Heaps and Heapsort

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February 1, 2022

Priority Queues

Priority Queues

Definition

A priority queue supports the following operations on a set S.

 $\mathbf{Insert}(S, x)$: Inserts the element x into the set S.

Maximum(S): Returns the element of S with the largest key.

 $\operatorname{ExtractMax}(S)$: Removes and returns the element of S with the largest key.

IncreaseKey(S, x, k): Increases the value of x's key to k. Assumes $k \geq x$.key.

Implementing Priority Queues as (Binary) Heaps

A heap implementation of an n-element priority queue achieves the following running times.

Insert	$O(\log n)$
Maximum	O(1)
ExtractMax	$O(\log n)$
IncreaseKey	$O(\log n)$

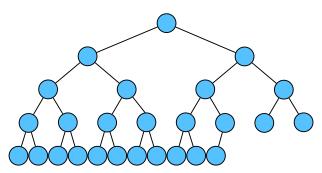
Additionally,

- an n-element heap can be constructed in O(n) time,
- heaps can be used to obtain a $O(n \log n)$ sorting algorithm: Heapsort.

Heaps

Heap Shape

A binary tree T has heap shape if T is completely filled on all levels except possibly the lowest, which is filled from the left up to a point.



Storing a Heap as an Array

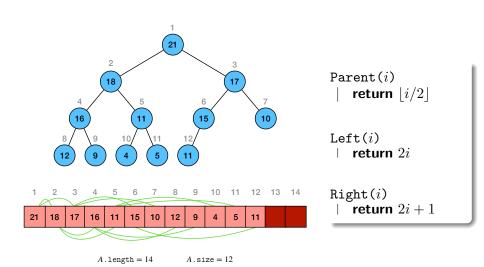
ullet Use an array A with two attributes:

A.length: the number of elements in the array.

A.size: The number of heap elements stored within A.

- ▶ Only the elements in A[1], ..., A[A.size] are valid elements of the heap.
- Number nodes consecutively starting with 1 for the root, going level by level from top to bottom and left to right within each level.
- Put node i in A[i].
- ullet Given the index i of a node, it is easy to compute the indices of its parent, left child, and right child.

Storing a Heap as an Array

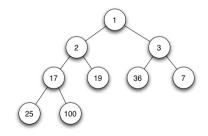


Min Heaps (not the focus for now)

Definition

In a min-heap, for every node i other than the root,

$$A[\mathtt{Parent}(i)] \leq A[i].$$



Source: Wikipedia

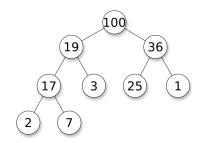
The smallest element in a min-heap is at the root.

Max Heaps

Definition

In a \max -heap, for every node i other than the root,

$$A[\mathtt{Parent}(i)] \geq A[i].$$



Source: Wikipedia

The largest element in a max-heap is stored at the root.

 $\begin{array}{c|c} {\tt Maximum}\,(A) \\ & | & {\tt return}\,\,A[1] \end{array}$

Fact

 ${\tt Maximum}$ runs in O(1) time, regardless of the size of the heap.

Fact

An n-element heap has

- ullet height $\lfloor \log n \rfloor$ and
- ullet at most $\lceil n/2^{h+1} \rceil$ nodes of any height h.

Maintaining a Heap

Heapify

- Assume we are dealing with max-heaps.
- Heapify takes as input an array A and an index i into A.
- Heapify assumes that the trees rooted at Left(i) and Right(i) are heaps.
- ullet A[i] might be smaller than its children, thus violating the heap property.
- ullet Heapify percolates the value at A[i] down the heap so that the subtree rooted at index i obeys the heap property.

```
Heapify(A, i)
   l = Left(i)
    r = Right(i)
   if l \leq A.\mathtt{size} and A[l] > A[i] then
        largest = l
    else
        largest = i
   if r \leq A.\mathtt{size} and A[r] > A[\mathtt{largest}] then
       largest = r
   if largest \neq i then
       exchange A[i] with A[largest]
       Heapify(A, largest)
```

Theorem

The running time of Heapify on a node of height h is O(h).

Building a Heap

```
\begin{array}{c|c} \texttt{BuildHeap}(A) \\ & A.\mathtt{size} = A.\mathtt{length} \\ & \textbf{for} \ i = \lfloor A.\mathtt{length}/2 \rfloor \ \textbf{downto} \ 1 \ \textbf{do} \\ & & | \ \ \mathtt{Heapify}(A,i) \end{array}
```

Note

- Let n = A.length.
- Each of $A[\lfloor n/2 \rfloor + 1], \ldots, A[n]$ is a leaf.
- ullet Thus, each of $A[\lfloor n/2 \rfloor + 1], \ldots, A[n]$ is initially a 1-element heap.

Theorem

BuildHeap converts an array A into a heap.

Proof.

BuildHeap maintains the following.

Loop Invariant

At the start of iteration i of the **for** loop of Heapify, each of nodes $i+1, i+2, \ldots, n$ is the root of a heap.



Theorem

BuildHeap rearranges an n-element into a heap in O(n) time.

Proof.

- Recall that an n-element heap has height $\lfloor \log n \rfloor$ and at most $\lceil n/2^{h+1} \rceil$ nodes of any height h.
- Heapify takes O(h) time when called on a node of height h.
- Thus, the total cost of BuildHeap is

$$O\left(\sum_{h=0}^{\lfloor \log n \rfloor} \left\lceil \frac{n}{2^{h+1}} \right\rceil \cdot h\right)$$

• Next, we show that the sum is O(n).



Proving that $\sum_{h=0}^{\lfloor \log n \rfloor} \left\lceil \frac{n}{2^{h+1}} \right\rceil \cdot h = O(n)$

$$\begin{split} \sum_{h=0}^{\lfloor \log n \rfloor} \left\lceil \frac{n}{2^{h+1}} \right\rceil \cdot h &\leq n \sum_{h=0}^{\lfloor \log n \rfloor} \frac{h}{2^h} \\ &\leq n \sum_{h=0}^{\infty} \frac{h}{2^h} \\ &= 2n, \qquad \text{since } \sum_{k=0}^{\infty} k x^k = \frac{x}{(1-x)^2}, \text{ for } |x| < 1, \\ &= O(n). \end{split}$$

Implementing Priority Queues Using Heaps

```
 \begin{array}{c|c} \operatorname{ExtractMax}(A) \\ & \text{if } A.\operatorname{size} < 1 \text{ then} \\ & & \operatorname{error} \text{ "underflow"} \\ & \operatorname{max} = A[1] \\ & A[1] = A[A.\operatorname{size}] \\ & A.\operatorname{size} = A.\operatorname{size} - 1 \\ & \operatorname{Heapify}(A,1) \\ & \operatorname{return} \operatorname{max} \\ \end{array}
```

Fact

ExtractMax runs in $O(\log n)$ time on an n-element heap.

```
\begin{tabular}{ll} IncreaseKey $(A,i,$ key)$ & if key $<$ $A[i]$ then & | error "new key is smaller than current key" & $A[i] = $key$ & while $i > 1$ and $A[Parent(i)] < $A[i]$ do & | exchange $A[i]$ with $A[Parent(i)]$ & $i = Parent(i)$ & $i
```

Fact

IncreaseKey runs in $O(\log n)$ time on an n-element heap.

Insert(A, key)

$$A.\mathtt{size} = A.\mathtt{size} + 1$$

$$A[A.\mathtt{size}] = -\infty$$

IncreaseKey(A, A.size, key)

Fact

Insert runs in $O(\log n)$ time on an n-element heap.

Heapsort

Heapsort

To sort an n element array A, call BuildHeap(A) to convert A into a max-heap, and then repeat the following n-1 times.

- The maximum element is A[1], so we put it into its correct final position by exchanging A[1] with A[n].
- ullet Discard node n by decrementing $A.\mathtt{size}$.
- The children of the root remain max-heaps, but the new root element might violate the max-heap property.
- To restore the heap property, call Heapify(A,1), which leaves a heap in $A[1],\ldots,A[n-1]$.

```
\begin{tabular}{ll} \mbox{Heapsort}(A) \\ \mbox{ buildHeap}(A) \\ \mbox{ for } i = A.\mbox{length downto } 2 \mbox{ do} \\ \mbox{ exchange } A[1] \mbox{ with } A[i] \\ \mbox{ $A.$size} = A.\mbox{size} - 1 \\ \mbox{ Heapify}(A,1) \\ \end{tabular}
```

Correctness of Heapsort

Loop Invariant

At the start of each iteration of the **for** loop,

- subarray $A[1], \ldots, A[i]$ is a max-heap containing the i smallest elements of $A[1], \ldots, A[n]$, and
- subarray $A[i+1],\ldots,A[n]$ contains the n-i largest elements of $A[1],\ldots,A[n]$, sorted.

Theorem

Heapsort takes time $O(n \log n)$ to sort an n-element array.

Proof.

BuildHeap takes time O(n) and each of the n-1 calls to Heapify takes time $O(\log n)$.

Bibliography

Reference

[CLRS] Thomas H. Cormen, Charles E. Leiserson, Ronald L. Rivest and Clifford Stein, *Introduction to Algorithms* (3rd edition), MIT Press, 2009.