#### Some Recent Research Ideas

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- Let (Y, X, Z) be random variables equipped with some unknown joint distribution Q on  $\mathcal{Y} \times \mathcal{X} \times \mathcal{Z} \subset \mathbb{R} \times \mathbb{R} \times \mathbb{R}^d$ ;
- Let  $E_Q(Y|X=x,Z=z)=f(x,z;\theta)$  with f being some known function depending on a parameter  $\theta \in \Theta \subset \mathbb{R}^k$
- Suppose we have two datasets independently drawn from Q:  $\{Y_i^A, Z_i^A\}_{i=1}^N$  and  $\{X_i^B, Z_i^B\}_{i=1}^M$ . What can we learn about  $\theta$ ?

- Common approach frequently used to handle the problem described before is to predict  $X_i^A$  by  $Z_i^A$  from information in  $\{X_j^B, Z_j^B\}_{j=1}^M$ . That is:
  - Assume that  $E(X|Z=z)=g(z;\gamma)$  for some known g and unknown  $\gamma \in \Gamma \subset \mathbb{R}^p$ ;
  - Estimate  $\gamma$  using  $(X_i^B, Z_i^B)_{i=1}^M$ ;
  - ▶ In dataset A, use  $g(Z_i^A; \hat{\gamma})$  instead of absent  $X_i^A$  to estimate  $\theta$ .
- However, validity of the procedure described above relies heavily on functional forms of f and g;
- It requires some strong independence assumptions even when both f and g are linear (Ogburn et. al (2021)).

- Manski and Tamer (2002) focus on a similar problem where researcher also does not directly observe  $X_i$  but instead of auxiliary dataset has information on bounds of each  $X_i$ :  $\{Y_i, X_{l,i}, X_{u,i}, Z_i\}_{i=1}^N$ ,  $P(X_{l,i} \leq X_i \leq X_{u,i}) = 1$
- Using partial identification techniques, authors establish sharp bounds for  $\theta$ :

$$\mathcal{H}[\theta] = \{\theta \in \Theta : f(X_I, Z; \theta) \le E_Q[Y|X_I, X_u, Z] \le f(X_u, Z; \theta) \text{ a.s.}\}$$

• Perhaps, instead of using  $\{X_j^B, Z_j^B\}_{j=1}^M$  to predict  $X_i^A$  based on  $Z_i^A$ , we can use  $\{X_j^B, Z_j^B\}_{j=1}^M$  to estimate bounds of  $X_i^A | Z_i^A$  and then use Manski and Tamer (2002) approach to estimate sharp interval of  $\theta$ .

- To illustrate the idea, suppose that instead of having  $\{Y_i^A, Z_i^A\}_{i=1}^N$  and  $\{X_j^B, Z_j^B\}_{j=1}^M$ , we had only  $\{Y_i, Z_i\}_{i=1}^N$  and knowledge of support of X|Z=z for every realization of Z;
- Define the support of *X* as follows:

$$supp(X) = \{X \in \mathbb{R} : \forall r > 0, P_X(B(x,r)) > 0\}$$

- Assume that supp(X) is bounded;
- Define  $X_{l,i} = inf[supp(X|Z=Z_i)]$  and  $X_{u,i} = sup[supp(X|Z=Z_i)]$ . Now we may use Manski and Tamer techniques to estimate bounds of  $\theta$ .

- In reality, we do not have perfect knowledge of support of X|Z and only observe  $\{X_i^B, Z_i^B\}_{i=1}^M$ ;
- Still, perhaps we may use  $\{X_j^B, Z_j^B\}_{j=1}^M$  to come up with a procedure that would asymptotically resemble perfect knowledge of bounds of X|Z.

#### Idea Sketch

Assume that random vector Z has finite support:

$$supp(Z) = \{z_1, ..., z_l; P(Z = z_i) > 0, \forall i \in \{1, ..., l\}\}$$

• Partition  $\{X_j^B, Z_j^B\}_{j=1}^M$  into I sets defined as follows:

$$\forall i \in \{1, ..., I\}, A_i = \{(x, z) \in \{X_j^B, Z_j^B\}_{j=1}^M : z = z_i\}$$

- Define  $\hat{X}_{l,i} = inf_X A_i$  and  $\hat{X}_{u,i} = sup_X A_i$ . It could be shown that  $\hat{X}_{l,i} \stackrel{p}{\to} inf[supp(X|Z=z_i)]$  and  $\hat{X}_{u,i} \stackrel{p}{\to} sup[supp(X|Z=z_i)]$
- Hence, Manski and Tamer (2002) results could (hopefully) be applied without much change;
- If some dimension of Z is continuous/unbounded, we may use various discretization techniques.



### Difference-in-Differences when CVaR is an object of interest

- Oftentimes policymaker may be interested in estimating the effects of treatment on tails of distribution of respective treatment group (e.g., vaccine trials, change in insurance policy, etc.);
- Natural measure of weighted well-being in one of the tails of outcome distribution is CVaR (superquantile);
- Existing approach to superquantile regression (e.g., Rockafellar et. al 2014) does not allow for tractable characterization of ATT and hypothesis testing.

### Difference-in-Differences when CVaR is an object of interest

- Athey and Imbens (2006) present a technique using which it is possible to estimate entire counterfactual distribution of outcomes for the treatment group;
- As a result, their approach allowed to obtain estimator of  $\alpha$ -quantile ATT and deduce its asymptotic distribution;
- The same could be done for CVaR both for continuous and discrete outcomes.

### Athey and Imbens (2006) Setting

Let  $G \in \{0,1\}$  denote group and  $T \in \{0,1\}$  denote time.

Further, let  $Y_{g,t}^I$  and  $Y_{g,t}^N$  be random outcomes upon receiving and not receiving treatment conditional on G = g, T = t, respectively.

Authors are interested in estimates of ATT and  $\alpha$ -quantile ATT:

$$ATT = E[Y_{1,1}^{I}] - E[Y_{1,1}^{N}]$$

$$Q_{\alpha}(ATT) = F_{Y_{1,1}^{\prime}}^{-1}(\alpha) - F_{Y_{1,1}^{\prime}}^{-1}(\alpha)$$

### Athey and Imbens (2006) Results

Athey and Imbens show that under certain assumptions we can recover counterfactual distribution of outcomes for the treatment group:

$$F_{Y_{1,1}^N}(y) = F_{Y_{1,0}^N}(F_{Y_{0,0}^N}^{-1}(F_{Y_{0,1}^N}(y)))$$

As a result:

$$ATT = E[Y_{1,1}^I] - E[Y_{1,1}^N] = E[Y_{1,1}^I] - E[F_{Y_{0,1}^N}^{-1}(F_{Y_{0,0}^N}(Y_{1,0}^N))]$$

$$Q_{\alpha}(ATT) = F_{Y_{1,1}^{I}}^{-1}(\alpha) - F_{Y_{1,1}^{N}}^{-1}(\alpha) = F_{Y_{1,1}^{I}}^{-1}(\alpha) - F_{Y_{0,1}^{N}}^{-1}(F_{Y_{0,0}^{N}}(F_{Y_{1,0}^{N}}(q)))$$

Both expressions have finite-sample counterparts with tractable asymptotic characterization.

### Athey and Imbens (2006) application to CVaR

Recall that for continuous Y,  $CVaR_{\alpha} = \frac{1}{1-\alpha}E[I_{\{Y \geq F_{Y}^{-1}(\alpha)\}}Y]$ .

Hence, given the results described above, in case when Y is continuous it is straightforward to characterize  $CVaR_{\alpha}(ATT)$ , find its finite-sample counterpart and work out its asymptotic distribution.

Then, more advanced techniques could be adapted to do the same for discrete Y.