Chapter 8 – Work and Kinetic energy

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Agenda

- Motivation
- Work
 - How to Calculate Work in Various Situations?
 - Example: Work Done on/by a Spring
 - Examples: Work Along a Curved Path
- Work and Motion
 - Kinetic Energy and Work-Kinetic Energy Theorem
 - Power

Motivation Work Work and Motion

Motivation

Motivation

Mechanics

- Kinematics $(\bar{r}, \bar{v}, \bar{a})$ HOW?
- Dynamics $(\bar{F}, \bar{a} = \frac{\bar{F}}{m})$ WHY?

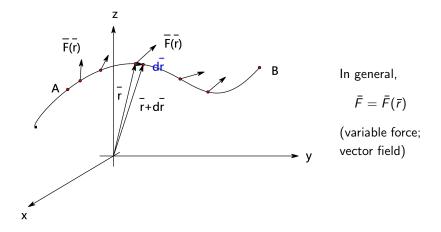
New scalar quantities

- Concept of *work*: How to measure the "effort" put into moving the particle from one place to another?
- Kinetic energy and work-kinetic energy theorem: How does this "effort" change the state of the particle (e.g. its speed)?

How to Calculate Work in Various Situations? Example: Work Done on/by a Spring Examples: Work Along a Curved Path

Work

Work



Elementary work done by \bar{F} when the particle moves from \bar{r} to $\bar{r}+d\bar{r}$

$$\delta W = \bar{F} \circ d\bar{r}$$

Work

Total work done by \bar{F} when the particle moves from A to B along the curve Γ_{AB} — add all infinitesimal contributions

$$W_{AB} = \int_{\Gamma_{AB}} \bar{F} \circ d\bar{r}$$

How to calculate work in various situations?

(A) Constant force in the direction of the displacement; displacement along a straight line

$$\delta W = \vec{F} \circ d\vec{r} = |\vec{F}| \cdot |d\vec{r}| \qquad \vec{F} \qquad \vec{F} \qquad \cos \angle(\vec{F}, d\vec{r}) = 1$$

$$W_{AB} = \int_{\Gamma_{AB}} \bar{F} \circ d\bar{r} = \int_{\Gamma_{AB}} |\bar{F}| |d\bar{r}| = |\bar{F}| \int_{\Gamma_{AB}} |d\bar{r}| = |\bar{F}| S_{AB},$$

where S_{AB} is the length of AB. Hence, in this case

$$W_{AB} = |\bar{F}| S_{AB}$$

(B) Constant force acting at an angle to the direction of straight-line displacement

$$\delta W = \vec{F} \circ d\vec{r}$$

$$= |\vec{F}| \cdot |d\vec{r}| \cos \alpha$$

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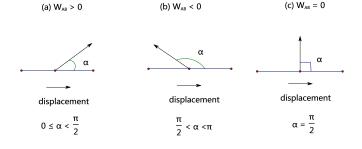
$$W_{AB} = \int_{\Gamma_{AB}} \bar{F} \circ d\bar{r} = \int_{\Gamma_{AB}} |\bar{F}| \cdot |d\bar{r}| \cos\alpha = |\bar{F}| \cos\alpha \int_{S_{AB}} |d\bar{r}|$$
$$= |\bar{F}| S_{AB} \cos\alpha$$

Hence, in this case,

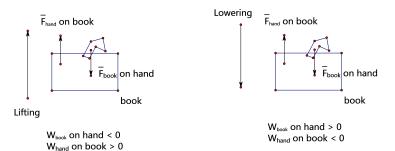
$$W_{AB} = |ar{F}| S_{AB} \cos lpha$$

Conclusion: Work may either positive or negative or zero.

Illustration. Positive/negative work.



Remember what does work on what!



Remark. Elementary work done in the case when multiple forces act on a particle

$$\delta W = (\bar{F}_1 + \bar{F}_2 + \dots + \bar{F}_N) \circ d\bar{r} = \bar{F}_1 \circ d\bar{r} + \bar{F}_2 \circ d\bar{r} + \dots + \bar{F}_N \circ d\bar{r}$$
$$= \delta W_1 + \delta W_2 + \dots + \delta W_N$$

or, equivalently,

$$\delta W = ar{F}_{net} \circ dar{r}$$

(C) Force of varying magnitude acting along a straight-line path

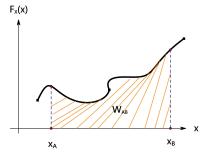
$$ar{F} = (\underbrace{F_X(x)}_{\text{function of x only}}, 0, 0)$$

A B X and $d\bar{r} = (dx, 0, 0)$

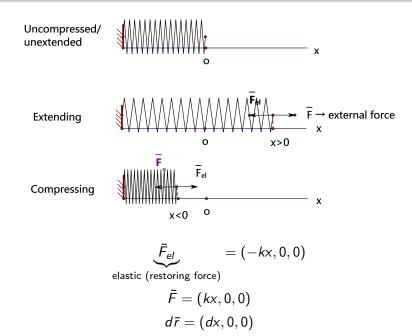
$$\delta W = \bar{F} \circ d\bar{r} = F_X(x) \, dx$$
 (takes care of the sign)
$$W_{AB} = \int\limits_{\Gamma_{AB}} \delta W = \int\limits_{\Gamma_{AB}} F_X(x) \, dx = \int\limits_{x_A}^{x_B} F_X(x) \, dx$$

z

Interpretation (area under the curve)



Example: Work Done on/by a Spring



If the position of the right (free) end of the spring changes from x_1 to x_2



Work done by

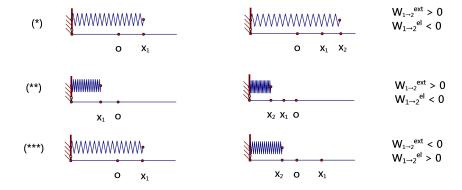
• the external force (e.g. hand) on the spring

$$W_{1\to 2}^{ext} = \int_{x_1}^{x_2} kx \, dx = \frac{1}{2}kx_2^2 - \frac{1}{2}kx_1^2$$

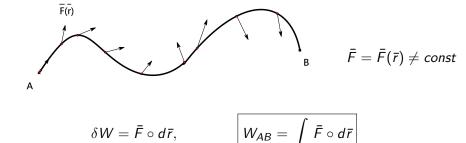
• the elastic force (spring) on the hand

$$W_{1\to 2}^{el} = \int_{x_1}^{x_2} -kx \, dx = -\left(\frac{1}{2}kx_2^2 - \frac{1}{2}kx_1^2\right) = -W_{1\to 2}^{\text{ext}}$$

Illustration



(D) General case – varying force, curved path



Example (work along a parabola)

Calculate work done by the force $\bar{F}(\bar{r}) = (x^2 + y^2)\hat{n}_x + x\hat{n}_y$ [N], acting on a particle moving from (0,0) to (1,1) along a segment of parabola $y = x^2$.

Example 1 (work along a parabola)

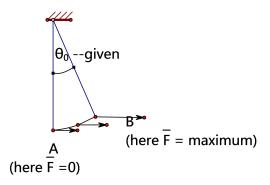
$$\Gamma_{AB}: \begin{cases} 0 \le x \le 1 \\ y = x^2 \end{cases}$$

$$W_{AB} = \int_{\Gamma_{AB}} \bar{F} \circ d\bar{r} = \int_{\Gamma_{AB}} F_x dx + F_y dy = \int_{\Gamma_{AB}} (x^2 + y^2) dx + x dy$$
$$= \int_{0}^{1} [(x^2 + x^4) + (x \cdot 2x)] dx = \frac{1}{3} + \frac{1}{5} + \frac{2}{3} = \frac{18}{15} \quad [J]$$

Note that for all the points on the parabola dy = 2x dx.

Example 2 (less abstract one; work along a curve)

Find the minimum work needed to move an object of weight Q, suspended on a light rod with length R, from A to B, acting with a horizontal force.



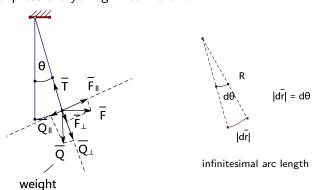
$$W_{A\to B}=\int\limits_{\Gamma_{AB}} \bar{F}\circ d\bar{r}$$

First Method

Idea: Decompose the force

$$\delta W = \bar{F} \circ d\bar{r} = (\bar{F}_{\parallel} + \bar{F}_{\perp}) \circ d\bar{r} = \underbrace{\bar{F}_{\parallel}}_{\text{varies}} \circ d\bar{r}$$

and express everything in terms of $\boldsymbol{\theta}$



$$\delta W = F_{\parallel} |d\bar{r}| = Q \sin \theta R \, d\theta$$

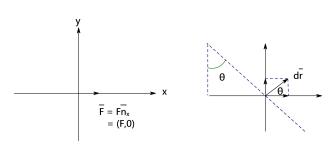
Work done by \bar{F} on the path $A \to B$ (arc of a circle with

Work done by
$$F$$
 on the path $A o B$ (arc of a circle with $\boxed{W_{A o B}} = \int_{\Gamma_{AB}} \bar{F} \cdot d\bar{r} = \int_0^{\theta_0} \underbrace{Q \sin \theta}_{F_u} R \, d\theta = QR \int_0^{\theta_0} \sin \theta \, d\theta$

 $= |QR[1-\cos\theta_0]|$

Second Method

Idea: Rewrite both the force and the elementary displacement in terms of their Cartesian coordinates.



$$d\bar{r} = |d\bar{r}|\cos\theta\,\hat{n}_x + |d\bar{r}|\sin\theta\,\hat{n}_y = (|d\bar{r}|\cos\theta, |d\bar{r}|\sin\theta)$$

$$\delta W = \bar{F} \circ d\bar{r} = F \cos \theta \underbrace{|d\bar{r}|}_{R d\theta} = F \cos \theta R d\theta$$

and $F\cos\theta=Q\sin\theta$, so that $\delta W=Q\sin\theta R\,d\theta$. Eventually,

$$W_{A o B}=\int^{ heta_0}Q\sin heta R\,d heta=QR\left[1-\cos heta_0
ight]$$

Work and Motion

Motivation

Observations

- W > 0 \Longrightarrow particle speeds up
- W < 0 \Longrightarrow particle slows down
- W=0 \Longrightarrow no change in speed

Conclusion. Work done by the net force implies a change in the particle's speed (or another quantity that is a function of speed).

Kinetic Energy and Work-Kinetic Energy Theorem

Recall that $\delta W = \bar{F} \circ d\bar{r}$ so, the rate of work being done by the <u>net force</u> on a particle

$$\frac{\delta W}{dt} = \bar{F} \circ \frac{d\bar{r}}{dt} = \bar{F} \circ \dot{\bar{r}} = m \, \bar{a} \circ \bar{v} = m \, \dot{\bar{v}} \circ \bar{v}$$

But
$$v^2 = \bar{v} \circ \bar{v}$$
, so $\frac{d}{dt}(v^2) = \frac{d}{dt}(\bar{v} \circ \bar{v}) = \dot{\bar{v}} \circ \bar{v} + \bar{v} \circ \dot{\bar{v}} = 2\bar{v} \circ \dot{\bar{v}}$

$$\frac{\delta W}{dt} = \frac{d}{dt} \underbrace{\left(\frac{1}{2}mv^2\right)}_{K}$$

where
$$K = \frac{1}{2}mv^2$$
 is the **kinetic energy**. Hence,

$$\frac{\delta W}{dt} = \frac{dK}{dt}$$
 or $\delta W = dK$

Work-Kinetic Energy Theorem

Work done by the net force on a particle is equal to the change in the particle's kinetic energy.

For finite changes

$$W = \Delta K$$

$$W>0 \Longrightarrow \Delta K>0 \Longrightarrow \Delta v>0$$

 $W<0 \Longrightarrow \Delta K<0 \Longrightarrow \Delta v<0$
 $W=0 \Longrightarrow K={\rm const} \Longrightarrow v={\rm const}$

- Derived in a general case; no assumptions about the nature of the force or the particle's trajectory made
- Used Newton's second law; can use only in inertial FoRs.
- **3** Kinetic energy has the units of work $[J = N \cdot M = kg \frac{m^2}{s^2}]$

Power

Power - characterizes "how fast" work is being done

$$\dfrac{\delta W}{\dfrac{dt}{dt}} = ar{F} \circ ar{v} = ar{P}$$
 instantaneous power $\dfrac{W}{\Delta t} = P_{av}$

Units: [W] (Watt)

Alternative units:
$$hp = 746W = 0.746kW$$

Example (*Power of engines in vehicles*): Abrams battle tank 1500 hp, Volvo C30 108hp, Harley-Davidson 1600ccm 63 hp, Porsche 911 GT2 523 hp, Boeing 747-300 (@ 0.84 Mach, 35k feet) 330 000 hp, Diesel locomotive 5000 hp