

esp

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Contents

1	TODO separate project agnositc stuff	2
2	TODO fix user wheel group problem	2
3	TODO ideas	2
3.1	try to let gopro (cam) interface with esp	2
4	file-gen	2
5	hardware	4
5.1	esp32	4
5.1.1	pinout	4
5.1.2	block-diagram	4
5.1.3	hacks	4
6	API references	4
6.1	micropython implementation of espressif	4
6.2	Microdot	4
7	api_{test.py}	4
8	curl (test API)	5
8.0.1	Root / Doc	5
8.0.2	Digital	6
8.0.3	Analog	6
8.0.4	ds18b20	6

9	tools	6
9.1	TODO document img flashin process	6
9.2	TODO cli _{socket.py}	6
9.3	doc extractor (docer.py)	6
9.4	rshell (filesystem)	8
9.5	webrepl _{cli} (hotswap code)	8
9.6	screen (connect to console/repl)	8
9.7	webrepl.html	9
10	specification	9
10.1	TODO ULP API	9
10.2	I/Os	9
10.3	Control-Loops	9
10.4	UI features	9
10.5	API	9
10.6	sensors	10
10.6.1	pt100	10
10.6.2	OEM DS18B20	10
11	merge org files	10
	[NAME] is a web based dashboard running on a esp32, with it, you can control all I/O peripherals plus read some metadata from the esp	

1 **TODO** separate project agnositc stuff

2 **TODO** fix user wheel group problem

3 **TODO** ideas

3.1 try to let gopro (cam) interface with esp

4 file-gen

```

from os import popen
"""this script outputs an emacs-org table (simple ascii table with '-' and '|'),
  which is programmatically aggregated.
  Since this is meant to be used in an org-file,
  there is a return statement in the global scope"""

src = "./src/"          # src directory from where files are grabbed

```

```

url = "192.168.43.31:/"      # ws domain where files are transferred [col 'esp']
files = popen(f"ls {src}").read().split("\n")[:-1]

webrepl_cli_bin = "/home/$USER/py/esp/webrepl/webrepl_cli.py" # [col 'esp']

pop = lambda c: popen(c).read()[:-1] # because it sucks to always read, especially with
tab = lambda l: "|" + "|".join(l) + "|" # outputs the table rows -> |x|y|z|
emacs_link = lambda t,l,n: f"[{t}:{l}][{n}]"
f_link = lambda l,n: emacs_link("file", l, n)
s_link = lambda l,n: emacs_link("shell", l.split("&")[0] + " &", n)

rows = (
    {"head": "files",
     "body": lambda f: f_link(src + f, f),
     "tail": f"[file:{src}][{src}]",
    {"head": "esp",
     "body": lambda f: s_link(f"{webrepl_cli_bin} {src}{f} {url}{f}", "->"),
     "tail": ""},
    {"head": "du",
     "body": lambda f: pop(f"du -h {src}{f}").split()[0],
     "tail": pop(f"du -S -h {src}").split()[0]},
    {"head": "wc",
     "body": lambda f: ", ".join(pop(f"cat {src}{f} | wc ").split()),
     "tail": ", ".join(pop(f"cat {src}* | wc ").split())})

def table_as_string():
    return "\n".join(
        (tab(c["head"] for c in rows),
         "|-",
         "\n".join(tab([c["body"] (f) for c in rows]) for f in files),
         tab(c["tail"] for c in rows)))

if __name__ == "__main__":
    return table_as_string() # for emacs-org src_blocks
    # print(table_as_string() # to not get an error otherwise

import uasyncio; from api import coro

```

5 hardware

5.1 esp32

5.1.1 pinout

left-side right-side discription

1. legacy pinouts pinout pinout_

5.1.2 block-diagram

block-diagram

5.1.3 hacks

make adc resolve 12bit `adc.atten(ADC.ATTN_11DB)` #3.3V full range of voltage

6 API references

6.1 micropython implementation of espressif

uasyncio

6.2 Microdot

Tut of Microdot

7 `apitest.py`

```
#!/usr/bin/env python3
```

```
"""this script for the [NAME] api"""
```

```
import requests
from time import perf_counter
```

```
ROOT_URL = "http://192.168.43.31:5000/"
```

```
get_gen = lambda calls: (requests.get(ROOT_URL + call["route"], params=call["payload"])
                        for call in calls)
```

```

def benchmark(gen, count):
    t1 = perf_counter()
    return {"results": [[requests.get(ROOT_URL + call["route"], params=call["payload"])
                           .json()
                           for call in api_calls] for i in range(count)],
            "time": (t := perf_counter() - t1),
            "count": count,
            "average_ms": t / count,
            "request/s": 1 / (t / count)}

def pop_keys(keys, *dicts):
    """removes all keys in dicts and returns a list of the resulting dicts"""
    res_dict = []
    for b in dicts:
        [b.pop(k) for k in keys]
        res_dict.append(b)
    return res_dict

api_calls = ({ "route": "api/gpio/set",
                "payload": {"pin":26}}, )

# gpio_bench = pop_keys((), benchmark(get_gen(api_calls), 1))
gpio_bench = benchmark(get_gen(api_calls), 1)

for report in gpio_bench:
    for k in report:
        print(k, " -> ", report[k])

```

8 curl (test API)

api spec

8.0.1 Root / Doc

```
/ <- /gpio <-
```

8.0.2 Digital

```
-> /gpio/get 2 -> curl-G-d"pin=33"192.168.43.31:5000/api/gpio/get&  
-> /gpio/get type error str instead of int -> curl-G-d"pin=26"192.168.  
43.31:5000/api/gpio/set& -> /gpio/set 2 toggle -> /gpio/set 2 OFF ->  
/gpio/set 2 ON -> /gpio/set 2 type error str instead of int
```

8.0.3 Analog

```
/gpio/read 33 <- /gpio/read 33 type error str instead of int <-
```

8.0.4 ds18b20

```
/gpio/ds18 4 <-
```

9 tools

9.1 TODO document img flashin process

9.2 TODO cli_{socket.py}

```
import websockets  
#!/usr/bin/env python  
  
import asyncio  
import websockets  
  
uri = "ws://192.168.43.31:8266"  
  
async def hello():  
    msg = ""  
    async with websockets.connect(uri) as websocket:  
        await websocket.send(msg)  
        msg = input(">>>" + await websocket.recv())  
  
asyncio.run(hello())
```

9.3 doc extractor (docer.py)

```
#!/usr/bin/env python  
"""this python script extracts signature and docstring, of given functions.  
Recogniseing decoratores is yet not implemented.
```

The data is then outputted to a json or org file,
 later is especially usefull, if this script is
 implemented in a org file. In that case, make
 sure that the src_block has the ':results raw' option added
 """

```
from os import popen
from json import dump
from datetime import datetime as dt
```

```
SRC_PATH = "./src/"
OUT_FILE = "./docs.json"
```

```
files = [SRC_PATH + f for f in popen("ls ./src").read().split("\n") if ".py" in f]
```

```
def extract_docs(files):
    """outputs a dict with given filenames as keys,
    whose values are dicts with function signature
    and docstring key value pairs"""
    docs = {}
    for file in files:
        functions = {}
        for f in "".join(open(file, "r").readlines()).split("def "):
            try:
                doc = f.split('"""')[1]
            except IndexError:
                doc = "N/A"
            functions.update({f.split("\n")[0]: doc})
        docs.update({file: functions})
    return docs
```

```
def dict_to_org(d, indent=1):
    """recursivly transforms a dict to an org-file.
    The heading level is controled by the indent parameter
    e.g.
    >>> dict_to_org({"foo": "bar", "bar": {"oof": "baz"}}, indent=2)"""
    # ** foo
    #   bar
    # ** bar
    # *** off
```

```

#     baz
return "\n".join([
    "\n".join((
        "*"*(indent) + " " + str(k),
        dict_to_org(d[k], indent+1)
        if isinstance(d[k], dict)
        else str(d[k])))
    for k in d])

return "** -> docstrings (" \
    + dt.now().strftime("%Y-%m-%d - %H:%M:%S") \
    + ")\n" \
    + dict_to_org(extract_docs(files), indent=3)

# dump(docs, open(OUT_FILE, "w"), indent=2)

```

9.4 rshell (filesystem)

rshell provides a shell which mounts the filesystem of the microcontroller (eps32) under the path /pyboard rshell -p /dev/ttyUSB0 -b 115200

rshell also supports scripts (-f option) edit and tangel this rshell script block,

```
cp /home/nls/py/esp/src/boot.py /pyboard
```

and execute it `sudo rshell -p /dev/ttyUSB0 -b 115200 -f ~/py/esp/dist.rshell&`
 <-

9.5 webrepl_{cli} (hotswap code)

transfer a file with webrepl (don't forget to save the file beforhand) -> gpio
 -> main

9.6 screen (connect to console/repl)

C-c to abort the programm and access `screen /dev/ttyUSB0 115200`

9.7 webrepl.html

10 specification

10.1 TODO ULP API

10.2 I/Os

type	location	porpuse	pin
INPUTS			
tcp/ip ui	portable		
dht22	lung		
dht22	bloom		
dht22			
humid	soil / bloom		
co2	bloom		
pt100	outdoor		
OUTPUTS			
light	bloom		
light	veg		
circ	bloom		
circ	vig		
exhaust			
mister	lung		
dosage-punp	feed		

10.3 Control-Loops

actor	sensor
light	time
mister	humid, gro
exhaust	temperature

10.4 UI features

- E-Stop (Mute)
- abstract mapping

10.5 API

test the api with curl read <- docs.json generate docs -> docs.json

```
return "\n".join([l for l in open("./src/api.py", "r").readlines() if l[0] == "@"])
```

10.6 sensors

10.6.1 pt100

desired resistor for pt100: ~2.57kOhm

10.6.2 OEM DS18B20

tutorial for esp32

11 merge org files

```
FILE=~/base.org  
echo "*" -> "$FILE  
cat $FILE | sed 's,[*] ,** ,'
```