

MACHINE LEARNING & PUBLIC POLICY

LECTURE 4: ANOMALOUS PATTERN DETECTION & SURVEILLANCE SYSTEMS

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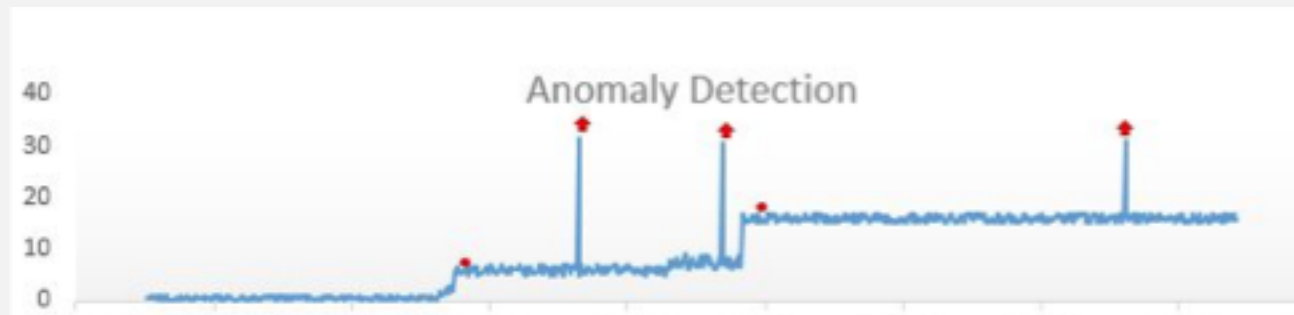
University of Minnesota

ANOMALY DETECTION

Observation II: Sometimes goal is one of detection or discovery

ANOMALY DETECTION PARADIGM

- Identifying when a “system” deviates away from its expected behavior.



ANOMALY DETECTION

- Challenges?
 - How many outliers are there in the data?
 - Method is unsupervised
 - Validation can be quite challenging
 - Finding needle in a haystack
- Working assumption?
 - There are considerably more “normal” observations than “abnormal” observations (outliers/anomalies) in the data

ANOMALY DETECTION

- General Steps?
 - Build a **profile** of the “normal” behavior
 - I.e., patterns or summary statistics for the overall population
 - Use the “normal” profile to detect **anomalies**
 - I.e., observations whose characteristics differ significantly from the normal profile
- Detection schemes?
 - Graphical
 - Distance/proximity - based
 - Statistical/model-based

MODEL BASED ANOMALY DETECTION

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GENERALIZED EXTREME STUDENTIZED DEVIATE

r : upper-bound on # of anomalies

x : sample average

σ : sample standard deviation

α : significance level

H_0 : There are no anomalies in the data

H_a : There are up to r anomalies in the data

$$R_i = \frac{\max_i |x_i - x|}{\sigma}$$

$$\lambda_i = \frac{(n-1)t_{p,n-i-1}}{\sqrt{(n-i-1+t_{p,n-i-1}^2)(n-i+1)}}$$

Remove the observation i and recompute. Repeat until r observations have been removed, result in the r test statistics R_1, R_2, \dots, R_r .

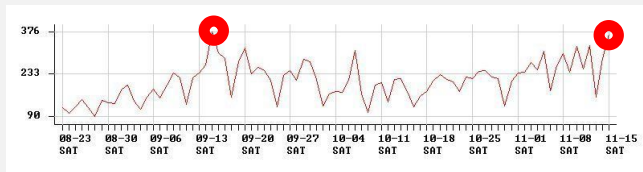
$$P(\cup_i \{R_i \geq \lambda_i\}) \leq \alpha$$

- Select largest i such that $R_i > \lambda_i$
- Assumes Gaussian Distribution
- Seasonality unaware

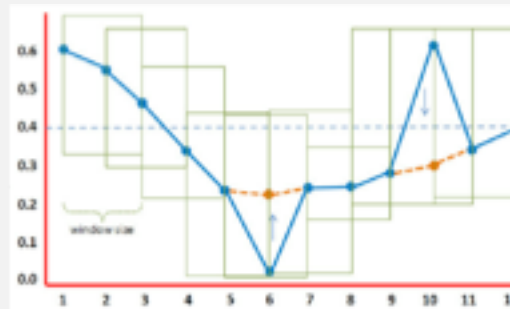
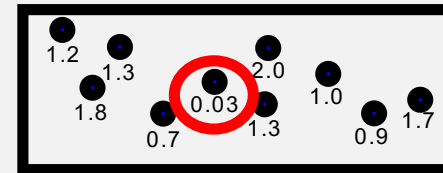
SPATIAL AND TEMPORAL ANOMALY DETECTION

- A simple model-based anomaly detection when we monitor a single real-valued quantity over time and/or space.
- Report any observed value that is significantly above or below its expected value (e.g., using GESD).

Time series data



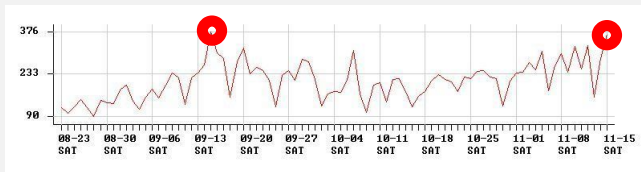
Spatially distributed data



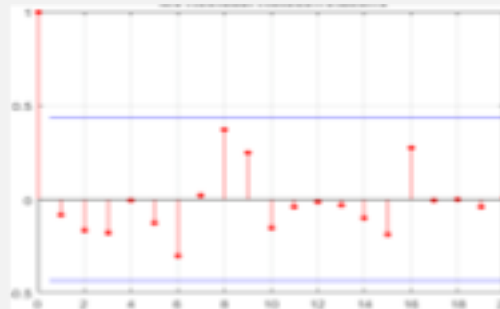
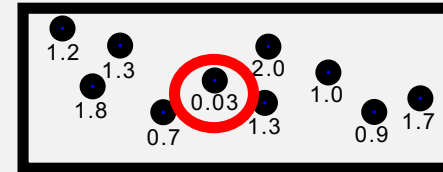
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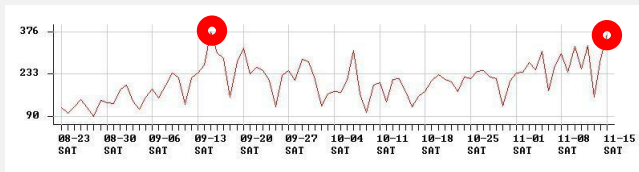
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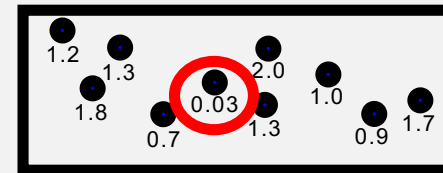
Time series analysis: the expected value for time step t is a function of the values for time steps 1 through $t - 1$.

Exponentially weighted averaging:

$$E[x_t] = (\sum w_i x_i) / (\sum w_i), w_i = e^{-(t-i)/b}$$

where $i = 1 \dots t - 1$.

Spatially distributed data



Spatial regression: the expected value for location s is a function of the values for all other locations.

Kernel regression, exponential kernel:

$$E[x_s] = (\sum w_i x_i) / (\sum w_i), w_i = e^{-d(s, i)/b}$$

where $i \neq s$ and d is Euclidean distance.

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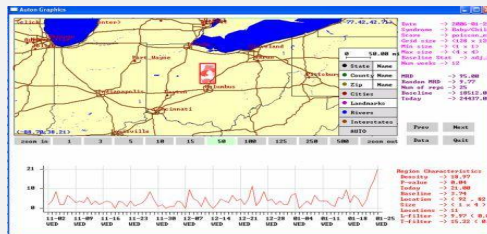
ANOMALOUS PATTERN DETECTION

Main goal of pattern detection: to **identify** and **characterize** relevant subsets of a massive dataset, i.e. groups of records that differ from the rest of the data in an interesting way.

Question 1: Are any relevant patterns present in the data, or is the entire dataset “normal”?

Example: outbreak detection

Are there any emerging outbreak on Twitter? If so, what type of outbreak, and what areas are affected?



Question 2: If there are any patterns, identify the pattern type and the affected subset of data records for each.

Example: financial analysis

Can we deduce the membership and structure of money laundering ring based on known links between suspected individuals?



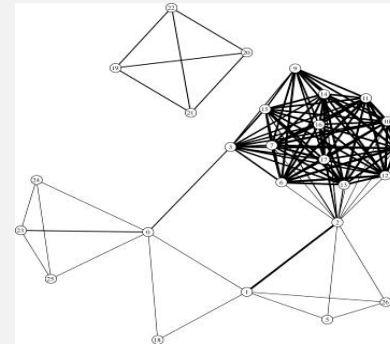
ANOMALOUS PATTERN DETECTION

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What makes a group of records “relevant”?

I. Matching some known pattern or structure.

Group detection: given a financial network, find highly connected sets of individuals.



Many efficient algorithms have been developed to find dense subgraphs or other structures in network data.

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What makes a group of records “relevant”?

1. Matching some known pattern or structure.
2. Multiple related records that are individually anomalous.

Fraud detection: look for individuals with a history of suspicious transactions.

Network intrusion detection: look for suspicious combinations of activities (e.g. port scanning).

In these domains, multiple “slightly anomalous” behaviors may together provide evidence of a major deviation from normal.

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What makes a group of records “relevant”?

1. Matching some known pattern or structure.
2. Multiple related records that are individually anomalous.
3. Higher (or lower) than expected number of records with some combination of attributes.
4. Change in data distribution as compared to the rest of the dataset.

Cluster detection: find spatial areas or periods of time with more records than expected.

Event detection: is the recent data differently distributed than the past?

Key concept: A group of records may be highly anomalous or interesting even if none of the individual records is itself anomalous.

SUBSET SCANNING

We can scan over subsets of the dataset in order to find those groups of records that correspond to a pattern.

Step 1: Compute **score** $F(S, P)$ for each subset $S = \{x_i\}$ and for each pattern type P , where higher score means more likely to be a pattern.

Step 2: Consider the highest scoring potential patterns (S, P) and decide whether each actually represents a pattern.

There are many options for computing the score of a subset S .

WHAT'S STRANGE ABOUT RECENT EVENTS?

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In the WSARE method (“What’s Strange About Recent Events”), we consider the subsets of the data defined by a one- or two-component rule R , and find rules where the current data is significantly different than the past.

For each rule, we create a 2x2 contingency table comparing current and past data:

	<u>Current</u>	<u>Past</u>
# records satisfying R	48	45
# records satisfying $\sim R$	86	220



Compute p-value using a statistical test (C^2 or Fisher’s Exact). Lower p-value = higher score.

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For example, using WSARE for hospital Emergency Department surveillance resulted in finding the following significant rule, corresponding to an outbreak of respiratory illness on 9/6/2000.

```
### Rule 3: Wed 09-06-2000 (daynum 36774, dayindex 131)
SCORE = -0.00000000 PVALUE = 0.00000000
17.16% ( 23/134) of today's cases have Prodrome = Respiratory
and age2 less than 40
4.53% ( 12/265) of other cases have Prodrome = Respiratory
and age2 less than 40
```

MODEL-BASED PATTERN DETECTION

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In the **model-based** anomalous pattern detection approach, we model the effects of each pattern type P on the affected subset of the data S .

Now we create tables comparing the numbers of anomalous and normal records:

	<u>Anomalous</u>	<u>Normal</u>
# records satisfying R	17	5
# records satisfying $\sim R$	93	400



Compute p-value using a statistical test (C^2 or Fisher's Exact). Lower p-value = higher score.

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Commonly we compute the **likelihood ratio statistic**

$$\Pr(\text{Data} \mid H_1(S, P)) / \Pr(\text{Data} \mid H_0) \text{ for each } (S, P).$$

In **event detection**, we model the null hypothesis H_0 by estimating expected counts for each data stream assuming no events.

Each pattern P is assumed to increase the counts for some data streams in the affected set of spatial locations S .

WHICH PATTERNS TO REPORT?

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Option 1: Report the k highest scoring subsets, ordered by score.

The disadvantage of this approach is that the user is not informed whether any of the discovered patterns are likely to be relevant.

However, this may be acceptable in monitoring systems or scientific discovery applications where the user is willing to evaluate a fixed number of potential patterns.

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Option 2: Perform hypothesis tests, and report all **significant** patterns (S, P) .

In the hypothesis testing framework, we must adjust for the fact that we're performing so many tests. Otherwise we will report too many false positives!

In model-based approaches, one way to do this is **randomization**: we generate a large number of simulated datasets assuming the null model, and compare the scores of the potential patterns in the real dataset to the highest scoring patterns in the simulated data.

An alternative is to adjust the p-value threshold for each test based on the number of tests performed (e.g. Bonferroni threshold = $.05 / \# \text{ tests}$)

References

- A coherent text on anomalous pattern detection has yet to be written, but many methods have been proposed and are becoming common:
 - WSARE: W.-K. Wong et al., “Rule-based anomaly pattern detection for detecting disease outbreaks,” *Proc. 18th Natl. Conf. on Artificial Intelligence*, 2002.
 - APD (“Anomaly Pattern Detection”). K. Das, J. Schneider, and D.B. Neill, *Proc. KDD 2008*.
 - D.B. Neill and W.-K. Wong, “A Tutorial on Event Detection,” presented at *KDD 2009* conference.
 - Edward McFowland III, Skyler Speakman, and Daniel B. Neill. Fast generalized subset scan for anomalous pattern detection. *Journal of Machine Learning Research*, 14: 1533-1561, 2013.
- Software for spatial cluster detection and for WSARE is available on the Auton Laboratory web page, <http://www.autonlab.org>.