

vv255: Line Integrals.

Dr. Olga Danilkina

UM-SJTU Joint Institute



July 17, 2019

Vector Fields

We have already encountered functions from \mathbb{R}^n to \mathbb{R}^n in the context of changing variables in the multivariable integral.

Vector Fields

We have already encountered functions from \mathbb{R}^n to \mathbb{R}^n in the context of changing variables in the multivariable integral. These abstract entities can also be viewed as **vector fields**. That is, a function that maps points in n -dimensional Euclidean space to n -dimensional vectors.

Vector Fields

We have already encountered functions from \mathbb{R}^n to \mathbb{R}^n in the context of changing variables in the multivariable integral. These abstract entities can also be viewed as **vector fields**. That is, a function that maps points in n -dimensional Euclidean space to n -dimensional vectors.

Definition

A **vector field on \mathbb{R}^n** is a function $F : D \longrightarrow \mathbb{R}^n$ where $D \subseteq \mathbb{R}^n$

Vector Fields

We have already encountered functions from \mathbb{R}^n to \mathbb{R}^n in the context of changing variables in the multivariable integral. These abstract entities can also be viewed as **vector fields**. That is, a function that maps points in n -dimensional Euclidean space to n -dimensional vectors.

Definition

A **vector field on \mathbb{R}^n** is a function $F : D \longrightarrow \mathbb{R}^n$ where $D \subseteq \mathbb{R}^n$

- ▶ Vector fields arise frequently in mathematical models of physical problems. For example, the velocity of a fluid flowing through 3D space is naturally modelled by a vector field on \mathbb{R}^3

Vector Fields

We have already encountered functions from \mathbb{R}^n to \mathbb{R}^n in the context of changing variables in the multivariable integral. These abstract entities can also be viewed as **vector fields**. That is, a function that maps points in n -dimensional Euclidean space to n -dimensional vectors.

Definition

A **vector field on \mathbb{R}^n** is a function $F : D \longrightarrow \mathbb{R}^n$ where $D \subseteq \mathbb{R}^n$

- ▶ Vector fields arise frequently in mathematical models of physical problems. For example, the velocity of a fluid flowing through 3D space is naturally modelled by a vector field on \mathbb{R}^3
- ▶ Vector fields can be used to visualise families of solutions to differential equations.

A vector field $F : D \longrightarrow \mathbb{R}^2$ where $D \subseteq \mathbb{R}^2$ can be visualised by selecting a finite number of (possibly uniformly distributed) points $(x_1, y_1), \dots, (x_n, y_n)$ in D and plotting vectors corresponding to $F(x_1, y_1), \dots, F(x_n, y_n)$ at the points $(x_1, y_1), \dots, (x_n, y_n)$ on the Cartesian plane.

Vector Fields

We have already encountered functions from \mathbb{R}^n to \mathbb{R}^n in the context of changing variables in the multivariable integral. These abstract entities can also be viewed as **vector fields**. That is, a function that maps points in n -dimensional Euclidean space to n -dimensional vectors.

Definition

A **vector field on \mathbb{R}^n** is a function $F : D \longrightarrow \mathbb{R}^n$ where $D \subseteq \mathbb{R}^n$

- ▶ Vector fields arise frequently in mathematical models of physical problems. For example, the velocity of a fluid flowing through 3D space is naturally modelled by a vector field on \mathbb{R}^3
- ▶ Vector fields can be used to visualise families of solutions to differential equations.

A vector field $F : D \longrightarrow \mathbb{R}^2$ where $D \subseteq \mathbb{R}^2$ can be visualised by selecting a finite number of (possibly uniformly distributed) points $(x_1, y_1), \dots, (x_n, y_n)$ in D and plotting vectors corresponding to $F(x_1, y_1), \dots, F(x_n, y_n)$ at the points $(x_1, y_1), \dots, (x_n, y_n)$ on the Cartesian plane. This method can also be used to visualise a vector field $F : \mathbb{R}^3 \longrightarrow \mathbb{R}^3$ in 3D space.

Vector Fields

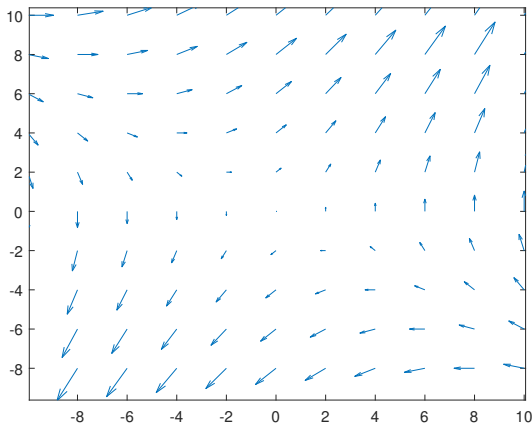
Example

Consider the vector field $F : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$ defined by $F(x, y) = y\bar{i} + (x + y)\bar{j}$

Vector Fields

Example

Consider the vector field $F : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$ defined by $F(x, y) = y\bar{i} + (x + y)\bar{j}$



Vector Fields

Example

(Continued.) The commands that I used to produce this are...

```
>> [x,y] = meshgrid(-10:2:10);  
>> dx= y;  
>> dy= x+y;  
>> quiver(x,y,dx,dy);
```

But you can probably do better!

Vector Fields

Example

(Continued.) The commands that I used to produce this are...

```
>> [x,y] = meshgrid(-10:2:10);  
>> dx= y;  
>> dy= x+y;  
>> quiver(x,y,dx,dy);
```

But you can probably do better!

The obvious example of a vector field that we have encountered already is the gradient of a differentiable function f of n variables (∇f).

Vector Fields

Example

(Continued.) The commands that I used to produce this are...

```
>> [x,y] = meshgrid(-10:2:10);  
>> dx= y;  
>> dy= x+y;  
>> quiver(x,y,dx,dy);
```

But you can probably do better!

The obvious example of a vector field that we have encountered already is the gradient of a differentiable function f of n variables (∇f).

Example

Consider $f(x, y, z) = x \cos\left(\frac{y}{z}\right)$. $\nabla f(x, y, z)$ is a vector field on \mathbb{R}^3 :

$$\nabla f(x, y, z) = \frac{\partial f}{\partial x} \bar{i} + \frac{\partial f}{\partial y} \bar{j} + \frac{\partial f}{\partial z} \bar{k}$$

Vector Fields

Example

(Continued.)

$$\nabla f(x, y, z) = \cos\left(\frac{y}{z}\right) \bar{i} - \frac{x}{z} \sin\left(\frac{y}{z}\right) \bar{j} + \frac{xy}{z^2} \sin\left(\frac{y}{z}\right) \bar{k}$$

Vector Fields

Example

(Continued.)

$$\nabla f(x, y, z) = \cos\left(\frac{y}{z}\right) \bar{i} - \frac{x}{z} \sin\left(\frac{y}{z}\right) \bar{j} + \frac{xy}{z^2} \sin\left(\frac{y}{z}\right) \bar{k}$$

Definition

Let $F : D \longrightarrow \mathbb{R}^n$ where $D \subseteq \mathbb{R}^n$ be a vector field on \mathbb{R}^n .

We say that F is **conservative** if there exists a differentiable function

$$f : D \longrightarrow \mathbb{R} \text{ such that for all } \bar{x} \in D \quad F(\bar{x}) = \nabla f(\bar{x})$$

If $F : D \longrightarrow \mathbb{R}^n$ where $D \subseteq \mathbb{R}^n$ is a conservative vector field and $f : D \longrightarrow \mathbb{R}$ is such that for all $\bar{x} \in D$, $F(\bar{x}) = \nabla f(\bar{x})$, then f is called a **potential function** for F .

Vector Fields

Example

The vector field $F : \mathbb{R}^3 \longrightarrow \mathbb{R}^3$ defined by

$$F(x, y, z) = (y^2 z^3, 2xyz^3, 3xy^2 z^2)$$

is conservative.

Vector Fields

Example

The vector field $F : \mathbb{R}^3 \longrightarrow \mathbb{R}^3$ defined by

$$F(x, y, z) = (y^2 z^3, 2xyz^3, 3xy^2 z^2)$$

is conservative. To see this, consider $f(x, y, z) = xy^2 z^3$. We have

$$\frac{\partial f}{\partial x} = y^2 z^3 \qquad \frac{\partial f}{\partial y} = 2xyz^3 \qquad \frac{\partial f}{\partial z} = 3xy^2 z^2$$

so f is a potential function for F .

Vector Fields

The vector field $F : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$ defined by

$F(x, y) = (x^2 - yx)\bar{i} + (y^2 - xy)\bar{j}$ is NOT conservative.

Vector Fields

The vector field $F : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$ defined by

$F(x, y) = (x^2 - yx)\vec{i} + (y^2 - xy)\vec{j}$ is NOT conservative.

Proof.

Suppose, for a contradiction, that f is a potential function for F .

Vector Fields

The vector field $F : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$ defined by $F(x, y) = (x^2 - yx)\bar{i} + (y^2 - xy)\bar{j}$ is NOT conservative.

Proof.

Suppose, for a contradiction, that f is a potential function for F . Therefore

$$\frac{\partial f}{\partial x} = x^2 - yx \text{ and } \frac{\partial f}{\partial y} = y^2 - xy$$

Vector Fields

The vector field $F : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$ defined by $F(x, y) = (x^2 - yx)\bar{i} + (y^2 - xy)\bar{j}$ is NOT conservative.

Proof.

Suppose, for a contradiction, that f is a potential function for F . Therefore

$$\frac{\partial f}{\partial x} = x^2 - yx \text{ and } \frac{\partial f}{\partial y} = y^2 - xy$$

But then

$$\frac{\partial^2 f}{\partial y \partial x} = -x \text{ and } \frac{\partial^2 f}{\partial x \partial y} = -y$$

Vector Fields

The vector field $F : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$ defined by $F(x, y) = (x^2 - yx)\bar{i} + (y^2 - xy)\bar{j}$ is NOT conservative.

Proof.

Suppose, for a contradiction, that f is a potential function for F . Therefore

$$\frac{\partial f}{\partial x} = x^2 - yx \text{ and } \frac{\partial f}{\partial y} = y^2 - xy$$

But then

$$\frac{\partial^2 f}{\partial y \partial x} = -x \text{ and } \frac{\partial^2 f}{\partial x \partial y} = -y$$

And so $f_{yx} \neq f_{xy}$, which contradicts Clairaut's Theorem.



Vector Fields

The vector field $F : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$ defined by $F(x, y) = (x^2 - yx)\bar{i} + (y^2 - xy)\bar{j}$ is NOT conservative.

Proof.

Suppose, for a contradiction, that f is a potential function for F . Therefore

$$\frac{\partial f}{\partial x} = x^2 - yx \text{ and } \frac{\partial f}{\partial y} = y^2 - xy$$

But then

$$\frac{\partial^2 f}{\partial y \partial x} = -x \text{ and } \frac{\partial^2 f}{\partial x \partial y} = -y$$

And so $f_{yx} \neq f_{xy}$, which contradicts Clairaut's Theorem. □

Example

The vector field $F : D \longrightarrow \mathbb{R}^2$, where $D = \mathbb{R}^2 \setminus \{\langle 0, 0 \rangle\}$, defined by

$$F(x, y) = \left(\frac{-y}{x^2 + y^2}, \frac{x}{x^2 + y^2} \right)$$

is called the **vortex vector field**. F is NOT conservative, but we do not have the tools to show this yet!

Line Integrals

So far, we have seen how to integrate functions of more than one variable over closed rectangles and bounded regions. We now turn to defining a notion of integral that aims to simulate the integral of a function of a single variable over an arbitrary curve in 2D or 3D space.

Line Integrals

So far, we have seen how to integrate functions of more than one variable over closed rectangles and bounded regions. We now turn to defining a notion of integral that aims to simulate the integral of a function of a single variable over an arbitrary curve in 2D or 3D space.

Let \mathcal{C} be a smooth curve in 2D space described by the parametric equations $x = f(t)$ and $y = g(t)$ where $t \in [a, b]$.

Line Integrals

So far, we have seen how to integrate functions of more than one variable over closed rectangles and bounded regions. We now turn to defining a notion of integral that aims to simulate the integral of a function of a single variable over an arbitrary curve in 2D or 3D space.

Let \mathcal{C} be a smooth curve in 2D space described by the parametric equations $x = f(t)$ and $y = g(t)$ where $t \in [a, b]$. Recall that the distance along \mathcal{C} starting from the point a is described by the function

$$s(t) = \int_a^t \sqrt{(f'(u))^2 + (g'(u))^2} \, du$$

Line Integrals

So far, we have seen how to integrate functions of more than one variable over closed rectangles and bounded regions. We now turn to defining a notion of integral that aims to simulate the integral of a function of a single variable over an arbitrary curve in 2D or 3D space.

Let \mathcal{C} be a smooth curve in 2D space described by the parametric equations $x = f(t)$ and $y = g(t)$ where $t \in [a, b]$. Recall that the distance along \mathcal{C} starting from the point a is described by the function

$$s(t) = \int_a^t \sqrt{(f'(u))^2 + (g'(u))^2} du$$

Suppose that $(x_0, y_0), \dots, (x_{n+1}, y_{n+1})$ are point on \mathcal{C} and $t_0, \dots, t_{n+1} \in [a, b]$ are such that $t_0 = a$ and $t_{n+1} = b$, and for all $0 \leq k \leq n+1$,

$$x_k = f(t_k) \text{ and } y_k = g(t_k)$$

$(x_0, y_0), \dots, (x_{n+1}, y_{n+1})$ look like a partition of the curve \mathcal{C} and $P = \{t_0, \dots, t_{n+1}\}$ is a partition of $[a, b]$

Line Integrals

Let $h : D \longrightarrow \mathbb{R}$, where $D \subseteq \mathbb{R}^2$ and \mathcal{C} is contained in D , be continuous.

Line Integrals

Let $h : D \rightarrow \mathbb{R}$, where $D \subseteq \mathbb{R}^2$ and \mathcal{C} is contained in D , be continuous. Observe that the following two sums (that are obvious analogues of the upper and lower Darboux sums) are approximations of the area of the surface that is bounded by the lines $x = x_0$, $y = y_0$, and $x = x_{n+1}$, $y = y_{n+1}$, the curve \mathcal{C} , and the graph $z = h(x, y)$:

$$U = \sum_{k=0}^n \sup\{h(f(t), g(t)) \mid t \in [t_k, t_{k+1}]\} \sqrt{(x_{k+1} - x_k)^2 + (y_{k+1} - y_k)^2}$$

$$L = \sum_{k=0}^n \inf\{h(f(t), g(t)) \mid t \in [t_k, t_{k+1}]\} \sqrt{(x_{k+1} - x_k)^2 + (y_{k+1} - y_k)^2}$$

Line Integrals

Let $h : D \longrightarrow \mathbb{R}$, where $D \subseteq \mathbb{R}^2$ and \mathcal{C} is contained in D , be continuous. Observe that the following two sums (that are obvious analogues of the upper and lower Darboux sums) are approximations of the area of the surface that is bounded by the lines $x = x_0$, $y = y_0$, and $x = x_{n+1}$, $y = y_{n+1}$, the curve \mathcal{C} , and the graph $z = h(x, y)$:

$$U = \sum_{k=0}^n \sup\{h(f(t), g(t)) \mid t \in [t_k, t_{k+1}]\} \sqrt{(x_{k+1} - x_k)^2 + (y_{k+1} - y_k)^2}$$

$$L = \sum_{k=0}^n \inf\{h(f(t), g(t)) \mid t \in [t_k, t_{k+1}]\} \sqrt{(x_{k+1} - x_k)^2 + (y_{k+1} - y_k)^2}$$

Let $M_k = \sup\{h(f(t), g(t)) \mid t \in [t_k, t_{k+1}]\}$ and $m_k = \inf\{h(f(t), g(t)) \mid t \in [t_k, t_{k+1}]\}$ for all $0 \leq k \leq n$,

$$U = \sum_{k=0}^n M_k (t_{k+1} - t_k) \sqrt{\left(\frac{x_{k+1} - x_k}{t_{k+1} - t_k}\right)^2 + \left(\frac{y_{k+1} - y_k}{t_{k+1} - t_k}\right)^2}$$

$$L = \sum_{k=0}^n m_k (t_{k+1} - t_k) \sqrt{\left(\frac{x_{k+1} - x_k}{t_{k+1} - t_k}\right)^2 + \left(\frac{y_{k+1} - y_k}{t_{k+1} - t_k}\right)^2}$$

Line Integrals

Therefore as the partitions $(x_0, y_0), \dots, (x_{n+1}, y_{n+1})$ and $P = \{t_0, \dots, t_{n+1}\}$ become arbitrarily fine, U gets closer to $U(h, P)$ and L gets closer to $L(\alpha, P)$ where $U(\alpha, P)$ is the the single variable upper Darboux sum and $L(\alpha, P)$ is the single variable lower Darboux sum, and

$$\alpha(t) = h(f(t), g(t)) \sqrt{(f'(t))^2 + (g'(t))^2}$$

This motivates the following definition:

Line Integrals

Therefore as the partitions $(x_0, y_0), \dots, (x_{n+1}, y_{n+1})$ and $P = \{t_0, \dots, t_{n+1}\}$ become arbitrarily fine, U gets closer to $U(h, P)$ and L gets closer to $L(\alpha, P)$ where $U(\alpha, P)$ is the the single variable upper Darboux sum and $L(\alpha, P)$ is the single variable lower Darboux sum, and

$$\alpha(t) = h(f(t), g(t)) \sqrt{(f'(t))^2 + (g'(t))^2}$$

This motivates the following definition:

Definition

Let \mathcal{C} be a smooth curve in 2D space described by the parametric equations $x = f(t)$ and $y = g(t)$ where $t \in [a, b]$. Let $h(x, y)$ be a function that is defined and continuous on \mathcal{C} . The **line integral** of h along \mathcal{C} is defined by

$$\int_{\mathcal{C}} h(x, y) \, ds = \int_a^b h(f(t), g(t)) \sqrt{(f'(t))^2 + (g'(t))^2} \, dt$$

Line Integrals

Example

Let \mathcal{C} be the curve described by $x = t^2$, $y = 2t$, $0 \leq t \leq 3$. Compute

$$\int_{\mathcal{C}} y \, ds$$

Line Integrals

Example

Let \mathcal{C} be the curve described by $x = t^2$, $y = 2t$, $0 \leq t \leq 3$. Compute

$$\int_{\mathcal{C}} y \, ds$$

Example

Let \mathcal{C} be the curve described by the circle $x^2 + y^2 = 4$ in the left half-plane. Compute

$$\int_{\mathcal{C}} xy^4 \, ds$$

Line Integrals

Formalising the reasoning on the preceding slides would allow one to show that the line integral gives the area of the surface that lies between the graph $z = h(x, y)$ and the curve \mathcal{C} on the xy -plane.

Line Integrals

Formalising the reasoning on the preceding slides would allow one to show that the line integral gives the area of the surface that lies between the graph $z = h(x, y)$ and the curve \mathcal{C} on the xy -plane.

The preceding reasoning can also be generalized to motivate the line integral of a function of three variables over a smooth curve in 3D space.

Definition

*Let \mathcal{C} be a smooth curve in 3D space described by the parametric equations $x = f(t)$, $y = g(t)$ and $z = h(t)$ where $t \in [a, b]$. Let $\gamma(x, y, z)$ be a function that is defined and continuous on \mathcal{C} . The **line integral** of γ along \mathcal{C} is defined by*

$$\int_{\mathcal{C}} \gamma(x, y, z) \, ds = \int_a^b \gamma(f(t), g(t), h(t)) \sqrt{(f'(t))^2 + (g'(t))^2 + (h'(t))^2} \, dt$$

Line Integrals

Formalising the reasoning on the preceding slides would allow one to show that the line integral gives the area of the surface that lies between the graph $z = h(x, y)$ and the curve \mathcal{C} on the xy -plane.

The preceding reasoning can also be generalized to motivate the line integral of a function of three variables over a smooth curve in 3D space.

Definition

*Let \mathcal{C} be a smooth curve in 3D space described by the parametric equations $x = f(t)$, $y = g(t)$ and $z = h(t)$ where $t \in [a, b]$. Let $\gamma(x, y, z)$ be a function that is defined and continuous on \mathcal{C} . The **line integral** of γ along \mathcal{C} is defined by*

$$\int_{\mathcal{C}} \gamma(x, y, z) \, ds = \int_a^b \gamma(f(t), g(t), h(t)) \sqrt{(f'(t))^2 + (g'(t))^2 + (h'(t))^2} \, dt$$

The assumption that the curve \mathcal{C} is smooth in the above definitions is appealed to in order to get that the derivative of the curve's length is given by the function $\sqrt{(f'(t))^2 + (g'(t))^2 + (h'(t))^2}$.

Line Integrals

Recall that a function that is discontinuous only at a finite number of points is still integrable. Similarly, the line integral over a curve that fails to be smooth only at a finite number of points remains valid.

Line Integrals

Recall that a function that is discontinuous only at a finite number of points is still integrable. Similarly, the line integral over a curve that fails to be smooth only at a finite number of points remains valid.

Definition

A curve \mathcal{C} in 2D or 3D space is said to be *piecewise-smooth* if \mathcal{C} is composed of a finite number of smooth curves $\mathcal{C}_1, \dots, \mathcal{C}_n$ such that for all $1 \leq i \leq n-1$, the initial point on \mathcal{C}_{i+1} is terminal point on \mathcal{C}_i . If \mathcal{C} is a piecewise-smooth curve in 2D or 3D space composed of the smooth curves $\mathcal{C}_1, \dots, \mathcal{C}_n$ and f is a function that is continuous on \mathcal{C} , then define

$$\int_{\mathcal{C}} f \, ds = \sum_{k=1}^n \int_{\mathcal{C}_k} f \, ds$$

Line Integrals

Recall that a function that is discontinuous only at a finite number of points is still integrable. Similarly, the line integral over a curve that fails to be smooth only at a finite number of points remains valid.

Definition

A curve \mathcal{C} in 2D or 3D space is said to be *piecewise-smooth* if \mathcal{C} is composed of a finite number of smooth curves $\mathcal{C}_1, \dots, \mathcal{C}_n$ such that for all $1 \leq i \leq n-1$, the initial point on \mathcal{C}_{i+1} is terminal point on \mathcal{C}_i . If \mathcal{C} is a piecewise-smooth curve in 2D or 3D space composed of the smooth curves $\mathcal{C}_1, \dots, \mathcal{C}_n$ and f is a function that is continuous on \mathcal{C} , then define

$$\int_{\mathcal{C}} f \, ds = \sum_{k=1}^n \int_{\mathcal{C}_k} f \, ds$$

Example

Let \mathcal{C} consist of the arc of the circle $x^2 + y^2 = 4$ from $(2, 0)$ to $(0, 2)$ followed by the line segment from $(0, 2)$ to $(4, 3)$. Compute

$$\int_{\mathcal{C}} (x^2 + y^2) \, ds$$

Line Integrals

We will also have cause to consider the following variants of the line integral that integrate a function with respect to x , y and z respectively.

Definition

Let \mathcal{C} be a smooth curve in 3D space described by the parametric equations $x = f(t)$, $y = g(t)$ and $z = h(t)$ where $t \in [a, b]$. Let $\gamma(x, y, z)$ be a function that is defined and continuous on \mathcal{C} .

The *line integral of γ along \mathcal{C} with respect to x* is defined by

$$\int_{\mathcal{C}} \gamma(x, y, z) \, dx = \int_a^b \gamma(f(t), g(t), h(t)) f'(t) \, dt$$

Line Integrals

Definition

(Continued.) The *line integral of γ along \mathcal{C} with respect to y* is defined by

$$\int_{\mathcal{C}} \gamma(x, y, z) \, dy = \int_a^b \gamma(f(t), g(t), h(t)) g'(t) \, dt$$

The *line integral of γ along \mathcal{C} with respect to z* is defined by

$$\int_{\mathcal{C}} \gamma(x, y, z) \, dz = \int_a^b \gamma(f(t), g(t), h(t)) h'(t) \, dt$$

Line Integrals

Definition

(Continued.) The *line integral of γ along \mathcal{C} with respect to y* is defined by

$$\int_{\mathcal{C}} \gamma(x, y, z) \, dy = \int_a^b \gamma(f(t), g(t), h(t)) g'(t) \, dt$$

The *line integral of γ along \mathcal{C} with respect to z* is defined by

$$\int_{\mathcal{C}} \gamma(x, y, z) \, dz = \int_a^b \gamma(f(t), g(t), h(t)) h'(t) \, dt$$

This definition can be restricted in the obvious way to define the line integral of a function of two variables along a curve in 2D space with respect to x and y .

Line Integrals

Definition

(Continued.) The *line integral of γ along \mathcal{C} with respect to y* is defined by

$$\int_{\mathcal{C}} \gamma(x, y, z) \, dy = \int_a^b \gamma(f(t), g(t), h(t)) g'(t) \, dt$$

The *line integral of γ along \mathcal{C} with respect to z* is defined by

$$\int_{\mathcal{C}} \gamma(x, y, z) \, dz = \int_a^b \gamma(f(t), g(t), h(t)) h'(t) \, dt$$

This definition can be restricted in the obvious way to define the line integral of a function of two variables along a curve in 2D space with respect to x and y .

For reasons that will be revealed shortly, line integrals with respect to x , y and z often appear together as sums.

Line Integrals

For this reason, it is convenient to write

$$\int_C P(x, y) \, dx + Q(x, y) \, dy$$

instead of

$$\int_C P(x, y) \, dx + \int_C Q(x, y) \, dy$$

Line Integrals

For this reason, it is convenient to write

$$\int_C P(x, y) \, dx + Q(x, y) \, dy$$

instead of

$$\int_C P(x, y) \, dx + \int_C Q(x, y) \, dy$$

And

$$\int_C P(x, y, z) \, dx + Q(x, y, z) \, dy + R(x, y, z) \, dz$$

instead of

$$\int_C P(x, y, z) \, dx + \int_C Q(x, y, z) \, dy + \int_C R(x, y, z) \, dz$$

Be aware of the similarity in notation between the line integral along \mathcal{C} with respect to x (or y , or z) and the notion used for the partial integral. These are two very different things!

Line Integrals

Example

Let \mathcal{C} be the line running from the point $(1, 0, 0)$ to the point $(4, 1, 2)$.
Compute

$$\int_{\mathcal{C}} z^2 \, dx + x^2 \, dy + y^2 \, dz$$

Example

Let \mathcal{C} consist of two line segments from $(0, 0, 0)$ to $(1, 0, 1)$ and from $(1, 0, 1)$ to $(0, 1, 2)$. Evaluate

$$\int_{\mathcal{C}} (y + z) \, dx + (x + z) \, dy + (x + y) \, dz$$

Orientation of a curve

Let \mathcal{C} be a smooth curve in 3D space described by the parametric equations

$$x = f(t), \quad y = g(t), \quad z = h(t), \quad t \in [a, b].$$

In addition to describing \mathcal{C} , this parameterisation also endows \mathcal{C} with a direction:

The curve starts at $(f(a), g(a), h(a))$ and finishes at $(f(b), g(b), h(b))$.

Orientation of a curve

Let \mathcal{C} be a smooth curve in 3D space described by the parametric equations

$$x = f(t), \quad y = g(t), \quad z = h(t), \quad t \in [a, b].$$

In addition to describing \mathcal{C} , this parameterisation also endows \mathcal{C} with a direction:

The curve starts at $(f(a), g(a), h(a))$ and finishes at $(f(b), g(b), h(b))$.

In light of this, we write $-\mathcal{C}$ for the curve that is identical to \mathcal{C} except for the fact: it starts at $(f(b), g(b), h(b))$ and finishes at $(f(a), g(a), h(a))$.

$\Rightarrow -\mathcal{C}$ is the curve described by the parametric equations

$$x = f(b + a - t), \quad y = g(b + a - t), \quad z = h(b + a - t), \quad t \in [a, b].$$

If $\gamma(x, y, z)$ is a function that is defined and continuous on \mathcal{C} , then

$$\int_{\mathcal{C}} \gamma(x, y, z) \, dx = - \int_{-\mathcal{C}} \gamma(x, y, z) \, dx$$

and the same equation holds for the line integrals of γ along \mathcal{C} with respect to y and z . However,

$$\int_{\mathcal{C}} \gamma(x, y, z) \, ds = \int_{-\mathcal{C}} \gamma(x, y, z) \, ds$$

Line integrals of vector fields

Another important notion is the line integral of a vector field.

Definition

A vector field $F : D \longrightarrow \mathbb{R}^n$, where $D \subseteq \mathbb{R}^n$, is said to be *continuous* on $I \subseteq D$ if each of its components is continuous on I .

Line integrals of vector fields

Another important notion is the line integral of a vector field.

Definition

A vector field $F : D \longrightarrow \mathbb{R}^n$, where $D \subseteq \mathbb{R}^n$, is said to be *continuous* on $I \subseteq D$ if each of its components is continuous on I .

Definition

Let $F : D \longrightarrow \mathbb{R}^3$, where $D \subseteq \mathbb{R}^3$, be a vector field. Let $\vec{r} : [a, b] \longrightarrow \mathbb{R}^3$ be a vector function that describes a smooth curve \mathcal{C} that is contained in D and such that F is continuous on \mathcal{C} .

Define the *line integral of F along \mathcal{C}* by

$$\int_{\mathcal{C}} F \cdot d\vec{r} = \int_a^b F(\vec{r}(t)) \cdot \vec{r}'(t) dt$$

Line integrals of vector fields

Another important notion is the line integral of a vector field.

Definition

A vector field $F : D \longrightarrow \mathbb{R}^n$, where $D \subseteq \mathbb{R}^n$, is said to be *continuous* on $I \subseteq D$ if each of its components is continuous on I .

Definition

Let $F : D \longrightarrow \mathbb{R}^3$, where $D \subseteq \mathbb{R}^3$, be a vector field. Let $\vec{r} : [a, b] \longrightarrow \mathbb{R}^3$ be a vector function that describes a smooth curve \mathcal{C} that is contained in D and such that F is continuous on \mathcal{C} .

Define the *line integral of F along \mathcal{C}* by

$$\int_{\mathcal{C}} F \cdot d\vec{r} = \int_a^b F(\vec{r}(t)) \cdot \vec{r}'(t) dt$$

Note that by replacing F by a vector field on \mathbb{R}^2 and \mathcal{C} by a smooth curve in \mathbb{R}^2 in the above definition we obtain the definition of the line integral of a vector field in \mathbb{R}^2 over a smooth curve in \mathbb{R}^2 .

Line integrals of vector fields

Observe that

$$\frac{F(\vec{r}(t)) \cdot \vec{r}'(t)}{|\vec{r}'(t)|}$$

is the scalar projection of the vector $F(\vec{r}(t))$ along the direction of \mathcal{C} at the point $\vec{r}(t)$ on \mathcal{C} .

Line integrals of vector fields

Observe that

$$\frac{F(\vec{r}(t)) \cdot \vec{r}'(t)}{|\vec{r}'(t)|}$$

is the scalar projection of the vector $F(\vec{r}(t))$ along the direction of \mathcal{C} at the point $\vec{r}(t)$ on \mathcal{C} . And

$$\int_{\mathcal{C}} F \cdot d\vec{r} = \int_a^b \frac{F(\vec{r}(t)) \cdot \vec{r}'(t)}{|\vec{r}'(t)|} |\vec{r}'(t)| dt = \int_{\mathcal{C}} \frac{F(\vec{r}(t)) \cdot \vec{r}'(t)}{|\vec{r}'(t)|} ds$$

Line integrals of vector fields

Observe that

$$\frac{F(\vec{r}(t)) \cdot \vec{r}'(t)}{|\vec{r}'(t)|}$$

is the scalar projection of the vector $F(\vec{r}(t))$ along the direction of \mathcal{C} at the point $\vec{r}(t)$ on \mathcal{C} . And

$$\int_{\mathcal{C}} F \cdot d\vec{r} = \int_a^b \frac{F(\vec{r}(t)) \cdot \vec{r}'(t)}{|\vec{r}'(t)|} |\vec{r}'(t)| dt = \int_{\mathcal{C}} \frac{F(\vec{r}(t)) \cdot \vec{r}'(t)}{|\vec{r}'(t)|} ds$$

Therefore the line integral of a vector field F along a smooth curve \mathcal{C} is just the line integral of the scalar projection of F in the direction of \mathcal{C} along \mathcal{C} .

Line integrals of vector fields

Observe that

$$\frac{F(\vec{r}(t)) \cdot \vec{r}'(t)}{|\vec{r}'(t)|}$$

is the scalar projection of the vector $F(\vec{r}(t))$ along the direction of \mathcal{C} at the point $\vec{r}(t)$ on \mathcal{C} . And

$$\int_{\mathcal{C}} F \cdot d\vec{r} = \int_a^b \frac{F(\vec{r}(t)) \cdot \vec{r}'(t)}{|\vec{r}'(t)|} |\vec{r}'(t)| dt = \int_{\mathcal{C}} \frac{F(\vec{r}(t)) \cdot \vec{r}'(t)}{|\vec{r}'(t)|} ds$$

Therefore the line integral of a vector field F along a smooth curve \mathcal{C} is just the line integral of the scalar projection of F in the direction of \mathcal{C} along \mathcal{C} .

Example

Let \mathcal{C} be the curve described by the vector function $\vec{r} : [0, \frac{\pi}{2}] \rightarrow \mathbb{R}^3$ where $\vec{r}(t) = \cos t \vec{i} + \sin t \vec{j}$. Let $F : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be defined by $F(x, y) = x^2 \vec{i} - xy \vec{j}$. Compute

$$\int_{\mathcal{C}} F \cdot d\vec{r}$$

Line integrals of vector fields

Let $F : D \longrightarrow \mathbb{R}^3$, where $D \subseteq \mathbb{R}^3$, be a vector field s.t. $\forall (x, y, z) \in D$

$$F(x, y, z) = P(x, y, z)\bar{i} + Q(x, y, z)\bar{j} + R(x, y, z)\bar{k}$$

Line integrals of vector fields

Let $F : D \longrightarrow \mathbb{R}^3$, where $D \subseteq \mathbb{R}^3$, be a vector field s.t. $\forall (x, y, z) \in D$

$$F(x, y, z) = P(x, y, z)\vec{i} + Q(x, y, z)\vec{j} + R(x, y, z)\vec{k}$$

Let $\vec{r} : [a, b] \longrightarrow \mathbb{R}^3$ be a vector function that describes a smooth curve \mathcal{C} that is contained in D and is defined by

$$\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}$$

Line integrals of vector fields

Let $F : D \longrightarrow \mathbb{R}^3$, where $D \subseteq \mathbb{R}^3$, be a vector field s.t. $\forall (x, y, z) \in D$

$$F(x, y, z) = P(x, y, z)\vec{i} + Q(x, y, z)\vec{j} + R(x, y, z)\vec{k}$$

Let $\vec{r} : [a, b] \longrightarrow \mathbb{R}^3$ be a vector function that describes a smooth curve \mathcal{C} that is contained in D and is defined by

$$\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}$$

If F is continuous on \mathcal{C} , then

$$\int_{\mathcal{C}} F \cdot d\vec{r} = \int_a^b F(\vec{r}(t)) \cdot \vec{r}'(t) dt$$

Line integrals of vector fields

Let $F : D \longrightarrow \mathbb{R}^3$, where $D \subseteq \mathbb{R}^3$, be a vector field s.t. $\forall (x, y, z) \in D$

$$F(x, y, z) = P(x, y, z)\vec{i} + Q(x, y, z)\vec{j} + R(x, y, z)\vec{k}$$

Let $\vec{r} : [a, b] \longrightarrow \mathbb{R}^3$ be a vector function that describes a smooth curve \mathcal{C} that is contained in D and is defined by

$$\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}$$

If F is continuous on \mathcal{C} , then

$$\begin{aligned}\int_{\mathcal{C}} F \cdot d\vec{r} &= \int_a^b F(\vec{r}(t)) \cdot \vec{r}'(t) \, dt \\ &= \int_a^b (P(x, y, z), Q(x, y, z), R(x, y, z)) \cdot (x'(t), y'(t), z'(t)) \, dt\end{aligned}$$

Line integrals of vector fields

Let $F : D \longrightarrow \mathbb{R}^3$, where $D \subseteq \mathbb{R}^3$, be a vector field s.t. $\forall (x, y, z) \in D$

$$F(x, y, z) = P(x, y, z)\bar{i} + Q(x, y, z)\bar{j} + R(x, y, z)\bar{k}$$

Let $\bar{r} : [a, b] \longrightarrow \mathbb{R}^3$ be a vector function that describes a smooth curve \mathcal{C} that is contained in D and is defined by

$$\bar{r}(t) = x(t)\bar{i} + y(t)\bar{j} + z(t)\bar{k}$$

If F is continuous on \mathcal{C} , then

$$\begin{aligned}\int_{\mathcal{C}} F \cdot d\bar{r} &= \int_a^b F(\bar{r}(t)) \cdot \bar{r}'(t) dt \\&= \int_a^b (P(x, y, z), Q(x, y, z), R(x, y, z)) \cdot (x'(t), y'(t), z'(t)) dt \\&= \int_a^b P(x(t), y(t), z(t))x'(t) dt + \int_a^b Q(x(t), y(t), z(t))y'(t) dt \\&\quad + \int_a^b R(x(t), y(t), z(t))z'(t) dt = \int_{\mathcal{C}} P(x, y, z) dx + Q(x, y, z) dy + R(x, y, z) dz\end{aligned}$$

Line integrals of vector fields

Example

Let \mathcal{C} be the curve described by the vector function $\vec{r} : [0, 1] \rightarrow \mathbb{R}^3$ defined by

$$\vec{r}(t) = t\vec{i} + t^2\vec{j} + t^3\vec{k}$$

Let $F : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be defined by

$$F(x, y, z) = xy\vec{i} + yz\vec{j} + zx\vec{k}$$

Compute

$$\int_{\mathcal{C}} F \cdot d\vec{r}$$

The Fundamental Theorem of Line Integrals

Recall that the First Fundamental Theorem of Calculus says that

$$\int_a^b F'(x) \, dx = F(b) - F(a)$$

The Fundamental Theorem of Line Integrals

Recall that the First Fundamental Theorem of Calculus says that

$$\int_a^b F'(x) \, dx = F(b) - F(a)$$

The line integral can be thought of as simulating the integral of a function of a single variable for a multivariable function over a curve in 2D or 3D space. It is therefore not surprising that we get an analogue of the First Fundamental Theorem of Calculus.

The Fundamental Theorem of Line Integrals

Recall that the First Fundamental Theorem of Calculus says that

$$\int_a^b F'(x) \, dx = F(b) - F(a)$$

The line integral can be thought of as simulating the integral of a function of a single variable for a multivariable function over a curve in 2D or 3D space. It is therefore not surprising that we get an analogue of the First Fundamental Theorem of Calculus.

Theorem

(Fundamental Theorem of Line Integrals) Let \mathcal{C} be a smooth curve described by the vector function $\vec{r} : [a, b] \rightarrow \mathbb{R}^3$. Let $f : D \rightarrow \mathbb{R}$, where $D \subseteq \mathbb{R}^3$ and \mathcal{C} is contained in D , be differentiable on D with ∇f continuous on \mathcal{C} . Then

$$\int_{\mathcal{C}} \nabla f \cdot d\vec{r} = f(\vec{r}(b)) - f(\vec{r}(a))$$

The Fundamental Theorem of Line Integrals

Proof.

Let $\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}$.

The Fundamental Theorem of Line Integrals

Proof.

Let $\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}$.

$$\int_C \nabla f \cdot d\vec{r} = \int_a^b \nabla f(\vec{r}(t)) \cdot \vec{r}'(t) dt$$

The Fundamental Theorem of Line Integrals

Proof.

Let $\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}$.

$$\begin{aligned}\int_C \nabla f \cdot d\vec{r} &= \int_a^b \nabla f(\vec{r}(t)) \cdot \vec{r}'(t) dt \\ &= \int_a^b \left(\frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} + \frac{\partial f}{\partial z} \frac{dz}{dt} \right) dt\end{aligned}$$

The Fundamental Theorem of Line Integrals

Proof.

Let $\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}$.

$$\begin{aligned}\int_C \nabla f \cdot d\vec{r} &= \int_a^b \nabla f(\vec{r}(t)) \cdot \vec{r}'(t) dt \\&= \int_a^b \left(\frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} + \frac{\partial f}{\partial z} \frac{dz}{dt} \right) dt \\&= \int_a^b \frac{d}{dt} f(\vec{r}(t)) dt = f(\vec{r}(b)) - f(\vec{r}(a))\end{aligned}$$

where the last equation is obtained by applying the First Fundamental Theorem of Calculus.



The Fundamental Theorem of Line Integrals

Proof.

Let $\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}$.

$$\begin{aligned}\int_C \nabla f \cdot d\vec{r} &= \int_a^b \nabla f(\vec{r}(t)) \cdot \vec{r}'(t) dt \\&= \int_a^b \left(\frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} + \frac{\partial f}{\partial z} \frac{dz}{dt} \right) dt \\&= \int_a^b \frac{d}{dt} f(\vec{r}(t)) dt = f(\vec{r}(b)) - f(\vec{r}(a))\end{aligned}$$

where the last equation is obtained by applying the First Fundamental Theorem of Calculus. □

The same result also holds for line integrals of gradient vector field of functions of two variables over smooth curves in 2D space.

Paths and path independence

Definition

*Let P and Q be points in 2D or 3D space. A piecewise-smooth curve C with initial point P and terminal point Q is called a **path** between P and Q .*

Paths and path independence

Definition

Let P and Q be points in 2D or 3D space. A piecewise-smooth curve C with initial point P and terminal point Q is called a **path** between P and Q .

Definition

Let $F : D \longrightarrow \mathbb{R}^3$, where $D \subseteq \mathbb{R}^3$, be a continuous vector field. We say that the **line integral of F is independent of path** if for all P and Q in D and for all paths C_1 and C_2 from P to Q ,

$$\int_{C_1} F \cdot d\vec{r} = \int_{C_2} F \cdot d\vec{r}$$

Paths and path independence

Definition

Let P and Q be points in 2D or 3D space. A piecewise-smooth curve C with initial point P and terminal point Q is called a **path** between P and Q .

Definition

Let $F : D \longrightarrow \mathbb{R}^3$, where $D \subseteq \mathbb{R}^3$, be a continuous vector field. We say that the **line integral of F is independent of path** if for all P and Q in D and for all paths C_1 and C_2 from P to Q ,

$$\int_{C_1} F \cdot d\vec{r} = \int_{C_2} F \cdot d\vec{r}$$

Definition

A piecewise-smooth curve C is said to be a **closed path** if C starts and ends at the same point.

Paths and path independence

Theorem

Let $F : D \longrightarrow \mathbb{R}^3$, where $D \subseteq \mathbb{R}^3$, be a continuous vector field. The line integral of F is independent of path if and only if for every closed path \mathcal{C} ,

$$\int_{\mathcal{C}} F \cdot d\vec{r} = 0$$

Paths and path independence

Theorem

Let $F : D \longrightarrow \mathbb{R}^3$, where $D \subseteq \mathbb{R}^3$, be a continuous vector field. The line integral of F is independent of path if and only if for every closed path \mathcal{C} ,

$$\int_{\mathcal{C}} F \cdot d\vec{r} = 0$$

Proof.

\Rightarrow : Let \mathcal{C} be a closed path. Let P and Q be points on \mathcal{C} .

Paths and path independence

Theorem

Let $F : D \longrightarrow \mathbb{R}^3$, where $D \subseteq \mathbb{R}^3$, be a continuous vector field. The line integral of F is independent of path if and only if for every closed path \mathcal{C} ,

$$\int_{\mathcal{C}} F \cdot d\vec{r} = 0$$

Proof.

\Rightarrow : Let \mathcal{C} be a closed path. Let P and Q be points on \mathcal{C} . So, P and Q divide \mathcal{C} into two paths \mathcal{C}_1 and \mathcal{C}_2 from P to Q .

Paths and path independence

Theorem

Let $F : D \longrightarrow \mathbb{R}^3$, where $D \subseteq \mathbb{R}^3$, be a continuous vector field. The line integral of F is independent of path if and only if for every closed path \mathcal{C} ,

$$\int_{\mathcal{C}} F \cdot d\vec{r} = 0$$

Proof.

\Rightarrow : Let \mathcal{C} be a closed path. Let P and Q be points on \mathcal{C} . So, P and Q divide \mathcal{C} into two paths \mathcal{C}_1 and \mathcal{C}_2 from P to Q . We have

$$\int_{\mathcal{C}} F \cdot d\vec{r} = \int_{\mathcal{C}_1} F \cdot d\vec{r} + \int_{-\mathcal{C}_2} F \cdot d\vec{r} = \int_{\mathcal{C}_1} F \cdot d\vec{r} - \int_{\mathcal{C}_2} F \cdot d\vec{r} = 0,$$

by path independence.

Paths and path independence

Proof.

(Continued.) \Leftarrow : Conversely, let \mathcal{C}_1 and \mathcal{C}_2 be paths from P to Q .

Paths and path independence

Proof.

(Continued.) \Leftarrow : Conversely, let C_1 and C_2 be paths from P to Q . Let C_1 and $-C_2$ form a closed path C that starts and ends at P and

$$0 = \int_C F \cdot d\vec{r} = \int_{C_1} F \cdot d\vec{r} + \int_{-C_2} F \cdot d\vec{r} = \int_{C_1} F \cdot d\vec{r} - \int_{C_2} F \cdot d\vec{r}$$

Paths and path independence

Proof.

(Continued.) \Leftarrow : Conversely, let C_1 and C_2 be paths from P to Q . Let C_1 and $-C_2$ form a closed path C that starts and ends at P and

$$0 = \int_C F \cdot d\vec{r} = \int_{C_1} F \cdot d\vec{r} + \int_{-C_2} F \cdot d\vec{r} = \int_{C_1} F \cdot d\vec{r} - \int_{C_2} F \cdot d\vec{r}$$

So the line integral of F is independent of path.



Paths and path independence

Proof.

(Continued.) \Leftarrow : Conversely, let C_1 and C_2 be paths from P to Q . Let C_1 and $-C_2$ form a closed path C that starts and ends at P and

$$0 = \int_C F \cdot d\vec{r} = \int_{C_1} F \cdot d\vec{r} + \int_{-C_2} F \cdot d\vec{r} = \int_{C_1} F \cdot d\vec{r} - \int_{C_2} F \cdot d\vec{r}$$

So the line integral of F is independent of path. □

The following is an immediate consequence of the Fundamental Theorem of Line Integrals:

Theorem

Let $F : D \longrightarrow \mathbb{R}^3$, where $D \subseteq \mathbb{R}^3$, be a continuous vector field. If F is conservative, then the line integral of F is independent of path.

Paths and Path Independence: Example

Let \mathcal{C} be the closed path that is composed of

\mathcal{C}_1 : $x = y^2$, $z = 0$ between $(0, 0, 0)$ and $(1, 1, 0)$

\mathcal{C}_2 : is the straight line joining $(1, 1, 0)$ and $(1, 1, 1)$

\mathcal{C}_3 : is the straight line joining $(1, 1, 1)$ and $(0, 0, 0)$

Consider the vector field $F : \mathbb{R}^3 \longrightarrow \mathbb{R}^3$ defined by

$$F(x, y, z) = yz\bar{i} + xy\bar{j} + zx\bar{k}$$

Paths and Path Independence: Example

Let \mathcal{C} be the closed path that is composed of

\mathcal{C}_1 : $x = y^2$, $z = 0$ between $(0, 0, 0)$ and $(1, 1, 0)$

\mathcal{C}_2 : is the straight line joining $(1, 1, 0)$ and $(1, 1, 1)$

\mathcal{C}_3 : is the straight line joining $(1, 1, 1)$ and $(0, 0, 0)$

Consider the vector field $F : \mathbb{R}^3 \longrightarrow \mathbb{R}^3$ defined by

$$F(x, y, z) = yz\bar{i} + xy\bar{j} + zx\bar{k}$$

Along \mathcal{C}_1 , $\bar{r}(y) = y^2\bar{i} + y\bar{j}$ for $0 \leq y \leq 1$ and $F(\bar{r}(y)) = y^3\bar{j}$.

Paths and Path Independence: Example

Let \mathcal{C} be the closed path that is composed of

\mathcal{C}_1 : $x = y^2$, $z = 0$ between $(0, 0, 0)$ and $(1, 1, 0)$

\mathcal{C}_2 : is the straight line joining $(1, 1, 0)$ and $(1, 1, 1)$

\mathcal{C}_3 : is the straight line joining $(1, 1, 1)$ and $(0, 0, 0)$

Consider the vector field $F : \mathbb{R}^3 \longrightarrow \mathbb{R}^3$ defined by

$$F(x, y, z) = yz\vec{i} + xy\vec{j} + zx\vec{k}$$

Along \mathcal{C}_1 , $\vec{r}(y) = y^2\vec{i} + y\vec{j}$ for $0 \leq y \leq 1$ and $F(\vec{r}(y)) = y^3\vec{j}$.

$$\Rightarrow \frac{d\vec{r}}{dy} = 2y\vec{i} + \vec{j}$$

Paths and Path Independence: Example

Let \mathcal{C} be the closed path that is composed of

\mathcal{C}_1 : $x = y^2$, $z = 0$ between $(0, 0, 0)$ and $(1, 1, 0)$

\mathcal{C}_2 : is the straight line joining $(1, 1, 0)$ and $(1, 1, 1)$

\mathcal{C}_3 : is the straight line joining $(1, 1, 1)$ and $(0, 0, 0)$

Consider the vector field $F : \mathbb{R}^3 \longrightarrow \mathbb{R}^3$ defined by

$$F(x, y, z) = yz\vec{i} + xy\vec{j} + zx\vec{k}$$

Along \mathcal{C}_1 , $\vec{r}(y) = y^2\vec{i} + y\vec{j}$ for $0 \leq y \leq 1$ and $F(\vec{r}(y)) = y^3\vec{j}$.

$$\Rightarrow \frac{d\vec{r}}{dy} = 2y\vec{i} + \vec{j}$$

$$\Rightarrow \int_{\mathcal{C}_1} F \cdot d\vec{r} = \int_0^1 y^3 dy = \frac{1}{4}$$

Paths and Path Independence: Example (Continued.)

Along C_2 , $\bar{r}(z) = \bar{i} + \bar{j} + z\bar{k}$ for $0 \leq z \leq 1$ and $F(\bar{r}(z)) = z\bar{i} + \bar{j} + z\bar{k}$.

Paths and Path Independence: Example (Continued.)

Along C_2 , $\bar{r}(z) = \bar{i} + \bar{j} + z\bar{k}$ for $0 \leq z \leq 1$ and $F(\bar{r}(z)) = z\bar{i} + \bar{j} + z\bar{k}$.

Therefore

$$\frac{d\bar{r}}{dz} = \bar{k}$$

Paths and Path Independence: Example (Continued.)

Along C_2 , $\vec{r}(z) = \vec{i} + \vec{j} + z\vec{k}$ for $0 \leq z \leq 1$ and $F(\vec{r}(z)) = z\vec{i} + \vec{j} + z\vec{k}$.

Therefore

$$\frac{d\vec{r}}{dz} = \vec{k}$$

$$\Rightarrow \int_{C_2} F \cdot d\vec{r} = \int_0^1 z \, dz = \frac{1}{2}$$

Paths and Path Independence: Example (Continued.)

Along C_2 , $\vec{r}(z) = \vec{i} + \vec{j} + z\vec{k}$ for $0 \leq z \leq 1$ and $F(\vec{r}(z)) = z\vec{i} + \vec{j} + z\vec{k}$.

Therefore

$$\frac{d\vec{r}}{dz} = \vec{k}$$

$$\Rightarrow \int_{C_2} F \cdot d\vec{r} = \int_0^1 z \, dz = \frac{1}{2}$$

Along C_3 , $\vec{r}(x) = x\vec{i} + x\vec{j} + x\vec{k}$ for $1 \geq x \geq 0$ and $F(\vec{r}(x)) = x^2\vec{i} + x^2\vec{j} + x^2\vec{k}$.

Paths and Path Independence: Example (Continued.)

Along C_2 , $\vec{r}(z) = \vec{i} + \vec{j} + z\vec{k}$ for $0 \leq z \leq 1$ and $F(\vec{r}(z)) = z\vec{i} + \vec{j} + z\vec{k}$.

Therefore

$$\frac{d\vec{r}}{dz} = \vec{k}$$

$$\Rightarrow \int_{C_2} F \cdot d\vec{r} = \int_0^1 z \, dz = \frac{1}{2}$$

Along C_3 , $\vec{r}(x) = x\vec{i} + x\vec{j} + x\vec{k}$ for $1 \geq x \geq 0$ and $F(\vec{r}(x)) = x^2\vec{i} + x^2\vec{j} + x^2\vec{k}$. Therefore

$$\frac{d\vec{r}}{dx} = \vec{i} + \vec{j} + \vec{k}$$

Paths and path independence

Example

(Continued.) So,

$$\int_{C_3} F \cdot \bar{dr} = - \int_0^1 3x^2 \, dx = -1$$

Paths and path independence

Example

(Continued.) So,

$$\int_{C_3} F \cdot \bar{dr} = - \int_0^1 3x^2 dx = -1$$

In total, we get

$$\int_C F \cdot \bar{dr} = \int_{C_1} F \cdot \bar{dr} + \int_{C_2} F \cdot \bar{dr} + \int_{C_3} F \cdot \bar{dr} = \frac{1}{4} + \frac{1}{2} - 1 \neq 0$$

Paths and path independence

Example

(Continued.) So,

$$\int_{C_3} F \cdot \bar{dr} = - \int_0^1 3x^2 dx = -1$$

In total, we get

$$\int_C F \cdot \bar{dr} = \int_{C_1} F \cdot \bar{dr} + \int_{C_2} F \cdot \bar{dr} + \int_{C_3} F \cdot \bar{dr} = \frac{1}{4} + \frac{1}{2} - 1 \neq 0$$

This shows that the line integral of the vector field F is NOT independent of path.

Paths and path independence

Example

(Continued.) So,

$$\int_{C_3} F \cdot \bar{dr} = - \int_0^1 3x^2 dx = -1$$

In total, we get

$$\int_C F \cdot \bar{dr} = \int_{C_1} F \cdot \bar{dr} + \int_{C_2} F \cdot \bar{dr} + \int_{C_3} F \cdot \bar{dr} = \frac{1}{4} + \frac{1}{2} - 1 \neq 0$$

This shows that the line integral of the vector field F is NOT independent of path. This means that F is not conservative (although, this can also be obtained by appealing to Clairaut's Theorem as we did previously).

Paths and path independence

Example

(Continued.) So,

$$\int_{C_3} F \cdot \bar{dr} = - \int_0^1 3x^2 dx = -1$$

In total, we get

$$\int_C F \cdot \bar{dr} = \int_{C_1} F \cdot \bar{dr} + \int_{C_2} F \cdot \bar{dr} + \int_{C_3} F \cdot \bar{dr} = \frac{1}{4} + \frac{1}{2} - 1 \neq 0$$

This shows that the line integral of the vector field F is NOT independent of path. This means that F is not conservative (although, this can also be obtained by appealing to Clairaut's Theorem as we did previously).

We now turn to developing some machinery that will allow us to show that a vector is conservative.

Paths and path independence

Example

(Continued.) So,

$$\int_{C_3} F \cdot \bar{dr} = - \int_0^1 3x^2 dx = -1$$

In total, we get

$$\int_C F \cdot \bar{dr} = \int_{C_1} F \cdot \bar{dr} + \int_{C_2} F \cdot \bar{dr} + \int_{C_3} F \cdot \bar{dr} = \frac{1}{4} + \frac{1}{2} - 1 \neq 0$$

This shows that the line integral of the vector field F is NOT independent of path. This means that F is not conservative (although, this can also be obtained by appealing to Clairaut's Theorem as we did previously).

We now turn to developing some machinery that will allow us to show that a vector is conservative.

Definition

We say that $D \subseteq \mathbb{R}^n$ is *open* if for all $\bar{a} \in D$, there exists $\epsilon > 0$ such that $B(\bar{a}, \epsilon) \subseteq D$.

Conservative vector fields

That is, $D \subseteq \mathbb{R}^n$ is open if every point in D can be enclosed in a ball that is contained in D .

Conservative vector fields

That is, $D \subseteq \mathbb{R}^n$ is open if every point in D can be enclosed in a ball that is contained in D . Note that an open set of \mathbb{R}^n is a set that contains NONE of its boundary points.

Conservative vector fields

That is, $D \subseteq \mathbb{R}^n$ is open if every point in D can be enclosed in a ball that is contained in D . Note that an open set of \mathbb{R}^n is a set that contains NONE of its boundary points.

Definition

We say that $D \subseteq \mathbb{R}^n$ (for $n = 2$ or $n = 3$) is *connected* if for all points P and Q in D , there is a path from P to Q that is contained in D .

Conservative vector fields

That is, $D \subseteq \mathbb{R}^n$ is open if every point in D can be enclosed in a ball that is contained in D . Note that an open set of \mathbb{R}^n is a set that contains NONE of its boundary points.

Definition

We say that $D \subseteq \mathbb{R}^n$ (for $n = 2$ or $n = 3$) is *connected* if for all points P and Q in D , there is a path from P to Q that is contained in D .

Theorem

Let F be a vector field on \mathbb{R}^3 (or \mathbb{R}^2) that is continuous on an open connected region D in \mathbb{R}^3 (\mathbb{R}^2 , respectively). If the line integral of F on D is independent of path, then F is conservative.

Conservative vector fields

That is, $D \subseteq \mathbb{R}^n$ is open if every point in D can be enclosed in a ball that is contained in D . Note that an open set of \mathbb{R}^n is a set that contains NONE of its boundary points.

Definition

We say that $D \subseteq \mathbb{R}^n$ (for $n = 2$ or $n = 3$) is *connected* if for all points P and Q in D , there is a path from P to Q that is contained in D .

Theorem

Let F be a vector field on \mathbb{R}^3 (or \mathbb{R}^2) that is continuous on an open connected region D in \mathbb{R}^3 (\mathbb{R}^2 , respectively). If the line integral of F on D is independent of path, then F is conservative.

We will sketch a proof of this result for vector fields on \mathbb{R}^2 . It should be reasonably clear how the argument can be modified to deal with vector fields on \mathbb{R}^3 .

Conservative vector fields

Proof.

(Sketch.) Let $F = \alpha(x, y)\vec{i} + \beta(x, y)\vec{j}$ where α and β are continuous on the open connected region D . Let P be any point in D .

Conservative vector fields

Proof.

(Sketch.) Let $F = \alpha(x, y)\vec{i} + \beta(x, y)\vec{j}$ where α and β are continuous on the open connected region D . Let P be any point in D . Define $f : D \rightarrow \mathbb{R}$ by: $f(x, y)$ is the line integral of F from P to (x, y) along a path from P to (x, y) in D .

Conservative vector fields

Proof.

(Sketch.) Let $F = \alpha(x, y)\vec{i} + \beta(x, y)\vec{j}$ where α and β are continuous on the open connected region D . Let P be any point in D . Define $f : D \rightarrow \mathbb{R}$ by: $f(x, y)$ is the line integral of F from P to (x, y) along a path from P to (x, y) in D . Since D is open and connected, and the line integral of F is independent of path, f is well-defined.

Conservative vector fields

Proof.

(Sketch.) Let $F = \alpha(x, y)\vec{i} + \beta(x, y)\vec{j}$ where α and β are continuous on the open connected region D . Let P be any point in D . Define $f : D \rightarrow \mathbb{R}$ by: $f(x, y)$ is the line integral of F from P to (x, y) along a path from P to (x, y) in D . Since D is open and connected, and the line integral of F is independent of path, f is well-defined. Since D is open, we can find an open ball B that is centered at (x, y) and is contained in D .

Conservative vector fields

Proof.

(Sketch.) Let $F = \alpha(x, y)\vec{i} + \beta(x, y)\vec{j}$ where α and β are continuous on the open connected region D . Let P be any point in D . Define $f : D \rightarrow \mathbb{R}$ by: $f(x, y)$ is the line integral of F from P to (x, y) along a path from P to (x, y) in D . Since D is open and connected, and the line integral of F is independent of path, f is well-defined. Since D is open, we can find an open ball B that is centered at (x, y) and is contained in D . Let (x', y) be a point in B with $x' < x$. Let C_1 be a path from P to (x', y) , let C_2 be the (horizontal) line that connects (x', y) and (x, y) .

Conservative vector fields

Proof.

(Sketch.) Let $F = \alpha(x, y)\vec{i} + \beta(x, y)\vec{j}$ where α and β are continuous on the open connected region D . Let P be any point in D . Define $f : D \rightarrow \mathbb{R}$ by: $f(x, y)$ is the line integral of F from P to (x, y) along a path from P to (x, y) in D . Since D is open and connected, and the line integral of F is independent of path, f is well-defined. Since D is open, we can find an open ball B that is centered at (x, y) and is contained in D . Let (x', y) be a point in B with $x' < x$. Let C_1 be a path from P to (x', y) , let C_2 be the (horizontal) line that connects (x', y) and (x, y) . Therefore

$$f(x, y) = \int_{C_1} F \cdot d\vec{r} + \int_{C_2} F \cdot d\vec{r}$$

Conservative vector fields

Proof.

(Sketch.) Let $F = \alpha(x, y)\bar{i} + \beta(x, y)\bar{j}$ where α and β are continuous on the open connected region D . Let P be any point in D . Define $f : D \rightarrow \mathbb{R}$ by: $f(x, y)$ is the line integral of F from P to (x, y) along a path from P to (x, y) in D . Since D is open and connected, and the line integral of F is independent of path, f is well-defined. Since D is open, we can find an open ball B that is centered at (x, y) and is contained in D . Let (x', y) be a point in B with $x' < x$. Let C_1 be a path from P to (x', y) , let C_2 be the (horizontal) line that connects (x', y) and (x, y) . Therefore

$$f(x, y) = \int_{C_1} F \cdot d\vec{r} + \int_{C_2} F \cdot d\vec{r}$$

Note that the line integral of F along C_1 is constant, so

$$\frac{\partial}{\partial x} f(x, y) = \frac{\partial}{\partial x} \int_{C_2} F \cdot d\vec{r}$$

Conservative vector fields

Proof.

Now,

$$\int_{C_2} \mathbf{F} \cdot d\vec{r} = \int_{C_2} \alpha(x, y) \, dx + \beta(x, y) \, dy$$

Conservative vector fields

Proof.

Now,

$$\int_{\mathcal{C}_2} \mathbf{F} \cdot d\vec{r} = \int_{\mathcal{C}_2} \alpha(x, y) \, dx + \beta(x, y) \, dy$$

The line integral of \mathbf{F} along \mathcal{C}_2 with respect to y is 0 (\mathcal{C}_2 is a horizontal line).

Conservative vector fields

Proof.

Now,

$$\int_{C_2} F \cdot d\vec{r} = \int_{C_2} \alpha(x, y) dx + \beta(x, y) dy$$

The line integral of F along C_2 with respect to y is 0 (C_2 is a horizontal line). Therefore

$$\int_{C_2} F \cdot d\vec{r} = \int_{C_2} \alpha(x, y) dx = \int_{x'}^x \alpha(t, y) dt$$

Conservative vector fields

Proof.

Now,

$$\int_{\mathcal{C}_2} F \cdot d\vec{r} = \int_{\mathcal{C}_2} \alpha(x, y) dx + \beta(x, y) dy$$

The line integral of F along \mathcal{C}_2 with respect to y is 0 (\mathcal{C}_2 is a horizontal line). Therefore

$$\int_{\mathcal{C}_2} F \cdot d\vec{r} = \int_{\mathcal{C}_2} \alpha(x, y) dx = \int_{x'}^x \alpha(t, y) dt$$

And, by the Second Fundamental Theorem,

$$\frac{\partial}{\partial x} f(x, y) = \frac{\partial}{\partial x} \int_{x'}^x \alpha(t, y) dt = \alpha(x, y)$$

Conservative vector fields

Proof.

Now,

$$\int_{\mathcal{C}_2} F \cdot d\vec{r} = \int_{\mathcal{C}_2} \alpha(x, y) dx + \beta(x, y) dy$$

The line integral of F along \mathcal{C}_2 with respect to y is 0 (\mathcal{C}_2 is a horizontal line). Therefore

$$\int_{\mathcal{C}_2} F \cdot d\vec{r} = \int_{\mathcal{C}_2} \alpha(x, y) dx = \int_{x'}^x \alpha(t, y) dt$$

And, by the Second Fundamental Theorem,

$$\frac{\partial}{\partial x} f(x, y) = \frac{\partial}{\partial x} \int_{x'}^x \alpha(t, y) dt = \alpha(x, y)$$

A similar argument where \mathcal{C}_2 is replaced by a vertical line shows that

$$\frac{\partial}{\partial y} f(x, y) = \beta(x, y)$$

Conservative vector fields

Proof.

Since $(x, y) \in D$ was arbitrary, it follows that $\nabla f = F$ and so F is conservative.



Conservative vector fields

Proof.

Since $(x, y) \in D$ was arbitrary, it follows that $\nabla f = F$ and so F is conservative. □

Example

Recall that the vortex vector field $F : D \rightarrow \mathbb{R}^2$, where $D = \mathbb{R}^2 \setminus \{(0, 0)\}$, defined by

$$F(x, y) = \left(\frac{-y}{x^2 + y^2} \right) \bar{i} + \left(\frac{x}{x^2 + y^2} \right) \bar{j}$$

Let \mathcal{C} be the unit circle described by $x^2 + y^2 = 1$ (i.e. \mathcal{C} is a closed path). Since

$$\int_{\mathcal{C}} F \cdot d\bar{r} = 2\pi,$$

the line integral of F is not independent of path and so F is NOT conservative.

Conservative vector fields

Example

Consider $F : \mathbb{R}^3 \longrightarrow \mathbb{R}^3$ defined by

$$F(x, y, z) = yz\vec{i} + xz\vec{j} + (xy + 2z)\vec{k}$$

Find $f : \mathbb{R}^3 \longrightarrow \mathbb{R}$ such that $\nabla f = F$ and compute

$$\int_{\mathcal{C}} F \cdot d\vec{r}$$

where \mathcal{C} is the line that connects $(1, 0, -2)$ and $(4, 6, 3)$.

Line Integrals: First Summary

1. The **line integral** of γ along \mathcal{C} is defined by

$$\int_{\mathcal{C}} \gamma(x, y, z) \, ds = \int_a^b \gamma(f(t), g(t), h(t)) \sqrt{(f'(t))^2 + (g'(t))^2 + (h'(t))^2} \, dt$$

2. The **line integral of F along \mathcal{C}** by

$$\int_{\mathcal{C}} F \cdot d\vec{r} = \int_a^b F(\vec{r}(t)) \cdot \vec{r}'(t) \, dt$$

3. **Fundamental Theorem of Line Integrals**

$$\int_{\mathcal{C}} \nabla f \cdot d\vec{r} = f(\vec{r}(b)) - f(\vec{r}(a))$$

4. **Theorem:** The line integral of F is independent of path if and only if for every closed path \mathcal{C} ,

$$\int_{\mathcal{C}} F \cdot d\vec{r} = 0$$

5. **Theorem:** If F is conservative, then the line integral of F is independent of path.
6. **Theorem:** If the line integral of a continuous on an open connected region D vector field F on D is independent of path, then F is conservative.

Today

1. Simple curves and simply-connected regions
2. Positively oriented simple closed curves
3. Green's Theorem

Simple Curves and Simply-connected Regions

Definition

Let \mathcal{C} be a curve described by the vector function $\bar{r} : [a, b] \longrightarrow \mathbb{R}^n$. We say that \mathcal{C} is *simple* if for all $a < t_1 < t_2 < b$, $\bar{r}(t_1) \neq \bar{r}(t_2)$. We say that \mathcal{C} is a *simple closed curve* if \mathcal{C} is simple and $\bar{r}(a) = \bar{r}(b)$.

Simple Curves and Simply-connected Regions

Definition

Let \mathcal{C} be a curve described by the vector function $\bar{r} : [a, b] \rightarrow \mathbb{R}^n$. We say that \mathcal{C} is *simple* if for all $a < t_1 < t_2 < b$, $\bar{r}(t_1) \neq \bar{r}(t_2)$. We say that \mathcal{C} is a *simple closed curve* if \mathcal{C} is simple and $\bar{r}(a) = \bar{r}(b)$.

- ▶ A simple curve is a curve that does not intersect itself, except, possibly, at its initial and terminal point

Simple Curves and Simply-connected Regions

Definition

Let \mathcal{C} be a curve described by the vector function $\bar{r} : [a, b] \rightarrow \mathbb{R}^n$. We say that \mathcal{C} is *simple* if for all $a < t_1 < t_2 < b$, $\bar{r}(t_1) \neq \bar{r}(t_2)$. We say that \mathcal{C} is a *simple closed curve* if \mathcal{C} is simple and $\bar{r}(a) = \bar{r}(b)$.

- ▶ A simple curve is a curve that does not intersect itself, except, possibly, at its initial and terminal point
- ▶ A simple closed curve is a closed path that does not intersect itself

Simple Curves and Simply-connected Regions

Definition

Let \mathcal{C} be a curve described by the vector function $\bar{r} : [a, b] \rightarrow \mathbb{R}^n$. We say that \mathcal{C} is *simple* if for all $a < t_1 < t_2 < b$, $\bar{r}(t_1) \neq \bar{r}(t_2)$. We say that \mathcal{C} is a *simple closed curve* if \mathcal{C} is simple and $\bar{r}(a) = \bar{r}(b)$.

- ▶ A simple curve is a curve that does not intersect itself, except, possibly, at its initial and terminal point
- ▶ A simple closed curve is a closed path that does not intersect itself
- ▶ A simple closed curve \mathcal{C} defines the boundary of region D that we call the *region enclosed by \mathcal{C}* . Note that we will always include the points on \mathcal{C} in the region enclosed by \mathcal{C} . So, the region enclosed by \mathcal{C} is a bounded region that contains all of its boundary points.

Simple Curves and Simply-connected Regions

Definition

Let \mathcal{C} be a curve described by the vector function $\vec{r} : [a, b] \rightarrow \mathbb{R}^n$. We say that \mathcal{C} is *simple* if for all $a < t_1 < t_2 < b$, $\vec{r}(t_1) \neq \vec{r}(t_2)$. We say that \mathcal{C} is a *simple closed curve* if \mathcal{C} is simple and $\vec{r}(a) = \vec{r}(b)$.

- ▶ A simple curve is a curve that does not intersect itself, except, possibly, at its initial and terminal point
- ▶ A simple closed curve is a closed path that does not intersect itself
- ▶ A simple closed curve \mathcal{C} defines the boundary of region D that we call the *region enclosed by \mathcal{C}* . Note that we will always include the points on \mathcal{C} in the region enclosed by \mathcal{C} . So, the region enclosed by \mathcal{C} is a bounded region that contains all of its boundary points.

Definition

A region $D \subseteq \mathbb{R}^n$ (for $n = 2$ or $n = 3$) is said to be *simply-connected* if D is connected and for all simple closed curves \mathcal{C} contained in D , the region enclosed by \mathcal{C} is contained in D .

Simple Curves and Simply-connected Regions

Example

The region

$$D_1 = \{(x, y) \in \mathbb{R}^2 \mid x^2 + y^2 \leq 1\}$$

is simply-connected.

Simple Curves and Simply-connected Regions

Example

The region

$$D_1 = \{(x, y) \in \mathbb{R}^2 \mid x^2 + y^2 \leq 1\}$$

is simply-connected. The region

$$D_2 = \{(x, y) \in \mathbb{R}^2 \mid 0 < x^2 + y^2 \leq 1\}$$

is not simply connected because the simple closed curve described by $\vec{r}(t) = \frac{1}{2}(\cos(t)\vec{i} + \sin(t)\vec{j})$ is contained in D_2 and encloses the point $(0, 0)$ that is not in D_2 .

Simple Curves and Simply-connected Regions

Example

The region

$$D_1 = \{(x, y) \in \mathbb{R}^2 \mid x^2 + y^2 \leq 1\}$$

is simply-connected. The region

$$D_2 = \{(x, y) \in \mathbb{R}^2 \mid 0 < x^2 + y^2 \leq 1\}$$

is not simply connected because the simple closed curve described by $\vec{r}(t) = \frac{1}{2}(\cos(t)\vec{i} + \sin(t)\vec{j})$ is contained in D_2 and encloses the point $(0, 0)$ that is not in D_2 .

Intuitively, simply connected regions are connected regions that have no holes.

Simple Curves and Simply-connected Regions

Example

The region

$$D_1 = \{(x, y) \in \mathbb{R}^2 \mid x^2 + y^2 \leq 1\}$$

is simply-connected. The region

$$D_2 = \{(x, y) \in \mathbb{R}^2 \mid 0 < x^2 + y^2 \leq 1\}$$

is not simply connected because the simple closed curve described by $\bar{r}(t) = \frac{1}{2}(\cos(t)\bar{i} + \sin(t)\bar{j})$ is contained in D_2 and encloses the point $(0, 0)$ that is not in D_2 .

Intuitively, simply connected regions are connected regions that have no holes.

Let \mathcal{C} be a simple closed curve described by $\bar{r} : [a, b] \rightarrow \mathbb{R}^2$. As was mentioned we were discussing line integral, in addition to specifying the points on \mathcal{C} , the parameterisation \bar{r} also specifies a direction — \mathcal{C} runs from $\bar{r}(a)$ to $\bar{r}(b)$.

Green's Theorem

In light of this, we introduce the following terminology that allows us to talk about the direction specified by the parameterisation of a curve:

Definition

Let \mathcal{C} be a simple closed curve described by $\bar{r} : [a, b] \longrightarrow \mathbb{R}^2$. We say that \mathcal{C} is *positively oriented* and call \bar{r} a *positive orientation of \mathcal{C}* if $\bar{r}(t)$ moves anticlockwise around \mathcal{C} as t ranges from a to b .

Green's Theorem

In light of this, we introduce the following terminology that allows us to talk about the direction specified by the parameterisation of a curve:

Definition

Let \mathcal{C} be a simple closed curve described by $\bar{r} : [a, b] \rightarrow \mathbb{R}^2$. We say that \mathcal{C} is *positively oriented* and call \bar{r} a *positive orientation of \mathcal{C}* if $\bar{r}(t)$ moves anticlockwise around \mathcal{C} as t ranges from a to b .

We will use the symbols

$$\oint_{\mathcal{C}} \text{ or } \oint_{\mathcal{C}}$$

to indicate that we are invoking a line integral around a positively oriented curve \mathcal{C} , or indicate that the line integral is being computed using the positive orientation of \mathcal{C} if the orientation of \mathcal{C} is ambiguous.

Green's Theorem

In light of this, we introduce the following terminology that allows us to talk about the direction specified by the parameterisation of a curve:

Definition

Let \mathcal{C} be a simple closed curve described by $\bar{r} : [a, b] \rightarrow \mathbb{R}^2$. We say that \mathcal{C} is *positively oriented* and call \bar{r} a *positive orientation of \mathcal{C}* if $\bar{r}(t)$ moves anticlockwise around \mathcal{C} as t ranges from a to b .

We will use the symbols

$$\oint_{\mathcal{C}} \text{ or } \oint_{\mathcal{C}}$$

to indicate that we are invoking a line integral around a positively oriented curve \mathcal{C} , or indicate that the line integral is being computed using the positive orientation of \mathcal{C} if the orientation of \mathcal{C} is ambiguous. We may also use the symbol

$$\oint$$

if \mathcal{C} is **not** positively oriented.

Green's Theorem

- ▶ Previously, we established a version of the First Fundamental Theorem of Calculus for line integrals of multivariable functions.

Green's Theorem

- ▶ Previously, we established a version of the First Fundamental Theorem of Calculus for line integrals of multivariable functions.
- ▶ We now turn to discussing a result that can be viewed as a "First Fundamental Theorem of Calculus for double integrals".

Green's Theorem

- ▶ Previously, we established a version of the First Fundamental Theorem of Calculus for line integrals of multivariable functions.
- ▶ We now turn to discussing a result that can be viewed as a "First Fundamental Theorem of Calculus for double integrals".
- ▶ One way of interpreting the First Fundamental Theorem of Calculus is by reading it as saying that the integral of a function f over an interval $[a, b]$ is completely determined by the behaviour of the antiderivative of f at the boundary points of $[a, b]$.

Green's Theorem

- ▶ Previously, we established a version of the First Fundamental Theorem of Calculus for line integrals of multivariable functions.
- ▶ We now turn to discussing a result that can be viewed as a "First Fundamental Theorem of Calculus for double integrals".
- ▶ One way of interpreting the First Fundamental Theorem of Calculus is by reading it as saying that the integral of a function f over an interval $[a, b]$ is completely determined by the behaviour of the antiderivative of f at the boundary points of $[a, b]$.
- ▶ Viewing the First Fundamental Theorem from this perspective, we may speculate that the double integral of a function f over a region \mathcal{R} might be completely determined by the behaviour of something that looks like the antiderivative of f on the boundary of \mathcal{R} .

Green's Theorem

Theorem

(Green's Theorem) Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} . Let $D \subseteq \mathbb{R}^2$ be an open region that contains \mathcal{R} .

If $P : D \rightarrow \mathbb{R}$ and $Q : D \rightarrow \mathbb{R}$ have continuous partial derivatives on D , then

$$\int_{\mathcal{C}} P \, dx + Q \, dy = \iint_{\mathcal{R}} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \, dA$$

Green's Theorem

Theorem

(Green's Theorem) Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} . Let $D \subseteq \mathbb{R}^2$ be an open region that contains \mathcal{R} .

If $P : D \rightarrow \mathbb{R}$ and $Q : D \rightarrow \mathbb{R}$ have continuous partial derivatives on D , then

$$\int_{\mathcal{C}} P \, dx + Q \, dy = \iint_{\mathcal{R}} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \, dA$$

If $D \subseteq \mathbb{R}^2$ is a bounded simply-connected region that contains all of its boundary points and the boundary of D is a piecewise-smooth simple closed curve, then we will sometimes use ∂D to denote this boundary curve.

Green's Theorem

Theorem

(Green's Theorem) Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} . Let $D \subseteq \mathbb{R}^2$ be an open region that contains \mathcal{R} .

If $P : D \rightarrow \mathbb{R}$ and $Q : D \rightarrow \mathbb{R}$ have continuous partial derivatives on D , then

$$\int_{\mathcal{C}} P \, dx + Q \, dy = \iint_{\mathcal{R}} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$$

If $D \subseteq \mathbb{R}^2$ is a bounded simply-connected region that contains all of its boundary points and the boundary of D is a piecewise-smooth simple closed curve, then we will sometimes use ∂D to denote this boundary curve. Therefore the conclusion of Green's Theorem could also be written

$$\oint_{\partial \mathcal{R}} P \, dx + Q \, dy = \iint_{\mathcal{R}} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$$

Green's Theorem

To give an idea of why Green's Theorem might be true and what is going on behind the scenes we will sketch the proof of a very specific case of Green's Theorem. Recall that when we were discussing double integrals we encountered regions that could be described as both type I and type II bounded regions (we used this to change the order of integration).

Green's Theorem

To give an idea of why Green's Theorem might be true and what is going on behind the scenes we will sketch the proof of a very specific case of Green's Theorem. Recall that when we were discussing double integrals we encountered regions that could be described as both type I and type II bounded regions (we used this to change the order of integration).

Definition

*We say that a bounded region \mathcal{R} in \mathbb{R}^2 is **simple** if \mathcal{R} is both a type I and a type II bounded region.*

Green's Theorem

To give an idea of why Green's Theorem might be true and what is going on behind the scenes we will sketch the proof of a very specific case of Green's Theorem. Recall that when we were discussing double integrals we encountered regions that could be described as both type I and type II bounded regions (we used this to change the order of integration).

Definition

*We say that a bounded region \mathcal{R} in \mathbb{R}^2 is **simple** if \mathcal{R} is both a type I and a type II bounded region.*

Proof.

(Sketch of a very specific case of Green's Theorem) We will sketch a proof of Green's Theorem in the case that \mathcal{R} is a simple bounded region described by smooth functions and \mathcal{C} is the boundary of \mathcal{R} .

Green's Theorem

To give an idea of why Green's Theorem might be true and what is going on behind the scenes we will sketch the proof of a very specific case of Green's Theorem. Recall that when we were discussing double integrals we encountered regions that could be described as both type I and type II bounded regions (we used this to change the order of integration).

Definition

We say that a bounded region \mathcal{R} in \mathbb{R}^2 is *simple* if \mathcal{R} is both a type I and a type II bounded region.

Proof.

(Sketch of a very specific case of Green's Theorem) We will sketch a proof of Green's Theorem in the case that \mathcal{R} is a simple bounded region described by smooth functions and \mathcal{C} is the boundary of \mathcal{R} .

Let $g_1 : [a, b] \rightarrow \mathbb{R}$ and $g_2 : [a, b] \rightarrow \mathbb{R}$ be smooth functions such that for all $a \leq x \leq b$, $g_1(x) \leq g_2(x)$ and

$$\mathcal{R} = \{(x, y) \in \mathbb{R}^2 \mid a \leq x \leq b, g_1(x) \leq y \leq g_2(x)\}$$

Green's Theorem

Proof.

So \mathcal{C} is the piecewise-smooth curve composed of the smooth curves \mathcal{C}_1 , \mathcal{C}_2 , \mathcal{C}_3 and $-\mathcal{C}_4$ where:

Green's Theorem

Proof.

So \mathcal{C} is the piecewise-smooth curve composed of the smooth curves \mathcal{C}_1 , \mathcal{C}_2 , \mathcal{C}_3 and $-\mathcal{C}_4$ where:

- ▶ \mathcal{C}_1 is the line between $(a, g_2(a))$ and $(a, g_1(a))$

Green's Theorem

Proof.

So \mathcal{C} is the piecewise-smooth curve composed of the smooth curves \mathcal{C}_1 , \mathcal{C}_2 , \mathcal{C}_3 and $-\mathcal{C}_4$ where:

- ▶ \mathcal{C}_1 is the line between $(a, g_2(a))$ and $(a, g_1(a))$
- ▶ \mathcal{C}_2 is the curve parameterised by $g_1(t)$ for $t \in [a, b]$

Green's Theorem

Proof.

So \mathcal{C} is the piecewise-smooth curve composed of the smooth curves \mathcal{C}_1 , \mathcal{C}_2 , \mathcal{C}_3 and $-\mathcal{C}_4$ where:

- ▶ \mathcal{C}_1 is the line between $(a, g_2(a))$ and $(a, g_1(a))$
- ▶ \mathcal{C}_2 is the curve parameterised by $g_1(t)$ for $t \in [a, b]$
- ▶ \mathcal{C}_3 is the line between $(b, g_1(b))$ and $(b, g_2(b))$

Green's Theorem

Proof.

So \mathcal{C} is the piecewise-smooth curve composed of the smooth curves \mathcal{C}_1 , \mathcal{C}_2 , \mathcal{C}_3 and $-\mathcal{C}_4$ where:

- ▶ \mathcal{C}_1 is the line between $(a, g_2(a))$ and $(a, g_1(a))$
- ▶ \mathcal{C}_2 is the curve parameterised by $g_1(t)$ for $t \in [a, b]$
- ▶ \mathcal{C}_3 is the line between $(b, g_1(b))$ and $(b, g_2(b))$
- ▶ \mathcal{C}_4 is the curve parameterised by $g_2(t)$ for $t \in [a, b]$

Green's Theorem

Proof.

So \mathcal{C} is the piecewise-smooth curve composed of the smooth curves \mathcal{C}_1 , \mathcal{C}_2 , \mathcal{C}_3 and $-\mathcal{C}_4$ where:

- ▶ \mathcal{C}_1 is the line between $(a, g_2(a))$ and $(a, g_1(a))$
- ▶ \mathcal{C}_2 is the curve parameterised by $g_1(t)$ for $t \in [a, b]$
- ▶ \mathcal{C}_3 is the line between $(b, g_1(b))$ and $(b, g_2(b))$
- ▶ \mathcal{C}_4 is the curve parameterised by $g_2(t)$ for $t \in [a, b]$

To prove Green's Theorem for \mathcal{R} and \mathcal{C} , let $D \supseteq \mathcal{R}$ be open and suppose that $Q : D \rightarrow \mathbb{R}$ and $P : D \rightarrow \mathbb{R}$ have continuous partial derivatives on D .

Green's Theorem

Proof.

So \mathcal{C} is the piecewise-smooth curve composed of the smooth curves \mathcal{C}_1 , \mathcal{C}_2 , \mathcal{C}_3 and $-\mathcal{C}_4$ where:

- ▶ \mathcal{C}_1 is the line between $(a, g_2(a))$ and $(a, g_1(a))$
- ▶ \mathcal{C}_2 is the curve parameterised by $g_1(t)$ for $t \in [a, b]$
- ▶ \mathcal{C}_3 is the line between $(b, g_1(b))$ and $(b, g_2(b))$
- ▶ \mathcal{C}_4 is the curve parameterised by $g_2(t)$ for $t \in [a, b]$

To prove Green's Theorem for \mathcal{R} and \mathcal{C} , let $D \supseteq \mathcal{R}$ be open and suppose that $Q : D \rightarrow \mathbb{R}$ and $P : D \rightarrow \mathbb{R}$ have continuous partial derivatives on D . Now,

$$\begin{aligned} \iint_{\mathcal{R}} \frac{\partial P}{\partial y} dA &= \int_a^b \int_{g_1(x)}^{g_2(x)} \frac{\partial P}{\partial y} dy dx \\ &= \int_a^b (P(x, g_2(x)) - P(x, g_1(x))) dx \end{aligned}$$

Green's Theorem

Proof.

(Continued.) Now, the curves \mathcal{C}_1 and \mathcal{C}_3 are vertical lines, so

$$\int_{\mathcal{C}_1} P \, dx = \int_{\mathcal{C}_3} P \, dx = 0$$

Green's Theorem

Proof.

(Continued.) Now, the curves \mathcal{C}_1 and \mathcal{C}_3 are vertical lines, so

$$\int_{\mathcal{C}_1} P \, dx = \int_{\mathcal{C}_3} P \, dx = 0$$

The curve \mathcal{C}_2 is parameterised by $\bar{r}_2(t) = t\bar{i} + g_1(t)\bar{j}$, so

$$\int_{\mathcal{C}_2} P \, dx = \int_a^b P(x, g_1(x)) \, dx$$

Green's Theorem

Proof.

(Continued.) Now, the curves C_1 and C_3 are vertical lines, so

$$\int_{C_1} P \, dx = \int_{C_3} P \, dx = 0$$

The curve C_2 is parameterised by $\vec{r}_2(t) = t\vec{i} + g_1(t)\vec{j}$, so

$$\int_{C_2} P \, dx = \int_a^b P(x, g_1(x)) \, dx$$

Similarly, the curve C_4 is parameterised by $\vec{r}_2(t) = t\vec{i} + g_2(t)\vec{j}$, so

$$\int_{-C_4} P \, dx = - \int_a^b P(x, g_2(x)) \, dx$$

Green's Theorem

Proof.

(Continued.) Now, the curves C_1 and C_3 are vertical lines, so

$$\int_{C_1} P \, dx = \int_{C_3} P \, dx = 0$$

The curve C_2 is parameterised by $\vec{r}_2(t) = t\vec{i} + g_1(t)\vec{j}$, so

$$\int_{C_2} P \, dx = \int_a^b P(x, g_1(x)) \, dx$$

Similarly, the curve C_4 is parameterised by $\vec{r}_2(t) = t\vec{i} + g_2(t)\vec{j}$, so

$$\int_{-C_4} P \, dx = - \int_a^b P(x, g_2(x)) \, dx$$

Therefore,

$$\int_C P \, dx = \int_a^b (P(x, g_1(x)) - P(x, g_2(x))) \, dx = - \iint_{\mathcal{R}} \frac{\partial P}{\partial y} \, dA$$

Green's Theorem

Proof.

(Continued.) Now, if \mathcal{R} can also be represented as a type II region, then a very similar argument shows that

$$\int_{\mathcal{C}} Q \, dy = \iint_{\mathcal{R}} \frac{\partial Q}{\partial x} \, dA$$

Green's Theorem

Proof.

(Continued.) Now, if \mathcal{R} can also be represented as a type II region, then a very similar argument shows that

$$\int_{\mathcal{C}} Q \, dy = \iint_{\mathcal{R}} \frac{\partial Q}{\partial x} \, dA$$

This shows that Green's Theorem holds in this special case.



Green's Theorem

Proof.

(Continued.) Now, if \mathcal{R} can also be represented as a type II region, then a very similar argument shows that

$$\int_{\mathcal{C}} Q \, dy = \iint_{\mathcal{R}} \frac{\partial Q}{\partial x} \, dA$$

This shows that Green's Theorem holds in this special case. □

This above proof can easily be extended to regions that can be broken apart into finitely many simple regions.

Green's Theorem

- ▶ One application of Green's Theorem is that it allows us to compute the area enclosed by arbitrary piecewise-smooth simple closed curves.

Green's Theorem

- ▶ One application of Green's Theorem is that it allows us to compute the area enclosed by arbitrary piecewise-smooth simple closed curves.
- ▶ Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .

Green's Theorem

- ▶ One application of Green's Theorem is that it allows us to compute the area enclosed by arbitrary piecewise-smooth simple closed curves.
- ▶ Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .
- ▶ Recall that the area of \mathcal{R} is given by

$$A = \iint_{\mathcal{R}} dA$$

Green's Theorem

- ▶ One application of Green's Theorem is that it allows us to compute the area enclosed by arbitrary piecewise-smooth simple closed curves.
- ▶ Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .
- ▶ Recall that the area of \mathcal{R} is given by

$$A = \iint_{\mathcal{R}} dA$$

- ▶ By choosing $P(x, y) = -\frac{1}{2}y$ and $Q(x, y) = \frac{1}{2}x$, Green's Theorem yields:

$$A = \frac{1}{2} \left(\oint_{\mathcal{C}} x \, dy - y \, dx \right)$$

Green's Theorem

- ▶ One application of Green's Theorem is that it allows us to compute the area enclosed by arbitrary piecewise-smooth simple closed curves.
- ▶ Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .
- ▶ Recall that the area of \mathcal{R} is given by

$$A = \iint_{\mathcal{R}} dA$$

- ▶ By choosing $P(x, y) = -\frac{1}{2}y$ and $Q(x, y) = \frac{1}{2}x$, Green's Theorem yields:

$$A = \frac{1}{2} \left(\oint_{\mathcal{C}} x \, dy - y \, dx \right)$$

- ▶ We could also choose $P(x, y) = 0$ and $Q(x, y) = x$ to get:

$$A = \oint_{\mathcal{C}} x \, dy$$

Green's Theorem

Example

Find the area of the ellipse described by $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$

Green's Theorem

Example

Find the area of the ellipse described by $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$

Example

Compute

$$\oint_C (y + e^{\sqrt{x}}) dx + (2x + \cos(y^2)) dy$$

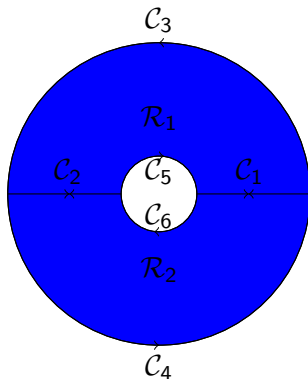
where C is the boundary of the region enclosed by the parabolas $y = x^2$ and $x = y^2$.

Extending Green's Theorem

Green's Theorem can also be extended to regions with holes in them. This is achieved using the same idea that we indicated could be used to extend the special case of Green's Theorem proved earlier. That is, if a region has a single hole then this region can be split into two simply-connected regions.

Extending Green's Theorem

Green's Theorem can also be extended to regions with holes in them. This is achieved using the same idea that we indicated could be used to extend the special case of Green's Theorem proved earlier. That is, if a region has a single hole then this region can be split into two simply-connected regions.



Extending Green's Theorem

Let $\mathcal{R} = \mathcal{R}_1 \cup \mathcal{R}_2$. Suppose that D is open and \mathcal{R} is contained in D , and $P : D \rightarrow \mathbb{R}$ and $Q : D \rightarrow \mathbb{R}$ have continuous partial derivatives on D .

Extending Green's Theorem

Let $\mathcal{R} = \mathcal{R}_1 \cup \mathcal{R}_2$. Suppose that D is open and \mathcal{R} is contained in D , and $P : D \rightarrow \mathbb{R}$ and $Q : D \rightarrow \mathbb{R}$ have continuous partial derivatives on D .

Now,

$$\iint_{\mathcal{R}} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA = \iint_{\mathcal{R}_1} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA + \iint_{\mathcal{R}_2} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$$

Extending Green's Theorem

Let $\mathcal{R} = \mathcal{R}_1 \cup \mathcal{R}_2$. Suppose that D is open and \mathcal{R} is contained in D , and $P : D \rightarrow \mathbb{R}$ and $Q : D \rightarrow \mathbb{R}$ have continuous partial derivatives on D .

Now,

$$\begin{aligned} \iint_{\mathcal{R}} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA &= \iint_{\mathcal{R}_1} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA + \iint_{\mathcal{R}_2} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA \\ &= \int_{C_1} P dx + Q dy + \int_{C_3} P dx + Q dy + \int_{-C_2} P dx + Q dy + \int_{C_5} P dx + Q dy \\ &\quad + \int_{-C_1} P dx + Q dy + \int_{C_6} P dx + Q dy + \int_{C_2} P dx + Q dy + \int_{C_4} P dx + Q dy \end{aligned}$$

Extending Green's Theorem

Let $\mathcal{R} = \mathcal{R}_1 \cup \mathcal{R}_2$. Suppose that D is open and \mathcal{R} is contained in D , and $P : D \rightarrow \mathbb{R}$ and $Q : D \rightarrow \mathbb{R}$ have continuous partial derivatives on D .

Now,

$$\begin{aligned} \iint_{\mathcal{R}} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA &= \iint_{\mathcal{R}_1} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA + \iint_{\mathcal{R}_2} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA \\ &= \int_{C_1} P dx + Q dy + \int_{C_3} P dx + Q dy + \int_{-C_2} P dx + Q dy + \int_{C_5} P dx + Q dy \\ &\quad + \int_{-C_1} P dx + Q dy + \int_{C_6} P dx + Q dy + \int_{C_2} P dx + Q dy + \int_{C_4} P dx + Q dy \\ &= \int_{C_3} P dx + Q dy + \int_{C_6} P dx + Q dy + \int_{C_5} P dx + Q dy + \int_{C_4} P dx + Q dy \end{aligned}$$

Extending Green's Theorem

Let $\mathcal{R} = \mathcal{R}_1 \cup \mathcal{R}_2$. Suppose that D is open and \mathcal{R} is contained in D , and $P : D \rightarrow \mathbb{R}$ and $Q : D \rightarrow \mathbb{R}$ have continuous partial derivatives on D .

Now,

$$\begin{aligned} \iint_{\mathcal{R}} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA &= \iint_{\mathcal{R}_1} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA + \iint_{\mathcal{R}_2} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA \\ &= \int_{\mathcal{C}_1} P dx + Q dy + \int_{\mathcal{C}_3} P dx + Q dy + \int_{-\mathcal{C}_2} P dx + Q dy + \int_{\mathcal{C}_5} P dx + Q dy \\ &\quad + \int_{-\mathcal{C}_1} P dx + Q dy + \int_{\mathcal{C}_6} P dx + Q dy + \int_{\mathcal{C}_2} P dx + Q dy + \int_{\mathcal{C}_4} P dx + Q dy \\ &= \int_{\mathcal{C}_3} P dx + Q dy + \int_{\mathcal{C}_6} P dx + Q dy + \int_{\mathcal{C}_5} P dx + Q dy + \int_{\mathcal{C}_4} P dx + Q dy \\ &= \oint_{\mathcal{C}_3 \cup \mathcal{C}_4} P dx + Q dy - \oint_{\mathcal{C}_5 \cup \mathcal{C}_6} P dx + Q dy \end{aligned}$$

Extending Green's Theorem

Example

Consider again the vortex vector field $F : D \longrightarrow \mathbb{R}^2$, where $D = \mathbb{R}^2 \setminus \{(0, 0)\}$, defined by

$$F(x, y) = \left(\frac{-y}{x^2 + y^2} \right) \bar{i} + \left(\frac{x}{x^2 + y^2} \right) \bar{j} = P(x, y)\bar{i} + Q(x, y)\bar{j}$$

Extending Green's Theorem

Example

Consider again the vortex vector field $F : D \longrightarrow \mathbb{R}^2$, where $D = \mathbb{R}^2 \setminus \{(0,0)\}$, defined by

$$F(x, y) = \left(\frac{-y}{x^2 + y^2} \right) \bar{i} + \left(\frac{x}{x^2 + y^2} \right) \bar{j} = P(x, y)\bar{i} + Q(x, y)\bar{j}$$

If \mathcal{C} is an arbitrary positively oriented simple closed path that encloses the origin $(0,0)$, then

$$\int_{\mathcal{C}} F \cdot d\vec{r} = 2\pi$$

Extending Green's Theorem

Example

Consider again the vortex vector field $F : D \rightarrow \mathbb{R}^2$, where $D = \mathbb{R}^2 \setminus \{(0,0)\}$, defined by

$$F(x, y) = \left(\frac{-y}{x^2 + y^2} \right) \bar{i} + \left(\frac{x}{x^2 + y^2} \right) \bar{j} = P(x, y)\bar{i} + Q(x, y)\bar{j}$$

If \mathcal{C} is an arbitrary positively oriented simple closed path that encloses the origin $(0,0)$, then

$$\int_{\mathcal{C}} F \cdot d\bar{r} = 2\pi$$

To see this, let a be small enough such that the circle \mathcal{C}_a of radius a centred at $(0,0)$ is contained in the region bound by \mathcal{C} .

Extending Green's Theorem

Example

Consider again the vortex vector field $F : D \rightarrow \mathbb{R}^2$, where $D = \mathbb{R}^2 \setminus \{(0,0)\}$, defined by

$$F(x, y) = \left(\frac{-y}{x^2 + y^2} \right) \bar{i} + \left(\frac{x}{x^2 + y^2} \right) \bar{j} = P(x, y)\bar{i} + Q(x, y)\bar{j}$$

If \mathcal{C} is an arbitrary positively oriented simple closed path that encloses the origin $(0,0)$, then

$$\int_{\mathcal{C}} F \cdot d\bar{r} = 2\pi$$

To see this, let a be small enough such that the circle \mathcal{C}_a of radius a centred at $(0,0)$ is contained in the region bound by \mathcal{C} .

Let \mathcal{R} be the region that lies outside of \mathcal{C}_a and within \mathcal{C} .

Extending Green's Theorem

Example

Consider again the vortex vector field $F : D \longrightarrow \mathbb{R}^2$, where $D = \mathbb{R}^2 \setminus \{(0,0)\}$, defined by

$$F(x,y) = \left(\frac{-y}{x^2 + y^2} \right) \bar{i} + \left(\frac{x}{x^2 + y^2} \right) \bar{j} = P(x,y)\bar{i} + Q(x,y)\bar{j}$$

If \mathcal{C} is an arbitrary positively oriented simple closed path that encloses the origin $(0,0)$, then

$$\int_{\mathcal{C}} F \cdot d\bar{r} = 2\pi$$

To see this, let a be small enough such that the circle \mathcal{C}_a of radius a centred at $(0,0)$ is contained in the region bound by \mathcal{C} .

Let \mathcal{R} be the region that lies outside of \mathcal{C}_a and within \mathcal{C} . Then

$$0 = \iint_{\mathcal{R}} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA = \oint_{\mathcal{C}} P dx + Q dy - \oint_{\mathcal{C}_a} P dx + Q dy$$

Extending Green's Theorem

Example

(Continued.) So,

$$\int_C F \cdot d\vec{r} = \oint_C P \, dx + Q \, dy = \oint_{C_a} P \, dx + Q \, dy = \int_{C_a} F \cdot d\vec{r} = 2\pi$$

Extending Green's Theorem

Example

(Continued.) So,

$$\int_C F \cdot d\vec{r} = \oint_C P \, dx + Q \, dy = \oint_{C_a} P \, dx + Q \, dy = \int_{C_a} F \cdot d\vec{r} = 2\pi$$

Similarly, if C is a closed curve such that $(0,0)$ is not in the region bounded by C , then

$$\int_C F \cdot d\vec{r} = \oint_C P \, dx + Q \, dy = \iint_{\mathcal{R}} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA = 0$$

Extending Green's Theorem

Example

(Continued.) So,

$$\int_C F \cdot d\vec{r} = \oint_C P \, dx + Q \, dy = \oint_{C_a} P \, dx + Q \, dy = \int_{C_a} F \cdot d\vec{r} = 2\pi$$

Similarly, if C is a closed curve such that $(0,0)$ is not in the region bounded by C , then

$$\int_C F \cdot d\vec{r} = \oint_C P \, dx + Q \, dy = \iint_{\mathcal{R}} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA = 0$$

When we first starting talking about conservative vector field we observed the following consequence of Clairaut's Theorem:

Theorem

If $F(x, y) = \alpha(x, y)\vec{i} + \beta(x, y)\vec{j}$ is a conservative vector field where α and β have continuous first-order partial derivatives on $D \subseteq \mathbb{R}^2$, then for all $(u, v) \in D$, $\alpha_y(u, v) = \beta_x(u, v)$

Green's Theorem

Theorem

Let $F : D \longrightarrow \mathbb{R}^2$ be described by $F(x, y) = \alpha(x, y)\vec{i} + \beta(x, y)\vec{j}$ where D is an open simply-connected region, and $\alpha(x, y)$ and $\beta(x, y)$ have continuous first-order partial derivatives. If for all $(u, v) \in D$, $\alpha_y(u, v) = \beta_x(u, v)$, then F is conservative.

Green's Theorem

Theorem

Let $F : D \rightarrow \mathbb{R}^2$ be described by $F(x, y) = \alpha(x, y)\vec{i} + \beta(x, y)\vec{j}$ where D is an open simply-connected region, and $\alpha(x, y)$ and $\beta(x, y)$ have continuous first-order partial derivatives. If for all $(u, v) \in D$, $\alpha_y(u, v) = \beta_x(u, v)$, then F is conservative.

Proof.

(Sketchy Outline.)

- ▶ This is just Green's Theorem with a "hack".

Green's Theorem

Theorem

Let $F : D \rightarrow \mathbb{R}^2$ be described by $F(x, y) = \alpha(x, y)\vec{i} + \beta(x, y)\vec{j}$ where D is an open simply-connected region, and $\alpha(x, y)$ and $\beta(x, y)$ have continuous first-order partial derivatives. If for all $(u, v) \in D$, $\alpha_y(u, v) = \beta_x(u, v)$, then F is conservative.

Proof.

(Sketchy Outline.)

- ▶ This is just Green's Theorem with a "hack".
- ▶ Suppose that for all $(u, v) \in D$, $\alpha_y(u, v) = \beta_x(u, v)$. Green's Theorem tells us that the line integral around any *simple* closed curve is 0.

Green's Theorem

Theorem

Let $F : D \longrightarrow \mathbb{R}^2$ be described by $F(x, y) = \alpha(x, y)\vec{i} + \beta(x, y)\vec{j}$ where D is an open simply-connected region, and $\alpha(x, y)$ and $\beta(x, y)$ have continuous first-order partial derivatives. If for all $(u, v) \in D$, $\alpha_y(u, v) = \beta_x(u, v)$, then F is conservative.

Proof.

(Sketchy Outline.)

- ▶ This is just Green's Theorem with a "hack".
- ▶ Suppose that for all $(u, v) \in D$, $\alpha_y(u, v) = \beta_x(u, v)$. Green's Theorem tells us that the line integral around any *simple* closed curve is 0.
- ▶ The general result can then be obtained by observing that a general closed curve can be viewed as a collection of simple curves that meet at a point.



Curl and divergence

Definition

The *vector differential operator*, pronounced "del" or "nabla", is the operator defined by

$$\nabla = \bar{i} \frac{\partial}{\partial x} + \bar{j} \frac{\partial}{\partial y} + \bar{k} \frac{\partial}{\partial z}$$

Curl and divergence

Definition

The *vector differential operator*, pronounced "del" or "nabla", is the operator defined by

$$\nabla = \bar{i} \frac{\partial}{\partial x} + \bar{j} \frac{\partial}{\partial y} + \bar{k} \frac{\partial}{\partial z}$$

This is consistent with the notation that we have been using for the gradient of a function f with three independent variables:

$$\nabla f = \bar{i} \frac{\partial f}{\partial x} + \bar{j} \frac{\partial f}{\partial y} + \bar{k} \frac{\partial f}{\partial z}$$

Curl and divergence

Definition

The *vector differential operator*, pronounced "del" or "nabla", is the operator defined by

$$\nabla = \bar{i} \frac{\partial}{\partial x} + \bar{j} \frac{\partial}{\partial y} + \bar{k} \frac{\partial}{\partial z}$$

This is consistent with the notation that we have been using for the gradient of a function f with three independent variables:

$$\nabla f = \bar{i} \frac{\partial f}{\partial x} + \bar{j} \frac{\partial f}{\partial y} + \bar{k} \frac{\partial f}{\partial z}$$

This differential operator allows us to define two "variants" of the derivative for vector fields on \mathbb{R}^3 .

Curl and divergence

Definition

The *vector differential operator*, pronounced "del" or "nabla", is the operator defined by

$$\nabla = \bar{i} \frac{\partial}{\partial x} + \bar{j} \frac{\partial}{\partial y} + \bar{k} \frac{\partial}{\partial z}$$

This is consistent with the notation that we have been using for the gradient of a function f with three independent variables:

$$\nabla f = \bar{i} \frac{\partial f}{\partial x} + \bar{j} \frac{\partial f}{\partial y} + \bar{k} \frac{\partial f}{\partial z}$$

This differential operator allows us to define two "variants" of the derivative for vector fields on \mathbb{R}^3 .

Definition

Let $F : D \longrightarrow \mathbb{R}^3$, where $D \subseteq \mathbb{R}^3$, be a vector field such that the components of F are differentiable on D . The *curl* of F is defined by $\text{curl}(F) = \nabla \times F$. The *divergence* of F is defined by $\text{div}(F) = \nabla \cdot F$.

Curl and divergence

Let $F(x, y, z) = P(x, y, z)\vec{i} + Q(x, y, z)\vec{j} + R(x, y, z)\vec{k}$ be a vector field.
Then

Curl and divergence

Let $F(x, y, z) = P(x, y, z)\bar{i} + Q(x, y, z)\bar{j} + R(x, y, z)\bar{k}$ be a vector field.
Then

$$\text{curl}(F) = \nabla \times F = \begin{vmatrix} \bar{i} & \bar{j} & \bar{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix}$$

Curl and divergence

Let $F(x, y, z) = P(x, y, z)\bar{i} + Q(x, y, z)\bar{j} + R(x, y, z)\bar{k}$ be a vector field.
Then

$$\begin{aligned}\operatorname{curl}(F) &= \nabla \times F = \begin{vmatrix} \bar{i} & \bar{j} & \bar{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} \\ &= \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \bar{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \bar{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \bar{k}\end{aligned}$$

Curl and divergence

Let $F(x, y, z) = P(x, y, z)\bar{i} + Q(x, y, z)\bar{j} + R(x, y, z)\bar{k}$ be a vector field.
Then

$$\begin{aligned}\operatorname{curl}(F) &= \nabla \times F = \begin{vmatrix} \bar{i} & \bar{j} & \bar{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} \\ &= \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \bar{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \bar{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \bar{k}\end{aligned}$$

Note that $\operatorname{curl}(F)$ is a vector.

Curl and divergence

Let $F(x, y, z) = P(x, y, z)\bar{i} + Q(x, y, z)\bar{j} + R(x, y, z)\bar{k}$ be a vector field.
Then

$$\begin{aligned}\operatorname{curl}(F) &= \nabla \times F = \begin{vmatrix} \bar{i} & \bar{j} & \bar{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} \\ &= \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \bar{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \bar{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \bar{k}\end{aligned}$$

Note that $\operatorname{curl}(F)$ is a vector. And

$$\operatorname{div}(F) = \nabla \cdot F = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$

Curl and divergence

Let $F(x, y, z) = P(x, y, z)\bar{i} + Q(x, y, z)\bar{j} + R(x, y, z)\bar{k}$ be a vector field.
Then

$$\begin{aligned}\operatorname{curl}(F) &= \nabla \times F = \begin{vmatrix} \bar{i} & \bar{j} & \bar{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} \\ &= \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \bar{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \bar{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \bar{k}\end{aligned}$$

Note that $\operatorname{curl}(F)$ is a vector. And

$$\operatorname{div}(F) = \nabla \cdot F = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$

Note that $\operatorname{div}(F)$ is a scalar.

Curl and divergence

Let $F(x, y, z) = P(x, y, z)\bar{i} + Q(x, y, z)\bar{j} + R(x, y, z)\bar{k}$ be a vector field.
Then

$$\begin{aligned}\operatorname{curl}(F) &= \nabla \times F = \begin{vmatrix} \bar{i} & \bar{j} & \bar{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} \\ &= \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \bar{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \bar{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \bar{k}\end{aligned}$$

Note that $\operatorname{curl}(F)$ is a vector. And

$$\operatorname{div}(F) = \nabla \cdot F = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$

Note that $\operatorname{div}(F)$ is a scalar. Physical interpretations of these operations can be obtained if one considers a vector field F that describes the flow of a fluid through space.

Curl and divergence

- ▶ $\text{curl}(F)$ describes the rotation of the fluid. The vector points in the direction of the axis of rotation with magnitude corresponding to the "magnitude" of the rotation.

Curl and divergence

- ▶ $\text{curl}(F)$ describes the rotation of the fluid. The vector points in the direction of the axis of rotation with magnitude corresponding to the "magnitude" of the rotation.
- ▶ $\text{div}(F)$ represents the rate of expansion per unit volume under the flow of the gas (or fluid).

If $\text{div}(F) = 0$, then the gas (fluid) is said to be **incompressible**. If $\text{div} < 0$ the gas (or fluid) is **compressing**.

Curl and divergence

- ▶ $\text{curl}(F)$ describes the rotation of the fluid. The vector points in the direction of the axis of rotation with magnitude corresponding to the "magnitude" of the rotation.
- ▶ $\text{div}(F)$ represents the rate of expansion per unit volume under the flow of the gas (or fluid).

If $\text{div}(F) = 0$, then the gas (fluid) is said to be **incompressible**. If $\text{div} < 0$ the gas (or fluid) is **compressing**.

Theorem

Let $f : D \rightarrow \mathbb{R}$, where $D \subseteq \mathbb{R}^3$, have continuous second-order derivatives. Then $\text{curl}(\nabla f) = 0$.

Curl and divergence

- ▶ $\text{curl}(F)$ describes the rotation of the fluid. The vector points in the direction of the axis of rotation with magnitude corresponding to the "magnitude" of the rotation.
- ▶ $\text{div}(F)$ represents the rate of expansion per unit volume under the flow of the gas (or fluid).

If $\text{div}(F) = 0$, then the gas (fluid) is said to be **incompressible**. If $\text{div} < 0$ the gas (or fluid) is **compressing**.

Theorem

Let $f : D \rightarrow \mathbb{R}$, where $D \subseteq \mathbb{R}^3$, have continuous second-order derivatives. Then $\text{curl}(\nabla f) = 0$.

Corollary

Let F be a vector field on \mathbb{R}^3 whose component functions have continuous partial derivatives. If F is conservative, then $\text{curl}(F) = 0$.

Curl and divergence

- ▶ $\text{curl}(F)$ describes the rotation of the fluid. The vector points in the direction of the axis of rotation with magnitude corresponding to the "magnitude" of the rotation.
- ▶ $\text{div}(F)$ represents the rate of expansion per unit volume under the flow of the gas (or fluid).

If $\text{div}(F) = 0$, then the gas (fluid) is said to be **incompressible**. If $\text{div} < 0$ the gas (or fluid) is **compressing**.

Theorem

Let $f : D \rightarrow \mathbb{R}$, where $D \subseteq \mathbb{R}^3$, have continuous second-order derivatives. Then $\text{curl}(\nabla f) = 0$.

Corollary

Let F be a vector field on \mathbb{R}^3 whose component functions have continuous partial derivatives. If F is conservative, then $\text{curl}(F) = 0$.

Theorem

Let F be a vector field on \mathbb{R}^3 whose component functions have continuous second-order partial derivatives. Then $\text{div}(\text{curl}(F)) = 0$.

Curl and divergence

Example

Consider $F(x, y, z) = (y^2 \cos(x) + z^3)\vec{i} + (2y \sin(x) - 4)\vec{j} + (3xz^2 + 2)\vec{k}$.
Find $\text{div}(F)$ and $\text{curl}(F)$.

Curl and divergence

Example

Consider $F(x, y, z) = (y^2 \cos(x) + z^3)\vec{i} + (2y \sin(x) - 4)\vec{j} + (3xz^2 + 2)\vec{k}$.
Find $\text{div}(F)$ and $\text{curl}(F)$.

The operator $\nabla \cdot \nabla$ is called the **Laplace operator** and is sometimes written ∇^2 . If f is a function of three variables whose second-order partial derivatives exist, then

$$\nabla^2 f = \nabla \cdot \nabla f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$$

Curl and divergence

Example

Consider $F(x, y, z) = (y^2 \cos(x) + z^3)\bar{i} + (2y \sin(x) - 4)\bar{j} + (3xz^2 + 2)\bar{k}$.
Find $\text{div}(F)$ and $\text{curl}(F)$.

The operator $\nabla \cdot \nabla$ is called the **Laplace operator** and is sometimes written ∇^2 . If f is a function of three variables whose second-order partial derivatives exist, then

$$\nabla^2 f = \nabla \cdot \nabla f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$$

If $F(x, y, z) = P\bar{i} + Q\bar{j} + R\bar{k}$ is a vector field, then

$$\nabla^2 F = \nabla \cdot \nabla F = \nabla^2 P\bar{i} + \nabla^2 Q\bar{j} + \nabla^2 R\bar{k}$$

Curl and divergence

Example

Consider $F(x, y, z) = (y^2 \cos(x) + z^3)\bar{i} + (2y \sin(x) - 4)\bar{j} + (3xz^2 + 2)\bar{k}$.
Find $\text{div}(F)$ and $\text{curl}(F)$.

The operator $\nabla \cdot \nabla$ is called the **Laplace operator** and is sometimes written ∇^2 . If f is a function of three variables whose second-order partial derivatives exist, then

$$\nabla^2 f = \nabla \cdot \nabla f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$$

If $F(x, y, z) = P\bar{i} + Q\bar{j} + R\bar{k}$ is a vector field, then

$$\nabla^2 F = \nabla \cdot \nabla F = \nabla^2 P\bar{i} + \nabla^2 Q\bar{j} + \nabla^2 R\bar{k}$$

This looks strange! The first ∇ operation on F (∇F) is not a dot product.

Identities involving divergence and curl

Theorem

Let F and G be a vector fields in \mathbb{R}^3 and let f and g be functions of three variables. If the partial derivatives of F , G , g and f that appear in the following equations exist and are continuous, then the following equations hold:

1. $\operatorname{div}(F + G) = \operatorname{div}(F) + \operatorname{div}(G)$
2. $\operatorname{curl}(F + G) = \operatorname{curl}(F) + \operatorname{curl}(G)$
3. $\operatorname{div}(fF) = f \operatorname{div}(F) + F \cdot \nabla f$
4. $\operatorname{curl}(fF) = f \operatorname{curl}(F) + \nabla f \times F$
5. $\operatorname{div}(F \times G) = G \cdot \operatorname{curl}(F) - F \cdot \operatorname{curl}(G)$
6. $\operatorname{div}(\nabla f \times \nabla g) = 0$
7. $\operatorname{curl}(\operatorname{curl}(F)) = \nabla(\operatorname{div}(F)) - \nabla^2 F$

Identities involving divergence and curl

Theorem

Let F and G be a vector fields in \mathbb{R}^3 and let f and g be functions of three variables. If the partial derivatives of F , G , g and f that appear in the following equations exist and are continuous, then the following equations hold:

1. $\operatorname{div}(F + G) = \operatorname{div}(F) + \operatorname{div}(G)$
2. $\operatorname{curl}(F + G) = \operatorname{curl}(F) + \operatorname{curl}(G)$
3. $\operatorname{div}(fF) = f \operatorname{div}(F) + F \cdot \nabla f$
4. $\operatorname{curl}(fF) = f \operatorname{curl}(F) + \nabla f \times F$
5. $\operatorname{div}(F \times G) = G \cdot \operatorname{curl}(F) - F \cdot \operatorname{curl}(G)$
6. $\operatorname{div}(\nabla f \times \nabla g) = 0$
7. $\operatorname{curl}(\operatorname{curl}(F)) = \nabla(\operatorname{div}(F)) - \nabla^2 F$

Example

Consider $F(x, y, z) = ye^x \bar{i} + (x^2 + z) \bar{j} + y^3 \cos(zx) \bar{k}$. Compute $\operatorname{curl}(\operatorname{curl}(F))$, $\nabla \operatorname{div}(F)$ and $\nabla^2 F$.

Vector formulation of Green's Theorem

Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .

Let $D \subseteq \mathbb{R}^2$ be open with \mathcal{R} contained in D .

Vector formulation of Green's Theorem

Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .

Let $D \subseteq \mathbb{R}^2$ be open with \mathcal{R} contained in D .

Consider the vector field $F(x, y, z) = P(x, y)\bar{i} + Q(x, y)\bar{j}$ in \mathbb{R}^3 , where P and Q have continuous partial derivatives on D .

Vector formulation of Green's Theorem

Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .

Let $D \subseteq \mathbb{R}^2$ be open with \mathcal{R} contained in D .

Consider the vector field $F(x, y, z) = P(x, y)\vec{i} + Q(x, y)\vec{j}$ in \mathbb{R}^3 , where P and Q have continuous partial derivatives on D . Now,

$$\int_{\mathcal{C}} F \cdot d\vec{r} = \int_{\mathcal{C}} P \, dx + Q \, dy$$

Vector formulation of Green's Theorem

Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .

Let $D \subseteq \mathbb{R}^2$ be open with \mathcal{R} contained in D .

Consider the vector field $F(x, y, z) = P(x, y)\vec{i} + Q(x, y)\vec{j}$ in \mathbb{R}^3 , where P and Q have continuous partial derivatives on D . Now,

$$\int_{\mathcal{C}} F \cdot d\vec{r} = \int_{\mathcal{C}} P \, dx + Q \, dy$$

And

$$(\text{curl}(F)) \cdot \vec{k} =$$

Vector formulation of Green's Theorem

Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .

Let $D \subseteq \mathbb{R}^2$ be open with \mathcal{R} contained in D .

Consider the vector field $F(x, y, z) = P(x, y)\bar{i} + Q(x, y)\bar{j}$ in \mathbb{R}^3 , where P and Q have continuous partial derivatives on D . Now,

$$\int_{\mathcal{C}} F \cdot d\bar{r} = \int_{\mathcal{C}} P \, dx + Q \, dy$$

And

$$(\text{curl}(F)) \cdot \bar{k} = \begin{vmatrix} \bar{i} & \bar{j} & \bar{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & 0 \end{vmatrix} \cdot \bar{k}$$

Vector formulation of Green's Theorem

Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .

Let $D \subseteq \mathbb{R}^2$ be open with \mathcal{R} contained in D .

Consider the vector field $F(x, y, z) = P(x, y)\bar{i} + Q(x, y)\bar{j}$ in \mathbb{R}^3 , where P and Q have continuous partial derivatives on D . Now,

$$\int_{\mathcal{C}} F \cdot d\bar{r} = \int_{\mathcal{C}} P \, dx + Q \, dy$$

And

$$\begin{aligned} (\text{curl}(F)) \cdot \bar{k} &= \begin{vmatrix} \bar{i} & \bar{j} & \bar{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & 0 \end{vmatrix} \cdot \bar{k} \\ &= \left(-\frac{\partial Q}{\partial z} \bar{i} + \frac{\partial P}{\partial z} \bar{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \bar{k} \right) \cdot \bar{k} = \end{aligned}$$

Vector formulation of Green's Theorem

Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .

Let $D \subseteq \mathbb{R}^2$ be open with \mathcal{R} contained in D .

Consider the vector field $F(x, y, z) = P(x, y)\bar{i} + Q(x, y)\bar{j}$ in \mathbb{R}^3 , where P and Q have continuous partial derivatives on D . Now,

$$\int_{\mathcal{C}} F \cdot d\bar{r} = \int_{\mathcal{C}} P \, dx + Q \, dy$$

And

$$\begin{aligned} (\text{curl}(F)) \cdot \bar{k} &= \begin{vmatrix} \bar{i} & \bar{j} & \bar{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & 0 \end{vmatrix} \cdot \bar{k} \\ &= \left(-\frac{\partial Q}{\partial z} \bar{i} + \frac{\partial P}{\partial z} \bar{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \bar{k} \right) \cdot \bar{k} = \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \end{aligned}$$

Vector formulation of Green's Theorem

Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .

Let $D \subseteq \mathbb{R}^2$ be open with \mathcal{R} contained in D .

Consider the vector field $F(x, y, z) = P(x, y)\bar{i} + Q(x, y)\bar{j}$ in \mathbb{R}^3 , where P and Q have continuous partial derivatives on D . Now,

$$\int_{\mathcal{C}} F \cdot d\bar{r} = \int_{\mathcal{C}} P \, dx + Q \, dy$$

And

$$\begin{aligned} (\text{curl}(F)) \cdot \bar{k} &= \begin{vmatrix} \bar{i} & \bar{j} & \bar{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & 0 \end{vmatrix} \cdot \bar{k} \\ &= \left(-\frac{\partial Q}{\partial z} \bar{i} + \frac{\partial P}{\partial z} \bar{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \bar{k} \right) \cdot \bar{k} = \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \end{aligned}$$

So, Green's Theorem yields:

$$\boxed{\int_{\mathcal{C}} F \cdot d\bar{r} = \iint_{\mathcal{R}} (\text{curl}(F)) \cdot \bar{k} \, dA}$$

2D Divergence Theorem

Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .

Let $D \subseteq \mathbb{R}^2$ be open with \mathcal{R} contained in D .

2D Divergence Theorem

Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .

Let $D \subseteq \mathbb{R}^2$ be open with \mathcal{R} contained in D .

Consider the vector function $F(x, y) = P(x, y)\vec{i} + Q(x, y)\vec{j}$ where P and Q have continuous partial derivatives on D .

2D Divergence Theorem

Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .

Let $D \subseteq \mathbb{R}^2$ be open with \mathcal{R} contained in D .

Consider the vector function $F(x, y) = P(x, y)\vec{i} + Q(x, y)\vec{j}$ where P and Q have continuous partial derivatives on D .

Let $\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j}$ for $t \in [a, b]$ be a parameterisation of \mathcal{C} .

2D Divergence Theorem

Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .

Let $D \subseteq \mathbb{R}^2$ be open with \mathcal{R} contained in D .

Consider the vector function $F(x, y) = P(x, y)\vec{i} + Q(x, y)\vec{j}$ where P and Q have continuous partial derivatives on D .

Let $\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j}$ for $t \in [a, b]$ be a parameterisation of \mathcal{C} .

$$\vec{r}'(t) = x'(t)\vec{i} + y'(t)\vec{j} \text{ and } \hat{r}'(t) = \frac{x'(t)}{|\vec{r}'(t)|}\vec{i} + \frac{y'(t)}{|\vec{r}'(t)|}\vec{j}$$

2D Divergence Theorem

Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .

Let $D \subseteq \mathbb{R}^2$ be open with \mathcal{R} contained in D .

Consider the vector function $F(x, y) = P(x, y)\bar{i} + Q(x, y)\bar{j}$ where P and Q have continuous partial derivatives on D .

Let $\bar{r}(t) = x(t)\bar{i} + y(t)\bar{j}$ for $t \in [a, b]$ be a parameterisation of \mathcal{C} .

$$\bar{r}'(t) = x'(t)\bar{i} + y'(t)\bar{j} \text{ and } \hat{r}'(t) = \frac{x'(t)}{|\bar{r}'(t)|}\bar{i} + \frac{y'(t)}{|\bar{r}'(t)|}\bar{j}$$

The unit normal vectors of the tangent lines to the curve \mathcal{C} are described by the vector function

$$\bar{n}(t) = \frac{y'(t)}{|\bar{r}'(t)|}\bar{i} - \frac{x'(t)}{|\bar{r}'(t)|}\bar{j}$$

2D Divergence Theorem

Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .

Let $D \subseteq \mathbb{R}^2$ be open with \mathcal{R} contained in D .

Consider the vector function $F(x, y) = P(x, y)\vec{i} + Q(x, y)\vec{j}$ where P and Q have continuous partial derivatives on D .

Let $\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j}$ for $t \in [a, b]$ be a parameterisation of \mathcal{C} .

$$\vec{r}'(t) = x'(t)\vec{i} + y'(t)\vec{j} \text{ and } \hat{r}'(t) = \frac{x'(t)}{|\vec{r}'(t)|}\vec{i} + \frac{y'(t)}{|\vec{r}'(t)|}\vec{j}$$

The unit normal vectors of the tangent lines to the curve \mathcal{C} are described by the vector function

$$\vec{n}(t) = \frac{y'(t)}{|\vec{r}'(t)|}\vec{i} - \frac{x'(t)}{|\vec{r}'(t)|}\vec{j}$$

\Rightarrow for all $t \in [a, b]$, $\vec{n}(t) \cdot \hat{r}'(t) = 0$ and $|\vec{n}(t)| = 1$.

2D Divergence Theorem

Let \mathcal{C} be a positively oriented, piecewise-smooth, simple closed curve in \mathbb{R}^2 and let \mathcal{R} be the region enclosed by \mathcal{C} .

Let $D \subseteq \mathbb{R}^2$ be open with \mathcal{R} contained in D .

Consider the vector function $F(x, y) = P(x, y)\vec{i} + Q(x, y)\vec{j}$ where P and Q have continuous partial derivatives on D .

Let $\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j}$ for $t \in [a, b]$ be a parameterisation of \mathcal{C} .

$$\vec{r}'(t) = x'(t)\vec{i} + y'(t)\vec{j} \text{ and } \hat{\vec{r}}'(t) = \frac{x'(t)}{|\vec{r}'(t)|}\vec{i} + \frac{y'(t)}{|\vec{r}'(t)|}\vec{j}$$

The unit normal vectors of the tangent lines to the curve \mathcal{C} are described by the vector function

$$\vec{n}(t) = \frac{y'(t)}{|\vec{r}'(t)|}\vec{i} - \frac{x'(t)}{|\vec{r}'(t)|}\vec{j}$$

\Rightarrow for all $t \in [a, b]$, $\vec{n}(t) \cdot \hat{\vec{r}}'(t) = 0$ and $|\vec{n}(t)| = 1$. Now,

$$\int_{\mathcal{C}} F \cdot \vec{n} \, ds = \int_a^b (F \cdot \vec{n})(t) |\vec{r}'(t)| \, dt$$

2D Divergence Theorem

Now,

$$(F \cdot \bar{n})(t) = \frac{P(x(t), y(t))y'(t)}{|\bar{r}'(t)|} - \frac{Q(x(t), y(t))x'(t)}{|\bar{r}'(t)|}$$

2D Divergence Theorem

Now,

$$(F \cdot \bar{n})(t) = \frac{P(x(t), y(t))y'(t)}{|\bar{r}'(t)|} - \frac{Q(x(t), y(t))x'(t)}{|\bar{r}'(t)|}$$

So

$$\int_C F \cdot \bar{n} \, ds = \int_a^b (P(x(t), y(t))y'(t) - Q(x(t), y(t))x'(t)) \, dt$$

2D Divergence Theorem

Now,

$$(F \cdot \bar{n})(t) = \frac{P(x(t), y(t))y'(t)}{|\bar{r}'(t)|} - \frac{Q(x(t), y(t))x'(t)}{|\bar{r}'(t)|}$$

So

$$\begin{aligned}\int_{\mathcal{C}} F \cdot \bar{n} \, ds &= \int_a^b (P(x(t), y(t))y'(t) - Q(x(t), y(t))x'(t)) \, dt \\ &= \int_{\mathcal{C}} P \, dx + Q \, dy = \iint_{\mathcal{R}} \left(\frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} \right)\end{aligned}$$

by Green's Theorem.

2D Divergence Theorem

Now,

$$(F \cdot \bar{n})(t) = \frac{P(x(t), y(t))y'(t)}{|\bar{r}'(t)|} - \frac{Q(x(t), y(t))x'(t)}{|\bar{r}'(t)|}$$

So

$$\begin{aligned}\int_{\mathcal{C}} F \cdot \bar{n} \, ds &= \int_a^b (P(x(t), y(t))y'(t) - Q(x(t), y(t))x'(t)) \, dt \\ &= \int_{\mathcal{C}} P \, dx + Q \, dy = \iint_{\mathcal{R}} \left(\frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} \right)\end{aligned}$$

by Green's Theorem. Therefore

$$\int_{\mathcal{C}} F \cdot \bar{n} \, ds = \iint_{\mathcal{R}} \operatorname{div}(F) \, dA$$