This print-out should have 15 questions. Multiple-choice questions may continue on the next column or page – find all choices before answering.

MatrixVecProd03 001 10.0 points

Determine $\mathbf{u}\mathbf{v}^T$ when

$$\mathbf{u} = \begin{bmatrix} -2 \\ -3 \\ -4 \end{bmatrix}, \quad \mathbf{v} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}.$$

1.
$$\mathbf{u}\mathbf{v}^T = \begin{bmatrix} -2a & -3a & -4a \\ -2b & -3b & -4b \\ -2c & -3c & -4c \end{bmatrix}$$

2.
$$\mathbf{u}\mathbf{v}^T = -2a - 3b - 4c$$

3.
$$\mathbf{u}\mathbf{v}^T = \begin{bmatrix} -2a & -2b & -2c \\ -3a & -3b & -3c \\ -4a & -4b & -4c \end{bmatrix}$$
 correct

4.
$$\mathbf{u}\mathbf{v}^T = -4a - 3b - 2c$$

Explanation:

Since

$$\mathbf{v}^T = [a \ b \ c],$$

we see that

$$\mathbf{u}\mathbf{v}^{T} = \begin{bmatrix} -2 \\ -3 \\ -4 \end{bmatrix} \begin{bmatrix} a & b & c \end{bmatrix}$$
$$= \begin{bmatrix} -2a & -2b & -2c \\ -3a & -3b & -3c \\ -4a & -4b & -4c \end{bmatrix}.$$

Consequently,

$$\mathbf{u}\mathbf{v}^{T} = \begin{bmatrix} -2a & -2b & -2c \\ -3a & -3b & -3c \\ -4a & -4b & -4c \end{bmatrix}.$$

M340LInverseTF04 002 10.0 points

There are some matrices A, B, C with AB = AC, A invertible and $B \neq C$.

True or False?

- 1. TRUE
- 2. FALSE correct

Explanation:

For all matrices such that AB = AC and A invertible, it is always true that $A^{-1}AB = A^{-1}AC$. Since $A^{-1}A = I$ it follows that B = C.

Consequently, the statement is



MatrixAlg02aT/F 003 10.0 points

There exist invertible matrices A, B such that

$$(AB)^{-1} \neq A^{-1}B^{-1}$$
.

True or False?

- 1. FALSE
- 2. TRUE correct

Explanation:

Set

$$A = \begin{bmatrix} a & 1 \\ -1 & 0 \end{bmatrix}, B = \begin{bmatrix} 0 & -1 \\ 1 & b \end{bmatrix}.$$

Then

$$AB = \begin{bmatrix} 1 & b-a \\ 0 & 1 \end{bmatrix}$$

and

$$A^{-1} = \begin{bmatrix} 0 & -1 \\ 1 & a \end{bmatrix}, \quad B^{-1} = \begin{bmatrix} b & 1 \\ -1 & 0 \end{bmatrix}.$$

In this case,

$$(AB)^{-1} = \begin{bmatrix} 1 & a-b \\ 0 & 1 \end{bmatrix},$$

while

$$A^{-1}B^{-1} = \begin{bmatrix} 1 & 0 \\ b - a & 1 \end{bmatrix},$$

so $(AB)^{-1} \neq A^{-1}B^{-1}$ when $a \neq b$.

Consequently, the statement is

InvertibleTF02a 004 10.0 points

If A and D are $n \times n$ matrices such that AD = I, then DA = I

True or False?

1. TRUE correct

2. FALSE

Explanation:

Because A and D are square matrices and AD = I, then A and D are both invertible, with $D = A^{-1}$ and $A = D^{-1}$. So using this substitution, the first equation can be rewritten as $AA^{-1} = I$, and the second as $DD^{-1} = I$. Both of these statements are true by the definition of inverse matrices.

Consequently, the statement is

LUDecomp3x4a 005 10.0 points

Determine the Lower Triangular Matrix L in an LU-decomposition of the matrix

$$A = \begin{bmatrix} -4 & -2 & 5 & -3 \\ 20 & 13 & -24 & 16 \\ 16 & 11 & -19 & 8 \end{bmatrix}.$$

$$\mathbf{1.} \ L = \begin{bmatrix} 1 & -5 & -4 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\mathbf{2.} \ L = \begin{bmatrix} 1 & 0 & 0 \\ 5 & 1 & 0 \\ 4 & -1 & 1 \end{bmatrix}$$

$$\mathbf{3.} \ L = \begin{bmatrix} 1 & -2 & 5 \\ 0 & 1 & -24 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\mathbf{4.} \ L = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 5 & 1 & 1 \end{bmatrix}$$

5.
$$L = \begin{bmatrix} 1 & 0 & 0 \\ -5 & 1 & 0 \\ -4 & 1 & 1 \end{bmatrix}$$
 correct

6.
$$L = \begin{bmatrix} -4 & -2 & -3 \\ 0 & 3 & 1 \\ 0 & 0 & -5 \end{bmatrix}$$

Explanation:

We first determine the elementary matrices reducing A to an echelon form U by row reductions downwards.

Set

$$E_1 = \begin{bmatrix} 1 & 0 & 0 \\ 5 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

so that

$$E_1 A = \begin{bmatrix} 1 & 0 & 0 \\ 5 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -4 & -2 & 5 & -3 \\ 20 & 13 & -24 & 16 \\ 16 & 11 & -19 & 8 \end{bmatrix}$$
$$= \begin{bmatrix} -4 & -2 & 5 & -3 \\ 0 & 3 & 1 & 1 \\ 16 & 11 & -19 & 8 \end{bmatrix} = A_1,$$

say. Next set

$$E_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 4 & 0 & 1 \end{bmatrix}$$

so that

$$E_2 A_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 4 & 0 & 1 \end{bmatrix} \begin{bmatrix} -4 & -2 & 5 & -3 \\ 0 & 3 & 1 & 1 \\ 16 & 11 & -19 & 8 \end{bmatrix}$$
$$= \begin{bmatrix} -4 & -2 & 5 & -3 \\ 0 & 3 & 1 & 1 \\ 0 & 3 & 1 & -4 \end{bmatrix} = A_2,$$

say. Finally, set

$$E_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}$$

so that the product

$$E_3 A_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} -4 & -2 & 5 & -3 \\ 0 & 3 & 1 & 1 \\ 0 & 3 & 1 & -4 \end{bmatrix}$$
$$= \begin{bmatrix} -4 & -2 & 5 & -3 \\ 0 & 3 & 1 & 1 \\ 0 & 0 & 0 & -5 \end{bmatrix} = U,$$

and

$$E_3E_2E_1A = E_3E_2A_1 = E_3A_2 = U$$

is an echelon form of A. But every elementary matrix is invertible. Thus A = LU, setting

$$L = E_1^{-1} E_2^{-1} E_3^{-1}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ -5 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -4 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ -5 & 1 & 0 \\ -4 & 1 & 1 \end{bmatrix}.$$

Consequently,

$$L = \begin{bmatrix} 1 & 0 & 0 \\ -5 & 1 & 0 \\ -4 & 1 & 1 \end{bmatrix}$$

Subspace05a 006 10.0 points

Let H be the set of all vectors

$$\begin{bmatrix} a - 2b \\ ab + 3a \\ b \end{bmatrix}$$

where a and b are real. Determine if H is a subspace of \mathbb{R}^3 , and then check the correct answer below.

- 1. H is not a subspace of \mathbb{R}^3 because it is not closed under vector addition. **correct**
- **2.** *H* is not a subspace of \mathbb{R}^3 because it does not contain **0**.

- **3.** *H* is a subspace of \mathbb{R}^3 because it can be written as $Span\{\mathbf{v}_1, \mathbf{v}_2\}$ with $\mathbf{v}_1, \mathbf{v}_2$ in \mathbb{R}^3 .
- **4.** *H* is a subspace of \mathbb{R}^3 because it can be written as Nul(A) for some matrix A.

Explanation:

To check if the set H of all vectors

$$\begin{bmatrix} a - 2b \\ ab + 3a \\ b \end{bmatrix}$$

is a subspace of \mathbb{R}^3 we check the properties defining a subspace:

1. the zero vector **0** is in H: set a = b = 0. Then

$$\begin{bmatrix} 0 - 0 \\ 0 + 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix},$$

so H contains $\mathbf{0}$.

2. for each \mathbf{u} , \mathbf{v} in H the sum $\mathbf{u} + \mathbf{v}$ is in H: set

$$\mathbf{v}_1 = \begin{bmatrix} a_1 - 2b_1 \\ a_1b_1 + 3a_1 \\ b_1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} a_2 - 2b_2 \\ a_2b_2 + 3a_2 \\ b_2 \end{bmatrix},$$

in H. Then

$$\mathbf{v}_1 + \mathbf{v}_2 = \begin{bmatrix} a_1 - 2b_1 \\ a_1b_1 + 3a_1 \\ b_1 \end{bmatrix} + \begin{bmatrix} a_2 - 2b_2 \\ a_2b_2 + 3a_2 \\ b_2 \end{bmatrix}$$
$$= \begin{bmatrix} (a_1 + a_2) - 2(b_1 + b_2) \\ a_1b_1 + a_2b_2 + 3(a_1 + a_2) \\ (b_1 + b_2) \end{bmatrix}.$$

But in general,

$$a_1b_1 + a_2b_2 \neq (a_1 + a_2)(b_1 + b_2),$$

in which case $\mathbf{u} + \mathbf{v}$ is not in H.

Consequently, H is not a subspace of \mathbb{R}^3 because it is

not closed under vector addition

DimRankTF02a 007 10.0 points

If \mathcal{B} is a basis for a subspace H, then each vector in H can be written in only one way as a linear combination of the vectors in \mathcal{B} .

True or False?

- 1. FALSE
- 2. TRUE correct

Explanation:

If H is a p-dimensional subspace of \mathbb{R}^n , then \mathcal{B} must be a set of p elements $\{\mathbf{v}_1, \mathbf{v}_2, \ldots, \mathbf{v}_p\}$. To represent any vector \mathbf{b} in H is to find the coefficients c_j in the linear combination

$$\mathbf{b} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \ldots + c_p \mathbf{v}_p$$

of vectors in \mathcal{B} whose sum is **b**. This is equivalent to solving a system of equations with p equations and p unknowns. Because the vectors are linearly independent by the definition of a basis, this means there can only be one solution.

Consequently, the statement is

TRUE

DetElemOps02TF 008 10.0 points

When the matrix

$$B = \begin{bmatrix} a & b \\ c + ka & d + kb \end{bmatrix}$$

is obtained from

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

by adding k times row 1 to row 2, then

$$\det[B] = \det[A].$$

True or False?

- 1. TRUE correct
- 2. FALSE

Explanation:

As 2×2 matrices,

$$det[B] = \begin{vmatrix} a & b \\ c + ka & d + kb \end{vmatrix}$$
$$= a(d+kb) - b(c+ka) = ad - bc,$$

while

$$\det[A] = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc.$$

Thus

$$det[B] = det[A]$$
.

Consequently, the statement is

DetInverseT/F01b 009 10.0 points

The matrix

$$A = \begin{bmatrix} 5 & 0 & -1 \\ 1 & -3 & -2 \\ 0 & 5 & 3 \end{bmatrix}$$

is invertible.

True or False?

- 1. FALSE correct
- 2. TRUE

Explanation:

The matrix A will be invertible if and only if $det(A) \neq 0$. Now

$$\det(A) = \begin{vmatrix} 5 & 0 & -1 \\ 1 & -3 & -2 \\ 0 & 5 & 3 \end{vmatrix}$$
$$= 5 \begin{vmatrix} -3 & -2 \\ 5 & 3 \end{vmatrix} - \begin{vmatrix} 1 & -3 \\ 0 & 5 \end{vmatrix}$$
$$= 5 \times 1 - 1 \times 5 = 0.$$

Consequently, the statement is

$egin{array}{ll} VectorSpace 01aT/F \ 010 & 10.0 \ points \end{array}$

The subset

$$V = \left\{ \begin{bmatrix} a \\ b \end{bmatrix} : ab \ge 0 \right\}$$

of \mathbb{R}^2 is closed under scalar multiplication.

True or False?

- 1. FALSE
- 2. TRUE correct

Explanation:

For each scalar k,

$$k \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} ka \\ kb \end{bmatrix}.$$

Now $(ka)(kb) = k^2(ab)$, so

$$ab \ge 0 \implies (ka)(kb) = k^2ab \ge 0$$

because $k^2 > 0$ for all k.

Consequently, the statement is

BasisNull02b 011 10.0 points

Find a basis for the Null space of the matrix $\,$

$$A = \begin{bmatrix} 2 & -6 & -4 & 4 \\ 1 & -3 & -5 & 8 \\ -2 & 6 & 5 & -6 \end{bmatrix}.$$

$$\mathbf{1.} \left\{ \begin{bmatrix} -3\\1\\0\\0 \end{bmatrix}, \begin{bmatrix} -2\\0\\-2\\1 \end{bmatrix} \right\}$$

$$\mathbf{2.} \left\{ \begin{bmatrix} -2\\0\\-2\\1 \end{bmatrix} \right\}$$

3.
$$\left\{ \begin{bmatrix} 3\\1\\0\\0 \end{bmatrix}, \begin{bmatrix} 2\\0\\2\\1 \end{bmatrix} \right\}$$
 correct

$$4. \left\{ \begin{bmatrix} 3\\1\\0\\0 \end{bmatrix}, \begin{bmatrix} -2\\0\\-2\\1 \end{bmatrix} \right\}$$

5.
$$\left\{ \begin{bmatrix} 2 \\ 0 \\ -2 \\ 1 \end{bmatrix} \right\}$$

6.
$$\left\{ \begin{bmatrix} -3\\1\\0\\0 \end{bmatrix} \right\}$$

Explanation:

We first row reduce $[A \ \mathbf{0}]$:

$$\operatorname{rref}([A \ \mathbf{0}]) = \begin{bmatrix} 1 & -3 & 0 & -2 & 0 \\ 0 & 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

to identify the free variables for \mathbf{x} in the homogeneous equation $A\mathbf{x} = \mathbf{0}$.

Thus x_1 and x_3 are basic variables, while x_2 and x_4 are free variables. So set $x_2 = s$ and $x_4 = t$. Then

$$x_1 = 3s + 2t, \quad x_3 = 2t,$$

and

$$\operatorname{Nul}(A) = \operatorname{Span} \left\{ \begin{bmatrix} 3 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 2 \\ 1 \end{bmatrix} \right\}.$$

Consequently,

$$\mathcal{B} = \left\{ \begin{bmatrix} 3\\1\\0\\0 \end{bmatrix}, \begin{bmatrix} 2\\0\\2\\1 \end{bmatrix} \right\}$$

is a basis for Nul(A).

LinIndSetsTF02e 012 10.0 points

If B is an echelon form of a matrix A, then the pivot columns of B form a basis for Col A.

True or False?

1. TRUE

2. FALSE correct

Explanation:

The pivot columns of A are the same as the pivot columns for B, and the pivot columns of A form a basis for Col(A). But row operations on a matrix can change the entries in a column, so the columns of B need not be in the column space of A. Thus the pivot columns of B need not form a basis for Col(A).

Consequently, the statement is

CoordVec01b 013 10.0 points

Find the coordinate vector $[\mathbf{x}]_{\mathcal{B}}$ in \mathbb{R}^2 for the vector

$$\mathbf{x} = \begin{bmatrix} 4 \\ 0 \end{bmatrix}$$

with respect to the basis

$$\mathcal{B} = \left\{ \begin{bmatrix} 1 \\ -2 \end{bmatrix}, \begin{bmatrix} 5 \\ -6 \end{bmatrix} \right\}$$

for \mathbb{R}^2 .

1.
$$[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} 2 \\ -6 \end{bmatrix}$$

$$\mathbf{2.} \ [\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} -6 \\ -2 \end{bmatrix}$$

3.
$$[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} 6 \\ 2 \end{bmatrix}$$

4.
$$[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} -6\\2 \end{bmatrix}$$
 correct

5.
$$[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} 2 \\ 6 \end{bmatrix}$$

6.
$$[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} -2 \\ -6 \end{bmatrix}$$

Explanation:

The coordinate vector $[\mathbf{x}]_{\mathcal{B}}$ of a vector \mathbf{x} in \mathbb{R}^2 with respect to a basis

$$\mathcal{B} = \{\mathbf{b}_1, \, \mathbf{b}_2\}$$

for \mathbb{R}^2 satisfies the matrix equation

$$A[\mathbf{x}]_{\mathcal{B}} = \mathbf{x}, \qquad A = \begin{bmatrix} \mathbf{b}_1 & \mathbf{b}_2 \end{bmatrix}.$$

Consequently, when

$$\mathcal{B} = \left\{ \begin{bmatrix} 1 \\ -2 \end{bmatrix}, \begin{bmatrix} 5 \\ -6 \end{bmatrix} \right\},\,$$

and

$$\mathbf{x} = \begin{bmatrix} 4 \\ 0 \end{bmatrix},$$

the associated augmented matrix is

$$\begin{bmatrix} A & \mathbf{x} \end{bmatrix} = \begin{bmatrix} 1 & 5 & 4 \\ -2 & -6 & 0 \end{bmatrix}.$$

But then

$$\operatorname{rref}[A \ \mathbf{x}] = \begin{bmatrix} 1 & 0 & -6 \\ 0 & 1 & 2 \end{bmatrix}.$$

Thus

$$[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} -6\\2 \end{bmatrix}$$
.

DimSubspace01b 014 10.0 points

Determine the dimension of the subspace

$$\operatorname{Span}\left\{ \begin{bmatrix} 1\\0\\2 \end{bmatrix}, \begin{bmatrix} 3\\1\\1 \end{bmatrix}, \begin{bmatrix} 9\\4\\-2 \end{bmatrix}, \begin{bmatrix} -7\\-3\\1 \end{bmatrix} \right\}$$

of \mathbb{R}^3 .

1.
$$\dim = 1$$

2. dim =
$$5$$

- **3.** $\dim = 4$
- 4. $\dim = 2 \text{ correct}$
- **5.** dim = 3

Explanation:

Since the subspace is the column space of the matrix

$$A = \begin{bmatrix} 1 & 3 & 9 & -7 \\ 0 & 1 & 4 & -3 \\ 2 & 1 & -2 & 1 \end{bmatrix}.$$

its dimension is the number of pivot columns in A. Now

$$\operatorname{rref}(A) = \begin{bmatrix} 1 & 0 & -3 & 2 \\ 0 & 1 & 4 & -3 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

Thus A has 2 pivot columns, so

dimension
$$= 2$$
.

RankTF06c 015 10.0 points

The dimensions of the row space and column space of an $m \times n$ matrix A are the same, even if $m \neq n$.

True or False?

- 1. FALSE
- 2. TRUE correct

Explanation:

Recall that the rank A is the number of pivot columns in A. Equivalently, rank A is the number of pivot positions in an echelon form B of A. Furthermore, since B has a nonzero row for each pivot, and since these rows form a basis for the row space of A, rank A is also the dimension of the row space.

Consequently, the statement is

TRUE .