

This print-out should have 15 questions. Multiple-choice questions may continue on the next column or page – find all choices before answering.

MatrixOpsTF01b
001 10.0 points

When

$$A = [\mathbf{a}_1 \ \mathbf{a}_2 \ \dots \ \mathbf{a}_n]$$

and B are matrices such that the product AB is defined, then

$$AB = [B\mathbf{a}_1 \ B\mathbf{a}_2 \ \dots \ B\mathbf{a}_n].$$

True or False?

1. FALSE **correct**

2. TRUE

Explanation:

The matrix

$$[B\mathbf{a}_1 \ B\mathbf{a}_2 \ \dots \ B\mathbf{a}_n]$$

is the product BA , *not* AB , and $AB \neq BA$ in general.

Consequently, the statement is

FALSE

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InverseProp01a
002 10.0 points

Which of the following shows that if A is an invertible $n \times n$ matrix and B is any $n \times n$ matrix such that $BA = I$, then $B = A^{-1}$.

1. Right-multiply each side of the equation $I = BA$ by A^{-1} . Then

$$A^{-1} = BAA^{-1} = BI = B,$$

so $B = A^{-1}$. **correct**

2. Add A^{-1} to both sides of the equation $I = BA$. Then

$$I + A^{-1} = BA + A^{-1},$$

so $A^{-1} = BI = B$.

3. Left-multiply each side of the equation $I = BA$ by A^{-1} . Then

$$A^{-1} = A^{-1}BA = BI = B,$$

so $B = A^{-1}$.

4. Subtract A^{-1} from both sides of the equation $I = BA$. Then

$$I - A^{-1} = BA - A^{-1},$$

so $A^{-1} = BI = B$.

Explanation:

By definition, an $n \times n$ matrix A is invertible if there exists an $n \times n$ matrix C such that $AC = I = CA$ where I is the $n \times n$ identity matrix; we usually write A^{-1} for this matrix C .

So if B is any $n \times n$ matrix such that $BA = I$, then after multiplying the equation $I = BA$ on the right by A^{-1} we see that

$$A^{-1} = (BA)A^{-1} = B(AA^{-1}) = BI = B$$

because of the associativity of matrix multiplication and the fact that I is the identity matrix.

InverseTF02a
003 10.0 points

If A is an $n \times n$ invertible matrix, then the same sequence of elementary row operations that row reduces A to the identity I_n also reduces A^{-1} to I_n .

True or False?

1. FALSE **correct**

2. TRUE

Explanation:

If an $n \times n$ matrix A is invertible, then there exist elementary matrices E_1, E_2, \dots, E_p such that

$$E_p E_{p-1} \dots E_2 E_1 A = I_n.$$

Now every elementary matrix is invertible, so

$$\begin{aligned} A &= E_1^{-1} E_2^{-1} \dots E_{p-1}^{-1} E_p^{-1} I_n \\ &= E_1^{-1} E_2^{-1} \dots E_{p-1}^{-1} E_p^{-1}. \end{aligned}$$

But then

$$A^{-1} = E_p E_{p-1} \dots E_2 E_1,$$

so

$$E_1^{-1} E_2^{-1} \dots E_{p-1}^{-1} E_p^{-1} A^{-1} = I_n.$$

Thus A^{-1} can be row reduced to I_n by the same elementary row operations as used to row reduce A to I_n , but we need to use their inverses and to apply them in the reverse order.

Consequently, the statement is

FALSE

Invertible01
004 10.0 points

A is an $n \times n$ matrix. Which of the following statements are equivalent to A being invertible?

- (i) A^T is an invertible matrix.
- (ii) The columns of A do not span \mathbb{R}^n .
- (iii) A is row equivalent to the $n \times n$ identity matrix.

1. None of these.

2. ii and iii

3. iii

4. i and iii **correct**

5. ii

6. i and ii

Explanation:

(i) Because A is an invertible matrix, then so is A^T , and the inverse of A^T is the transpose of A^{-1} . Mathematically, we can see that $I = I^T = (AA^{-1})^T = (A^{-1})^T A^T$. Hence because A is invertible, A^T must be invertible to satisfy this equation.

(ii) Since the equation $A\mathbf{x} = \mathbf{b}$ has at least one solution for each \mathbf{b} in \mathbb{R}^n , then by definition the columns of A span \mathbb{R}^n .

(iii) Since A is invertible, A has n pivot positions. With n pivot positions, the pivots must lie on the main diagonal, in which case the reduced echelon form of A is I_n .

LUDecomp2x3b

005 10.0 points

Determine the Lower Triangular matrix L in an LU -Decomposition of

$$A = \begin{bmatrix} -4 & 0 & 3 \\ -8 & 0 & 11 \end{bmatrix}.$$

1. $L = \begin{bmatrix} -4 & 0 \\ 2 & 5 \end{bmatrix}$

2. $L = \begin{bmatrix} -4 & 0 \\ 8 & 5 \end{bmatrix}$

3. $L = \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix}$

4. $L = \begin{bmatrix} -4 & 0 \\ -2 & 5 \end{bmatrix}$

5. $L = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix}$ **correct**

6. $L = \begin{bmatrix} -4 & 0 \\ -8 & 5 \end{bmatrix}$

Explanation:

We first determine the elementary matrix reducing A to echelon form U by row reduc-

tions *downwards*.

$$\begin{aligned} A &\sim E_1 A \\ &= \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} -4 & 0 & 3 \\ -8 & 0 & 11 \end{bmatrix} \\ &= \begin{bmatrix} -4 & 0 & 3 \\ 0 & 0 & 5 \end{bmatrix} = U. \end{aligned}$$

But an elementary matrix is always invertible.
Thus

$$L = E_1^{-1} = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix}.$$

Consequently,

$$\boxed{\begin{aligned} L &= \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix} \\ U &= \begin{bmatrix} -4 & 0 & 3 \\ 0 & 0 & 5 \end{bmatrix} \end{aligned}}.$$

NullSpace01a
006 10.0 points

Find a matrix A so that $\text{Nul}(A)$ is the set of all vectors

$$H = \left\{ \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} : \begin{aligned} a + 3b &= 2c, \\ 4a &= c - d, \end{aligned} \right\}$$

in \mathbb{R}^4 .

1. $A = \begin{bmatrix} 1 & 3 & -2 & 0 \\ 4 & 0 & -1 & 1 \end{bmatrix}$ **correct**

2. $A = \begin{bmatrix} 1 & -3 & 2 & 0 \\ 4 & 0 & -1 & 1 \end{bmatrix}$

3. $A = \begin{bmatrix} 1 & -3 & 2 & 0 \\ 4 & 0 & 1 & -1 \end{bmatrix}$

4. $A = \begin{bmatrix} 1 & -3 & -2 & 0 \\ 4 & 0 & 1 & -1 \end{bmatrix}$

5. $A = \begin{bmatrix} 1 & 3 & -2 & 0 \\ 4 & 0 & -1 & -1 \end{bmatrix}$

6. $A = \begin{bmatrix} 1 & 3 & 2 & 0 \\ 4 & 0 & 1 & -1 \end{bmatrix}$

Explanation:

Rewrite the conditions

$$a + 3b = 2c, \quad 4a = c - d$$

as

$$a + 3b - 2c = 0,$$

$$4a - c + d = 0,$$

and set

$$A = \begin{bmatrix} 1 & 3 & -2 & 0 \\ 4 & 0 & -1 & 1 \end{bmatrix}.$$

Then

$$\begin{aligned} A \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} &= \begin{bmatrix} 1 & 3 & -2 & 0 \\ 4 & 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} \\ &= \begin{bmatrix} a + 3b - 2c \\ 4a - c - d \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \end{aligned}$$

if and only if

$$a + 3b - 2c = 0,$$

$$4a - c + d = 0.$$

Consequently,

$$\boxed{\text{Nul}(A) = H}.$$

Rank02b
007 10.0 points

Determine the rank of the matrix

$$A = \begin{bmatrix} 1 & 2 & -2 \\ -3 & -5 & 7 \\ 1 & 5 & 1 \end{bmatrix}.$$

1. $\text{rank}(A) = 2$ **correct**

2. $\text{rank}(A) = 5$

3. $\text{rank}(A) = 4$

4. $\text{rank}(A) = 1$

5. $\text{rank}(A) = 3$

Explanation:

Since

$$\text{rref}(A) = \begin{bmatrix} 1 & 0 & -4 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix},$$

the first two rows of $\text{rref}(A)$ contain leading 1's, so

$$\boxed{\text{Rank}(A) = 2}.$$

DetElemOps01TF

008 10.0 points

When the matrix

$$B = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

is obtained from

$$A = \begin{bmatrix} c & d \\ a & b \end{bmatrix}$$

by interchanging rows, then

$$\det[B] = \det[A].$$

True or False?

1. FALSE correct

2. TRUE

Explanation:

As 2×2 matrices,

$$\det[B] = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc,$$

while

$$\det[A] = \begin{vmatrix} c & d \\ a & b \end{vmatrix} = bc - ad.$$

Thus

$$\det[B] = -\det[A].$$

Consequently, the statement is

$$\boxed{\text{FALSE}}.$$

DetInverseT/F01a

009 10.0 points

The matrix

$$A = \begin{bmatrix} 2 & 1 & 3 \\ 0 & 4 & -4 \\ 1 & 0 & 2 \end{bmatrix}$$

is invertible.

True or False?

1. TRUE

2. FALSE correct

Explanation:

The matrix A will be invertible if and only if $\det(A) \neq 0$. Now

$$\begin{aligned} \det(A) &= \begin{vmatrix} 2 & 1 & 3 \\ 0 & 4 & -4 \\ 1 & 0 & 2 \end{vmatrix} \\ &= 2 \begin{vmatrix} 4 & -4 \\ 0 & 2 \end{vmatrix} - \begin{vmatrix} 0 & -4 \\ 1 & 2 \end{vmatrix} + 3 \begin{vmatrix} 0 & 4 \\ 1 & 0 \end{vmatrix} \\ &= 2 \times 8 - 4 - 3 \times 4 = 0. \end{aligned}$$

Consequently, the statement is

$$\boxed{\text{FALSE}}.$$

SubspaceTF01

010 10.0 points

Let H be the set of points inside and on the unit circle in the xy -plane. That is, let

$$H = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} : x^2 + y^2 \leq 1 \right\}.$$

H is a subspace of \mathbb{R}^2 . True or false?

1. FALSE correct

2. TRUE

Explanation:

If $\mathbf{u} = \begin{bmatrix} .5 \\ .5 \end{bmatrix}$ and $c = 4$, then \mathbf{u} is in H but $c\mathbf{u}$ is not in H . Since H is not closed under

scalar multiplication, H is not a subspace of \mathbb{R}^2 . Consequently, the statement is

FALSE

BasisNull02a

011 10.0 points

Find a basis for the Null space of the matrix

$$A = \begin{bmatrix} 3 & 6 & 24 & -12 \\ -3 & -7 & -27 & 13 \\ 1 & -1 & -1 & -1 \end{bmatrix}.$$

1. $\left\{ \begin{bmatrix} -2 \\ -3 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 0 \\ 1 \end{bmatrix} \right\}$ **correct**

2. $\left\{ \begin{bmatrix} -2 \\ -1 \\ 0 \\ 1 \end{bmatrix} \right\}$

3. $\left\{ \begin{bmatrix} 2 \\ 3 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ -1 \\ 0 \\ 1 \end{bmatrix} \right\}$

4. $\left\{ \begin{bmatrix} -2 \\ -3 \\ 1 \\ 0 \end{bmatrix} \right\}$

5. $\left\{ \begin{bmatrix} -2 \\ 3 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ -1 \\ 0 \\ 1 \end{bmatrix} \right\}$

6. $\left\{ \begin{bmatrix} 2 \\ -1 \\ 0 \\ 1 \end{bmatrix} \right\}$

Explanation:

We first row reduce $[A \ 0]$:

$$\text{rref}([A \ 0]) = \begin{bmatrix} 1 & 0 & 2 & -2 & 0 \\ 0 & 1 & 3 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

to identify the free variables for \mathbf{x} in the homogeneous equation $A\mathbf{x} = \mathbf{0}$.

This shows that x_1, x_2 are basic variables, while x_3, x_4 are free variables. So set $x_3 = s, x_4 = t$. Then

$$x_1 = -2s + 2t, \quad x_2 = -3s + t,$$

and

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -2s + 2t \\ -3s + t \\ s \\ t \end{bmatrix} = s \begin{bmatrix} -2 \\ -3 \\ s \\ 0 \end{bmatrix} + t \begin{bmatrix} 2 \\ 1 \\ 0 \\ 1 \end{bmatrix}.$$

Thus

$$\text{Nul}(A) = \text{Span} \left\{ \begin{bmatrix} -2 \\ -3 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

Consequently,

$$\mathcal{B} = \left\{ \begin{bmatrix} -2 \\ -3 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 0 \\ 1 \end{bmatrix} \right\}$$

is a basis for $\text{Nul}(A)$.

LinIndSetsTF01b

012 10.0 points

When $\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_p$ are vectors in \mathbb{R}^n and

$$H = \text{Span}\{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_p\},$$

then $\{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_p\}$ is a basis for H .

True or False?

1. TRUE

2. FALSE **correct**

Explanation:

For the set $\{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_p\}$ to be a basis for H , BOTH of the conditions

(i) $H = \text{Span}\{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_p\}$,

(ii) *the set is linearly independent*,

have to be satisfied. Consequently, the statement is

FALSE

CoordVec01a
013 10.0 points

Find the vector \mathbf{x} in \mathbb{R}^2 having coordinate vector

$$[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} 8 \\ -5 \end{bmatrix}$$

with respect to the basis

$$\mathcal{B} = \left\{ \begin{bmatrix} 4 \\ 5 \end{bmatrix}, \begin{bmatrix} 6 \\ 7 \end{bmatrix} \right\}$$

for \mathbb{R}^2 .

1. $\mathbf{x} = \begin{bmatrix} 2 \\ 5 \end{bmatrix}$ **correct**

2. $\mathbf{x} = \begin{bmatrix} -2 \\ -5 \end{bmatrix}$

3. $\mathbf{x} = \begin{bmatrix} 5 \\ 2 \end{bmatrix}$

4. no such \mathbf{x} exists

5. $\mathbf{x} = \begin{bmatrix} -5 \\ -2 \end{bmatrix}$

Explanation:

The coordinate vector $[\mathbf{x}]_{\mathcal{B}}$ of a vector \mathbf{x} in \mathbb{R}^2 with respect to a basis

$$\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}$$

for \mathbb{R}^2 satisfies the matrix equation

$$A[\mathbf{x}]_{\mathcal{B}} = \mathbf{x}, \quad A = [\mathbf{b}_1 \quad \mathbf{b}_2].$$

Consequently, when

$$\mathcal{B} = \left\{ \begin{bmatrix} 4 \\ 5 \end{bmatrix}, \begin{bmatrix} 6 \\ 7 \end{bmatrix} \right\}, \quad [\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} 8 \\ -5 \end{bmatrix},$$

$$\mathbf{x} = \begin{bmatrix} 4 & 6 \\ 5 & 7 \end{bmatrix} \begin{bmatrix} 8 \\ -5 \end{bmatrix} = \begin{bmatrix} 2 \\ 5 \end{bmatrix}.$$

DimSubspace01a
014 10.0 points

Determine the dimension of the subspace

$$\text{Span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 9 \\ 4 \\ -2 \end{bmatrix}, \begin{bmatrix} -7 \\ -3 \\ 1 \end{bmatrix} \right\}$$

of \mathbb{R}^3 .

1. $\dim = 5$

2. $\dim = 2$ **correct**

3. $\dim = 3$

4. $\dim = 4$

5. $\dim = 1$

Explanation:

Since the subspace is the column space of the matrix

$$A = \begin{bmatrix} 1 & 3 & 9 & -7 \\ 0 & 1 & 4 & -3 \\ 2 & 1 & -2 & 1 \end{bmatrix}.$$

its dimension is the number of pivot columns in A . Now

$$\text{rref}(A) = \begin{bmatrix} 1 & 0 & -3 & 2 \\ 0 & 1 & 4 & -3 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

Thus A has 2 pivot columns, so

$$\text{dimension} = 2.$$

RankTF06b
015 10.0 points

If B is an echelon form of an $m \times n$ matrix A , and if B has three nonzero rows, then the first three row of A form a basis for $\text{Row}(A)$.

True or False?

1. FALSE **correct**

2. TRUE

Explanation:

Although row operations cannot change the linear dependence relations among *columns* of

a matrix, they can change the linear dependence among *rows* of a matrix. For example, when

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix},$$

and

$$B = \text{rref}(A) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix},$$

then $\text{Row}(A) = \mathbb{R}^3$. But the first 3 rows of A do not form a basis for \mathbb{R}^3 . Notice that B is obtained from A by the row operation of interchanging rows 3 and 4 of A .

Consequently, the answer is

FALSE

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