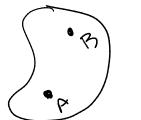
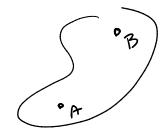
Types of R.B motron

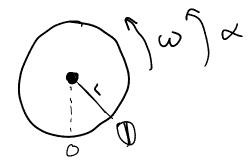
- 1. Translation
- 2. Fixed Axis rotation
- 3. General Planar Motion (TER)
- 4. 3Dm. hon

Every point en a rigid bedy moves with same velocity and acceleration





Fixed axi, rotation



D = Angular displacement W = angular velocity d = angular acceleration

$$\omega = \frac{d\theta}{dt}$$

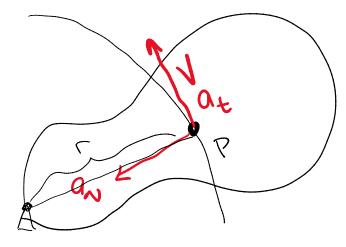
$$d = \frac{d\omega}{dt}$$
 or $\frac{d^2\omega}{dt^2}$ or $\omega \frac{d\omega}{dt}$

if constant angular acceleration

$$\omega = \omega_0 + \omega t$$

$$O = O_0 + \omega_0 t + \frac{1}{2} \omega t^2$$

$$\omega^2 = \omega_0^2 + 2\omega (O - O_0)$$



$$V = r\omega$$

$$Q_{k} = r\omega$$

$$Q_{N} = \omega^{2} r$$

$$S = \varnothing r$$

$$Q_{N} = \frac{\sqrt{2}}{\sqrt{2}}$$

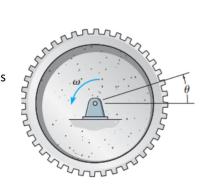
$$= \frac{\sqrt{2}}{\sqrt{2}}$$

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Example 1:

When the gear rotates 20 revolutions after starting from rest, it achieves an angular velocity ω = 30 rad/s. Determine its constant angular acceleration and the time required.



0,21

$$\omega_0 = 0$$
 $Q_f = 20 \text{ rev}$
 $A = ?$
 $A = ?$
 $W_f = 30 \text{ rad/s}$

$$26^{\text{rev}} \frac{2\pi r_{\text{od}}}{11^{\text{eV}}}$$

$$Q_f = 407$$

$$\omega_{f}^{2} = \omega_{o}^{2} + 2\omega (D_{f} - \Theta_{o})$$
 $30^{2} = 0 + 2\omega (40\pi - 0)$
 $\omega_{f}^{2} = 3.58 \text{ rad/s}$

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