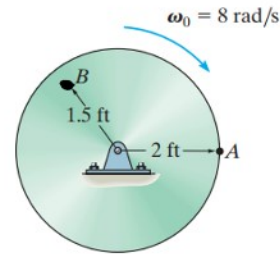


Example 2:

The disk is originally rotating at $\omega_0 = 8 \text{ rad/s}$. If it is subjected to a constant angular acceleration of $\alpha = 6 \text{ rad/s}^2$, determine the magnitude of the velocity and the n and t components of acceleration of point B just after the wheel undergoes 2 revolutions.



$$\omega_0 = 8 \text{ rad/s}$$

$$\alpha = 6 \text{ rad/s}^2$$

$$\theta_0 = 0$$

$$\theta_f = 2 \text{ revs}$$

$$(2 \text{ rev}) \frac{2\pi \text{ rad}}{1 \text{ rev}} = 12.56 \text{ rad/s}$$

$$V_B = ?$$

$$A_N = ?$$

$$A_T = ?$$

$$\omega_f^2 = \omega_0^2 + 2\alpha(\theta_f - \theta_0)$$

$$\omega_f^2 = 8^2 + 2(6)(12.56 - 0)$$

$$\omega_f = 14.65 \text{ rad/s}$$

$$V = r\omega$$

$$= (1.5)(14.65) = 22 \text{ ft/s}$$

$$a_t = r\alpha$$

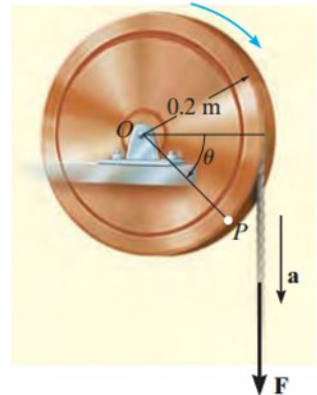
$$= (1.5)(6) = 9 \text{ ft/s}^2$$

$$a_N = \omega^2 r$$

$$= (14.65)^2(1.5) = 322 \text{ ft/s}^2$$

Example 3.

A cord is wrapped around a wheel initially at rest when $\theta = 0$. If a force is applied to the cord and gives it an acceleration $a = 4t \text{ m/s}^2$ where t is in seconds, determine as a function of time, the angular velocity of the wheel, and the angular position of the line OP in radians.



$$\omega_0 = 0 \quad a_t = 4t$$

$$\theta_0 = 0$$

$$a_t = r\alpha$$

$$\alpha = \frac{a_t}{r} = \frac{4t}{0.2} = 20t \text{ rad/s}^2$$

$$\alpha = \frac{d\omega}{dt}$$

$$20t = \frac{d\omega}{dt}$$

$$\int_0^t 20t \, dt = \int_0^\omega d\omega$$

$$10t^2 \Big|_0^t = \omega \Big|_0^\omega$$

$$\omega = 10t^2$$

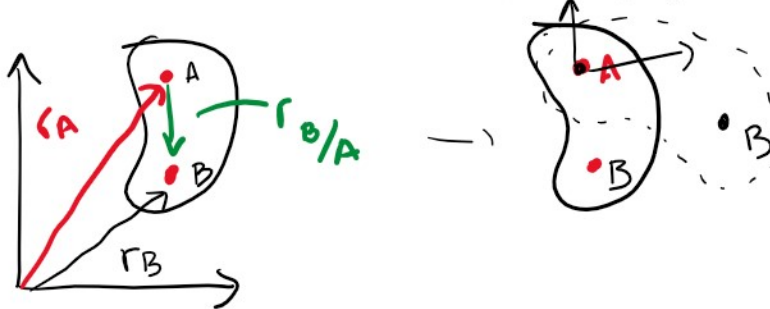
$$\omega = \frac{d\theta}{dt}$$

$$10t^2 = \frac{d\theta}{dt}$$

$$\int_0^t 10t^2 \, dt = \int_0^\theta d\theta$$

$$\frac{10t^3}{3} = \theta$$

General Planar Motion \rightarrow combination of translation and fixed axis rotation



$$\vec{r}_B = \vec{r}_A + \vec{r}_{B/A}$$

$$d\vec{r}_B = d\vec{r}_A + d\vec{r}_{B/A}$$

\uparrow translation + rotation translation rotation

$$\vec{V}_B = \vec{V}_A + \vec{V}_{B/A}$$

$$\vec{V}_B = \vec{V}_A + \vec{\omega} \times \vec{r}_{B/A}$$

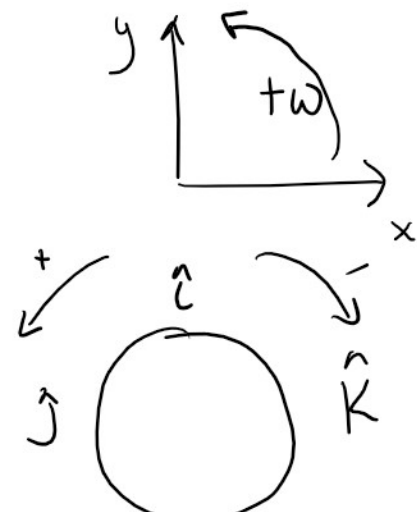
$$\vec{V}_A = \vec{V}_B + \vec{\omega} \times \vec{r}_{A/B}$$

V_B = Velocity of point "B"

V_A = Velocity of point "A"

ω = angular velocity

$\vec{r}_{B/A}$ = position of "B" w.r.t "A"



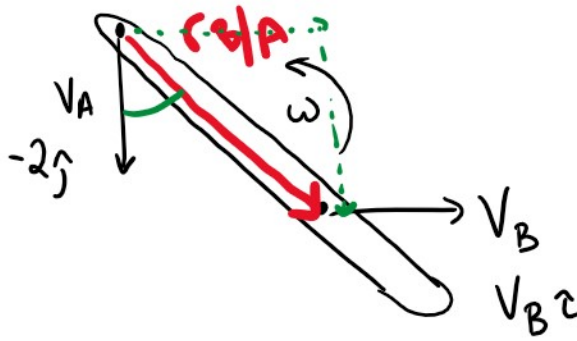
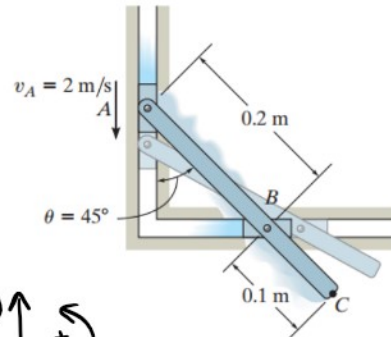


$$\hat{L} \times \hat{J} = +\hat{K}$$

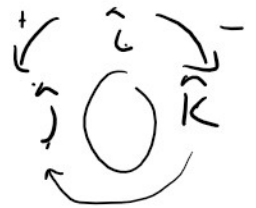
$$\hat{J} \times \hat{L} = -\hat{K}$$

$$\hat{K} \times \hat{L} = +\hat{J}$$

Example 1: The link is guided by two blocks at A and B, which move in fixed slots. If the velocity of A is 2 m/s downward, determine the velocity of B at the instant $\theta = 45^\circ$.



$$\mathbf{r}_{B/A} = 0.2 \sin 45^\circ \hat{i} - 0.2 \cos 45^\circ \hat{j}$$



$$\mathbf{V}_B = \mathbf{V}_A + \boldsymbol{\omega} \times \mathbf{r}_{B/A}$$

$$V_B \hat{i} = -2 \hat{j} + \omega \hat{k} \times (0.2 \sin 45^\circ \hat{i} - 0.2 \cos 45^\circ \hat{j})$$

$$V_B \hat{i} = -2 \hat{j} + 0.2 \sin 45^\circ \omega \hat{j} + 0.2 \cos 45^\circ \omega \hat{i}$$

collect terms

i:

$$V_B = 0.2 \cos 45^\circ \omega$$

$$V_B = 0.2 \cos 45^\circ (14.1)$$

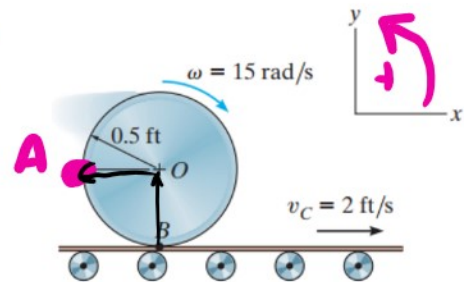
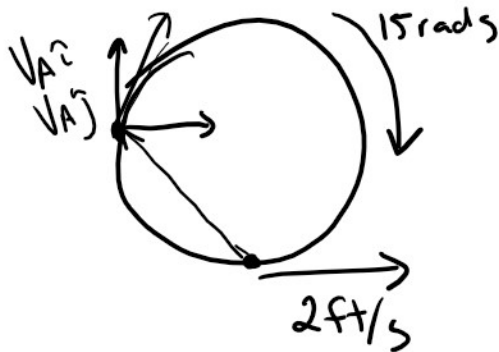
$$= 2 \text{ m/s} \rightarrow$$

j:

$$0 = -2 + 0.2 \sin 45^\circ \omega$$

$$\omega = 14.1 \text{ rad/s}$$

Example 2: The cylinder rolls without slipping on the surface of a conveyor belt moving at 2 ft/s. Determine the velocity of point A. The cylinder has a clockwise angular velocity $\omega = 15 \text{ rad/s}$



point of contact takes on same velocity as moving surface

$$V_A = ? \quad V_{Ai} + V_{Aj}$$

$$V_B = 2\hat{i}$$

$$\omega = -15\hat{k}$$

$$r_{A/B} = 0.5\hat{j} - 0.5\hat{i}$$

$$= -0.5\hat{i} + 0.5\hat{j}$$

$$\bar{V}_A = \bar{V}_B + \bar{\omega} \times \bar{r}_{A/B}$$

$$V_{Ai} + V_{Aj} = 2\hat{i} + (-15)\hat{k} \times (-0.5\hat{i} + 0.5\hat{j})$$

$$V_{Ai} + V_{Aj} = 2\hat{i} + 7.5\hat{j} + 7.5\hat{i}$$

\therefore

$$V_A = 2 + 7.5 = 9.5$$

\therefore

$$V_A = 7.5$$



$$V_A = \sqrt{9.5^2 + 7.5^2} = 12.1 \text{ ft/s}$$

$$\theta = \tan^{-1}\left(\frac{7.5}{9.5}\right) = 38.3^\circ$$

Example 3 : The collar in C is moving downward with a velocity of 2 m/s. Determine the angular velocity of CB **at this instant**. CB starts completely vertically.

