Research fields

- Search in uncertain conditions
 - <u>objective</u>: decision—making policy and trajectories of the agents
 - methods: probability theory, possibility theory, signal and image processing

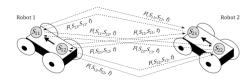


- Control of mobile robots and swarms
 - <u>objective</u>: path-planning and navigation algorithms
 - methods: control theory, probability theory, dynamical systems theory

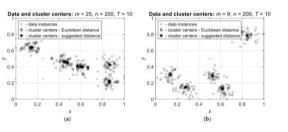




- Decision-making with uncertain information
 - <u>objective</u>: methods of rational and irrational decision-making and prediction
 - methods: probability theory, fuzzy logic, statistics



- Classification and statistical analysis
 - <u>objective</u>: algorithms for classification and analysis of multivariate data
 - methods: probability theory, statistics, fuzzy logic

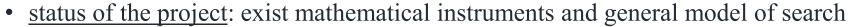


Current projects 1/3

Search for irrational targets

Targets can make decisions, which do not follow maximization or minimization of certain criteria, but are either irrational or follow unknown optimization criteria

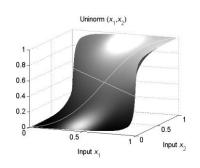
- <u>objective</u>: decision—making policy and trajectories of the search agents
- methods: probability theory, possibility theory, game theory



• still unknown: exact model of target's behavior, searchers' policy

• requirements:

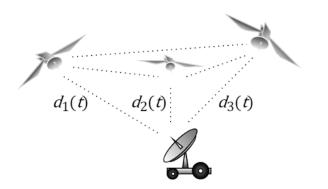
- desire and ability to learn methods of possibility theory and fuzzy logic
- knowledge or desire and ability to learn programming in Python / MATLAB



2500

Current projects 2/3

- Chases and escapes game between AI agents
 - The target and the searcher are AI governed mobile robots
 - <u>objective</u>: game between AI governed mobile robots
 - methods: AI platforms (Gemini, ChatGPT), control theory, game theory, protocol programming
 - <u>status of the project</u>: exist general model of the game, ideas of the protocol, Python API with Google, connection with Arduino controllers, Arduino controlled mobile robots
 - still unknown: project and implementation of the protocol, implementation of the game
 - requirements:
 - knowledge or desire and ability to learn programming in Python and C++ for Arduino
 - knowledge or desire and ability to learn mobile robots' programming and control

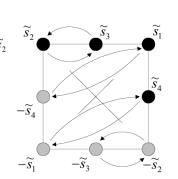


Current projects 3/3

• Fuzzy model of quantum computations

Modelling quantum computations and algorithms by analog computations

- <u>objective</u>: models of quantum computations by multivalued logic methods
- methods: quantum information, fuzzy logic, automata theory



- status of the project: exists mathematical model of quantum gates based on fuzzy Tsetlin automata
- <u>still unknown</u>: implementation and models of quantum algorithms based on the indicated model
- requirements:
 - desire and ability to learn methods of quantum information theory
 - desire and ability to learn methods of automata theory
 - knowledge or desire and ability to learn programming in Python / MATLAB