1 Equations Needed

To obtain the bousiness approximation we will need the 3-D Navier-Stokes Equations

$$\frac{\delta w}{\delta t} + w \cdot \nabla \vec{w} = -\frac{1}{\rho} \frac{\delta P}{\delta z} - g_z + \nu \nabla^2 w \tag{1}$$

$$\frac{\delta v}{\delta t} + v \cdot \nabla \vec{v} = -\frac{1}{\rho} \frac{\delta P}{\delta y} + \nu \nabla^2 v \tag{2}$$

$$\frac{\delta u}{\delta t} + u \cdot \nabla \vec{u} = -\frac{1}{\rho} \frac{\delta P}{\delta x} + \nu \nabla^2 u \tag{3}$$

$$P = \rho RT \tag{4}$$

$$\theta = T \left(\frac{P_s}{P}\right)^{\frac{R}{C_p}} = T \left(\frac{P_s}{P}\right)^{\kappa} \tag{5}$$

$$\frac{\delta\rho}{\delta t} + \nabla \cdot \rho \vec{v} = 0 \tag{6}$$

2 Decomposition

Assume that the velocity, pressure, temperature, and density are composed of a long term mean and a perturbation from the mean. Additionally, the vertical velocity mean on a synoptic scale is very close to zero. Meaning

$$\zeta = \zeta_o + \zeta'(x, y, z, t) \tag{7}$$

3 Equation of state

Start by applying equation 7 to the density, pressure, and temperature terms of the equation of state (equation 4)

$$P_{o} + P' = (\rho_{o} + \rho')R(T_{o} + T')$$

$$= R(\rho_{o}T_{o} + \rho_{o}T' + \rho'T_{o} + \rho'T')$$
(8)

Now take the mean of equation 8

$$\overline{P_o + P'} = \overline{R(\rho_o T_o + \rho_o T' + \rho' T_o + \rho' T')}$$

$$\overline{P_o} + \overline{P'} = R(\overline{\rho_o T_o} + \overline{\rho_o T'} + \overline{\rho' T_o} + \overline{\rho' T'})$$

$$P_o = R(\rho_o T_o + \overline{\rho' T'})$$
(9)

With this in mind divide equation 8 through by P_o and sub in equation 9

$$P_{o} + P' = R \left(\rho_{o} T_{o} + \rho_{o} T' + \rho' T_{o} + \rho' T' \right)$$

$$1 + \frac{P'}{P_{o}} = \frac{R \left(\rho_{o} T_{o} + \rho_{o} T' + \rho' T_{o} + \rho' T' \right)}{P_{o}}$$

$$= \frac{R \left(\rho_{o} T_{o} + \rho_{o} T' + \rho' T_{o} + \rho' T' \right)}{R \left(\rho_{o} T_{o} + \overline{\rho'} T' \right)}$$

$$= \frac{\rho_{o} T_{o}}{\left(\rho_{o} T_{o} + \overline{\rho'} T' \right)} + \frac{\rho_{o} T'}{\left(\rho_{o} T_{o} + \overline{\rho'} T' \right)} + \frac{\rho' T_{o}}{\left(\rho_{o} T_{o} + \overline{\rho'} T' \right)} + \frac{\rho' T'}{\left(\rho_{o} T_{o} + \overline{\rho'} T' \right)}$$

$$= \frac{1}{\left(1 + \frac{\overline{\rho'} T'}{\rho_{o} T_{o}} \right)} + \frac{T'}{\left(T_{o} + \frac{\overline{\rho'} T'}{\rho_{o}} \right)} + \frac{\rho'}{\left(\rho_{o} + \overline{\rho'} T' \right)} + \frac{\rho' T'}{\left(\rho_{o} T_{o} + \overline{\rho'} T' \right)}$$
(10)

If we assume that the covariance of the perturbations is much less than the product of the two mean terms (i.e. $\overline{\rho'T'} \ll \rho_o T_o$) we can deduce the following...

$$\frac{\overline{\rho'T'}}{T_o} << \rho_o$$

$$\frac{\overline{\rho'T'}}{\rho_o} << T_o$$

These relations reduce equation 10 to the following...

$$1 + \frac{P'}{P_o} = 1 + \frac{T'}{T_o} + \frac{\rho'}{\rho_o} + \frac{\rho'T'}{\rho_o T_o}$$

$$\frac{P'}{P_o} = \frac{T'}{T_o} + \frac{\rho'}{\rho_o} + \frac{\rho'T'}{\rho_o T_o}$$
(11)

If we use the shallow convection approximation, which states that pressure perturbations in the vertical are really small in comparison to the mean state, then we can ignore the pressure term in 11

$$\frac{\rho'}{\rho_o} = -\frac{T'}{T_o}$$
$$= -\frac{\theta'_{\rho}}{\theta_{\rho,o}}$$

Vertical Motion

Starting with equation 1, expand the pressure and density terms

$$\frac{\delta w}{\delta t} + w \cdot \nabla \vec{w} = -\frac{1}{(\rho_o + \rho')} \frac{\delta(P_o + P')}{\delta z} - g + \nu \nabla^2 w$$

$$= -\frac{1}{(\rho_o + \rho')} \frac{\delta P_o}{\delta z} - \frac{1}{(\rho_o + \rho')} \frac{\delta P'}{\delta z} - \frac{(\rho_o + \rho')}{(\rho_o + \rho')} g + \nu \nabla^2 w$$

$$= \frac{1}{(\rho_o + \rho')} \left(-\frac{\delta P_o}{\delta z} - \frac{\delta P'}{\delta z} - \rho_o g - \rho' g \right) + \nu \nabla^2 w \tag{12}$$

Now in equation 12 assume the hydrostatic approximation using the background pressure and density $\frac{\delta P_o}{\delta z}=-\rho_o g$

$$\frac{\delta w}{\delta t} + w \cdot \nabla \vec{w} = \frac{1}{(\rho_o + \rho')} \left(-\frac{\delta P_o}{\delta z} - \frac{\delta P'}{\delta z} + \frac{\delta P_o}{\delta z} - \rho' g \right) + \nu \nabla^2 w$$

$$= -\frac{1}{(\rho_o + \rho')} \left(\frac{\delta P'}{\delta z} + \rho' g \right) + \nu \nabla^2 w \tag{13}$$

In equation 13, expand the terms again and rearrange...

$$\frac{\delta w}{\delta t} + w \cdot \nabla \vec{w} = -\frac{1}{\rho_o (1 + \frac{\rho'}{\rho_o})} \left(\frac{\delta P'}{\delta z} + \rho' g \right) + \nu \nabla^2 w$$

If we assume that density perturbations are much much smaller then the mean state we can invoke the following,

$$\rho' << \rho_o$$

Therefore, $(1 + \frac{\rho'}{\rho_o}) \approx 1$. Thus,

$$\frac{\delta w}{\delta t} + w \cdot \nabla \vec{w} = -\frac{1}{\rho_o} \left(\frac{\delta P'}{\delta z} + \rho' g \right) + \nu \nabla^2 w$$

$$= -\frac{1}{\rho_o} \frac{\delta P'}{\delta z} - \frac{\rho'}{\rho_o} g + \nu \nabla^2 w$$

$$= -\frac{1}{\rho_o} \frac{\delta P'}{\delta z} + B + \nu \nabla^2 w$$

$$B = -\frac{\rho'}{\rho_o} g$$
(14)

Horizontal Motion

Combine the horizontal winds in equations 3 and 4 follow the same basic steps as in the Vertical Motion section

$$\frac{\delta \vec{V}_H}{\delta t} + \vec{V}_H \cdot \vec{\nabla} \vec{V}_H = -\frac{1}{\rho} \frac{\delta P}{\delta x} - \frac{1}{\rho} \frac{\delta P}{\delta y} + \nu \nabla^2 \vec{V}_H$$

$$= -\frac{1}{(\rho_o + \rho')} \frac{\delta (P_o + P')}{\delta x} - \frac{1}{(\rho_o + \rho')} \frac{\delta (P_o + P')}{\delta y} + \nu \nabla^2 V_H$$

$$= -\frac{1}{(\rho_o + \rho')} \frac{\delta (P_o)}{\delta x} - \frac{1}{(\rho_o + \rho')} \frac{\delta P'}{\delta x} - \frac{1}{(\rho_o + \rho')} \frac{\delta (P_o)}{\delta y} - \frac{1}{(\rho_o + \rho')} \frac{\delta P'}{\delta y} + \nu \nabla^2 \vec{V}_H$$
(16)

Since we are assuming horizontal homogenity then...

$$\frac{\delta(P_o)}{\delta x} = \frac{\delta(P_o)}{\delta y} = 0 \tag{17}$$

Place equation 17 into 16

$$\frac{\delta \vec{V}_H}{\delta t} + \vec{V}_H \cdot \vec{\nabla} \vec{V}_H = -\frac{1}{(\rho_o + \rho')} \frac{\delta P'}{\delta x} - \frac{1}{(\rho_o + \rho')} \frac{\delta P'}{\delta y} + \nu \nabla^2 \vec{V}_H$$

$$= -\frac{1}{\rho_o (1 + \frac{\rho'}{\rho_o})} \frac{\delta P'}{\delta x} - \frac{1}{\rho_o (1 + \frac{\rho'}{\rho_o})} \frac{\delta P'}{\delta y} + \nu \nabla^2 \vec{V}_H$$

$$= -\frac{1}{\rho_o} \frac{\delta P'}{\delta x} - \frac{1}{\rho_o} \frac{\delta P'}{\delta y} + \nu \nabla^2 \vec{V}_H$$
(18)

4 OTHER

$$\vec{\nabla}^2 p_d' = -\vec{\nabla} \cdot (\rho_o \vec{v} \cdot \nabla \vec{v}) + \vec{\nabla} \cdot (\rho_o \vec{F})$$

$$\vec{\nabla}^2 p_d' = -\rho_o \left[\left(\frac{\delta u}{\delta x} \right)^2 + \left(\frac{\delta v}{\delta y} \right)^2 + \left(\frac{\delta w}{\delta z} \right)^2 - \frac{d^2 ln \rho_o}{dz^2} w^2 \right] - 2\rho_o \left[\frac{\delta v}{\delta x} \frac{\delta u}{\delta y} + \frac{\delta w}{\delta x} \frac{\delta u}{\delta z} + \frac{\delta w}{\delta y} \frac{\delta v}{\delta z} \right] + \vec{\nabla} \cdot (\rho_o \vec{F})$$

$$\vec{v} \cdot \nabla \vec{v} = \frac{1}{2} \nabla \vec{v} \cdot \vec{v} - \vec{v} \times \nabla \times \vec{v}$$
$$= \frac{1}{2} \nabla \vec{v} \cdot \vec{v} - \vec{v} \times \omega$$

$$\omega = \left(\frac{\delta w}{\delta y} - \frac{\delta v}{\delta z}\right) i + \left(\frac{\delta u}{\delta z} - \frac{\delta w}{\delta x}\right) j + \left(\frac{\delta v}{\delta x} - \frac{\delta u}{\delta y}\right) k$$

$$\omega = \omega_x i + \omega_y j + \omega_z k$$

$$\vec{v} \times \omega = (v\omega_z - w\omega_y) i + (u\omega_z - w\omega_x) j + (v\omega_x - u\omega_y) k$$

$$(v\omega_z - w\omega_y) i = \left[v\frac{\delta v}{\delta x} - v\frac{\delta u}{\delta y} - w\frac{\delta u}{\delta z} + w\frac{\delta w}{\delta x}\right] i$$

$$(u\omega_z - w\omega_x) j = \left[u\frac{\delta v}{\delta x} - u\frac{\delta u}{\delta y} - w\frac{\delta w}{\delta z} + u\frac{\delta w}{\delta x}\right] j$$

$$(v\omega_x - u\omega_y) k = \left[v\frac{\delta w}{\delta y} - v\frac{\delta v}{\delta z} - u\frac{\delta u}{\delta z} + u\frac{\delta w}{\delta x}\right] k$$

$$\frac{1}{2}\nabla\vec{v} \cdot \vec{v} = \frac{1}{2} \left[\frac{\delta}{\delta x}(uu + vv + ww)i + \frac{\delta}{\delta y}(uu + vv + ww)j + \frac{\delta}{\delta z}(uu + vv + ww)k\right]$$

$$\nabla \cdot (\vec{v} \times \omega) = \vec{\omega} \cdot (\nabla \times \vec{v}) - \vec{v} \cdot (\nabla \times \vec{\omega})$$

$$\vec{\omega} \cdot \nabla \times \vec{v} = \vec{\omega} \cdot \vec{\omega}$$

$$= \omega_x \omega_x + \omega_y \omega_y + \omega_z \omega_z$$

$$\left(\frac{\delta w}{\delta y} - \frac{\delta v}{\delta z}\right) \left(\frac{\delta w}{\delta z} - \frac{\delta v}{\delta z}\right) = \frac{\delta w}{\delta z} \frac{\delta w}{\delta z} + \frac{\delta v}{\delta z} \frac{\delta v}{\delta z} - 2\frac{\delta w}{\delta y} \frac{\delta v}{\delta z}$$

$$\left(\frac{\delta u}{\delta z} - \frac{\delta w}{\delta x}\right) \left(\frac{\delta u}{\delta x} - \frac{\delta w}{\delta y}\right) = \frac{\delta u}{\delta z} \frac{\delta u}{\delta z} + \frac{\delta w}{\delta y} \frac{\delta w}{\delta z} - 2\frac{\delta w}{\delta x} \frac{\delta u}{\delta z}$$

$$\vec{v} \cdot (\nabla \times \vec{\omega}) = (ui + vj + wk).$$

$$\nabla \times \vec{\omega} = \left(\frac{\delta \omega_z}{\delta y} - \frac{\delta \omega_y}{\delta z}\right) i + \left(\frac{\delta \omega_x}{\delta z} - \frac{\delta \omega_x}{\delta x}\right) j + \left(\frac{\delta \omega_y}{\delta x} - \frac{\delta \omega_x}{\delta x}\right) k$$

$$\left(\frac{\delta \omega_z}{\delta y} - \frac{\delta \omega_y}{\delta z}\right) = \left(\frac{\delta}{\delta y} \left(\frac{\delta v}{\delta x} - \frac{\delta u}{\delta y}\right) - \frac{\delta}{\delta z} \left(\frac{\delta u}{\delta z} - \frac{\delta w}{\delta x}\right)$$

$$\left(\frac{\delta \omega_x}{\delta z} - \frac{\delta \omega_z}{\delta x}\right) = \left(\frac{\delta}{\delta z} \left(\frac{\delta w}{\delta y} - \frac{\delta v}{\delta z}\right) - \frac{\delta}{\delta z} \left(\frac{\delta w}{\delta z} - \frac{\delta w}{\delta z}\right)$$

$$\left(\frac{\delta \omega_y}{\delta x} - \frac{\delta \omega_z}{\delta x}\right) = \left(\frac{\delta}{\delta z} \left(\frac{\delta w}{\delta y} - \frac{\delta v}{\delta z}\right) - \frac{\delta}{\delta z} \left(\frac{\delta w}{\delta x} - \frac{\delta v}{\delta z}\right)$$

$$\left(\frac{\delta \omega_y}{\delta x} - \frac{\delta \omega_z}{\delta y}\right) = \left(\frac{\delta}{\delta z} \left(\frac{\delta w}{\delta y} - \frac{\delta v}{\delta z}\right) - \frac{\delta}{\delta z} \left(\frac{\delta w}{\delta z} - \frac{\delta w}{\delta z}\right)$$

$$\left(\frac{\delta \omega_y}{\delta x} - \frac{\delta \omega_z}{\delta y}\right) = \left(\frac{\delta}{\delta z} \left(\frac{\delta w}{\delta z} - \frac{\delta v}{\delta z}\right) - \frac{\delta}{\delta z} \left(\frac{\delta w}{\delta z} - \frac{\delta v}{\delta z}\right)$$

$$\left(\frac{\delta \omega_y}{\delta x} - \frac{\delta \omega_z}{\delta y}\right) = \left(\frac{\delta}{\delta z} \left(\frac{\delta w}{\delta z} - \frac{\delta v}{\delta z}\right) - \frac{\delta}{\delta z} \left(\frac{\delta w}{\delta z} - \frac{\delta v}{\delta z}\right)$$

$$\left(\frac{\delta \omega_y}{\delta x} - \frac{\delta \omega_z}{\delta y}\right) = \left(\frac{\delta}{\delta z} \left(\frac{\delta w}{\delta z} - \frac{\delta v}{\delta z}\right) - \frac{\delta}{\delta z} \left(\frac{\delta w}{\delta z} - \frac{\delta v}{\delta z}\right)$$

 $= \left(\frac{\delta}{\delta x}\frac{\delta u}{\delta z} - \frac{\delta}{\delta x}\frac{\delta w}{\delta x} - \frac{\delta}{\delta y}\frac{\delta w}{\delta y} + \frac{\delta}{\delta y}\frac{\delta v}{\delta z}\right)$

$$\begin{split} \vec{v} \cdot (\nabla \times \vec{\omega}) &= (ui + vj + wk) \cdot (\nabla \times (\nabla \times \vec{v})) \\ \nabla \times (\nabla \times \vec{v}) &= \nabla (\nabla \cdot \vec{v}) - \nabla^2 \vec{v} \\ \nabla (\nabla \cdot \vec{v}) &= \left(\frac{\delta}{\delta x}i + \frac{\delta}{\delta y}j + \frac{\delta}{\delta z}k\right) \cdot \left(\frac{\delta u}{\delta x} + \frac{\delta v}{\delta y} + \frac{\delta w}{\delta z}\right) \\ &= \frac{\delta}{\delta x} \left(\frac{\delta u}{\delta x} + \frac{\delta v}{\delta y} + \frac{\delta w}{\delta z}\right)i + \frac{\delta}{\delta y} \left(\frac{\delta u}{\delta x} + \frac{\delta v}{\delta y} + \frac{\delta w}{\delta z}\right)j + \frac{\delta}{\delta z} \left(\frac{\delta u}{\delta x} + \frac{\delta v}{\delta y} + \frac{\delta w}{\delta z}\right)k \\ &= \left(\frac{\delta}{\delta x}\frac{\delta u}{\delta x} + \frac{\delta}{\delta x}\frac{\delta v}{\delta y} + \frac{\delta}{\delta x}\frac{\delta w}{\delta z}\right)i + \left(\frac{\delta}{\delta y}\frac{\delta u}{\delta x} + \frac{\delta}{\delta y}\frac{\delta v}{\delta y} + \frac{\delta}{\delta y}\frac{\delta w}{\delta z}\right)j + \left(\frac{\delta}{\delta z}\frac{\delta u}{\delta x} + \frac{\delta}{\delta z}\frac{\delta v}{\delta y} + \frac{\delta}{\delta z}\frac{\delta w}{\delta z}\right)k \\ \nabla^2 \vec{v} &= \nabla^2 ui + \nabla^2 vj + \nabla^2 wk \\ &= \left(\frac{\delta}{\delta x}\frac{\delta}{\delta x}u + \frac{\delta}{\delta y}\frac{\delta}{\delta y}u + \frac{\delta}{\delta z}\frac{\delta}{\delta z}u\right)i + \left(\frac{\delta}{\delta x}\frac{\delta}{\delta x}v + \frac{\delta}{\delta y}\frac{\delta}{\delta y}v + \frac{\delta}{\delta z}\frac{\delta}{\delta z}v\right)j \\ &+ \left(\frac{\delta}{\delta x}\frac{\delta}{\delta x}w + \frac{\delta}{\delta y}\frac{\delta}{\delta y}w + \frac{\delta}{\delta z}\frac{\delta}{\delta z}w\right)k \end{split}$$

$$\begin{split} \nabla \times (\nabla \times \vec{v}) &= \nabla (\nabla \cdot \vec{v}) - \nabla^2 \vec{v} \\ &= \left(\frac{\delta}{\delta x} \frac{\delta u}{\delta x} + \frac{\delta}{\delta x} \frac{\delta v}{\delta y} + \frac{\delta}{\delta x} \frac{\delta w}{\delta z} \right) i + \left(\frac{\delta}{\delta y} \frac{\delta u}{\delta x} + \frac{\delta}{\delta y} \frac{\delta v}{\delta y} + \frac{\delta}{\delta y} \frac{\delta w}{\delta z} \right) j + \left(\frac{\delta}{\delta z} \frac{\delta u}{\delta x} + \frac{\delta}{\delta z} \frac{\delta v}{\delta z} \right) k \\ &- \left(\frac{\delta}{\delta x} \frac{\delta}{\delta x} u + \frac{\delta}{\delta y} \frac{\delta}{\delta y} u + \frac{\delta}{\delta z} \frac{\delta}{\delta z} u \right) i - \left(\frac{\delta}{\delta x} \frac{\delta}{\delta x} v + \frac{\delta}{\delta y} \frac{\delta}{\delta y} v + \frac{\delta}{\delta z} \frac{\delta}{\delta z} v \right) j \\ &- \left(\frac{\delta}{\delta x} \frac{\delta}{\delta x} w + \frac{\delta}{\delta y} \frac{\delta}{\delta y} w + \frac{\delta}{\delta z} \frac{\delta w}{\delta z} w \right) k \\ &= \left(\frac{\delta}{\delta x} \frac{\delta u}{\delta x} + \frac{\delta}{\delta x} \frac{\delta v}{\delta y} + \frac{\delta}{\delta x} \frac{\delta w}{\delta z} - \frac{\delta}{\delta x} \frac{\delta}{\delta x} u - \frac{\delta}{\delta y} \frac{\delta}{\delta y} u - \frac{\delta}{\delta z} \frac{\delta}{\delta z} u \right) i \\ &+ \left(\frac{\delta}{\delta y} \frac{\delta u}{\delta x} + \frac{\delta}{\delta y} \frac{\delta v}{\delta y} + \frac{\delta}{\delta y} \frac{\delta w}{\delta z} - \frac{\delta}{\delta x} \frac{\delta}{\delta x} v - \frac{\delta}{\delta y} \frac{\delta}{\delta y} v - \frac{\delta}{\delta z} \frac{\delta}{\delta z} v \right) j \\ &+ \left(\frac{\delta}{\delta z} \frac{\delta u}{\delta x} + \frac{\delta}{\delta z} \frac{\delta v}{\delta y} + \frac{\delta}{\delta z} \frac{\delta w}{\delta z} - \frac{\delta}{\delta x} \frac{\delta u}{\delta x} w - \frac{\delta}{\delta y} \frac{\delta}{\delta y} w - \frac{\delta}{\delta z} \frac{\delta}{\delta z} w \right) k \\ &= \left(\frac{\delta}{\delta x} \frac{\delta v}{\delta y} + \frac{\delta}{\delta x} \frac{\delta w}{\delta z} - \frac{\delta}{\delta y} \frac{\delta u}{\delta y} - \frac{\delta}{\delta z} \frac{\delta u}{\delta z} \right) i \\ &+ \left(\frac{\delta}{\delta y} \frac{\delta u}{\delta x} + \frac{\delta}{\delta y} \frac{\delta w}{\delta z} - \frac{\delta}{\delta x} \frac{\delta v}{\delta x} - \frac{\delta}{\delta z} \frac{\delta v}{\delta z} \right) j \\ &+ \left(\frac{\delta}{\delta z} \frac{\delta u}{\delta x} + \frac{\delta}{\delta z} \frac{\delta w}{\delta y} - \frac{\delta}{\delta x} \frac{\delta w}{\delta x} - \frac{\delta}{\delta z} \frac{\delta w}{\delta z} \right) k \end{split}$$

$$\begin{split} \overrightarrow{v} \cdot (\nabla \times (\nabla \times \overrightarrow{v})) &= \overrightarrow{v} \cdot (\nabla \times \overrightarrow{\omega}) \\ &= u \left(\frac{\delta}{\delta x} \frac{\delta v}{\delta y} + \frac{\delta}{\delta x} \frac{\delta w}{\delta z} - \frac{\delta}{\delta y} \frac{\delta u}{\delta y} - \frac{\delta}{\delta z} \frac{\delta u}{\delta z} \right) \\ &+ v \left(\frac{\delta}{\delta y} \frac{\delta u}{\delta x} + \frac{\delta}{\delta y} \frac{\delta w}{\delta z} - \frac{\delta}{\delta x} \frac{\delta v}{\delta x} - \frac{\delta}{\delta z} \frac{\delta v}{\delta z} \right) \\ &+ w \left(\frac{\delta}{\delta z} \frac{\delta u}{\delta x} + \frac{\delta}{\delta z} \frac{\delta v}{\delta y} - \frac{\delta}{\delta x} \frac{\delta w}{\delta x} - \frac{\delta}{\delta y} \frac{\delta w}{\delta y} \right) \end{split}$$