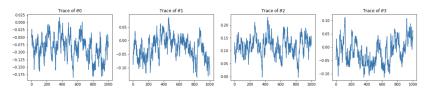


Figure 2: Trace plots of some parameters of θ obtained using SGLD.

Contribution: Stochastic Gradient

Hamiltonian Dynamics

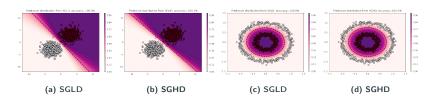
Contribution: Stochastic Gradient Hamiltonian Dynamics

- **Key motivation.** The Hamiltonian dynamic untangles the samples' correlation by introducing p: $\mathcal{H}(q,p) = -\log \pi(q) + p^T M_H p$.
- Idea. Use batch updates of the gradient in HMC.
 The leapfrog updates are computed on a mini-batch of n samples.

$$p_{1/2} = p + \frac{h}{2} \nabla_n \log \pi(q), \quad q' = q + h M p_{1/2}, \quad p' = p_{1/2} + \frac{h}{2} \nabla_n \log \pi(q').$$

o Application. Bayesian logistic regression.

Params: $n_{batch1} = 750, n_{batch2} = 50, h = 0.5, n_h = 80.$



Contribution: Stochastic Gradient Hamiltonian Dynamics

Application to the Bank Marketing Dataset (BMD).

Params:
$$a = 0.01, b = 100, \gamma = 0.6, n_{batch} = 140, h = 0.5, n_h = 80.$$

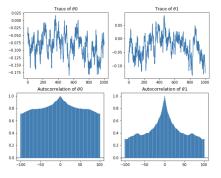


Figure 4: SGLD trace and auto-correlation plots.

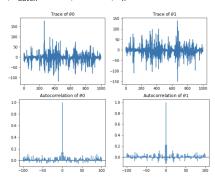


Figure 5: SGHD trace and auto-correlation plots.

	SGLD	SGHD	NUTS
Train acc.	0.801 ± 0.001	0.713 ± 0.042	0.801 ± 0.001
Test acc.	0.788 ± 0.003	0.708 ± 0.040	0.790 ± 0.002

Conclusion

Conclusion

SGLD.

- o Combines stochastic optimization and sampling in one single algorithm.
- o We obtain correlated chain moves.

SGHD.

- \circ Uncorrelates the moves and improves the mixing while updating p, q on a mini-batch.
- Performance sensitive to the initial θ_0 and M_H .
- o Acceptance probability needs to be computed over the whole data.

Perspectives.

- o SGHD performance on multimodal posterior distributions.
- o Integrate an optimization phase to SGHD.
- o Parameters tuning: a, b, γ for SGLD, M_H, h, n_h for SGHD.

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References

- Max Welling and Yee Whye Teh. "Bayesian Learning via Stochastic Gradient Langevin Dynamics". In: Proceedings of the 28th International Conference on International Conference on Machine Learning. ICML'11. Bellevue, Washington, USA: Omnipress, 2011, pp. 681–688. ISBN: 9781450306195.
- [2] Radford Neal. "MCMC using Hamiltonian Dynamics". In: Handbook of Markov Chain Monte Carlo (June 2012). DOI: 10.1201/b10905-6.

Appendix A

Transition to the sampling phase: $\frac{\epsilon_t N^2}{4n} \lambda_{max}(V_s) = \alpha \ll 1$, with V_s being the empirical covariance of the scores $s_i = \nabla \log p(x_i|\theta_t) + \frac{1}{N} \nabla p(\theta_t)$.

Convergence w.r.t. step size: $b = 100, \gamma = 0.6$

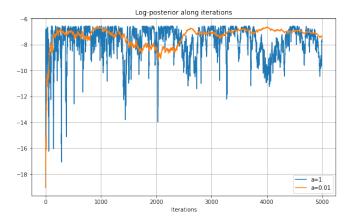
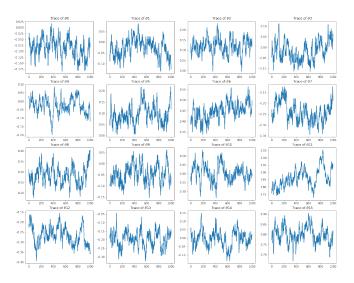


Figure 6: Log-posterior along iterations for small step sizes (a = 0.01) vs large step sizes (a = 1).

Trace plot of SGLD on the real dataset.



Trace plot of SGLD on the real dataset.

