

Markov Chains

Geometric Algorithms
Lecture 13

Practice Problem

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \mapsto \begin{bmatrix} x_1 + x_2 \\ 2x_2 \\ x_2 + bx_3 \end{bmatrix}$$

For what values of b is the above transformation singular? Explain your answer

Find the inverse of the matrix implementing the above transformation, given $b = 1$

Solution

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \mapsto \begin{bmatrix} x_1 + x_2 \\ 2x_2 \\ x_2 + bx_3 \end{bmatrix}$$

Objectives

1. Motivate linear dynamical systems
2. Analyze Markov chains and their properties
3. Learn to solve for steady-states of Markov chains
4. Connect this to graphs and random walks

Keywords

linear dynamical systems

recurrence relations

linear difference equations

state vector

probability vector

stochastic matrix

Markov chain

steady-state vector

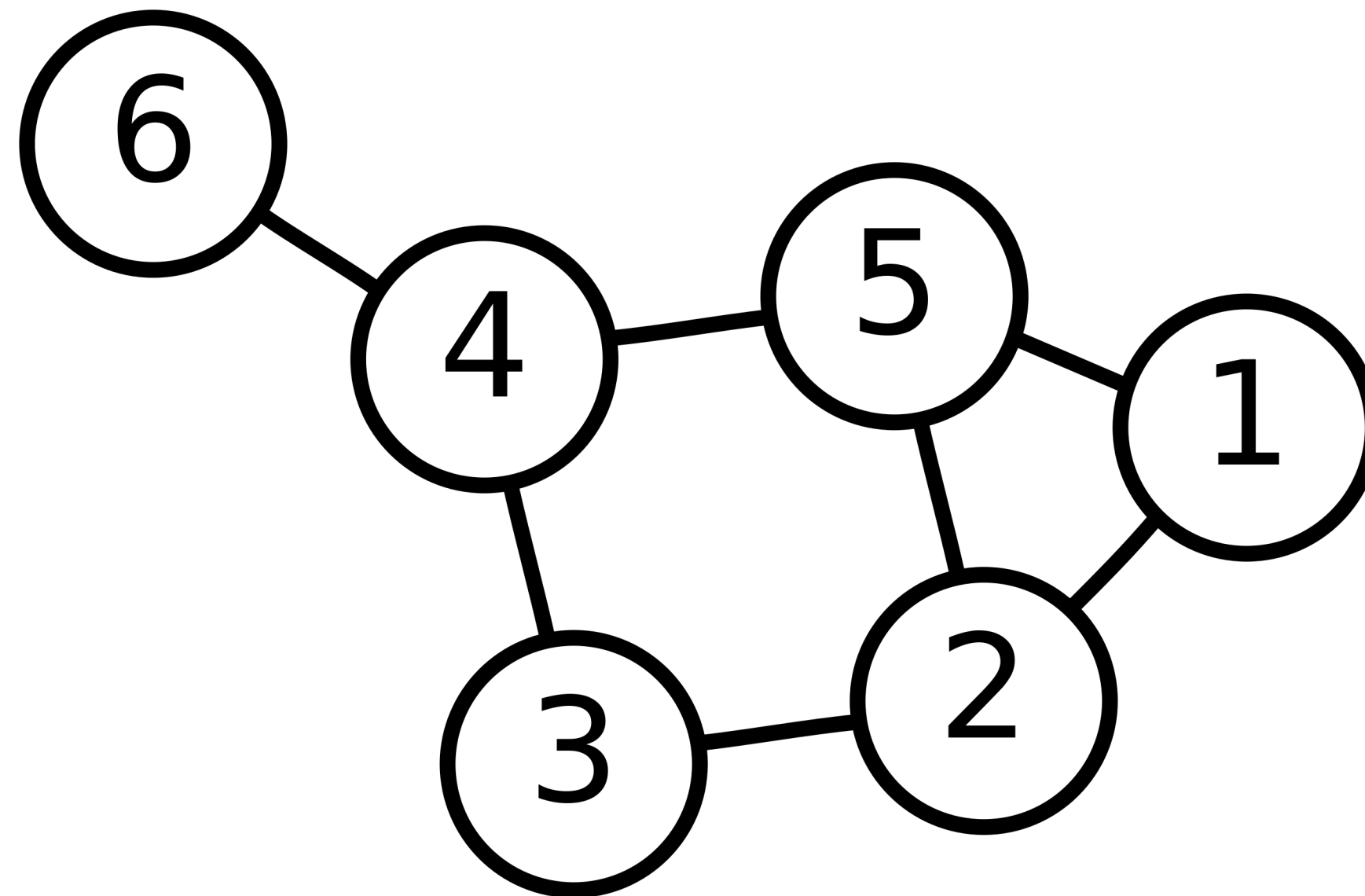
random walk

state diagram

Algebraic Graph Theory

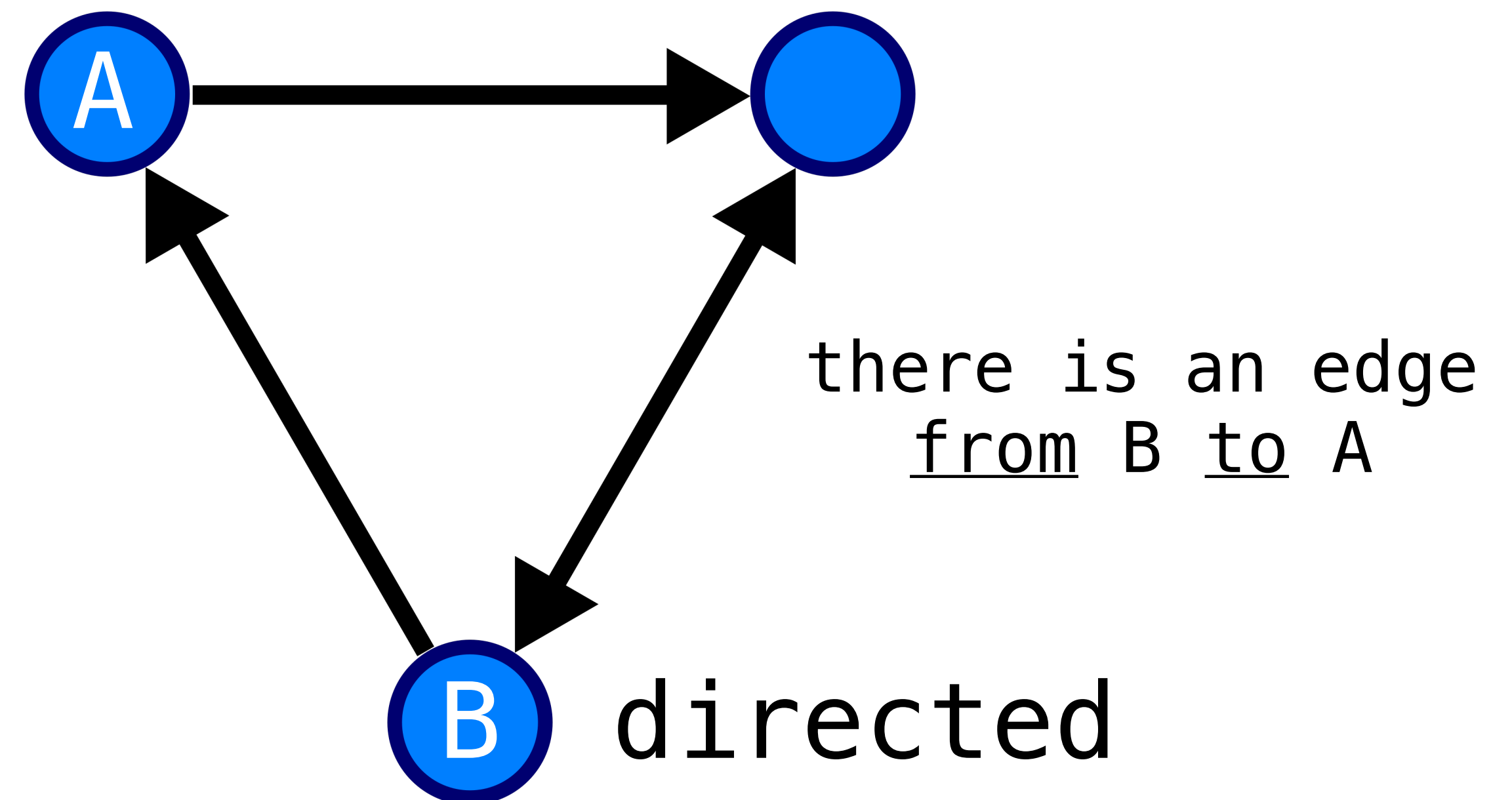
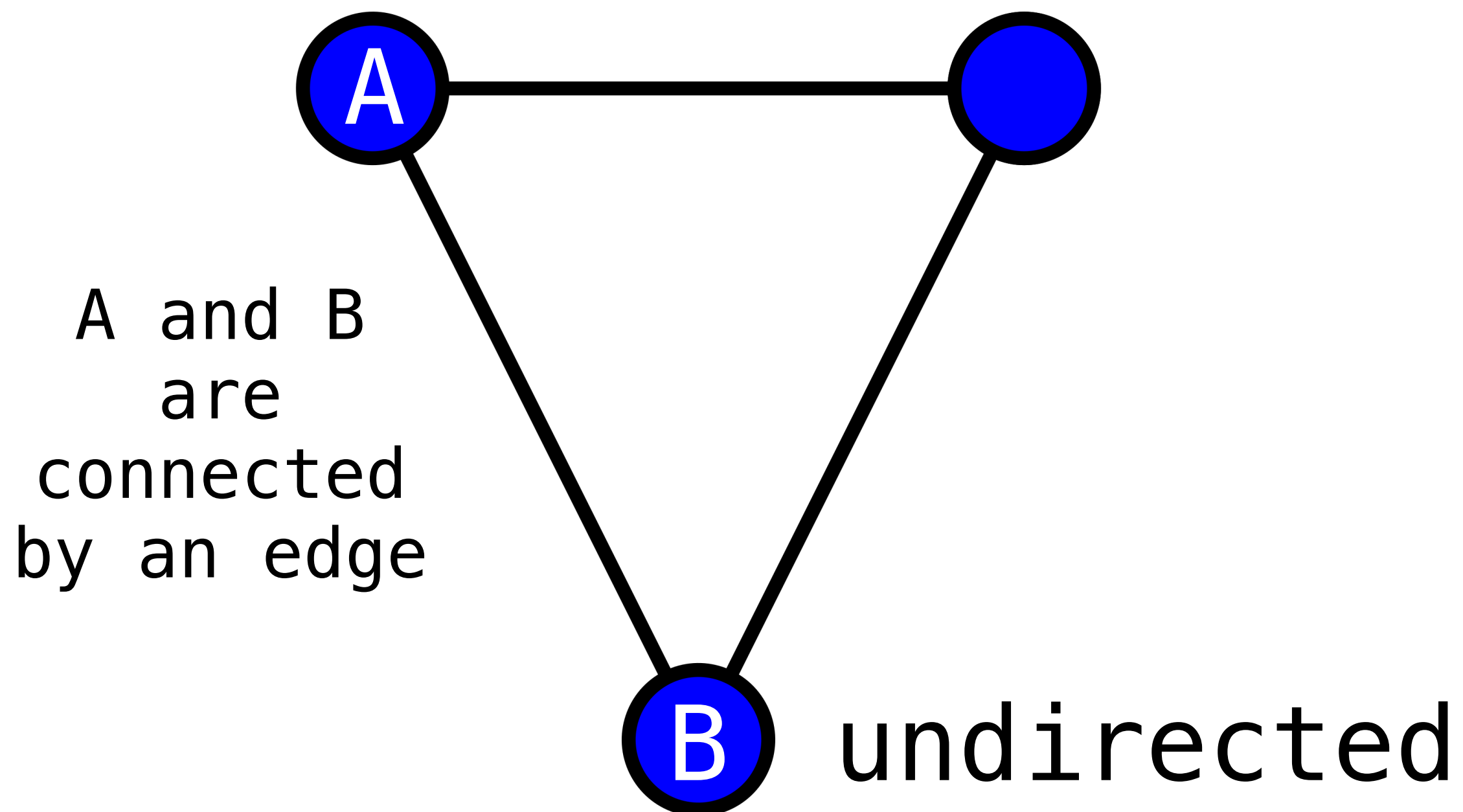
Graphs

Definition (Informal). A graph is a collection of nodes with edges between them



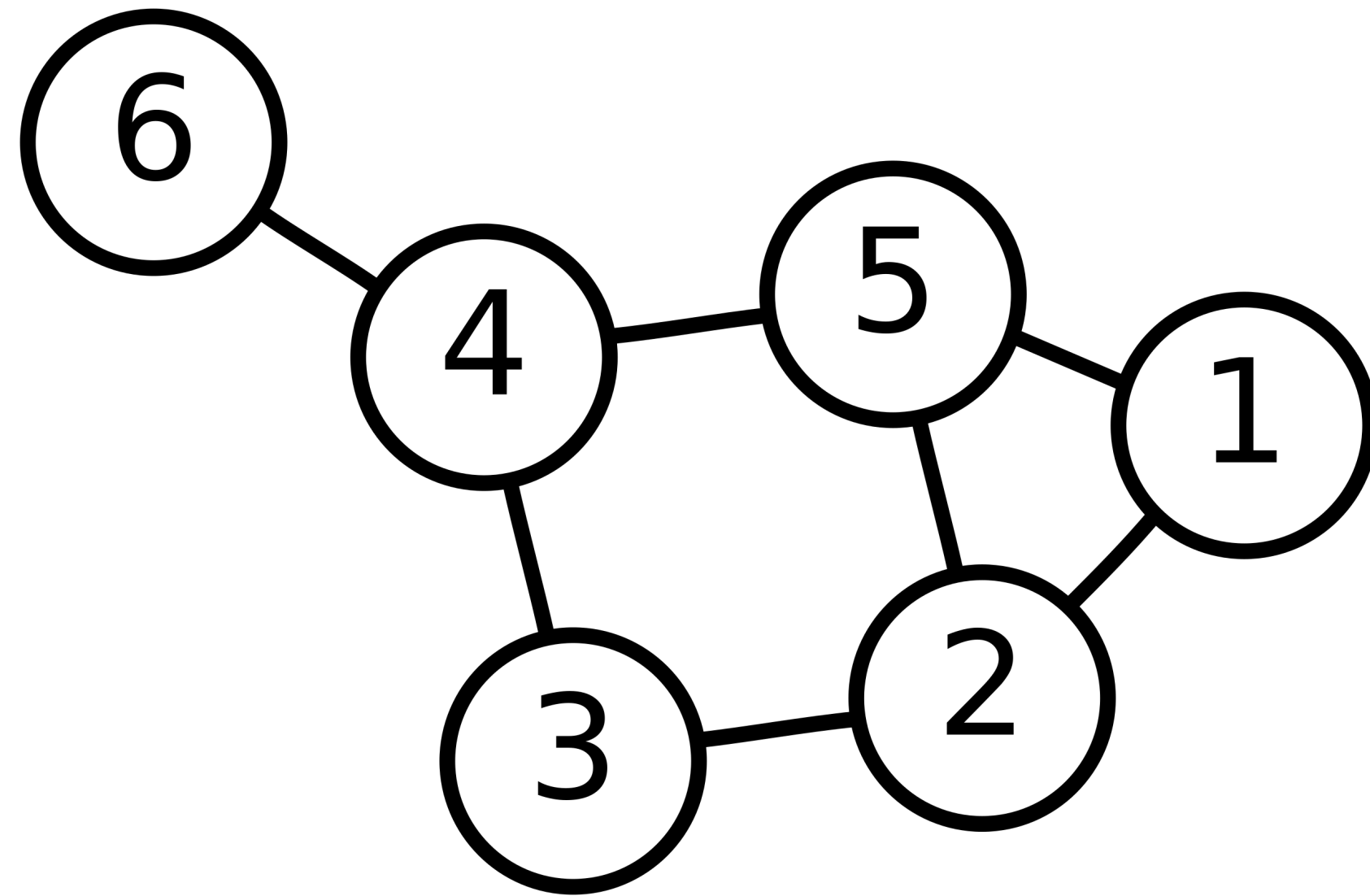
Directed vs. Undirected Graphs

A graph is **directed** if its edges have a direction

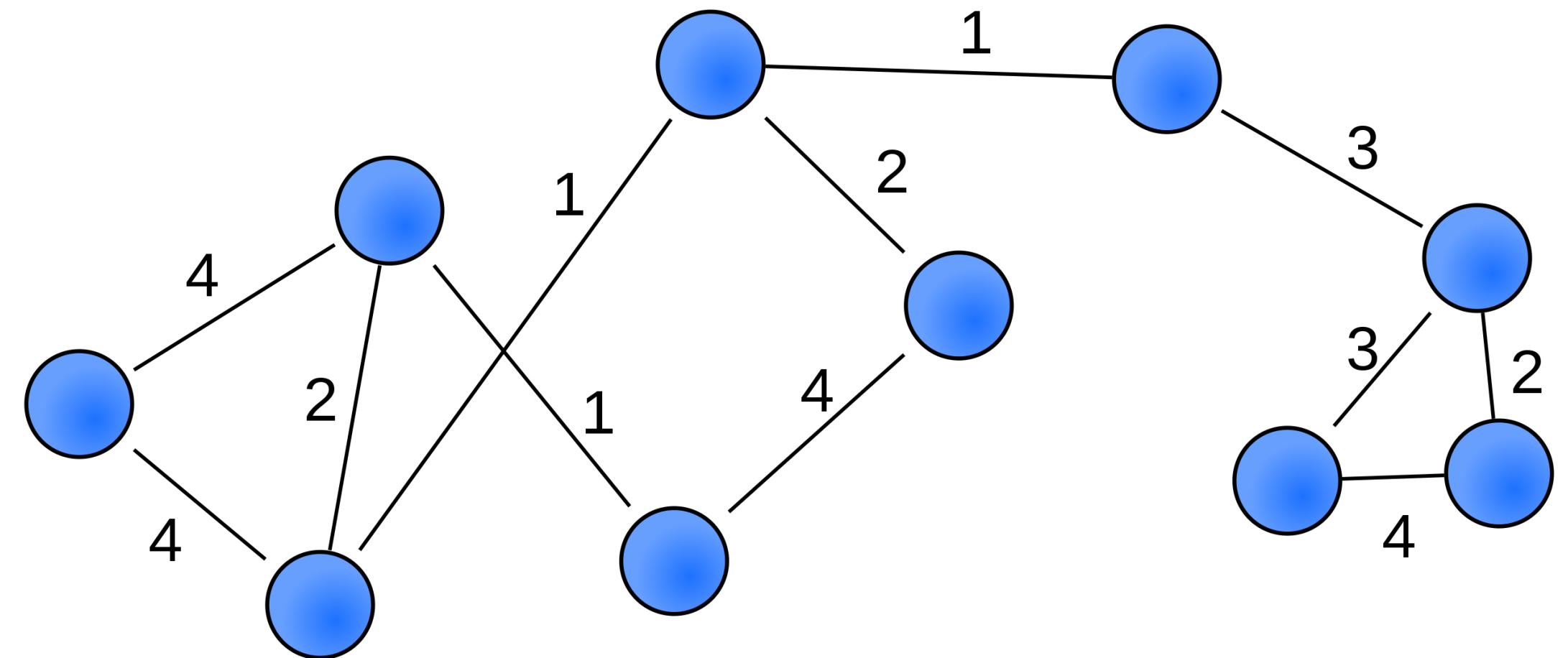


Weighted vs Unweighted graphs

A graph is **weighted** if its edges have associated values



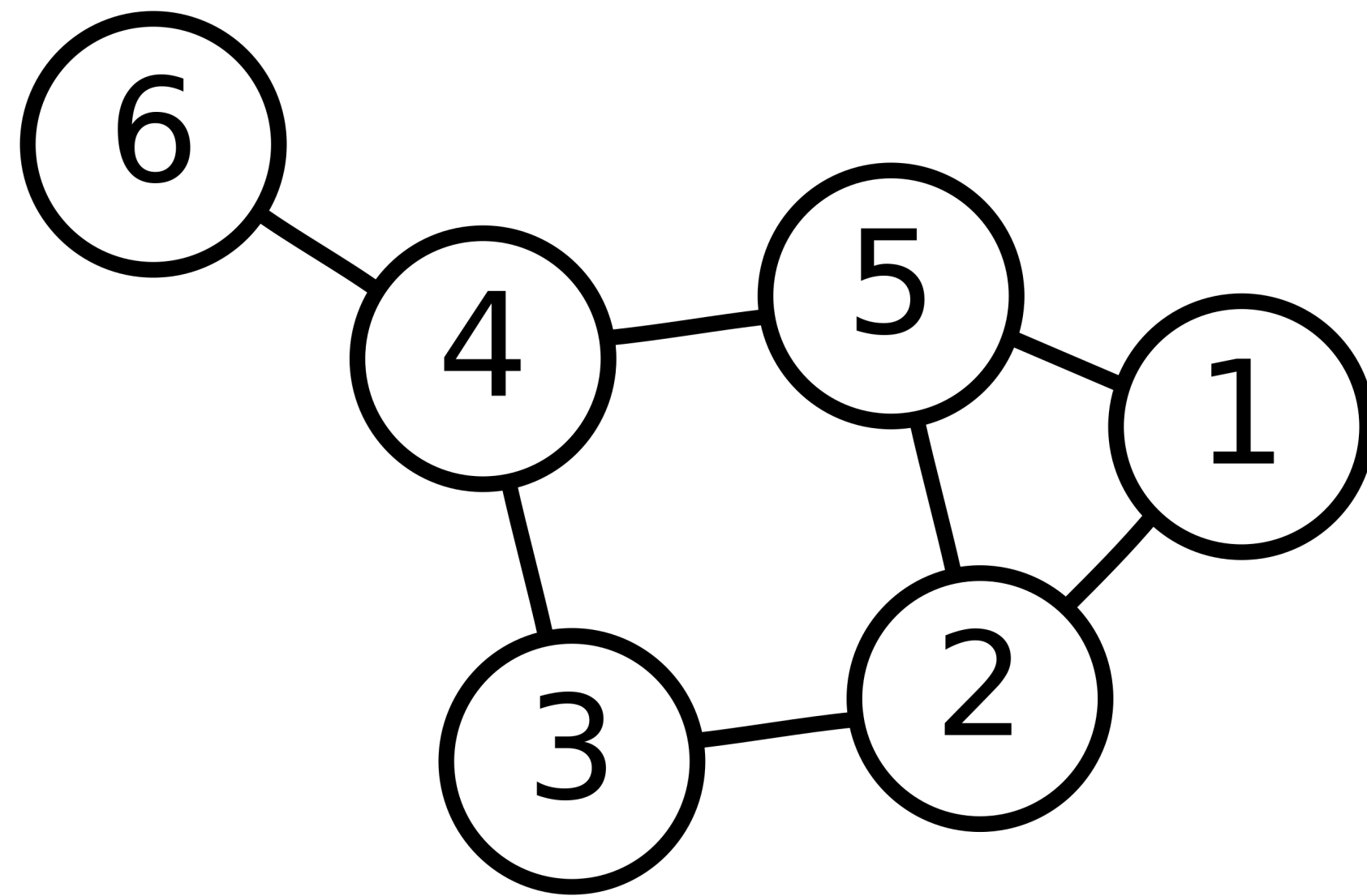
unweighted



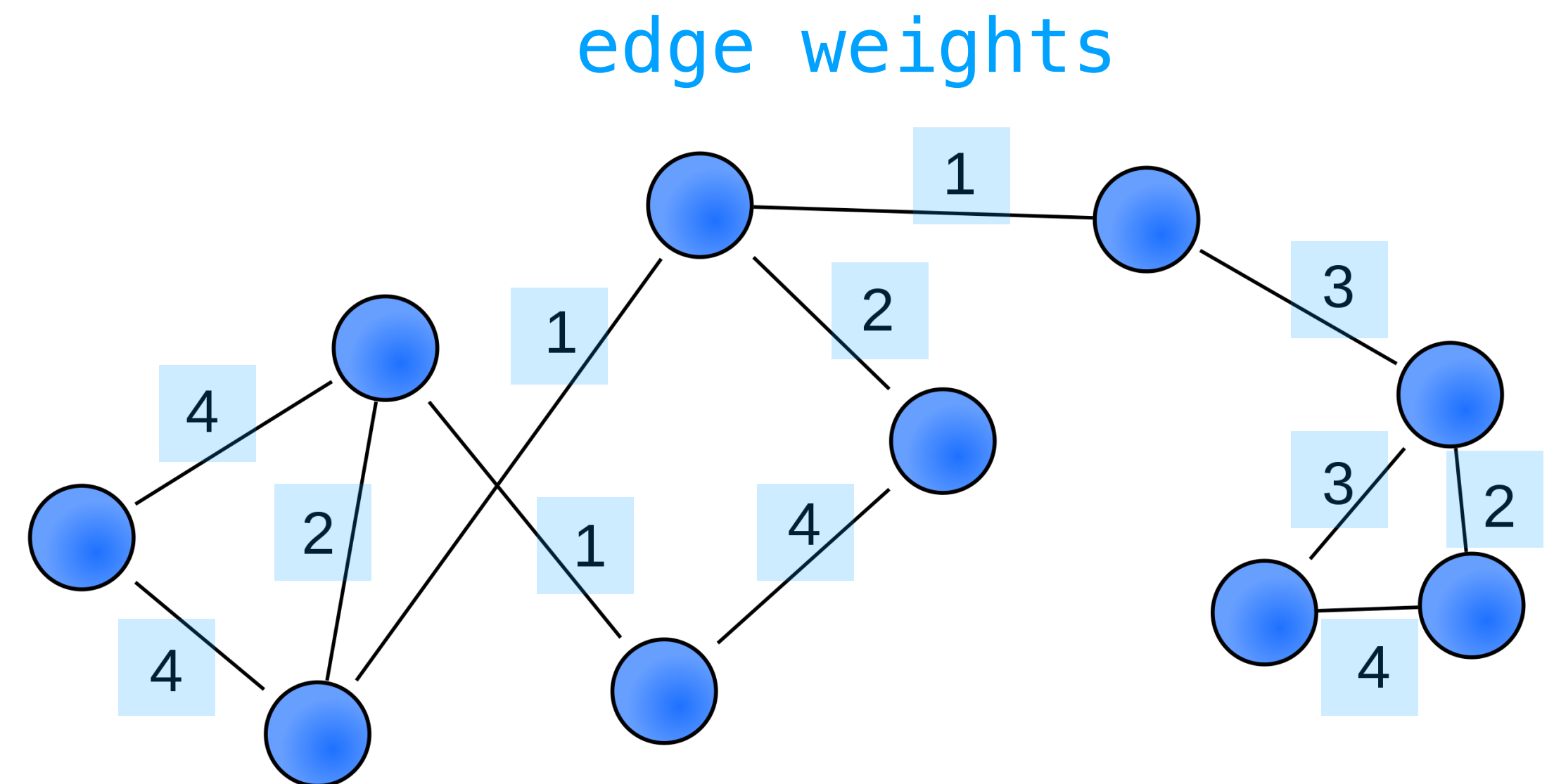
weighted

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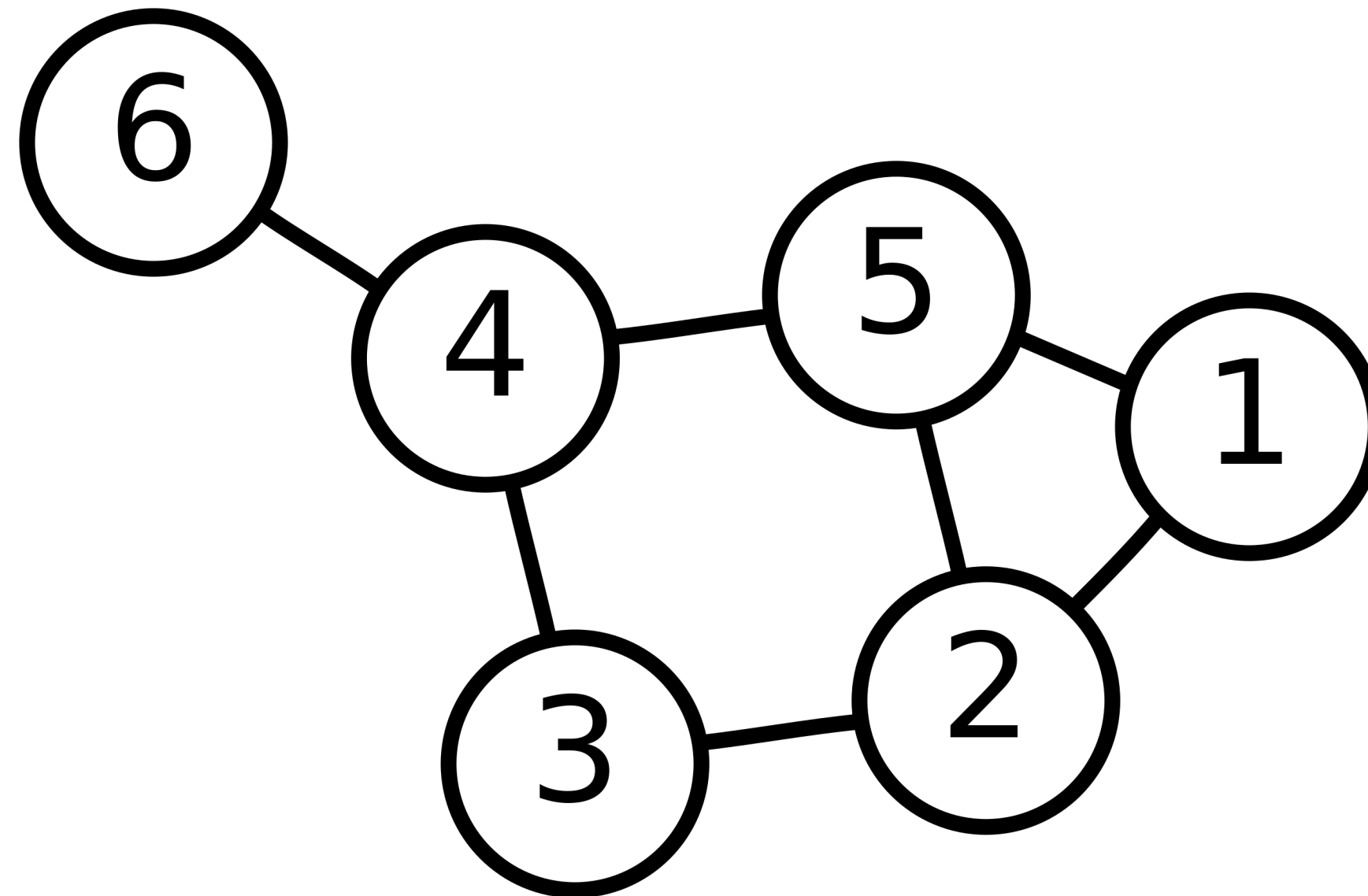
unweighted



weighted

Simple Graphs

A graph is **simple** if it is undirected, has no self loops, and no multi-edges



Four Kinds of Graphs

directed

undirected

weighted

nodes are traffic lights
edges are streets
weights are number of lanes

nodes are musicians
edges are collaborations
weights are number of collaborations

unweighted

nodes are instagram users
edges are follows

nodes are bodies of land
edges are pedestrian bridges

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Fundamental Question

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How do we represent a graph
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How do we represent a graph formally in a computer?

There are a couple ways, but one way is to use matrices

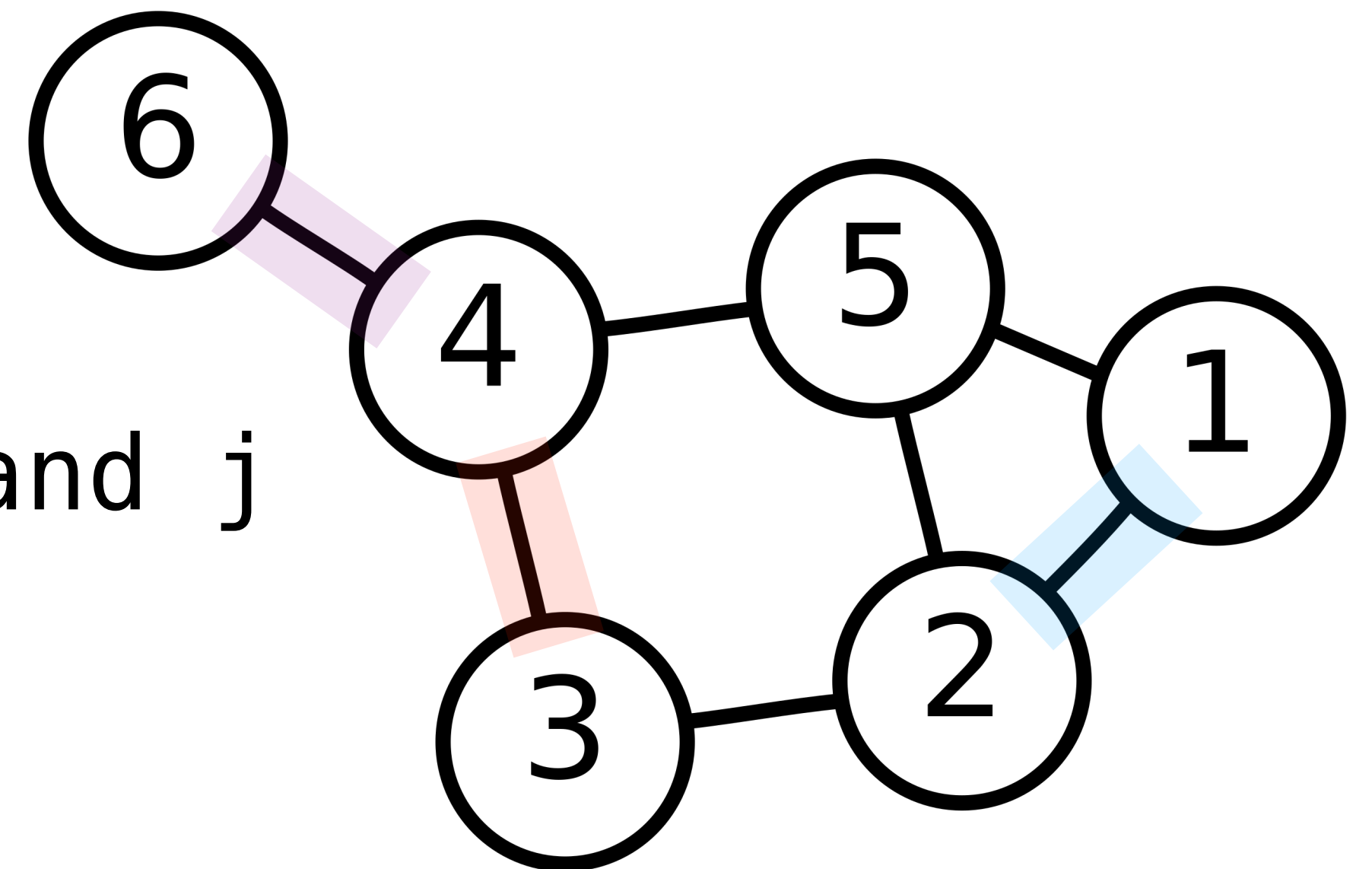
Adjacency Matrices

Let G be an simple graph with its nodes labeled by numbers 1 through n

We can create the **adjacency matrix** A for G as follows

$$A_{ij} = \begin{cases} 1 & \text{there is an edge between } i \text{ and } j \\ 0 & \text{otherwise} \end{cases}$$

$$\begin{matrix} & & A_{12} & & A_{34} & & A_{46} \\ A_{21} & \begin{bmatrix} 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \end{bmatrix} \end{matrix}$$



Symmetric Matrices

Definition. A $n \times n$ matrix is **symmetric** if

$$A^T = A$$

Example.

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \end{bmatrix}$$

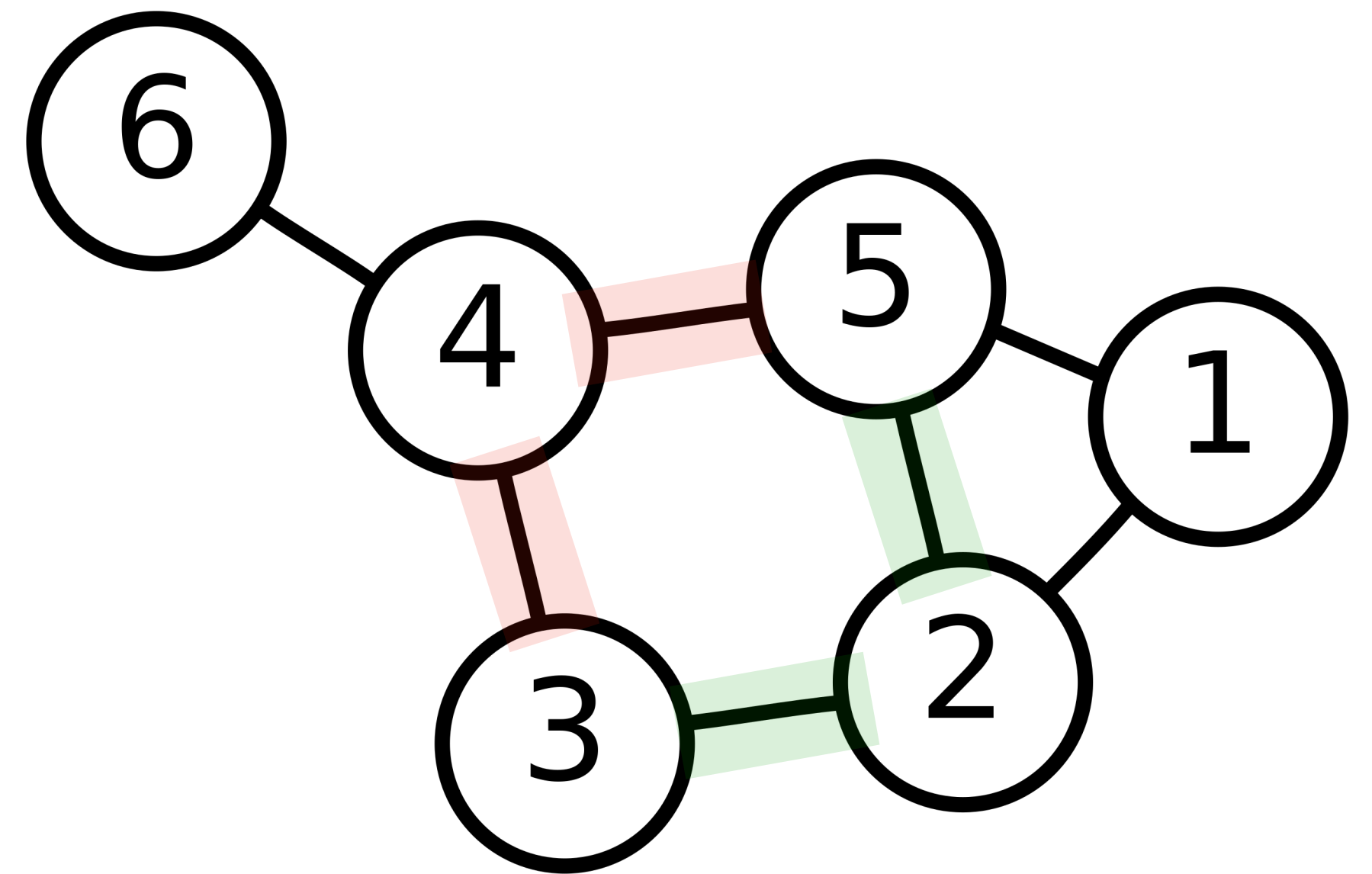
Once we have an adjacency matrix,
we can do linear algebra on
graphs

Example: Squared Adjacency Matrices

Given an adjacency matrix A , can we interpret anything meaningful from A^2 ?

Example: Squared Adjacency Matrices

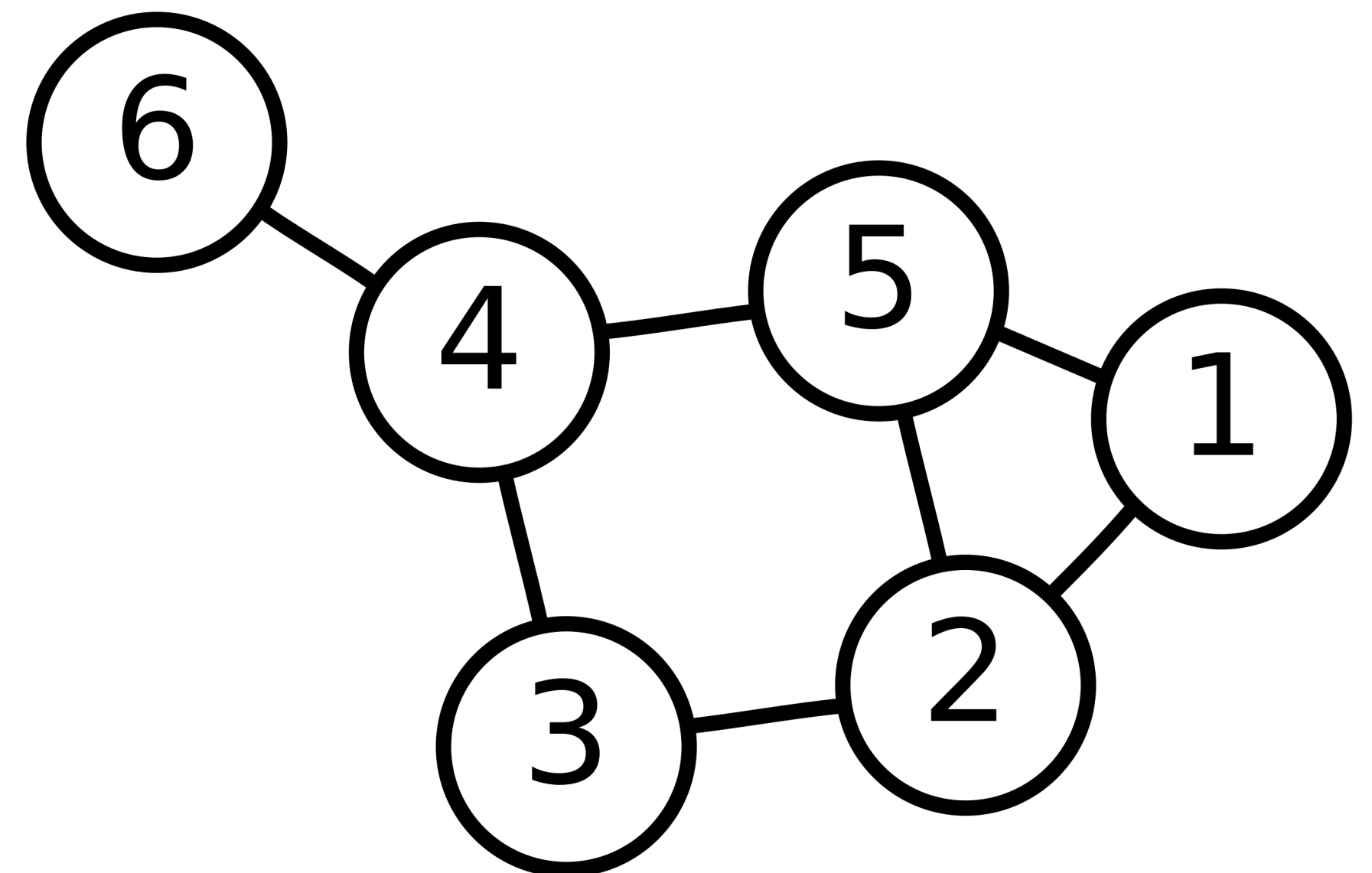
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$$(A^2)_{53} = 1(0) + 1(1) + 0(0) + 1(1) + 0(0) + 0(0) = 2$$

Example: Squared Adjacency Matrices

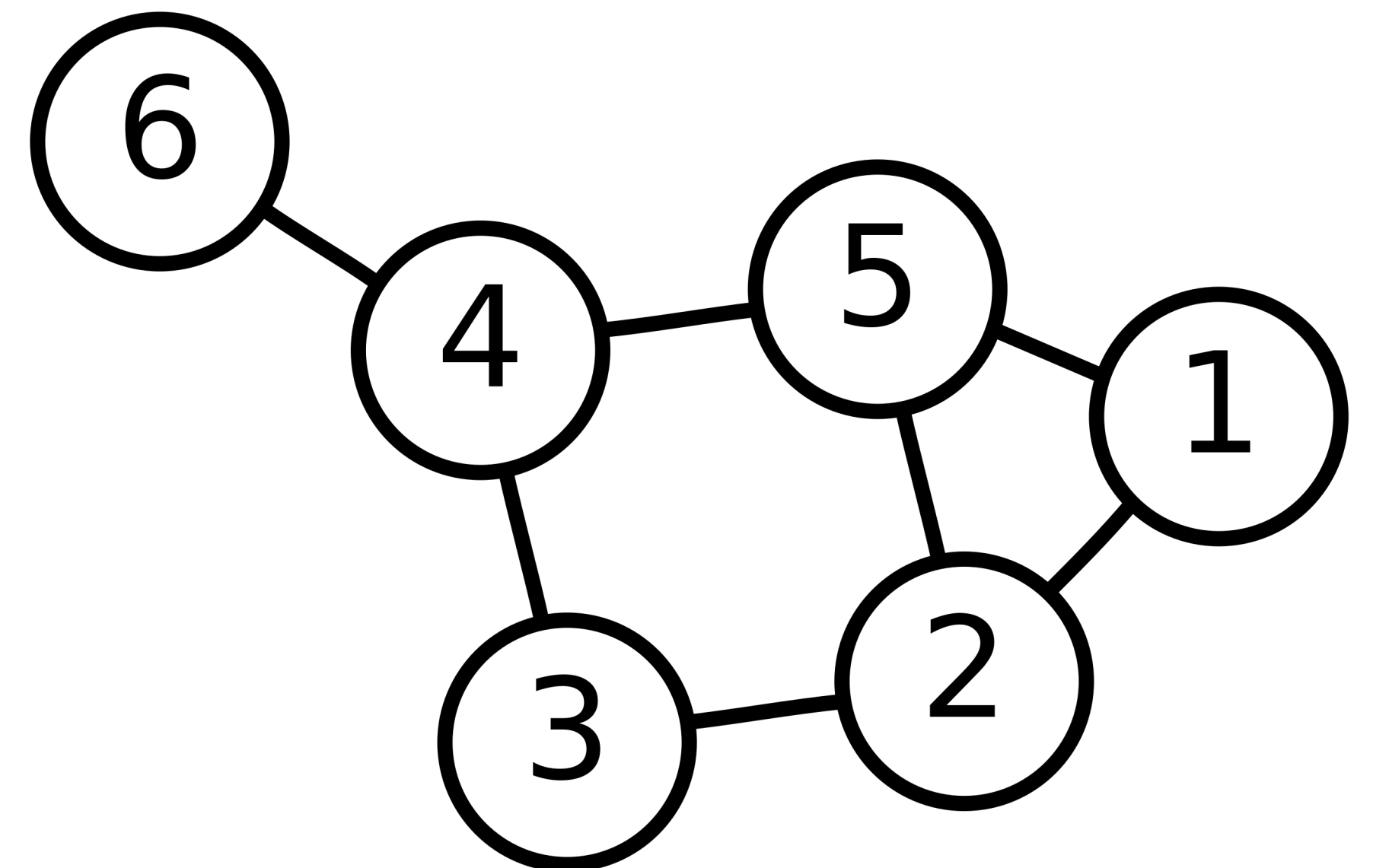
$$(A^2)_{ij} = A_{i1}A_{1j} + A_{i2}A_{2j} + \dots + A_{in}A_{nj}$$



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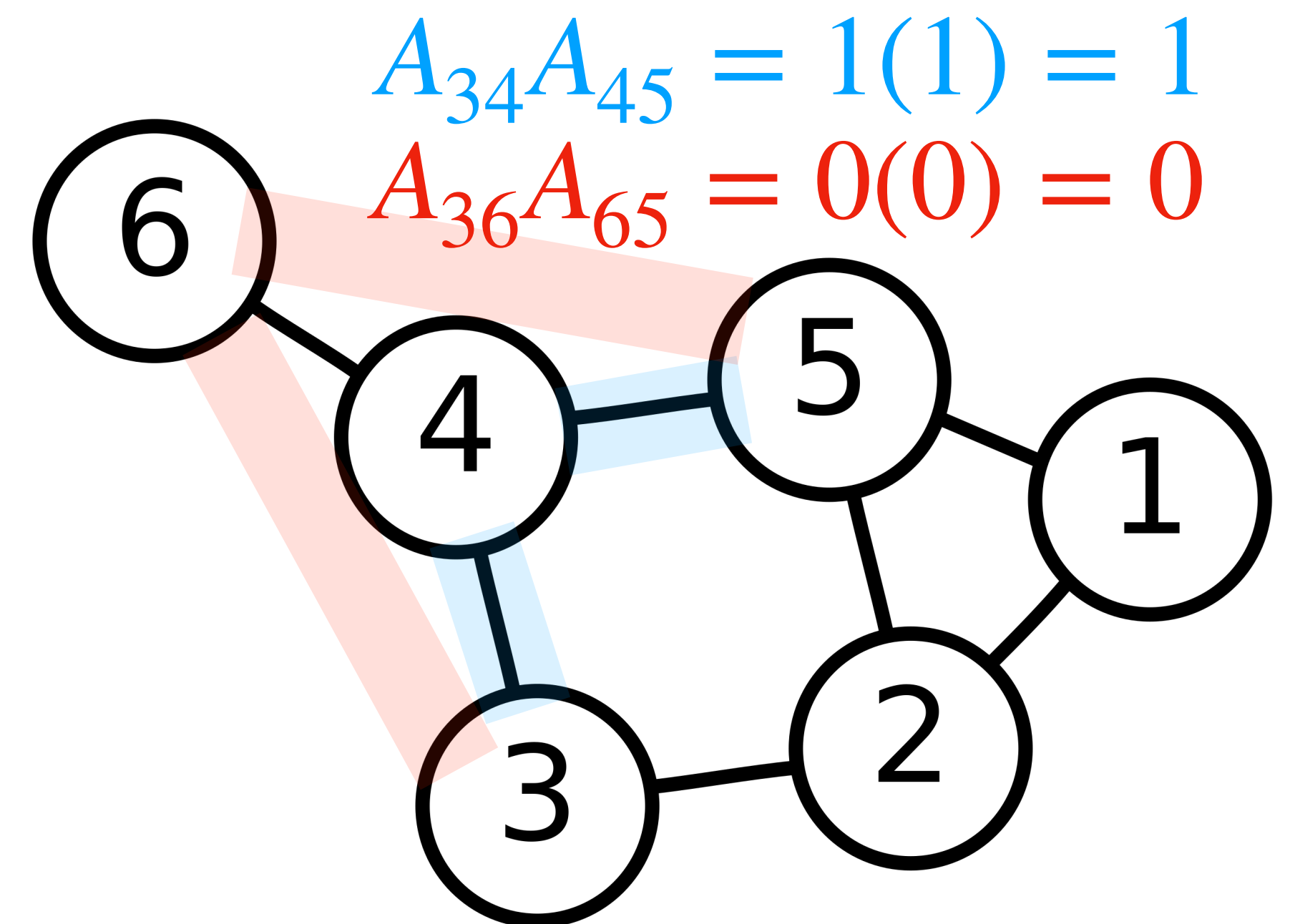
$$A_{ik}A_{kj} = \begin{cases} 1 & \text{there are edges } i \text{ to } k \text{ and } k \text{ to } j \\ 0 & \text{otherwise} \end{cases}$$



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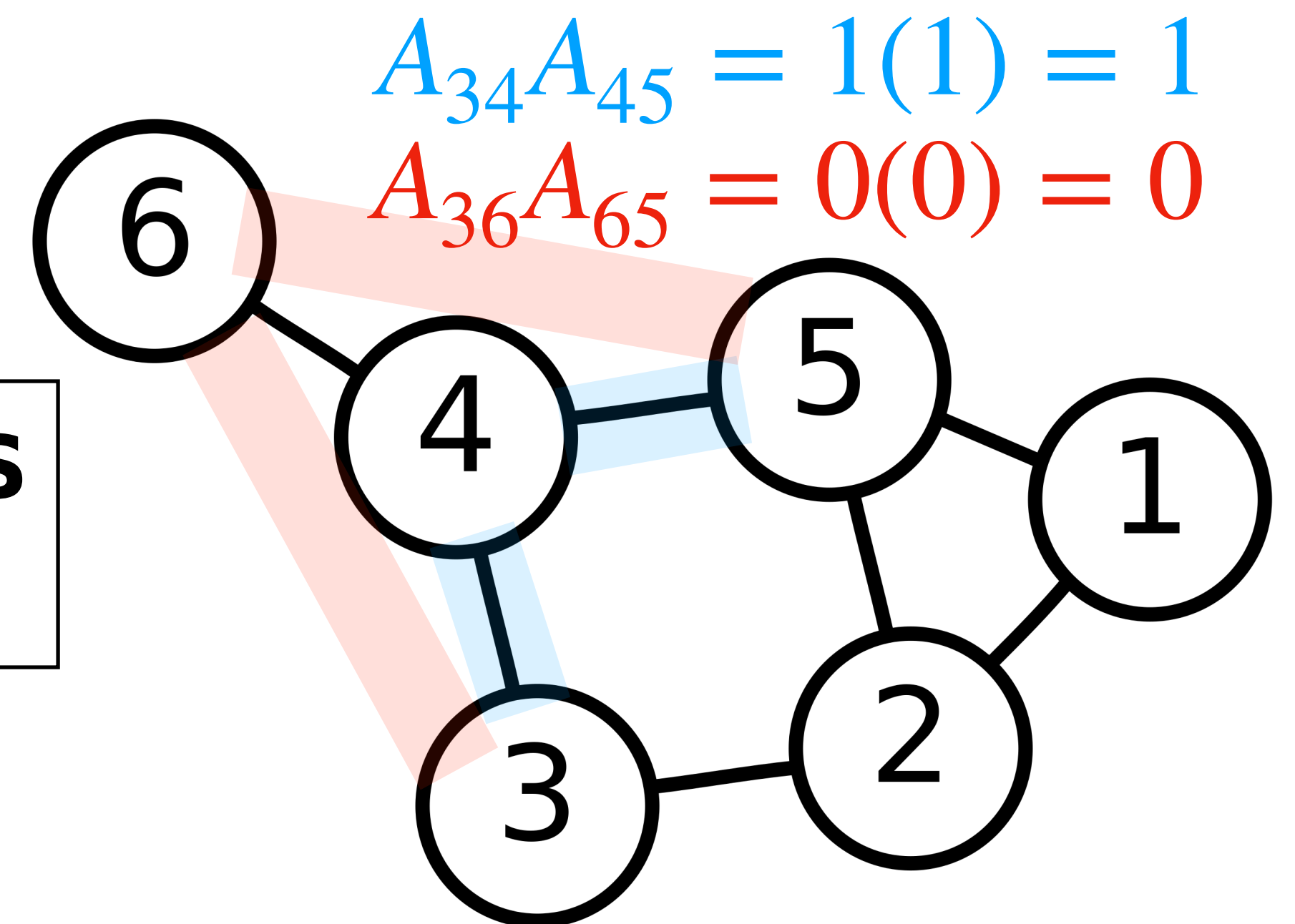


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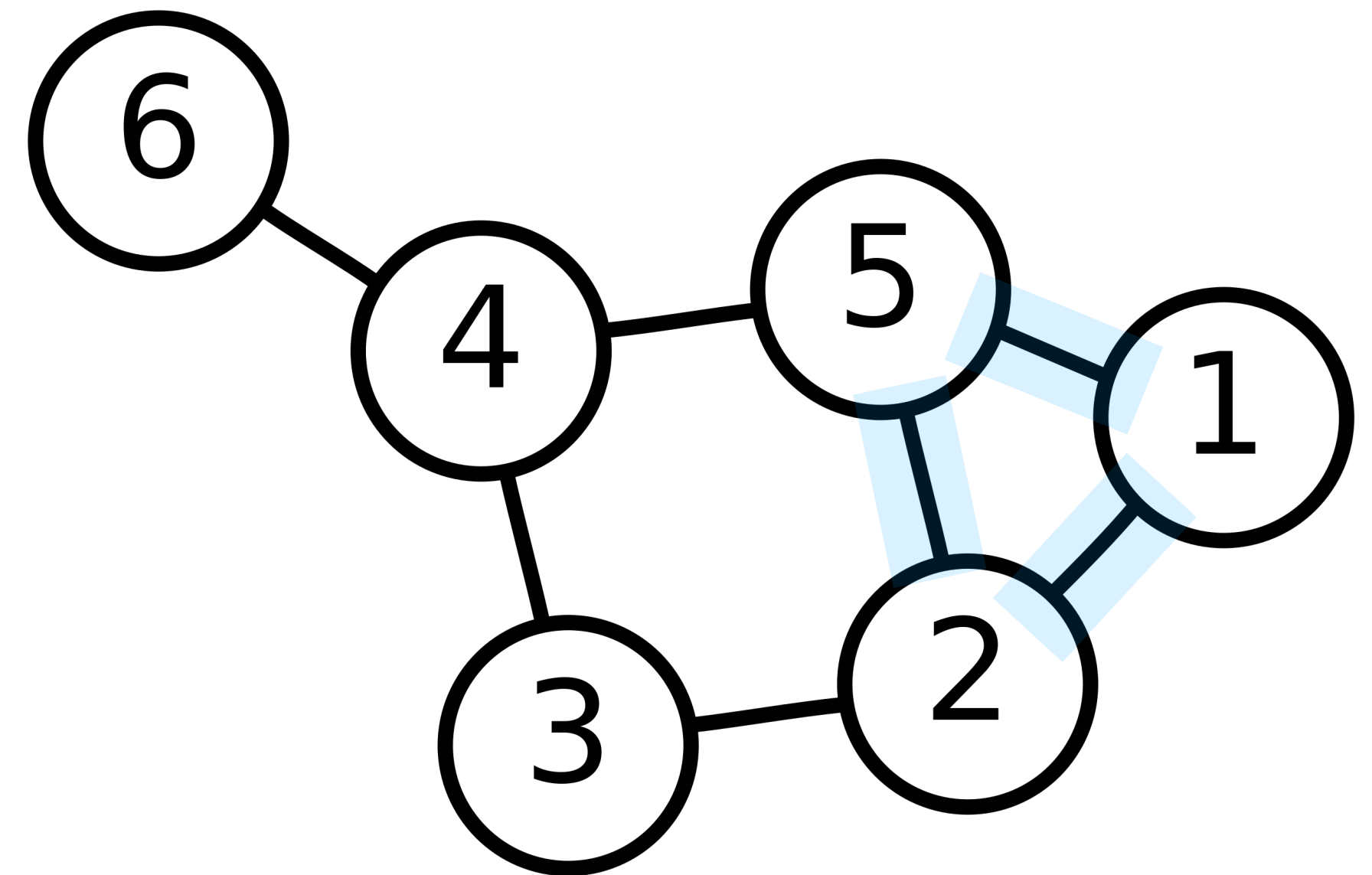
$$(A^2)_{ij} = \text{number of 2-step paths from } i \text{ to } j$$



Application: Triangle Counting

A **triangle** in an undirected graph is a set of three distinct nodes with edges between every pair of nodes

Triangles in a social network represent mutual friends and tight cohesion (among other things)



Application: Triangle Counting (Naive)

FUNCTION tri_count_naive(A):

count = 0

for i from 1 to n :

for j from $i + 1$ to n :

for k from $j + 1$ to n :

if $A_{ij} = 1$ and $A_{jk} = 1$ and $A_{ki} = 1$: # an edge between each pair

count += 1:

RETURN count

Application: Triangle Counting

Theorem. For an adjacency matrix A , the number of triangle containing the edge (i,j) is

$$(A^2)_{ij} * A_{ij}$$

Verify:

Application: Triangle Counting

FUNCTION tri_count(A):

 compute A^2

 count \leftarrow sum of $(A^2)_{ij} * A_{ij}$ for all distinct i and j

RETURN count / 6 # why divided by 6?

Application: Triangle Counting

FUNCTION tri_count(A):

in NumPy '*' is entry-wise multiplication

also called the HADAMARD PRODUCT

count \leftarrow sum of the entries of $A^2 * A$

RETURN count / 6

Application: Triangle Counting

```
FUNCTION tri_count(A):
```

```
    # in NumPy '*' is entry-wise multiplication
```

```
    #      also called the HADAMARD PRODUCT
```

```
    # and 'np.sum' sums the entry of a matrix
```

```
RETURN np.sum( (A @ A) * A ) / 6
```


demo

Dynamical Systems

Change

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Things change

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Things change from one state of affairs to
another state of affairs

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Things change often in unpredictable ways

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If something changes unpredictably, what can we say about it?

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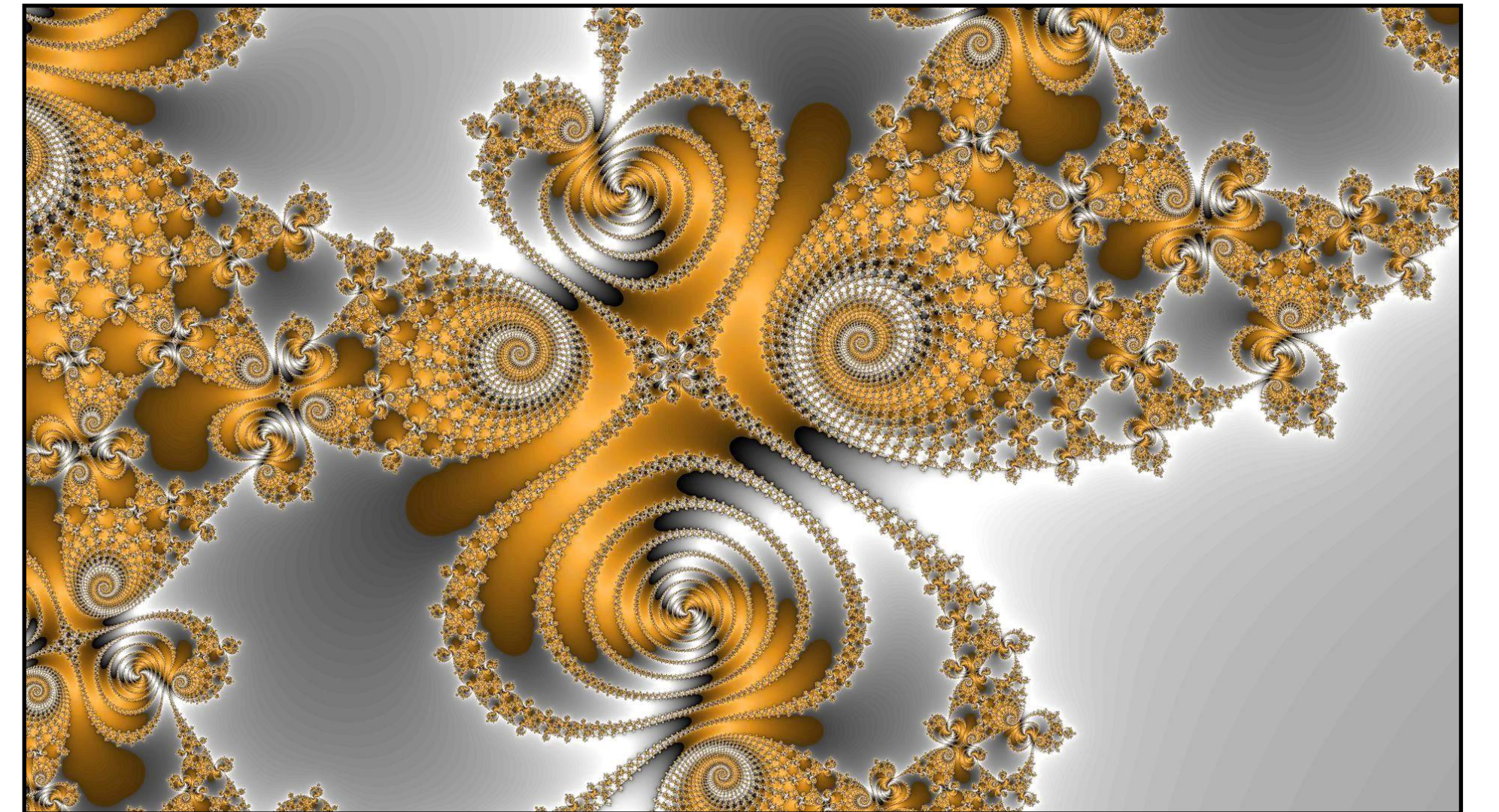
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Examples.

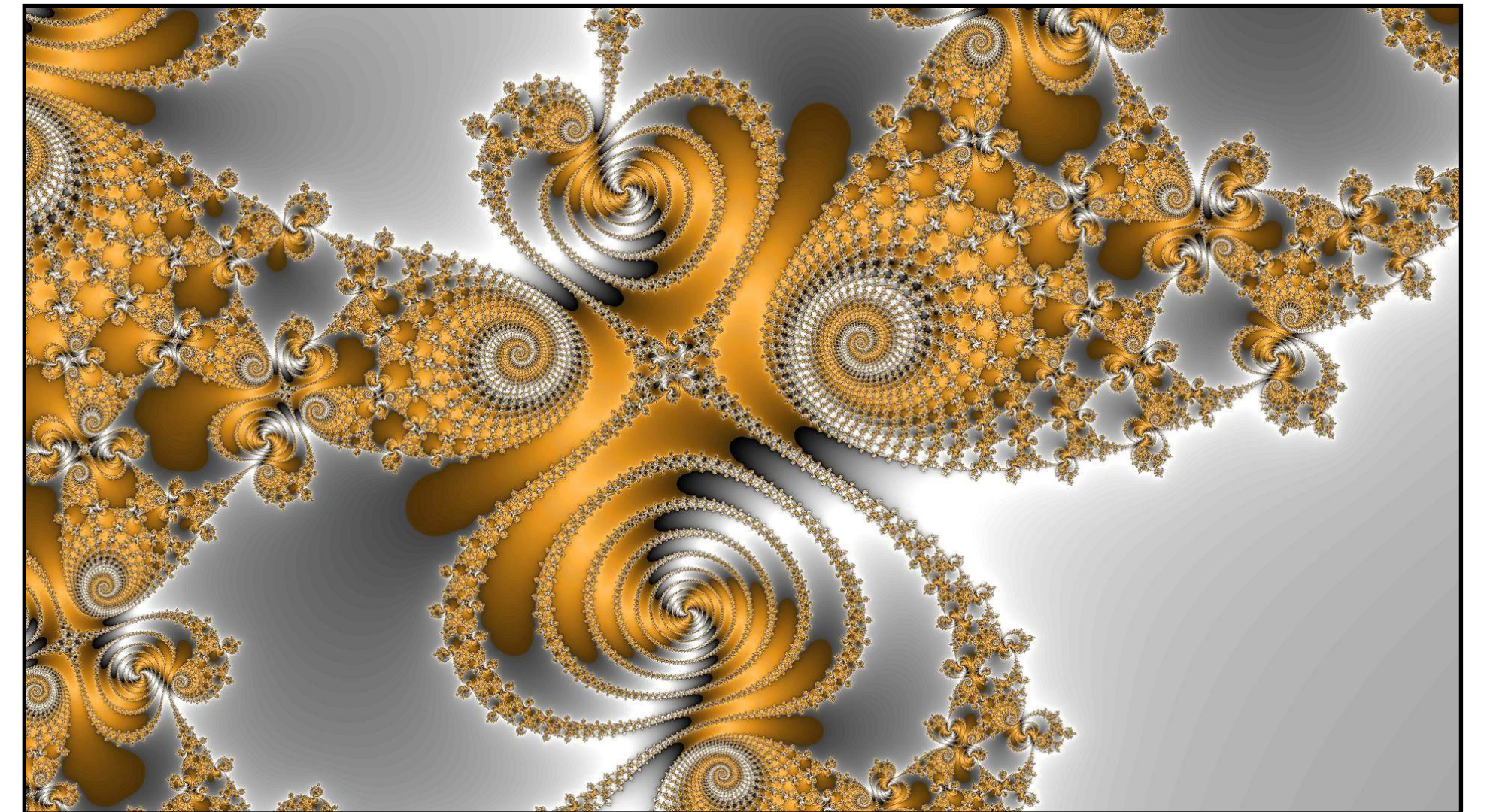
- » economics (stocks)
- » physical/chemical systems
- » populations
- » weather

An Aside: Chaos Theory



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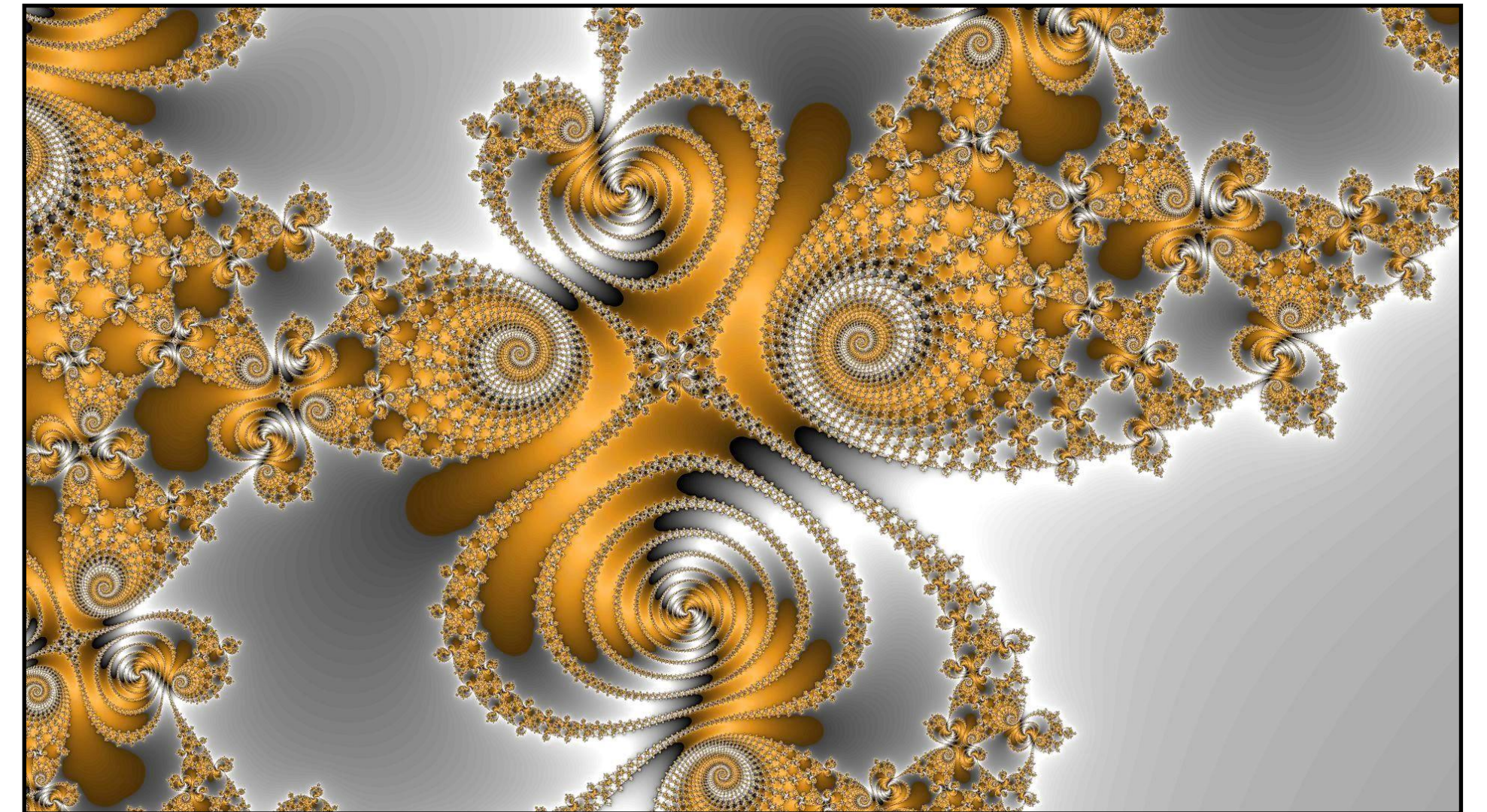
Complex systems like the weather
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An Aside: Chaos Theory

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But even in chaotic systems there are *underlying patterns* and *repeated structures*

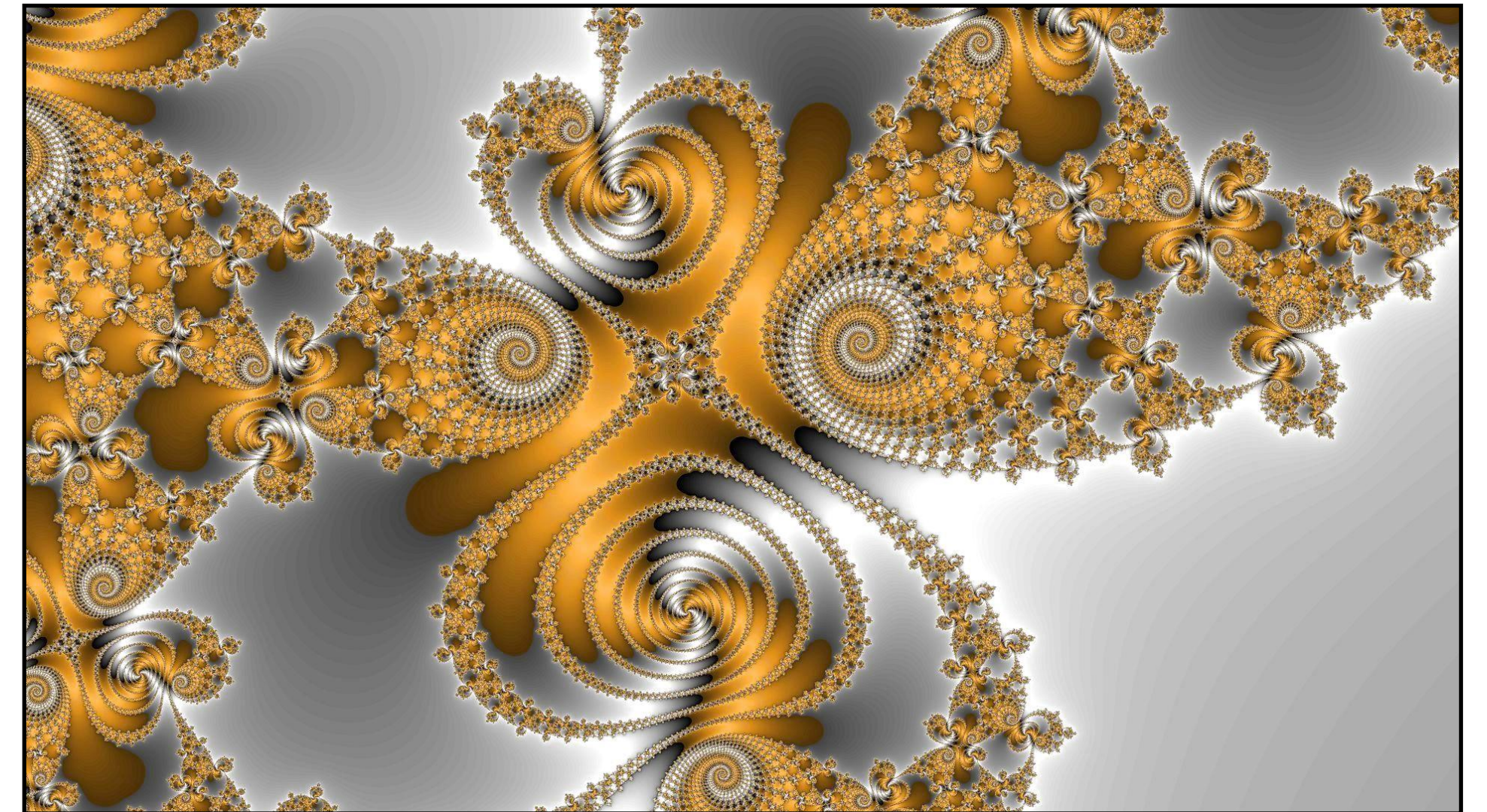


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Complex systems like the weather or the economy look nearly random

But even in chaotic systems there are *underlying patterns* and *repeated structures*

Often it's useful to consider chaotic systems in terms of global properties



Motivating Questions

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What does a dynamical system look like "in the long view?"

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Does it reach a kind of equilibrium? (think heat diffusion)

Or does some part of the system dominate over time? (think the population of rabbits without a predator)

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T A tells us how our system evolves over time

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State Vectors

$$\mathbf{v}_1 = A\mathbf{v}_0$$

$$\mathbf{v}_2 = A\mathbf{v}_1 = A(A\mathbf{v}_0)$$

$$\mathbf{v}_3 = A\mathbf{v}_2 = A(AA\mathbf{v}_0)$$

$$\mathbf{v}_4 = A\mathbf{v}_3 = A(AAA\mathbf{v}_0)$$

$$\mathbf{v}_5 = A\mathbf{v}_4 = A(AAAA\mathbf{v}_0)$$

\vdots

The state vector \mathbf{v}_k tells us what the system looks like after a number k time steps

This is also called a *recurrence relation* or a *linear difference function*

How to: Determining State Vectors

Question. Determine the state vector \mathbf{v}_i for the linear dynamical system with matrix A given the initial state vector \mathbf{v}_0

Solution. Compute

$$\mathbf{v}_i = A^i \mathbf{v}_0$$

Warm up: Population Dynamics

The Setup

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We're working for the census. We have population measurements for a city and a suburb which are geographically coincident

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We're working for the census. We have population measurements for a city and a suburb which are geographically coincident

We find by analyzing previous data that each year:

- » 5% of the population moves from city → suburb
- » 3% of the population moves from suburb → city

Fundamental Question

Can we make any predictions about the population of the city and suburb in 20 years?

Assumptions: No immigration, emigration, birth, death, etc. **The overall population stays fixed.**

Setting up Linear Equations

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If $\text{city}_0 = \text{city pop.} = 600,000$
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then the populations next year are given by:

$$\text{city}_1 = (0.95)\text{city}_0 + (0.03)\text{suburb}_0$$

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people who stayed

people who left

Setting up a Matrix

$$\begin{bmatrix} \text{city}_1 \\ \text{suburb}_1 \end{bmatrix} = \begin{bmatrix} 0.95 & 0.3 \\ 0.05 & 0.97 \end{bmatrix} \begin{bmatrix} \text{city}_0 \\ \text{suburb}_0 \end{bmatrix} = \begin{bmatrix} 582,000 \\ 418,000 \end{bmatrix}$$

We expect the population of the city to decrease in a year

Setting up a Matrix

$$\begin{bmatrix} \text{city}_2 \\ \text{suburb}_2 \end{bmatrix} = \begin{bmatrix} 0.95 & 0.3 \\ 0.05 & 0.97 \end{bmatrix} \begin{bmatrix} \text{city}_1 \\ \text{suburb}_1 \end{bmatrix} = \begin{bmatrix} 565,440 \\ 434,560 \end{bmatrix}$$

The next year, we expect the population of the city to *continue* to decrease

Will it decrease indefinitely?

Setting up a Matrix

$$\begin{bmatrix} \text{city}_k \\ \text{suburb}_k \end{bmatrix} = \begin{bmatrix} 0.95 & 0.3 \\ 0.05 & 0.97 \end{bmatrix} \begin{bmatrix} \text{city}_{k-1} \\ \text{suburb}_{k-1} \end{bmatrix}$$

This is a *linear dynamical system*

So we want to guess what the population will look like in 20 years, we need to compute

$$\begin{bmatrix} 0.95 & 0.03 \\ 0.05 & 0.97 \end{bmatrix}^{20} \begin{bmatrix} \text{city}_0 \\ \text{suburb}_0 \end{bmatrix}$$

demo

Markov Chains

Stochastic Matrices

$$\begin{bmatrix} 0.95 & 0.03 \\ 0.05 & 0.97 \end{bmatrix}$$

What's special about this matrix?

- » Its entries are nonnegative
- » Its columns sum to 1

This should make us think probability

Stochastic Matrices

Definition. A $n \times n$ matrix is **stochastic** if its entries are nonnegative and its columns sum to 1

Example.

$$\begin{bmatrix} 0.7 & 0.1 & 0.3 \\ 0.2 & 0.8 & 0.3 \\ 0.1 & 0.1 & 0.4 \end{bmatrix}$$

Markov Chains

Definition. A Markov chain is a linear dynamical system whose evolution function is given by a stochastic matrix

(We can construct a "chain" of state vectors, where each state vector only depends on the one before it)

Key Property of Stochastic Matrices

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Stochastic matrices redistribute the "stuff" in a vector.

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Theorem. For a stochastic matrix A and a vector \mathbf{v} ,

$$\begin{array}{c} \text{sum of entries of } \mathbf{v} \\ \parallel \\ \text{sum of entries of } A\mathbf{v} \end{array}$$

Key Property of Stochastic Matrices

The sum of the entries of \mathbf{v} can be computed as

$$\mathbf{1}^T \mathbf{v} = \langle \mathbf{1}, \mathbf{v} \rangle$$

So the previous statement can be written

$$\mathbf{1}^T (A\mathbf{v}) = \mathbf{1}^T \mathbf{v}$$

Key Property of Stochastic Matrices

$$\mathbf{1}^T(A\mathbf{v}) = \mathbf{1}^T\mathbf{v}$$

Let's verify this:

A is stochastic

More General Solutions

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In our example, we analyzed the dynamics of a *particular* population

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What if we're interested more generally in the behavior of the process for *any* population?

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What if we're interested more generally in the behavior of the process for *any* population?

We need to shift from a population vector to a population ***distribution*** vector

Returning to the Example

$$\begin{bmatrix} \text{city}_k \\ \text{suburb}_k \end{bmatrix} = \begin{bmatrix} 0.95 & 0.3 \\ 0.05 & 0.97 \end{bmatrix} \begin{bmatrix} \text{city}_{k-1} \\ \text{suburb}_{k-1} \end{bmatrix}$$

Returning to the Example

$$\begin{bmatrix} \text{city}_k \\ \text{suburb}_k \end{bmatrix} = \begin{bmatrix} 0.95 & 0.3 \\ 0.05 & 0.97 \end{bmatrix}^k \begin{bmatrix} \text{city}_0 \\ \text{suburb}_0 \end{bmatrix}$$

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But what if we start of with a different population?

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But what if we start of with a different population?

Do we have to do all our work over again?

Returning to the Example

$$\begin{bmatrix} \text{city}_k \\ \text{suburb}_k \end{bmatrix} = \begin{bmatrix} 0.95 & 0.3 \\ 0.05 & 0.97 \end{bmatrix}^k \begin{bmatrix} 0.6 \\ 0.4 \end{bmatrix}$$

60% of pop. in city
40% of pop. in suburb

Not really

But rather than thinking in terms of populations, we need to think about **how the population is distributed**

Probability Vectors

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These are really the same thing

Probability Vectors (Example)

The vector $\begin{bmatrix} 1/3 \\ 1/6 \\ 1/2 \end{bmatrix}$ represents the distribution where we choose:

1 with probability $1/3$

2 with probability $1/6$

3 with probability $1/2$

Probability Vectors (Example)

The vector $\begin{bmatrix} 0.6 \\ 0.4 \end{bmatrix}$ represented the distribution of the population, but we can also think of this as:

If we choose a random person from the population we'll get someone:

in the city with probability 0.6

in the suburbs with probability 0.4

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Since stochastic matrices preserve $\mathbf{1}^T \mathbf{v}$, they *transform* one distribution into another

Can we say something about how the distribution changes in the long run?

Steady-State Vectors

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Definition. A **steady-state vector** for a stochastic matrix A is a probability vector \mathbf{q} such that

$$A\mathbf{q} = \mathbf{q}$$

A steady-state vector is *not changed* by the stochastic matrix. They describe equilibrium distributions

Returning to the Example

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How do we interpret a steady-state vector for our example?

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The populations in the city and the suburb stay the same over time

Returning to the Example

How do we interpret a steady-state vector for our example?

The populations in the city and the suburb stay the same over time

The same number of people are moving into and out of the city each year

Fundamental Questions

Do steady states exist?

Are they unique?

How do we find them?

Finding Steady-State Vectors

$$Aq = q$$

Let's solve this equation for q :

Finding Steady-State Vectors

$$Aq - q = 0$$

Finding Steady-State Vectors

$$A\mathbf{q} - I\mathbf{q} = \mathbf{0}$$

Finding Steady-State Vectors

$$(A - I)\mathbf{q} = \mathbf{0}$$

Finding Steady-State Vectors

$$(A - I)\mathbf{q} = \mathbf{0}$$

This is a matrix equation so
we know how to solve it

How to: Steady-State Vectors

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How to: Steady-State Vectors

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Solution. Solve the equation $(A - I)\mathbf{x} = \mathbf{0}$ and find a solution whose entries sum to 1 (this will be possible given a free variable)

If there is no such solution, the system does not have a steady state

Example

$$\begin{bmatrix} 0.95 & 0.3 \\ 0.05 & 0.97 \end{bmatrix}$$

demo

Existence vs Convergence

If $(A - I)\mathbf{x} = \mathbf{0}$ infinitely many solutions, then it has a stable state

This does not mean:

- » the stable state is unique
- » the system converges to this state

Convergence

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And no vectors converge to the same stable state

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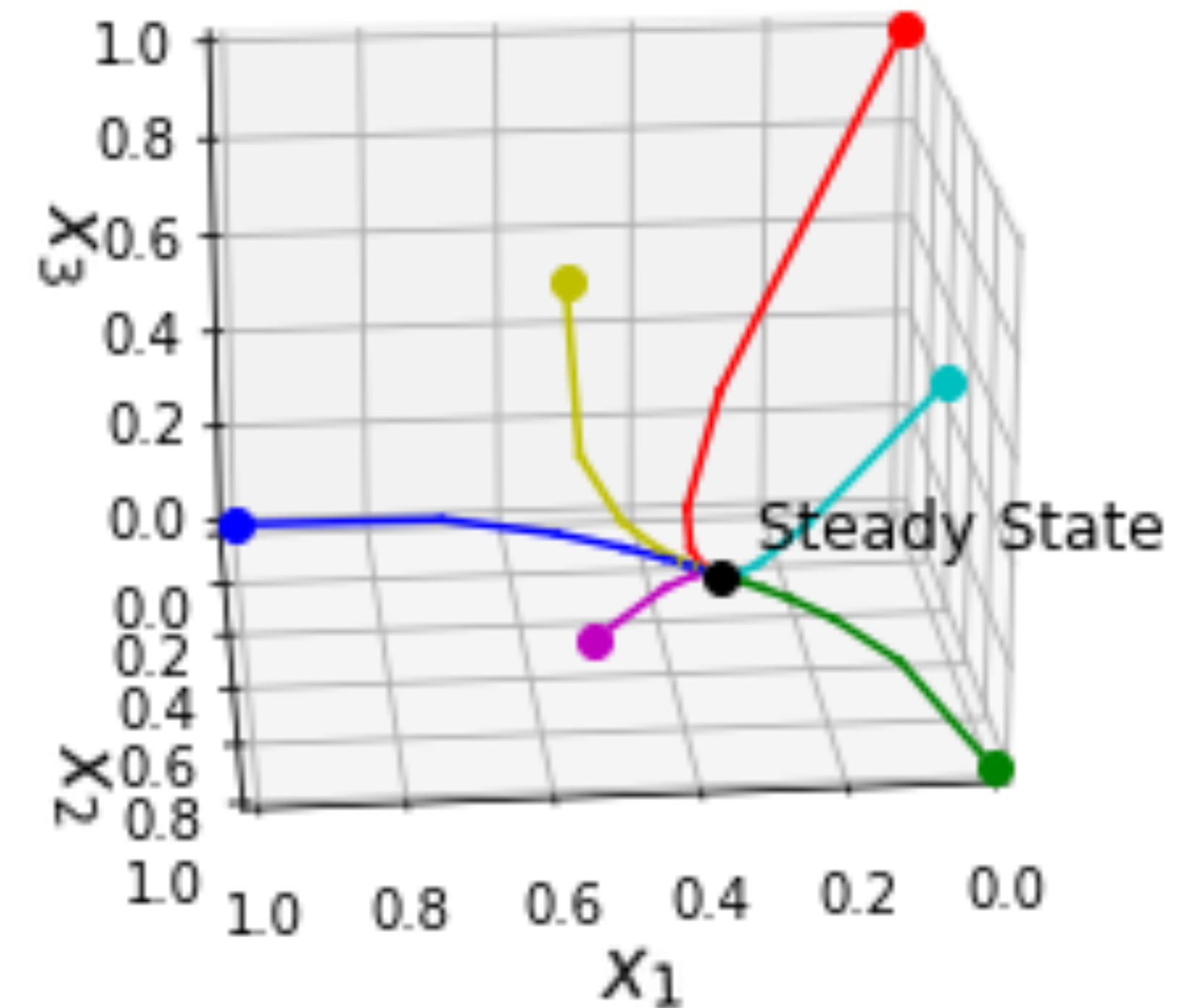
Theorem. A regular stochastic matrix P has a unique steady state, and

every probability vector
converges to it

Mixing

This process of converging to a unique steady state is called "mixing"

This theorem says, after some amount of mixing, we'll be close to the stable state, **no matter where we started**



How to: Regular Stochastic Matrices

Question. Show that A is regular, and then find its unique steady state

Solution. Find a power of A which has all positive entries, then solve the equation $(A - I)\mathbf{x} = \mathbf{0}$ as before

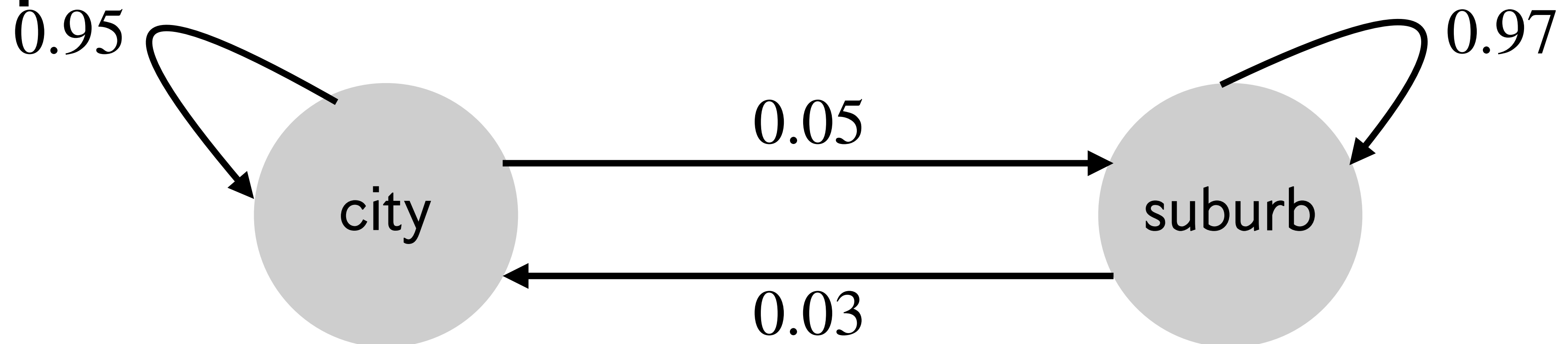
Example

$$\begin{bmatrix} 0.5 & 0.4 & 0 \\ 0.5 & 0.4 & 0.5 \\ 0 & 0.2 & 0.5 \end{bmatrix}$$

State Diagrams

Definition. A **state diagram** is a directed weighted graph whose adjacency matrix is stochastic.

Example.



Naming Convention Clash

The nodes of a state diagram are often called states

The vectors which are dynamically updated according to a linear dynamical system are called state vectors

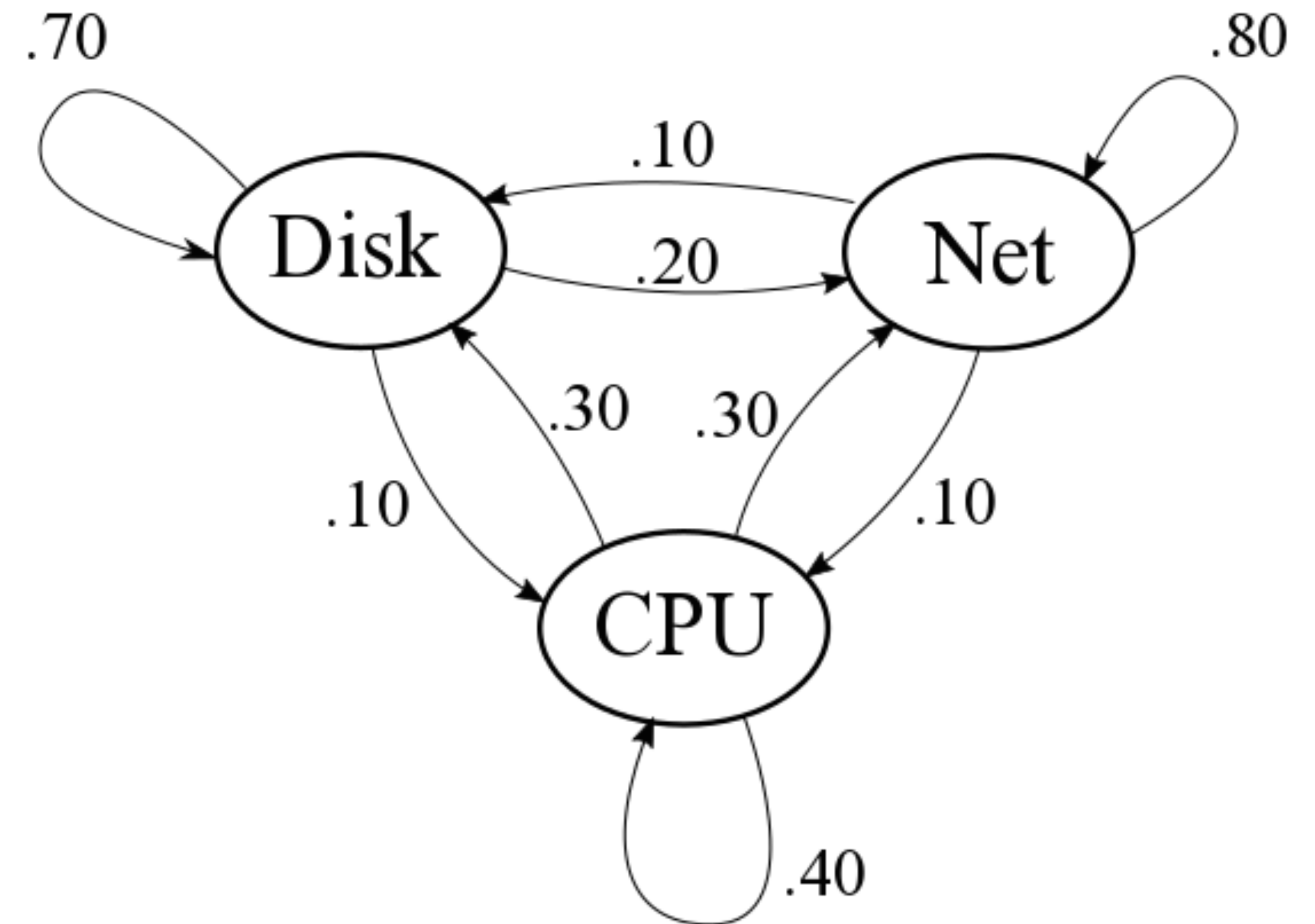
This is an unfortunate naming clash

Example: Computer System

Imagine a computer system in which tasks request service from disk, network or CPU

In the long term, which device is busiest?

This is about finding a stable state

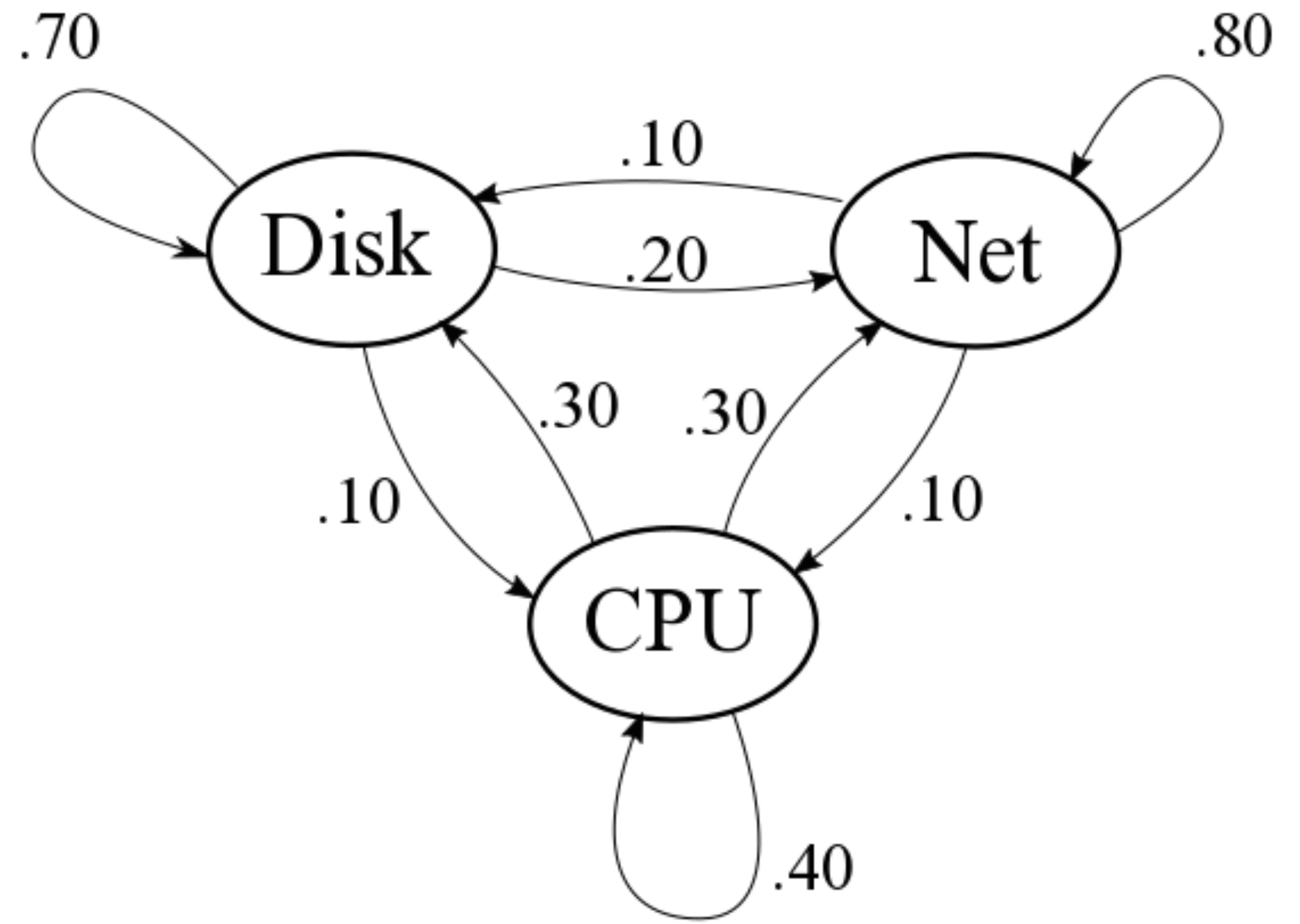


How To: State Diagram

Question. Given a state diagram, find the stable state for the corresponding linear dynamical system

Solution. Find the adjacency matrix for the state diagram and go from there

Example



Summary

Markov chains allow us to reason about dynamical systems that are dictated by some amount of randomness

Stable states represent global equilibrium