Cost-sensitive Boosting algorithms: Do we really need them?

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Adaboost (Freund & Schapire 1997)

Ensemble method - rich theoretical depth.

Train models sequentially.

Each model focuses on examples previously misclassified.

Combine by majority vote.

Define a distribution over the training set, $D_1(i) = \frac{1}{N}$, $\forall i$. for t = 1 to T do

Build a classifier h_t from the training set, using distribution D_t .

Set $\alpha_t = \frac{1}{2} \ln \left(\frac{1 - \epsilon_t}{\epsilon_t} \right)$ —— Majority voting confidence in classifier t Update D_{t+1} from D_t :

Set
$$D_{t+1}(i) = \frac{D_t(i)e^{-\alpha_t y_i h_t(x_i)}}{Z_t}$$
 — Distribution update

end for

$$H(x') = sign\Big(\sum_{t=1}^{T} \alpha_t h_t(x')\Big)$$
 ——— Majority vote on test example x'

Adaboost

How will it work on cost sensitive problems?

$$\begin{bmatrix} 0 & c_{FN} \\ c_{FP} & 0 \end{bmatrix}$$

i.e. with differing cost for a False Positive / False Negativedoes it minimize the expected cost?

```
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15+ boosting variantsover 20 years

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Some **re-invented** multiple times

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15+ boosting variantsover 20 years

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Most proposed as heuristic modifications to original AdaBoost

Many treat FP/FN costs as hyperparameters

A step back... Why is Adaboost interesting?

Functional Gradient Descent (Mason et al., 2000)

Decision Theory (Freund & Schapire, 1997)

Margin Theory (Schapire et al., 1998)

Probabilistic Modelling (Lebanon & Lafferty 2001; Edakunni et al 2011)

Set
$$\alpha_t = \frac{1}{2} \ln \left(\frac{1 - \epsilon_t}{\epsilon_t} \right)$$

Update D_{t+1} from D_t :
Set $D_{t+1}(i) = \frac{D_t(i)e^{-\alpha_t y_i h_t(x_i)}}{Z_t}$

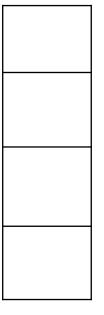
Functional Gradient Descent

Decision Theory

Margin Theory

Probabilistic Modelling

My new algorithm



"Does my new algorithm still follow from each?"

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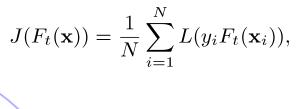


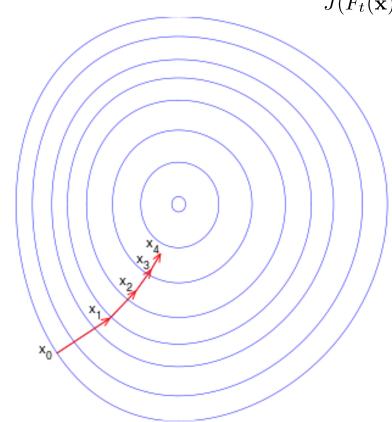


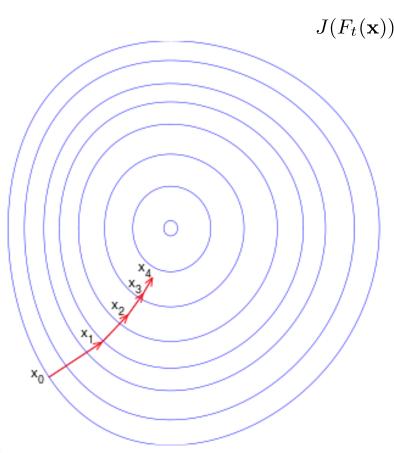
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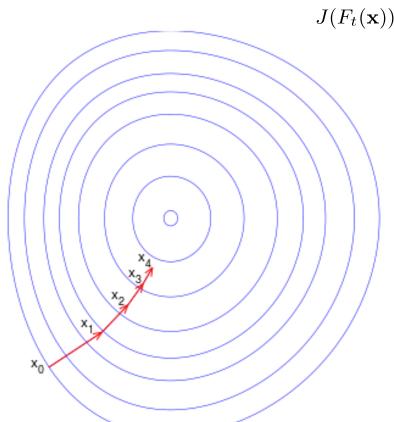






$$J(F_t(\mathbf{x})) = \frac{1}{N} \sum_{i=1}^{N} L(y_i F_t(\mathbf{x}_i)),$$

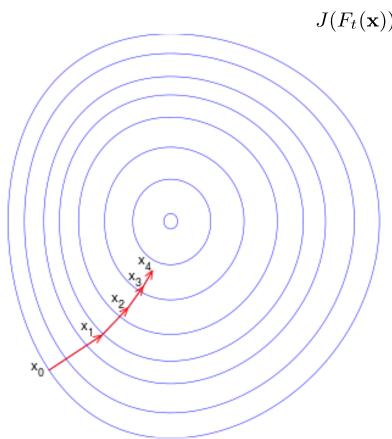
$$D_i^{t+1} = \frac{\frac{\partial}{\partial y_i F_t(\mathbf{x}_i)} J(F_t(\mathbf{x}))}{\sum_{j=1}^N \frac{\partial}{\partial y_j F_t(\mathbf{x}_j)} J(F_t(\mathbf{x}))}$$



$$J(F_t(\mathbf{x})) = \frac{1}{N} \sum_{i=1}^{N} L(y_i F_t(\mathbf{x}_i)),$$

Direction in function space

$$D_i^{t+1} = \frac{\frac{\partial}{\partial y_i F_t(\mathbf{x}_i)} J(F_t(\mathbf{x}))}{\sum_{j=1}^N \frac{\partial}{\partial y_j F_t(\mathbf{x}_j)} J(F_t(\mathbf{x}))}$$

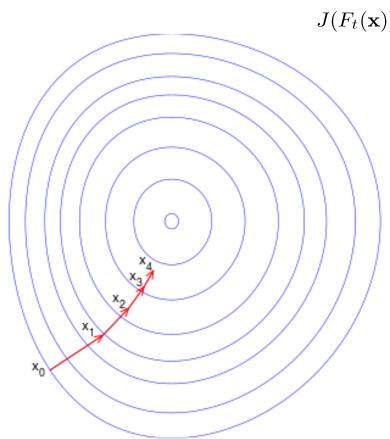


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$$\alpha_t^* = \arg\min_{\alpha_t} \left[\frac{1}{N} \sum_{i=1}^N L(y_i(F_{t-1}(\mathbf{x}_i) + \alpha_t h_t(\mathbf{x}_i))) \right].$$



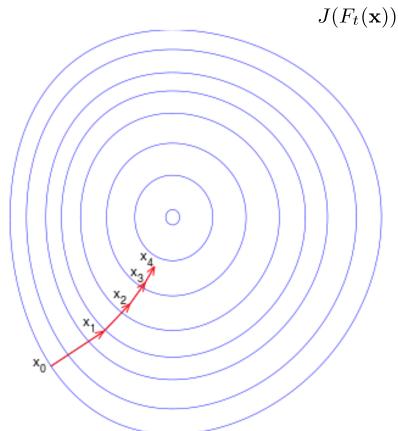
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Step size

$$\alpha_t^* = \arg\min_{\alpha_t} \left[\frac{1}{N} \sum_{i=1}^N L \left(y_i (F_{t-1}(\mathbf{x}_i) + \alpha_t h_t(\mathbf{x}_i)) \right) \right].$$



$$J(F_t(\mathbf{x})) = \frac{1}{N} \sum_{i=1}^{N} L(y_i F_t(\mathbf{x}_i)),$$

Direction in function space

$$D_i^{t+1} = \frac{\frac{\partial}{\partial y_i F_t(\mathbf{x}_i)} J(F_t(\mathbf{x}))}{\sum_{j=1}^{N} \frac{\partial}{\partial y_j F_t(\mathbf{x}_j)} J(F_t(\mathbf{x}))}$$

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Property: FGD-consistency

Are the voting weights and distribution updates consistent with each other?

(i.e. both derivable from FGD on a given loss)

Decision Theory

Ideally: Assign each example to risk-minimizing class.



$$\hat{p}(y=1|\mathbf{x}) > \frac{c_{FP}}{c_{FP} + c_{FN}}$$

$$\begin{bmatrix} 0 & c_{FN} \\ c_{FP} & 0 \end{bmatrix}$$

Decision Theory





$$\begin{bmatrix} 0 & c_{FN} \\ c_{FP} & 0 \end{bmatrix}$$

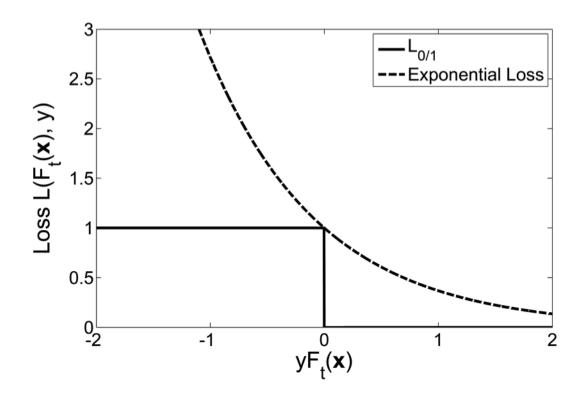
$$\hat{p}(y=1|\mathbf{x}) > \frac{c_{FP}}{c_{FP} + c_{FN}}$$

Property: Cost-consistency

Does the algorithm use the above (Bayes optimal) rule to make decisions?

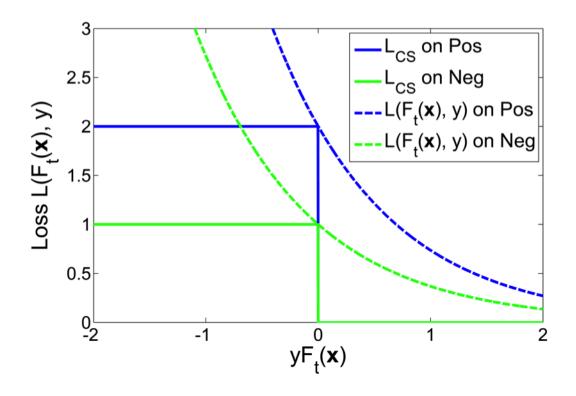
(assuming good probability estimates)

Margin Theory



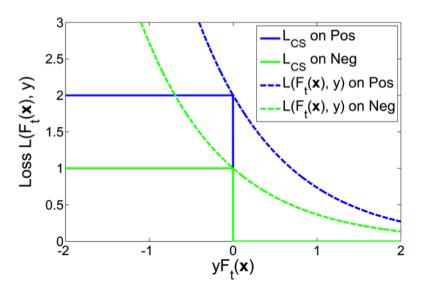
Large margins encourage small generalization error. Adaboost promotes large margins.

Margin Theory – with costs...

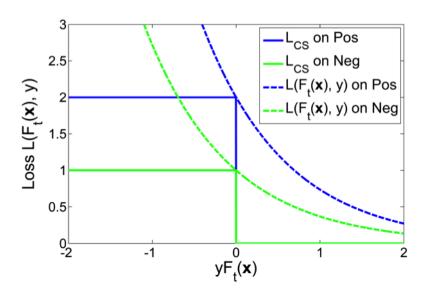


Different surrogate losses for each class.

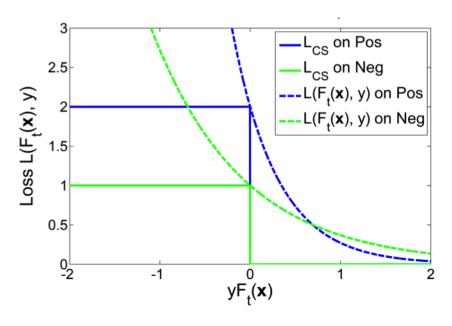
We expect this to be the case.



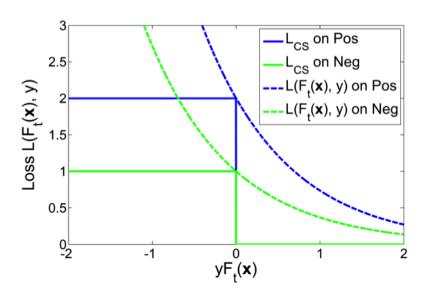
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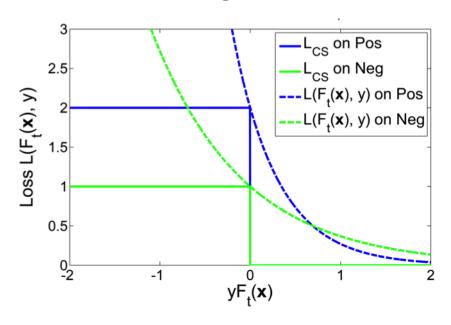
But some algorithms do this...



We expect this to be the case.



But some algorithms do this...



Property: Asymmetry preservation

Does the loss function preserve the **relative** importance of each class, for all margin values?

'AdaBoost does not produce good probability estimates.'

Niculescu-Mizil & Caruana, 2005

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'AdaBoost is successful at [..] classification [..] but not class probabilities.'

Mease et al., 2007

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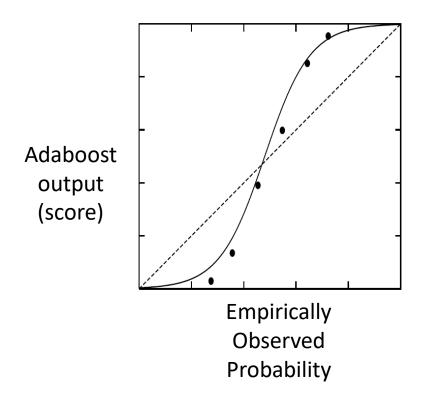
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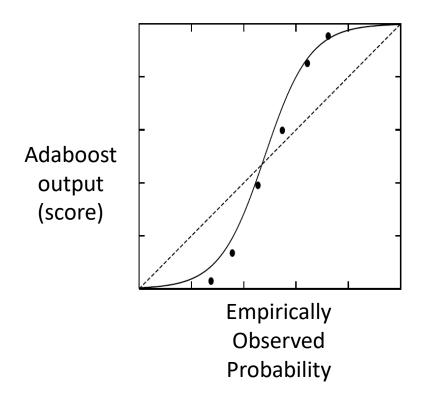
Mease et al., 2007

'This increasing tendency of [the margin] impacts the probability estimates by causing them to quickly diverge to 0 and 1.'

Mease & Wyner, 2008



Adaboost tends to produce overor under-estimates of probabilities.



Adaboost tends to produce overor under-estimates of probabilities.

Property: Calibrated estimates

Does the algorithm generate "calibrated" probability estimates?

The results are in...

Method	FGD-	Cost-	Asymmetry-	Calibrated
	consistent	consistent	preserving	estimates
AdaBoost (Freund & Schapire 1997)	1		✓	
AdaCost (Fan et al. 1999)				
$AdaCost(\beta_2)$ (Ting 2000)				
CSB0 (Ting 1998)			✓	
CSB1 (Ting 2000)			✓	
CSB2 (Ting 2000)			✓	
AdaC1 (Sun et al. 2005, 2007)		✓		
AdaC2 (Sun et al. 2005, 2007)	✓		✓	
AdaC3 (Sun et al. 2005, 2007)				
CSAda (Mashnadi-Shirazi & Vasconselos 2007, 2011)	✓	✓		
AdaDB (Landesa-Vázquez & Alba-Castro 2013)	✓	✓		
AdaMEC (Ting 2000, Nikolaou & Brown 2015)	✓	✓	✓	
CGAda (Landesa-Vázquez & Alba-Castro 2012, 2015)	✓	✓	✓	
AsymAda (Viola & Jones 2002)	✓	✓	✓	

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AdaCost (Fan et al. 1999)				
$AdaCost(\beta_2)$ (Ting 2000)				
CSB0 (Ting 1998)			✓	All
CSB1 (Ting 2000)			✓	algorithms
CSB2 (Ting 2000)			✓	produce
AdaC1 (Sun et al. 2005, 2007)		✓		uncalibrated
AdaC2 (Sun et al. 2005, 2007)	✓		✓	probability
AdaC3 (Sun et al. 2005, 2007)				estimates!
CSAda (Mashnadi-Shirazi & Vasconselos 2007, 2011)	✓	✓		Commutees
AdaDB (Landesa-Vázquez & Alba-Castro 2013)	✓	✓		
AdaMEC (Ting 2000, Nikolaou & Brown 2015)	✓	✓	✓	
CGAda (Landesa-Vázquez & Alba-Castro 2012, 2015)	✓	✓	✓	
AsymAda (Viola & Jones 2002)	✓	✓	✓	

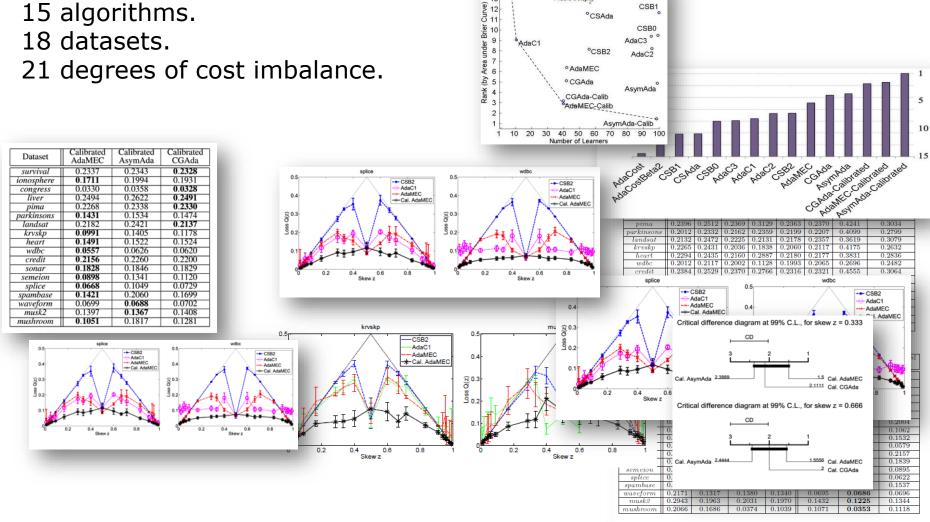
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CSAda (Mashnadi-Shirazi & Vasconselos 2007, 2011)	✓	✓		estimates.
AdaDB (Landesa-Vázquez & Alba-Castro 2013)	1	✓		
AdaMEC (Ting 2000, Nikolaou & Brown 2015)	√	✓	✓	
CGAda (Landesa-Vázquez & Alba-Castro 2012, 2015)	 	✓	✓	
AsymAda (Viola & Jones 2002)	✓	✓	✓	

So could we just calibrate these last three? We use "Platt scaling".

Experiments

15 algorithms.

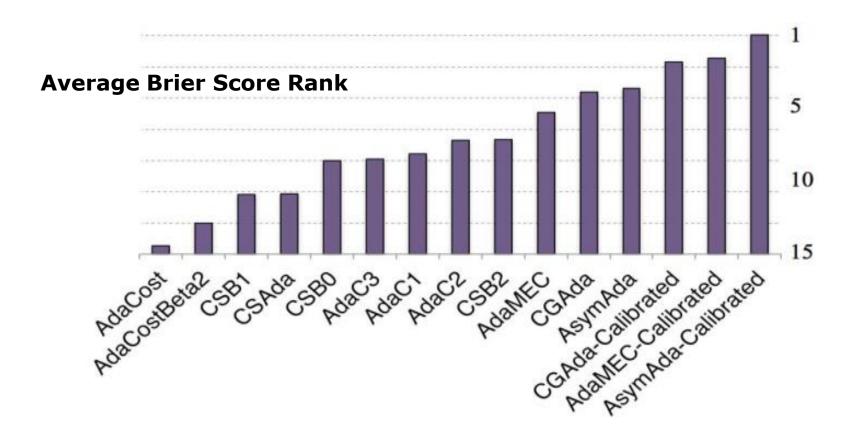


AdaCost

13

^oAdaCost(β_o)

CSB1



AdaMEC, CGAda & AsymAda outperform all others.

Their calibrated versions outperform the uncalibrated ones

"Calibrated-AdaMEC" was one of the top methods.

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- 1. Take <u>original</u> Adaboost.
- 2. Calibrate it (we use Platt scaling)
- 3. Shift the decision threshold...: $\frac{c_{FP}}{c_{FP}+c_{FN}}$

"Calibrated-AdaMEC" was one of the top methods.

- 1. Take <u>original</u> Adaboost.
- 2. Calibrate it (we use Platt scaling)
- 3. Shift the decision threshold.... $\frac{c_{FP}}{c_{FP}+c_{FN}}$

Consistent with all theory perspectives.

No extra hyperparameters added.

No need to retrain if cost ratio changes.

Consistently top (or joint top) in empirical comparisons.

Conclusions

We analyzed the cost-sensitive boosting literature

... 15+ variants over 20 years, from 4 different theoretical perspectives

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"Cost sensitive" modifications to the original Adaboost are not needed...

<u>... if</u> the scores are properly calibrated,<u>and</u> the decision rule is shifted according to the cost matrix.

Conclusions

We analyzed the cost-sensitive boosting literature

... 15+ variants over 20 years, from 4 different theoretical perspectives

"Cost sensitive" modifications to the original Adaboost are not needed...

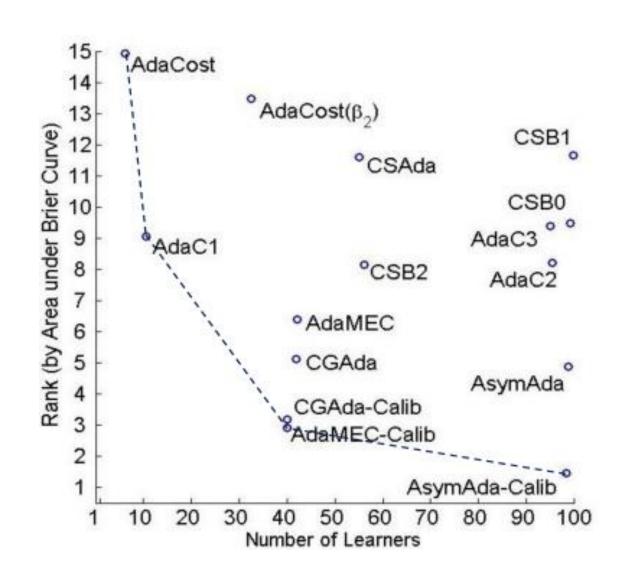
<u>... if</u> the scores are properly calibrated,<u>and</u> the decision rule is shifted according to the cost matrix.

Thank you!

Grazie!

Area under the Brier (cost) curve

Look at the pareto front!



A closer look at the Brier Curves.

