Project 1: Crowd Counting

11761 - Image and Video Analysis Master's Degree in Intelligent Systems

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O1. Preprocessing methods

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Static background removal







Common preprocessing steps

Background substraction











Main proposed pipelines

Proposal1

Proposal 2

Proposal 3

Static Background Removal

Background Substraction (unique image/image averaging)

Upper and lower thresholding

Otsu thresholding

Water removal (HSV thresholding)

Sand removal (simple thresholding)

Otsu thresholding

CLAHE

Background Substraction

Upper and lower thresholding

Otsu thresholding

AND Pixel Operator

02. Detection methods

Detection methods used

Simple Blob Detector

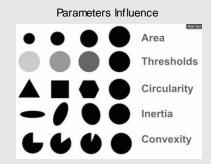
Contour Detector

DBScan

Simple Blob Detector

A Blob

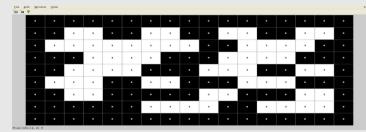
A group of connected pixels in an image that share some common property
Found through connected component Labelling



Parameters Us ed

Min area = 2 Max area = 100 Min Circularity = 0.75 Min Convexity = 0.75 Min Inertia Ratio = 0.15

Connected Component Labelling Example



Contour Detector

Contour

Curves joining all the continuous points along the boundary of an object, having the same color or intensity

Use Border Following
Algorithm. TopBottom, Left-Right
scanning for pixel of
right intensity to trace
contour.

Parameters Used

Contour Area < 50
cv2.CHAIN_APPROX_SIMPLE = compress
vert/horizontal/diagonals segments into
points
cv2.RETR_EXTERNAL = external contours

only Contour Detection Example



DBScan

Clusters

Near (Euclidean-based) points are identified as clusters.

(x,y) of high intesity pixels as points!

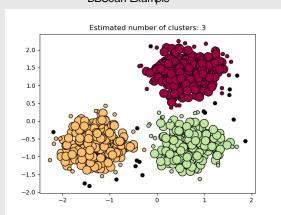
In this case, human pixels should be clustered.

Lower min_samples = more false detections!

Parameters Used

Epsilon = 4 Min_Samples = 40

DBScan Example



03. Evaluation methods

Evaluation methods used

Image-level

Mean Squared Error is used as an image-level indicator of performance.

Person-level

Based on the predictions obtained, we carry out a one near neighbor algorithm without replacement, with thresholded distance, to decide to which category the detection belongs (TP, FP, FN).

Distance between neighbor use Euclidean Distance of 100.

Precision, recall and F1-Score are computed.

04. Obtained results

MSE	16179.3
Mean Precision	0.431
Mean Recall	0.896
Mean F1-Score	0.582





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MSE	88323.5
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Mean F1-Score	0.41





MSE	88323.5
Mean Precision	0.26
Mean Recall	0.958
Mean F1-Score	0.41





Combined Pipeline

MSE	719.6
Mean Precision	0.696
Mean Recall	0.843
Mean F1-Score	0.762





Combined Pipeline

MSE	427.8
Mean Precision	0.827
Mean Recall	0.675
Mean F1-Score	0.743





Combined Pipeline

MSE	279.9
Mean Precision	0.734
Mean Recall	0.672
Mean F1-Score	0.702

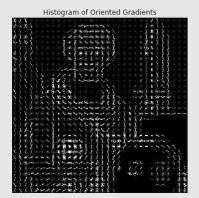




Conclusion

- Detections are only as good as mask!
- Combined Pipelines show good results in terms of curbing false positives.
- HOG-SVM Tried but not very good
- Potential
 - Better HSV thresholding!
 - Smart Pipeline Section!
 - Different Parameters for detection depending on areas in image.





References

Images

- o DBScan: 'https://scikit-learn.org/stable/auto_examples/cluster/plot_dbscan.html'
- $\\ \circ \quad \text{Contour: 'https://www.semanticscholar.org/paper/Fast-human-detection-in-crowded-scenes-by-contour-Beleznai-Bischof/bb3b6bb0c13d66be0a80f66172e943435efe68ab/figure/0'} \\$
- O Blob Parameters: 'https://learnopencv.com/blob-detection-using-opencv-python-c/'
- Connected Labeling: 'https://en.wikipedia.org/wiki/Connected-component_labeling'
- HOG-SVM: 'https://medium.com/analytics-vidhya/a-gentle-introduction-into-the-histogram-of-oriented-gradients-fdee9ed8f2aa"

Thank you for your attention