

view_frames Result

Recorded at time: 1860.866

map

Broadcaster: /rtabmap/rtabmap
Average rate: 20.202 Hz
Most recent transform: 1860.944 (-0.078 sec old)
Buffer length: 4.950 sec

odom

Broadcaster: /gazebo
Average rate: 10.204 Hz
Most recent transform: 1860.860 (0.006 sec old)
Buffer length: 4.900 sec

robot_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1860.866 sec old)
Buffer length: 0.000 sec

chassis

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1860.866 sec old)
Buffer length: 0.000 sec

camera

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1860.866 sec old)
Buffer length: 0.000 sec

hokuyo

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1860.800 (0.066 sec old)
Buffer length: 4.900 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1860.800 (0.066 sec old)
Buffer length: 4.900 sec

right_wheel