# Chapter 1f Program Verification

Mathematical Modeling (CO2011)

(Materials drawn from:

"Michael Huth and Mark Ryan. Logic in Computer Science: Modelling and Reasoning about Systems, 2nd Ed., Cambridge University Press, 2006.")

# Nguyen An Khuong

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#### **Program Verification**

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Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

### **Contents**

- 1 Core Programming Language
- 2 Hoare Triples; Partial and Total Correctness
- **3** Proof Calculus for Partial Correctness
- **4** Practical Aspects of Correctness Proofs
- **6** Correctness of the Factorial Function
- 6 Proof Calculus for Total Correctness
- **7** Homeworks

#### **Program Verification**

Nguyen An Khuong



#### **Contents**

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

### **Motivation**

### **Program Verification**

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- One way of checking the correctness of programs is to explore the possible states that a computation system can reach during the execution of the program.
- Problems with this *model checking* approach:
  - Models become infinite.
  - Satisfaction/validity becomes undecidable.
- In this lecture, we cover a proof-based framework for program verification.

#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# **Characteristics of the Approach**

Proof-based instead of model checking

Semi-automatic instead of automatic

Property-oriented not using full specification

Application domain fixed to sequential programs using integers

Interleaved with development rather than a-posteriori verification

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#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# **Reasons for Program Verification**

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**Program Verification** 



Documentation. Program properties formulated as theorems can serve as concise documentation

Time-to-market. Verification prevents/catches bugs and can reduce development time

Reuse. Clear specification provides basis for reuse

Certification. Verification is required in safety-critical domains such as nuclear power stations and aircraft cockpits

#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

### Framework for Software Verification

Convert informal description R of requirements for an application domain into formula  $\phi_R$ .

Write program P that meets  $\phi_R$ .

Prove that P satisfies  $\phi_R$ .

Each step provides risks and opportunities.

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#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

### **Program Verification**

Nguyen An Khuong



Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

Homeworks

**1** Core Programming Language

- 2 Hoare Triples; Partial and Total Correctness
- **3** Proof Calculus for Partial Correctness
- **4** Practical Aspects of Correctness Proofs
- **6** Correctness of the Factorial Function
- **6** Proof Calculus for Total Correctness
- Momeworks

# **Motivation of Core Language**

- Real-world languages are quite large; many features and constructs
- Verification framework would exceed time we have in CS5209
- Theoretical constructions such as Turing machines or lambda calculus are too far from actual applications; too low-level
- Idea: use subset of Pascal/C/C++/Java
- Benefit: we can study useful "realistic" examples

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#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# **Expressions in Core Language**

Expressions come as arithmetic expressions E:

$$E ::= n \mid x \mid (-E) \mid (E + E) \mid (E - E) \mid (E * E)$$

and boolean expressions B:

$$B ::= \mathtt{true} \mid \mathtt{false} \mid (!B) \mid (B \& B) \mid (B \parallel B) \mid (E < E)$$

Where are the other comparisons, for example ==?

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Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# **Commands in Core Language**

Commands cover some common programming idioms. Expressions are components of commands.

$$C ::= x = E \mid C; C \mid \text{if } B \mid C$$
 else  $\{C\} \mid \text{while } B \mid C \}$ 

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#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

### Consider the factorial function:

$$0! \stackrel{\text{def}}{=} 1$$
$$(n+1)! \stackrel{\text{def}}{=} (n+1) \cdot n!$$

We shall show that after the execution of the following Core program, we have y=x!.

```
y = 1;
z = 0;
while (z != x) { z = z + 1; y = y * z; }
```

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#### Contents

# Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

### **Program Verification**

Nguyen An Khuong



Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

Homeworks

**1** Core Programming Language

- **2** Hoare Triples; Partial and Total Correctness
- **3** Proof Calculus for Partial Correctness
- **4** Practical Aspects of Correctness Proofs
- **6** Correctness of the Factorial Function
- **6** Proof Calculus for Total Correctness
- **7** Homeworks

```
y = 1;
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### **Program Verification**

Nguyen An Khuong



Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

```
y = 1;
z = 0;
while (z != x) { z = z + 1; y = y * z; }
```

We need to be able to say that at the end, y is x!

#### **Program Verification**

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Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

```
y = 1;
z = 0;
while (z != x) { z = z + 1; y = y * z; }
```

- We need to be able to say that at the end, y is x!
- That means we require a post-condition y = x!

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Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

```
y = 1;
z = 0;
while (z != x) { z = z + 1; y = y * z; }
```

• Do we need pre-conditions, too?

#### **Program Verification**

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Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

```
y = 1;
z = 0;
while (z != x) { z = z + 1; y = y * z; }
```

Do we need pre-conditions, too?
 Yes, they specify what needs to be the case before execution.

Example: x > 0

### **Program Verification**

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Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

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y = 1;
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Do we need pre-conditions, too?
 Yes, they specify what needs to be the case before execution.

Example: x > 0

• Do we have to prove the postcondition in one go?

### **Program Verification**

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Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

```
y = 1;
z = 0;
while (z != x) { z = z + 1; y = y * z; }
```

Do we need pre-conditions, too?
 Yes, they specify what needs to be the case before execution.

Example: x > 0

Do we have to prove the postcondition in one go?
 No, the postcondition of one line can be the pre-condition of the next!

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**Contents** 

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# **Assertions on Programs**

### **Shape of assertions**

$$(\phi) P (\psi)$$

### **Informal meaning**

If the program P is run in a state that satisfies  $\phi$ , then the state resulting from P's execution will satisfy  $\psi$ .

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Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# (Slightly Trivial) Example

### **Informal specification**

Given a positive number x, the program P calculates a number y whose square is less than x.

### **Assertion**

$$(x > 0) P (y \cdot y < x)$$

# Example for P

$$y = 0$$

## Our first Hoare triple

$$(x > 0) y = 0 (y \cdot y < x)$$

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#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# (Slightly Less Trivial) Example

### Same assertion

$$(x > 0) P (y \cdot y < x)$$

### Another example for P

```
y = 0;
while (y * y < x) {
y = y + 1;
}
y = y - 1;</pre>
```

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Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# **Recall: Models in Predicate Logic**

### **Definition**

Let  $\mathcal F$  contain function symbols and  $\mathcal P$  contain predicate symbols. A model  $\mathcal M$  for  $(\mathcal F,\mathcal P)$  consists of:

- $\bullet$  A non-empty set A, the *universe*;
- 2 for each nullary function symbol  $f \in \mathcal{F}$  a concrete element  $f^{\mathcal{M}} \in A$ ;
- 3 for each  $f \in F$  with arity n > 0, a concrete function  $f^{\mathcal{M}}: A^n \to A$ ;
- 4 for each  $P \in \mathcal{P}$  with arity n > 0, a set  $P^{\mathcal{M}} \subseteq A^n$ .

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Nguyen An Khuong



Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

### **Recall: Satisfaction Relation**

The model  $\mathcal{M}$  satisfies  $\phi$  with respect to environment l, written  $\mathcal{M} \models_l \phi$ :

- in case  $\phi$  is of the form  $P(t_1, t_2, \ldots, t_n)$ , if the result  $(a_1, a_2, \ldots, a_n)$  of evaluating  $t_1, t_2, \ldots, t_n$  with respect to l is in  $P^{\mathcal{M}}$ ;
- in case  $\phi$  has the form  $\forall x\psi$ , if the  $\mathcal{M}\models_{l[x\mapsto a]}\psi$  holds for all  $a\in A$ ;
- in case  $\phi$  has the form  $\exists x \psi$ , if the  $\mathcal{M} \models_{l[x \mapsto a]} \psi$  holds for some  $a \in A$ ;

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#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# **Recall: Satisfaction Relation (continued)**

- in case  $\phi$  has the form  $\neg \psi$ , if  $\mathcal{M} \models_l \psi$  does not hold;
- in case  $\phi$  has the form  $\psi_1 \vee \psi_2$ , if  $\mathcal{M} \models_l \psi_1$  holds or  $\mathcal{M} \models_l \psi_2$  holds;
- in case  $\phi$  has the form  $\psi_1 \wedge \psi_2$ , if  $\mathcal{M} \models_l \psi_1$  holds and  $\mathcal{M} \models_l \psi_2$  holds; and
- in case  $\phi$  has the form  $\psi_1 \to \psi_2$ , if  $\mathcal{M} \models_l \psi_1$  holds whenever  $\mathcal{M} \models_l \psi_2$  holds.

#### **Program Verification**

Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# **Hoare Triples**

### **Definition**

An assertion of the form  $(\phi) P (\psi)$  is called a Hoare triple.

- ullet  $\phi$  is called the precondition,  $\psi$  is called the postcondition.
- A state of a Core program P is a function l that assigns each variable x in P to an integer l(x).
- A state l satisfies  $\phi$  if  $\mathcal{M} \models_l \phi$ , where  $\mathcal{M}$  contains integers and gives the usual meaning to the arithmetic operations.
- Quantifiers in  $\phi$  and  $\psi$  bind only variables that do *not* occur in the program P.

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Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

Let l(x) = -2, l(y) = 5 and l(z) = -1. We have:

- $l \models \neg (x + y < z)$
- $l \not\models y = x \cdot z < z$
- $l \not\models \forall u(y < u \rightarrow y \cdot z < u \cdot z)$

#### **Program Verification**

Nguyen An Khuong



Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

### **Partial Correctness**

### **Definition**

We say that the triple  $(\phi)$  P  $(\psi)$  is satisfied under partial correctness if, for all states which satisfy  $\phi$ , the state resulting from P's execution satisfies  $\psi$ , provided that P terminates.

### **Notation**

We write  $\models_{par} (\phi) P (\psi)$ .

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Nguyen An Khuong



Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# **Extreme Example**

$$(\phi)$$
 while true { x = 0; }  $(\psi)$ 

holds for all  $\phi$  and  $\psi$ .

#### **Program Verification**

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#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

### **Total Correctness**

### **Definition**

We say that the triple  $(\phi) P (\psi)$  is satisfied under total correctness if, for all states which satisfy  $\phi$ , P is guaranteed to terminate and the resulting state satisfies  $\psi$ .

### **Notation**

We write  $\models_{\text{tot}} (\phi) P (\psi)$ .

### **Program Verification**

Nguyen An Khuong



Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

### Consider Fac1:

```
y = 1;
z = 0;
while (z != x) { z = z + 1; y = y * z; }
```

### **Program Verification**

Nguyen An Khuong



Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

### Consider Fac1:

```
y = 1;
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while (z != x) { z = z + 1; y = y * z; }
```

•  $\models_{\text{tot}} (x \ge 0)$  Fac1 (y = x!)

#### **Program Verification**

#### Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

### Consider Fac1:

```
y = 1;
z = 0;
while (z != x) { z = z + 1; y = y * z; }
```

- $\models_{\text{tot}} (x \ge 0)$  Fac1 (y = x!)
- $\not\models_{\text{tot}} (\!(\top)\!) \text{ Fac1 } (\!(y=x!)\!)$

### **Program Verification**

#### Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

### Consider Fac1:

```
y = 1;
z = 0;
while (z != x) { z = z + 1; y = y * z; }
```

- $\models_{\text{tot}} (x \ge 0)$  Fac1 (y = x!)
- $\not\models_{\mathrm{tot}} (\!\!\mid \top \!\!\mid) \; \mathsf{Fac1} \; (\!\!\mid y = x! \!\!\mid)$
- $\models_{\text{par}} (x \ge 0)$  Fac1 (y = x!)

### **Program Verification**

#### Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

### Consider Fac1:

```
y = 1;
z = 0;
while (z != x) { z = z + 1; y = y * z; }
```

- $\models_{\text{tot}} (x \ge 0)$  Fac1 (y = x!)
- $\not\models_{\mathrm{tot}} (\!\!\mid \top \!\!\!\mid)$  Fac1 (y = x!)
- $\models_{\text{par}} (x \ge 0)$  Fac1 (y = x!)
- $\models_{\text{par}} (\top) \text{ Fac1 } (y = x!)$

### **Program Verification**

#### Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

### **Program Verification**

Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

# Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

Homeworks

**1** Core Programming Language

2 Hoare Triples; Partial and Total Correctness

- **3** Proof Calculus for Partial Correctness
- **4** Practical Aspects of Correctness Proofs
- **6** Correctness of the Factorial Function
- **6** Proof Calculus for Total Correctness
- **7** Homeworks

# **Strategy**

We are looking for a proof calculus that allows us to establish

$$\vdash_{\mathrm{par}} (\!\!(\phi)\!\!) P (\!\!(\psi)\!\!)$$

## where

- $\models_{par} (\!\!| \phi \!\!|) P (\!\!| \psi \!\!|)$  holds whenever  $\vdash_{par} (\!\!| \phi \!\!|) P (\!\!| \psi \!\!|)$  (correctness), and
- $\vdash_{par} (\!\! | \phi \!\! ) P (\!\! | \psi \!\! )$  holds whenever  $\models_{par} (\!\! | \phi \!\! ) P (\!\! | \psi \!\! )$  (completeness).

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Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

## **Rules for Partial Correctness**

$$(\phi) C_1 (\eta) (\eta) C_2 (\psi)$$

$$(\phi) C_1; C_2 (\psi)$$
[Composition]

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#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# Rules for Partial Correctness (continued)

[Assignment] 
$$([x \to E]\psi) \ x = E \ (\psi)$$

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### Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# **Examples**

Let P be the program x = 2. Using

[Assignment] 
$$([x \to E]\psi) \ x = E \ (\psi)$$

we can prove:

• 
$$(2=2) P (x=2)$$

• 
$$(2=4) P (x=4)$$

• 
$$(2 = y) P (x = y)$$

• 
$$(2 > 0) P (x > 0)$$

## **Program Verification**

Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# **More Examples**

Let P be the program x = x + 1. Using

we can prove:

• 
$$(x+1=2)$$
  $P(x=2)$ 

• 
$$(x+1=y) P (x=y)$$

## **Program Verification**

Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# **Rules for Partial Correctness (continued)**

$$(\phi \land B) \ C_1 \ (\psi) \qquad (\phi \land \neg B) \ C_2 \ (\psi)$$

$$(\phi) \ \text{if} \ B \ \{ \ C_1 \ \} \ \text{else} \ \{ \ C_2 \ \} \ (\psi)$$

## **Program Verification**

Nguyen An Khuong



Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# Rules for Partial Correctness (continued)

$$\vdash_{AR} \phi' \to \phi \qquad (\phi) C (\psi) \qquad \vdash_{AR} \psi \to \psi'$$

$$(\phi) C (\psi)$$

$$\vdash_{AR} \psi \rightarrow \psi'$$

[Implied]

$$(\phi') C (\psi')$$

### **Program Verification**

### Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

**Proof Calculus for** Partial Correctness

Practical Aspects of **Correctness Proofs** 

Correctness of the **Factorial Function** 

**Proof Calculus for Total Correctness** 

## **Proof Tableaux**

# **Proofs have tree shape**

All rules have the structure

something

something else

As a result, all proofs can be written as a tree.

## **Practical concern**

These trees tend to be very wide when written out on paper. Thus we are using a linear format, called *proof tableaux*.

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Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

## Interleave Formulas with Code

$$\frac{(\phi) C_1 (\eta) (\eta) C_2 (\psi)}{(\phi) C_1; C_2 (\psi)}$$
[Composition]

Shape of rule suggests format for proof of  $C_1; C_2; \ldots; C_n$ :

```
(\phi_0)
C_1;
(\phi_1) justification C_2;
```

 $(\phi_n)$  justification

### **Program Verification**

### Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# **Working Backwards**

# Overall goal

Find a proof that at the end of executing a program P, some condition  $\psi$  holds.

## **Common situation**

If P has the shape  $C_1; \ldots; C_n$ , we need to find the weakest formula  $\psi'$  such that

$$(\psi')$$
  $C_n$   $(\psi)$ 

## **Terminology**

The weakest formula  $\psi'$  is called *weakest precondition*.

### **Program Verification**

Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# **E**xample

### **Program Verification**

### Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# **Another Example**

u = z;

(u = x + y)

```
(\top)
(x + y = x + y) Implied
z = x;
(z + y = x + y) Assignment
z = z + y;
```

Assignment

(z = x + y) Assignment

Can we claim u = x + y after z = x; z = z + y; u = z; ?

### **Program Verification**

#### Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

## An Alternative Rule for If

We have:

Sometimes, the following *derived rule* is more suitable:

$$(\phi_1) C_1 (\psi) \qquad (\phi_2) C_2 (\psi)$$

 $(B \rightarrow \phi_1) \land (\neg B \rightarrow \phi_2)$  if  $B \in C_1$  else  $\{C_2 \in \psi\}$ 

### **Program Verification**

Nguyen An Khuong



#### **Contents**

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

 $[If\text{-}stmt^{\text{Total}}_{2}]^{\text{Correctness}}_{\text{Homeworks}}$ 

# **E**xample

# Consider this implementation of Succ:

```
a = x + 1;
if (a - 1 == 0) {
y = 1;
} else {
y = a;
}
```

Can we prove  $(\top)$  Succ (y = x + 1)?

## **Program Verification**

#### Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# **Another Example**

```
 \begin{array}{ll} \vdots \\ \text{if (a - 1 == 0) } \{ \\ & (1 = x + 1) \\ & y = 1; \\ & (y = x + 1) \\ & \text{Assignment} \\ \} \text{ else } \{ \\ & (a = x + 1) \\ & y = a; \\ & (y = x + 1) \\ & \text{Assignment} \\ \} \\ & (y = x + 1) \\ & \text{If-Statement 2} \\ \end{array}
```

### **Program Verification**

### Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# **Another Example**

$$\begin{array}{lll} (\top) \\ ((x+1-1=0\to 1=x+1) \land \\ (\neg (x+1-1=0)\to x+1=x+1)) & \text{Implied} \\ \mathbf{a}=\mathbf{x}+\mathbf{1}; \\ ((a-1=0\to 1=x+1) \land \\ (\neg (a-1=0)\to a=x+1)) & \text{Assignment} \\ \text{if (a-1=0)} & \mathbf{a}=x+1) & \text{If-Statement 2} \\ \mathbf{y}=\mathbf{1}; & (y=x+1) & \text{Assignment} \\ \mathbf{y}=\mathbf{1}; & (y=x+1) & \text{Assignment} \\ \mathbf{blue} & \mathbf{a} & \mathbf{blue} &$$

#### **Program Verification**

#### Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

## Recall: Partial-while Rule

$$(\psi \wedge B) C (\psi)$$

[Partial-while]

 $(\psi)$  while B { C }  $(\psi \land \neg B)$ 

### **Program Verification**

### Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# **Factorial Example**

We shall show that the following Core program Fac1 meets this specification:

```
y = 1;
z = 0;
while (z != x) { z = z + 1; y = y * z; }
```

Thus, to show:

$$(\top) \ \mathsf{Fac1} \ (y = x!)$$

## **Program Verification**

Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

## Partial Correctness of Fac1

```
(y=z!)
while (z != x) {
   (y = z! \land z \neq x)
                               Invariant
   (y \cdot (z+1) = (z+1)!)
                             Implied
  z = z + 1:
   (y \cdot z = z!)
                               Assignment
  y = y * z;
   (y=z!)
                               Assignment
(y = z! \land \neg (z \neq x))
                               Partial-while
(y = x!)
                               Implied
```

### **Program Verification**

### Nguyen An Khuong



#### **Contents**

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

## Partial Correctness of Fac1

```
 \begin{array}{ll} (\top) \\ ((1=0!)) & \text{Implied} \\ y=1; \\ (y=0!) & \text{Assignment} \\ z=0; \\ (y=z!) & \text{Assignment} \\ \text{while (}z!=x) & \{\\ \vdots \\ \{y=z! \land \neg(z\neq x)\} & \text{Partial-while} \\ (y=x!) & \text{Implied} \end{array}
```

### **Program Verification**

### Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

## **Program Verification**

Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

Homeworks

**1** Core Programming Language

- 2 Hoare Triples; Partial and Total Correctness
- **3** Proof Calculus for Partial Correctness
- **4** Practical Aspects of Correctness Proofs
- **6** Correctness of the Factorial Function
- **6** Proof Calculus for Total Correctness
- 7 Homeworks

## **Ideas for Total Correctness**

- The only source of non-termination is the while command.
- If we can show that the value of an integer expression decreases in each iteration, but never becomes negative, we have proven termination.
   Why? Well-foundedness of natural numbers
- We shall include this argument in a new version of the while rule.

### **Program Verification**

Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# Rules for Partial Correctness (continued)

$$\frac{(\psi \land B) \ C \ (\psi)}{(\psi) \ \text{while} \ B \ \{ \ C \ \} \ (\psi \land \neg B)}$$

$$(\psi \wedge B \wedge 0 \leq E = E_0) C (\psi \wedge 0 \leq E < E_0)$$

[Total-while]

$$(\psi \wedge 0 \leq E)$$
 while  $B$  {  $C$  }  $(\psi \wedge \neg B)$ 

### **Program Verification**

Nguyen An Khuong



**Contents** 

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# Factorial Example (Again!)

```
y = 1;
z = 0;
while (z != x) \{ z = z + 1; y = y * z; \}
```

What could be a good variant E?

### **Program Verification**

Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# Factorial Example (Again!)

```
y = 1;
z = 0;
while (z != x) { z = z + 1; y = y * z; }
```

What could be a good variant E?

E must strictly decrease in the loop, but not become negative.

### **Program Verification**

Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

# Factorial Example (Again!)

```
y = 1;
z = 0;
while (z != x) { z = z + 1; y = y * z; }
```

What could be a good variant E?

E must strictly decrease in the loop, but not become negative.

Answer:

x-z

## **Program Verification**

Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness

## Total Correctness of Fac1

```
(y=z! \land 0 \leq x-z)
while (z != x)
   \{y = z! \land z \neq x \land 0 \le x - z = E_0\}
                                                              Invariant
   (y \cdot (z+1) = (z+1)! \land 0 \le x - (z+1) < E_0)
                                                              Implied
   z = z + 1:
   \{y \cdot z = z! \land 0 \le x - z < E_0\}
                                                              Assignment
   y = y * z;
   (y = z! \land 0 \le x - z < E_0)
                                                              Assignment
\{y=z! \land \neg(z\neq x)\}
                                                              Total-while
(y = x!)
```

### **Program Verification**

Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the **Factorial Function** 

**Proof Calculus for Total Correctness** 

**Homeworks** 

**Implied** 

## Total Correctness of Fac1

## **Program Verification**

Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness



Do as much as possible (at least ALL marked) problems given in Section 4.6 in [2]

## **Program Verification**

Nguyen An Khuong



#### Contents

Core Programming Language

Hoare Triples; Partial and Total Correctness

Proof Calculus for Partial Correctness

Practical Aspects of Correctness Proofs

Correctness of the Factorial Function

Proof Calculus for Total Correctness