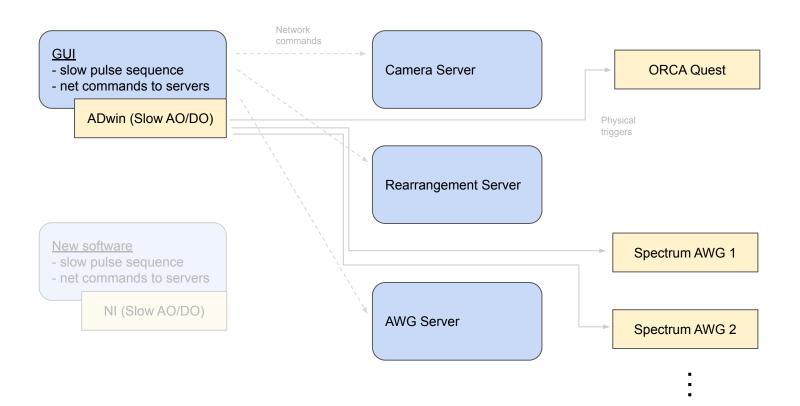
NI Experiment Control System

Agenda

- 1. Control system overview: what we're changing
- 2. Path to our current solution
- 3. Detour on synchronization
- 4. Current solution: features and front end
- 5. Current solution: back-end

Overall experiment control system suggestion -

- copy everything from AA1, only replace ADwin + old software



LabScript limitations

LabScript - a good hybrid:

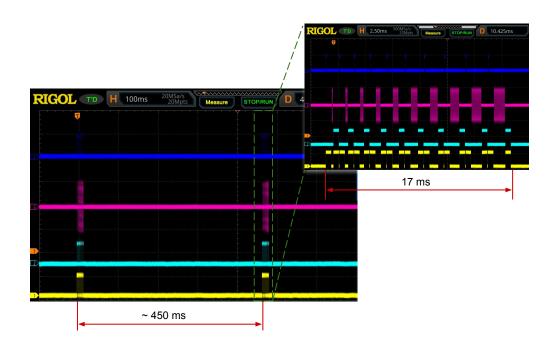
- script-based sequence definition
- GUI control of sequence params

Limitations: script loading takes >450ms

- If only one physical repetition per script max 2 Hz rep rate
- Also dependent on signal length

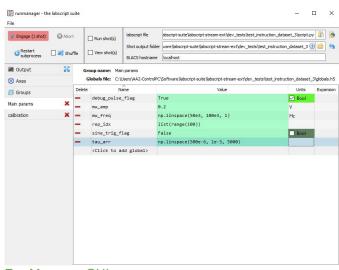
Ways to address:

- Eliminate signal-length dependence
- Decrease script-load overhead

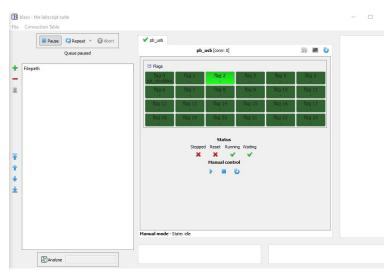


LabScript overview

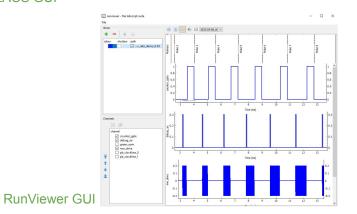




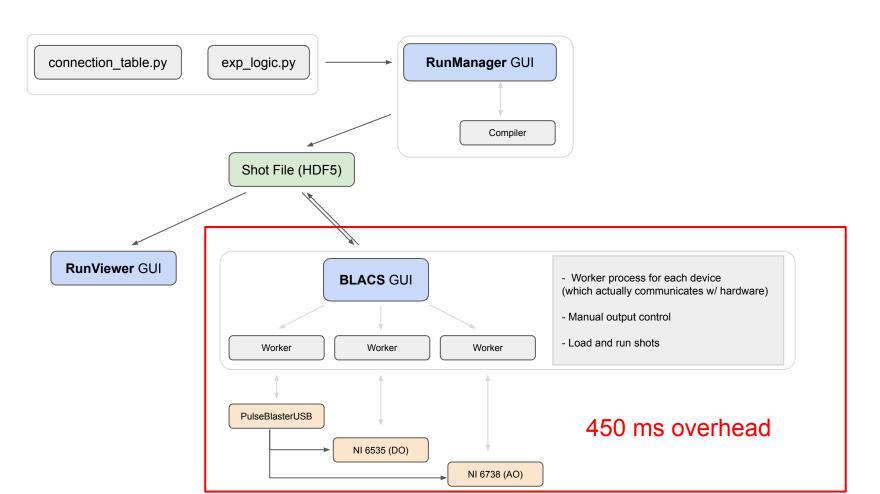
RunManager GUI



BLACS GUI



Typical LabScript workflow / main components



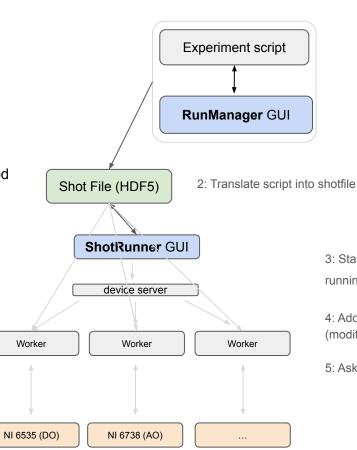
First modification (7.26): custom streaming shot-runner

Improvements:

- Runner overhead 450ms to 120ms
- Eliminated dependence on signal length

Problems:

- Labscript compiling is not fully understood
- GUI potentially redundant
- Complex server-client development, debugging, and cleanup



1: Write python code in compiler standards to specify the experiment design

- 3: Start the shotrunner client and server (if not running already)
- 4: Add .hdf5 files of interest to running queue (modify #repetitions for each file, if needed)
- 5: Ask the shotrunner to execute the queue

Second modification (8.16): full-stack Python

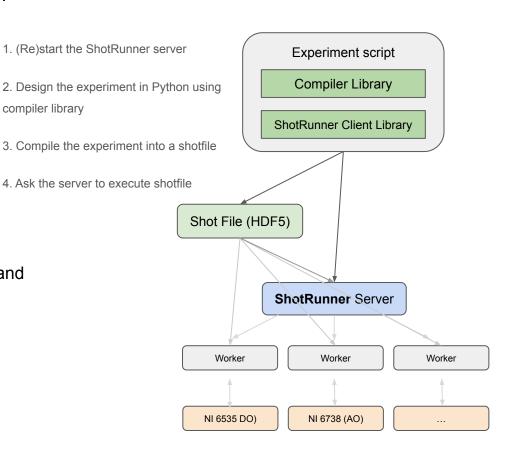
Improvements:

- Full-stack control over compiler behavior
- Compilation and running are easily automated

compiler library

Problems:

- Unnecessary shotfile
 - Each worker essentially "reconstructs" the experiment
- Complex server-client development, debugging, and cleanup
 - Zombie workers after server crash
 - Unresponsive server after worker crash



Third modification (9.7): Full streamline with Rust backend

Benefits

- Eliminate shotfile overhead (-40ms in the loop)
- One experiment, one script, one process
- Remove Python performance limitations

Non-Pythonic-backend: Why?

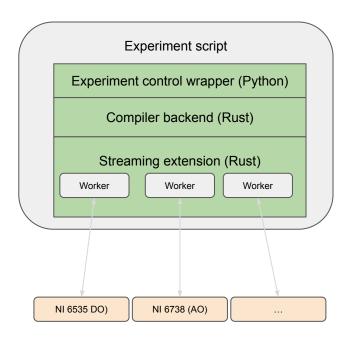
- Circumvent the Python GIL
- Multi-threading (~1ms) v.s. Python multiprocessing (~200ms)
- Stronger compiler checks means less buggy code

Why Rust?

- Interfaces easily with Python (front end) and C (NI driver)
- Very strong safety guarantees: less bugs
- Friendly development pipeline

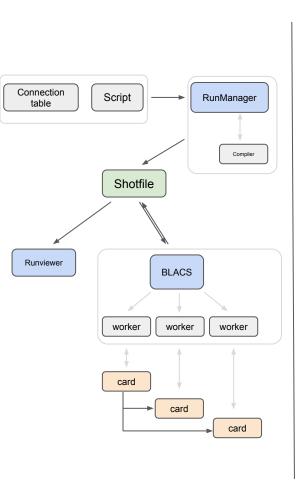
Trade-off

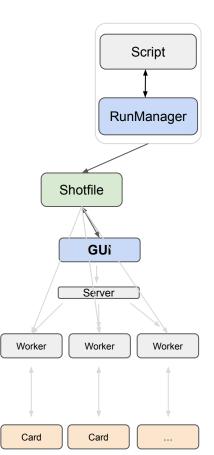
- Modifying streaming behavior requires editing Rust source

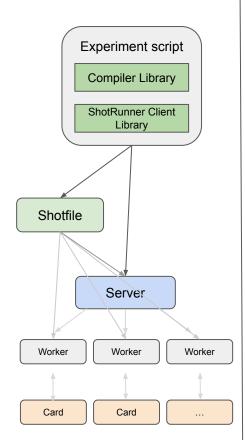


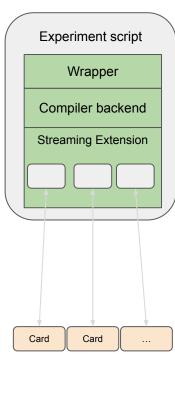
- 1 . Design the experiment in Python using the experiment control library.
- 2. Stream the experiment

Progress Recap: streaming and streamline









Detour: Synchronization

Method	Description	Pros and Cons
Start Trigger Synchronization	Devices share a common start trigger	 Most flexible, synchronizes between tasks and devices with different rates Inter-device drift increases with task length
Share Sample Clock	Devices obtain their sample clock from a designated source	 Supported on all devices Tasks need to run at the source rate
Reference Clock Synchronization	Devices phase-lock their clocks with a common reference	 Flexible, synchronizes between tasks and devices with different rates Not supported on all devices

Detour: Synchronization

Primary AO

- Exports start trigger (PXI_Trig0)
- Export 10MHz reference (PXI_Trig7)
- Flexible sampling rate

Secondary AO

- Expects start trigger (PXI_Trig0)
- Reference-locks to external 10MHz reference (PXI_Trig7)
- Flexible sampling rate

Secondary DO

- Expects start trigger (PXI_Trig0)
- Imports sampling clock from 10MHz reference (PXI_Trig7)
- Fixed sampling rate: 10MHz

