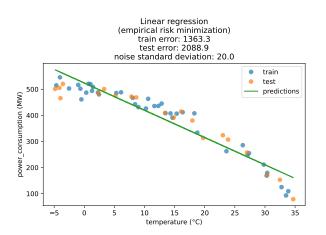
# Machine Learning Tek 5: train and test set, regression.



#### Content

Train sets and test sets, loss functions

Linear regression in one dimension

Polynomial regression and overfitting

General linear regression : Ordinary least squares, ridge regression and hyperparameters

# Linear regression

Linear regression is one of the most elementary methods used in ML regression problems. It is useful for many applications, and is often a component of more complex methods.

We will use is to illustrate several important aspects of ML that are also encountered when using other methods (kernels, trees, neural networks, etc.), namely :

- the train and test sets.
- overfitting (when the dimension d is not really small).

## Example problem

We want to predict the power that needs to be produced by a power plant in a city, as a function of the temperature only.

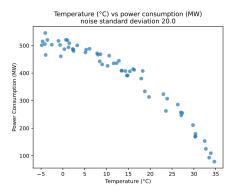


Figure - Dataset

The only information we have is a collection of n samples, called the dataset. Each sample consists in two values :

- the temperature in °C (the feature).
- the power consumption in W (the label).

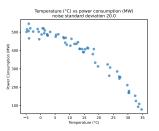


Figure - Dataset

# Supervised learning

Based on this **finite** dataset, our objective is to produce a function, noted  $\tilde{f}$ , called the **model**, the **predictor**, or the **estimator**, that will map a temperature to a power consumption.

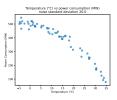


Figure - Dataset

The problem of supervised learning is that we want this function to perform well on **new**, **previously unseen samples**. It is not useful in itsself to perform well on the dataset!

# Supervised learning

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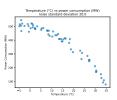


Figure - Dataset

Exercice 2: How could we estimate the performance of  $\tilde{f}$  on unseen data, using the dataset?

#### Train set and set set

We split the dataset in two parts :

- **b** the **train set** will be used to learn (train  $\tilde{f}$ )
- ightharpoonup the **test set** will be used to estimate the performance of  $\tilde{f}$  on unseen data.

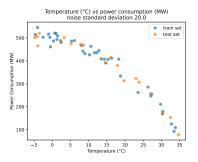


Figure – Splitted Dataset

## Loss functions

To evaluate the performance of  $\tilde{f}$ , we use a **loss function**. The loss function is be a measure of the **discrepancy** between a prediction  $\tilde{f}(x)$  and a label y (that are both real numbers). In regression, the most common loss function is the squared loss :

$$(\tilde{f}(x) - y)^2 \tag{1}$$

Averaging over the whole dataset, this leads to :

► The train error

$$\frac{1}{n_{\text{train}}} \sum_{(x_i, y_i) \in (X_{\text{train}} \times y_{\text{train}})} (\tilde{f}(x_i) - y_i)^2 \tag{2}$$

► The test error

$$\frac{1}{n_{\text{test}}} \sum_{(x_i, y_i) \in (X_{\text{test}} \times y_{\text{test}})} (\tilde{f}(x_i) - y_i)^2$$
 (3)

# Empirical risk minimization

The most common supervised learning process is then naturally to :

- Find  $\tilde{f}$  the as a small training error.
- ightharpoonup Compute the test error of  $\tilde{f}$  in order to estimate its performance on unseen data.

**Remark**: many of these two aspects will be discussed more deeply later in the couse (e.g. notions of validation set, or optimization error)

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# Linear regression

The remaining step is then to find  $\tilde{f}$ . The first step, called **model selection**, is to decide the type of function / model use. Many types of models exist, each one having potential drawbacks, for instance :

- linear functions (which we will use in this first example).
- polynomial functions
- kernels
- neural networks
- support vector machines

#### https:

//scikit-learn.org/stable/machine\_learning\_map.html

Exercice 3: Why are the samples not on a line (and not on a curved line either)?

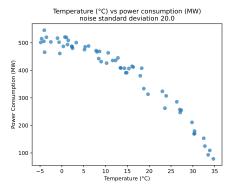


Figure - Dataset

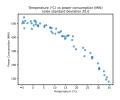


Figure – Dataset

The power consumption does not depend **only** on the temperature, but also on many other variables, that we do not have access to here:

- time in the day
- humidity, wind
- period of the year (holidays or not)
- other variables

## Linear regression

#### Formalization:

- ▶ input space (temperature in  $^{\circ}$ C) :  $\mathcal{X} = \mathbb{R}$
- lacktriangle output space (power consumption in W) :  $\mathcal{Y}=\mathbb{R}$
- ▶ dataset :  $D = \{(x_1, y_1), \dots, (x_n, y_n), i \in [1, n]\}.$

**linear regression** in dimension 1 (as  $x \in \mathbb{R}$ ), means that our estimator is of the form :

$$\tilde{f}(x) = \theta x + b \tag{4}$$

with  $\theta \in \mathbb{R}$ ,  $b \in \mathbb{R}$ .

# Empirical risk minimization

With the squared loss, and this function  $\tilde{f}$  the train error is :

$$R_{n_{train}}(\theta, b) = \frac{1}{n_{train}} \sum_{(x_i, y_i) \in (X_{train} \times y_{train})} (\theta x_i + b - y_i)^2$$
 (5)

The optimization problem is to find  $\theta$  and b such that  $R_{n_{train}}(\theta, b)$  has the smallest possible value.

# Numpy

Numpy demo.

# Computing empirical risks

#### Exercice 4:

```
cd code/day_1/1_linear_regression/
1D_linear_regression/
```

- Generate some data using create\_data.py. You can choose the amplitude of the noise by setting STD\_NOISE in constants.py (we will discuss the importance of this constant shortly).
- fix utils.py in order to correctly compute the train error and test error.

Launch main\_random\_params.py in order to test several values for  $\theta$  and b by evaluating their empirical risk.

# Analytic solutions

For some problems, like this one, it is possible to explicitely compute the optimal solution.

For some advanced reasons (convexity and differentiability of  $R_n(\theta)$ ), the points optimizing the empirical risk are obtained by finding  $(\theta^*, b^*)$  such that the gradient cancels (more on that later in the course).

$$\nabla_{(\theta,b)}R_n(\theta^*,b^*)=0 \tag{6}$$

#### **Derivatives**

We drop the  $\frac{1}{n}$  as it does not change the final result :

$$\frac{\partial R_n}{\partial \theta}(\theta, b) = \sum_{i=1}^n 2(\theta x_i + b - y_i) x_i$$

$$= 2\left[\theta \sum_{i=1}^n x_i^2 + b \sum_{i=1}^n x_i - \sum_{i=1}^n x_i y_i\right]$$
(7)

$$\frac{\partial R_n}{\partial b}(\theta, b) = \sum_{i=1}^n 2(\theta x_i + b - y_i)$$

$$= 2[\theta \sum_{i=1}^n x_i + nb - \sum_{i=1}^n y_i]$$
(8)

Hence we have a system of 2 equations with 2 unknowns (dropping the  $\theta^*$  notation)

$$\theta \sum_{i=1}^{n} x_i^2 + b \sum_{i=1}^{n} x_i - \sum_{i=1}^{n} x_i y_i = 0$$
 (9)

$$\theta \sum_{i=1}^{n} x_i + nb - \sum_{i=1}^{n} y_i = 0$$
 (10)

#### Which means

$$b = \frac{1}{n} \left( \sum_{i=1}^{n} y_i - \theta \sum_{i=1}^{n} x_i \right)$$
 (11)

$$\theta \sum_{i=1}^{n} x_i^2 + \frac{1}{n} \left( \sum_{i=1}^{n} y_i - \theta \sum_{i=1}^{n} x_i \right) \sum_{i=1}^{n} x_i - \sum_{i=1}^{n} x_i y_i = 0$$
 (12)

#### Finally:

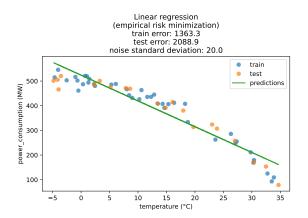
$$\theta(\sum_{i=1}^{n} x_i^2 - \frac{1}{n}(\sum_{i=1}^{n} x_i)^2) + \frac{1}{n} \sum_{i=1}^{n} x_i \sum_{i=1}^{n} y_i - \sum_{i=1}^{n} x_i y_i = 0$$
 (13)

or

$$\theta^* = \frac{\sum_{i=1}^n x_i y_i - \frac{1}{n} \sum_{i=1}^n x_i \sum_{i=1}^n y_i}{\sum_{i=1}^n x_i^2 - \frac{1}{n} [\sum_{i=1}^n x_i]^2}$$
(14)

#### Exercice 5:

Fix main\_optimal\_params.py in order to plot the linear regression found with the analytic solution on the same plot as the raw dataset.

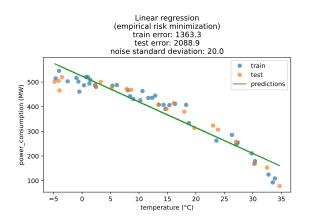


## Scikit

With main\_scikit.py, we can perform the same computation using scikit, and verify that the obtained estimator is identical.

## Different model?

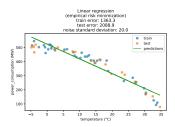
#### Exercice 6: Could we use a better model for this dataset?



Instead of a linear predictor, we could use a polynom. If t is the temperature, the polynomial predictor writes :

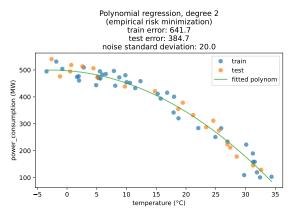
$$\tilde{f}(t) = a_0 + a_1 t + a_2 t^2 + \dots + a_d t^d$$
 (15)

with the **degree** *d* being a constant to determine.

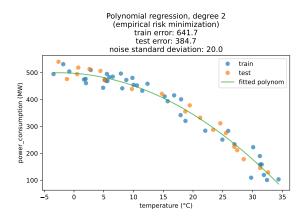


# Fitting polynomials

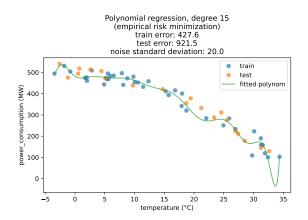
Using main\_polynomial\_regression.py, in which the optimization problem is directly handeled by numpy, we will make several observations.



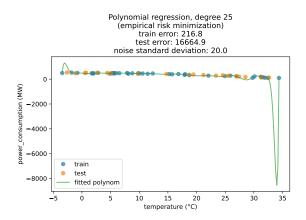
The test error is smaller with this polynomial fit of degree 2 than for the linear regression.



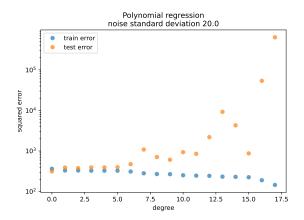
If the degree of the polynom is too large, overfitting happens.



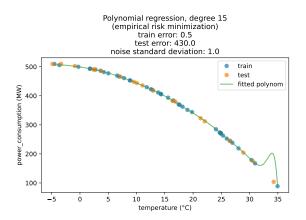
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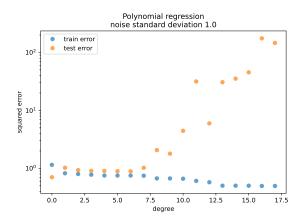
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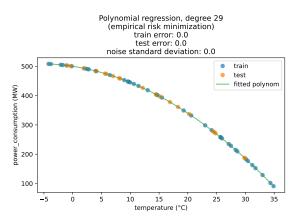
## Reducing the noise standard deviation reduces overfitting



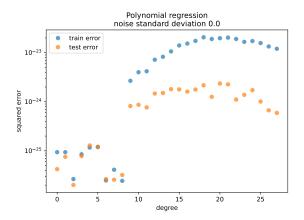
## Reducing the noise standard deviation reduces overfitting



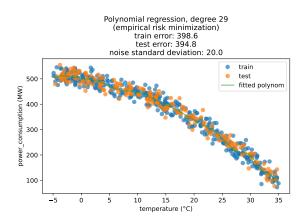
#### If there is no noise, there is no overfitting!



## If there is no noise, there is no overfitting!



#### Having more samples also reduces overfitting.



#### Conclusion

The amount of overfitting depend on the balance between :

- ▶ the number of parameters / features / dimension *d* of the problem
- the number of available samples

Neural networks show some specific behavior on that topic, that we will study later.

**Important remark**: most of the time, it is not possible to have such a direct **visualisation** of the data (as soon as d > 3)!

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#### Generalization

Linear regression also works in higher dimensions, when the inputs are multidimensional. For instance in dimension 3,  $x = (x_1, x_2, x_3)$  and :

$$h(x) = \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_3 + b \tag{16}$$

The parameter is now  $(\theta, b) = (\theta_1, \theta_2, \theta_3, b)$ .

Example: x contains the age, the profession, and the gender.

### Empirical risk

The empirical risk now writes (with adaptation to the relevant train / test dataset) :

$$R_n(\theta, b) = \frac{1}{n} \sum_{i=1}^n (\langle \theta, x_i \rangle + b - y_i)^2$$
 (17)

Almost similarly to the 1D case  $(\theta \in \mathbb{R}, x_i \in \mathbb{R})$ , where it was :

$$R_n(\theta, b) = \frac{1}{n} \sum_{i=1}^{n} (\theta x_i + b - y_i)^2$$
 (18)

#### Matrix notations

If we store the input data in a matrix X (called the **design matrix**) with n lines and d columns, and the labels in a vector y with n lines, the empirical risk writes :

$$X = \begin{pmatrix} x_1^T \\ \dots \\ x_i^T \\ \dots \\ x_n^T \end{pmatrix} = \begin{pmatrix} x_{11}, \dots, x_{1j}, \dots x_{1d} \\ \dots \\ x_{i1}, \dots, x_{ij}, \dots x_{id} \\ \dots \\ \dots \\ x_{n1}, \dots, x_{nj}, \dots x_{nd} \end{pmatrix}$$
(19)

$$R_n(\theta, b) = \frac{1}{n} ||X\theta - y + b||^2$$
 (20)

(more on the notion of norm later in the course)

#### **OLS** estimator

It is possible to show, with some maths notions, that the  $\theta$  that minimizes the empirical risk is :

$$\hat{\theta} = (X^T X)^{-1} X^T y \tag{21}$$

T is the transposition.

 $\hat{\theta}$  is called the **OLS estimator** (Ordinary least squares).

#### Scikit in 1D

We can use scikit-learn in order to obtain the OLS estimator directly.

https://scikit-learn.org

main\_scikit.py computes the OLS for the previous power consumption example.

https://scikit-learn.org/stable/modules/generated/sklearn.linear\_model.LinearRegression.html

## Overfitting

When d is of the same order of magnitude or larger than the number of samples n, it is possible to have a low **train error** and a high **test error**. As before, this is overfitting.

cd ../dD linear regression/

- Generate some data using generate data.py
- Example with OLS\_scikit.py

### Ridge regression

Ridge regression is a variation of OLS. For some advanced reasons, minimizing the Ridge risk might reduce overfitting. We can witness this with Ridge\_scikit.py.

OLS risk :

$$R_{n,OLS}(\theta,b) = \sum_{i=1}^{n} (\langle \theta, x_i \rangle + b - y_i)^2$$
 (22)

Ridge risk :

$$R_{n,Ridge}(\theta,b) = \sum_{i=1}^{n} (\langle \theta, x_i \rangle + b - y_i)^2 + \lambda ||\theta||^2$$
 (23)

with  $\lambda > 0$  a real number (regularization parameter).

### Ridge regression

https://scikit-learn.org/stable/modules/generated/sklearn.linear\_model.ridge.html
Importantly, we can see that Ridge() has some parameters, called hyperparameters. Almost all machine learning algorithms have hyperparameters.

#### Choice of the hyperparameters

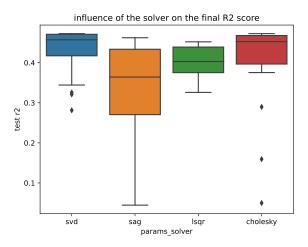
- ➤ The choice of the hyperparameters is very important. Most of the time, it is guided by experimentation and / or theoretical results.
- Some methods and libraries are helpful to look for good hyperparameters, such as optuna https://optuna.org/
- other classical methods : gridsearch, random search.

# Using optuna to tune Ridge regression

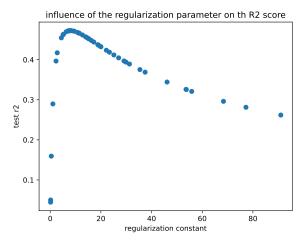
#### Exercice 7:

Use optuna\_ridge\_scikit.py in order to choose some good hyperparameters (alpha, solver) for ridge. You will need to study the optuna API and to edit the objective() function.

### Analysis of the hyperparameters

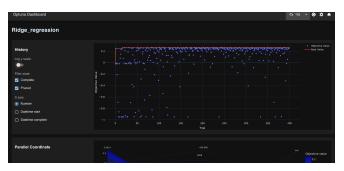


### Analysis of the hyperparameters



### Optuna dashboard

https://github.com/optuna/optuna-dashboard



## Multi-objective optimization

Optuna can be used to optimize several objectives, e.g. : optimize the score and minimize the computation time (both depend on the hyperparameters).

Notion of Pareto front.