

Computer Vision: K-means

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**Project team-up report template is online
everyone has to submit on your own
due on June 10th**

Next Monday (June 13th),
the lecture will discuss everything about the project.
Please bring your question

K-means

Unsupervised learning: Clustering

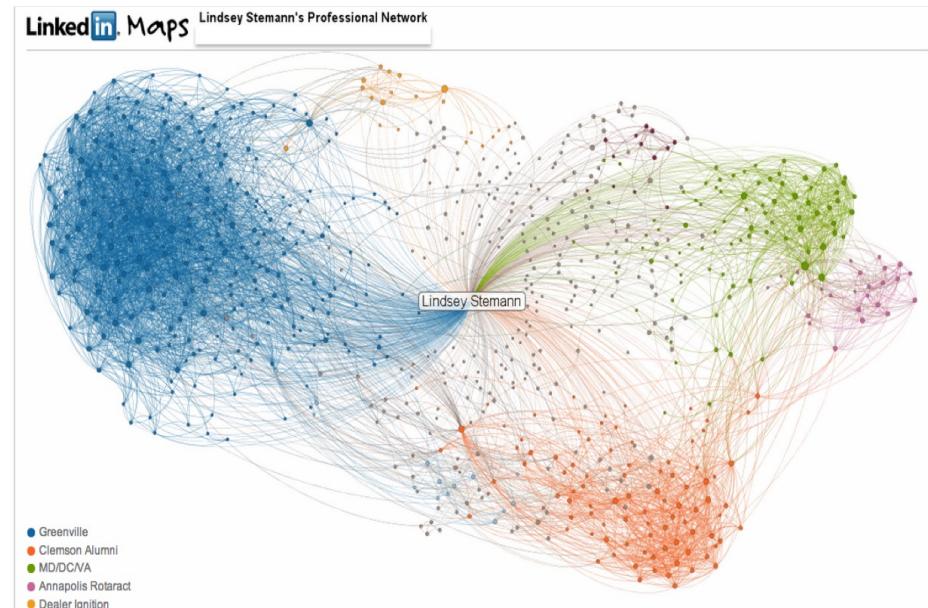
Application: Image segmentation & image retrieval

Method: K-means, K-means++, spectral clustering

Clustering



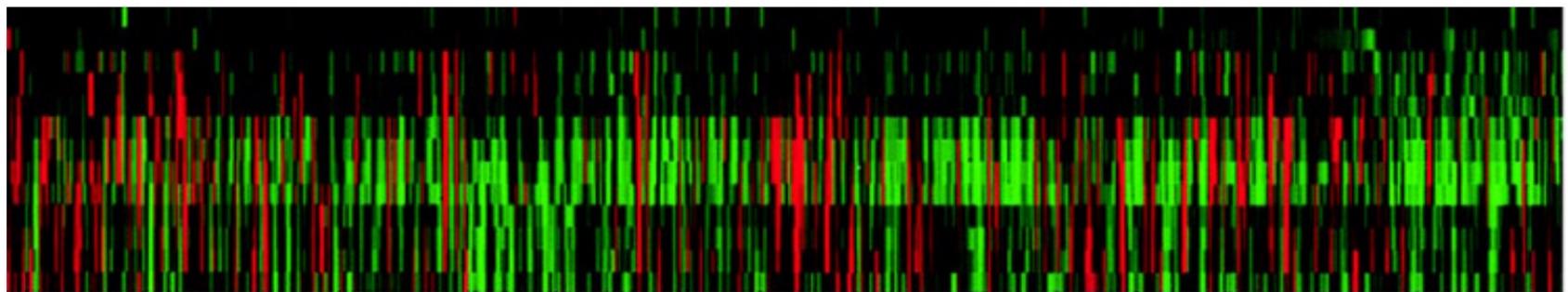
the task of grouping a set of objects in such a way that objects in the same group (called a cluster) are more similar (in some sense) to each other than to those in other groups (clusters)



Social networks

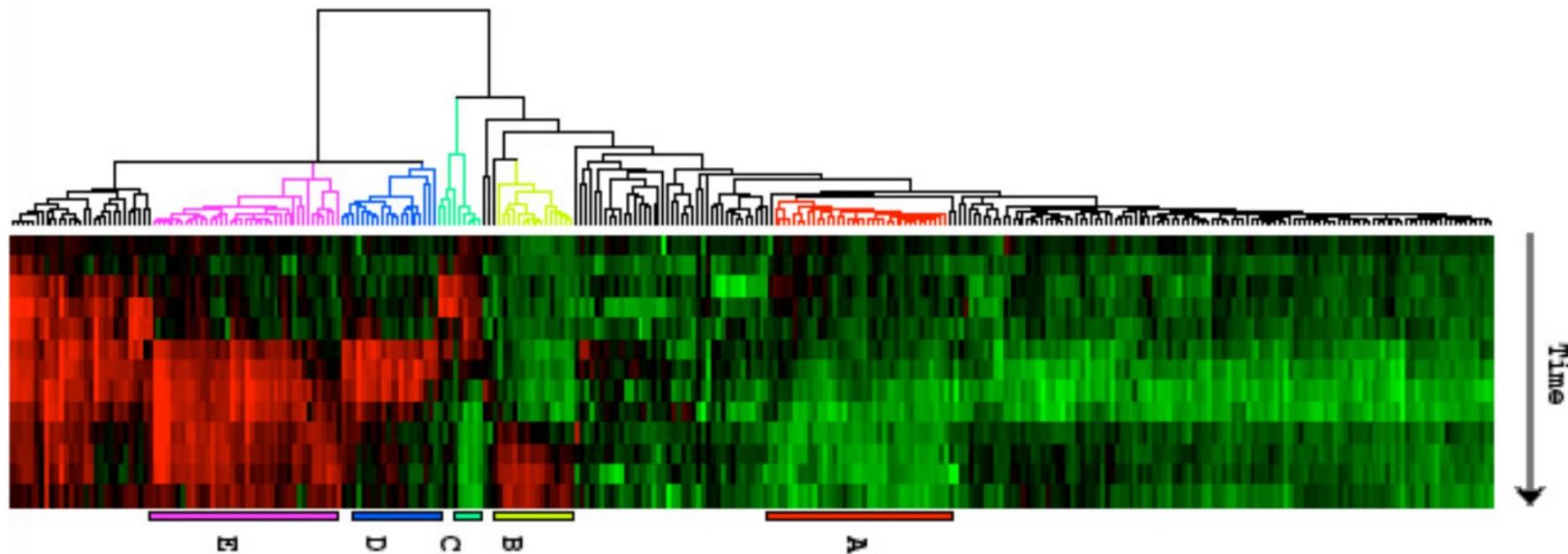
Clustering

Clustering gene expression data



Clustering

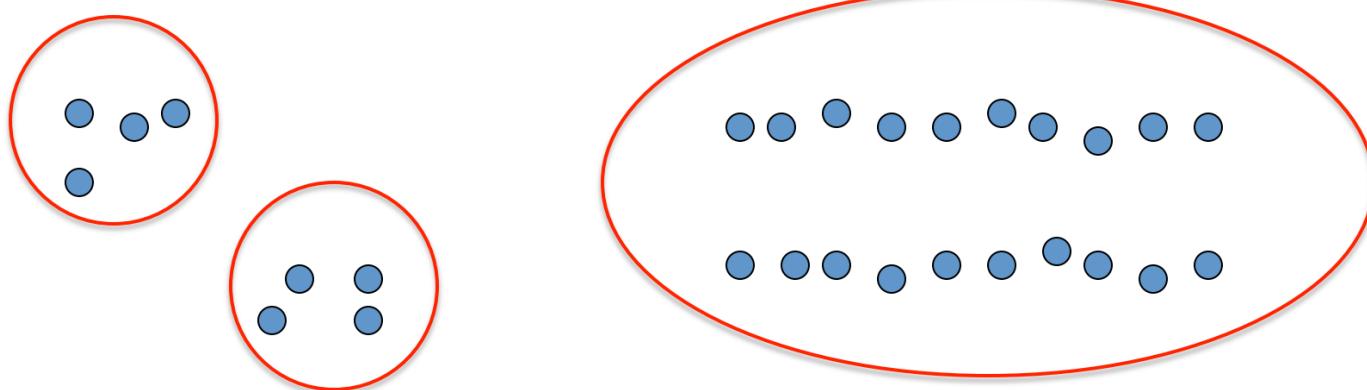
Clustering gene expression data



Clustering



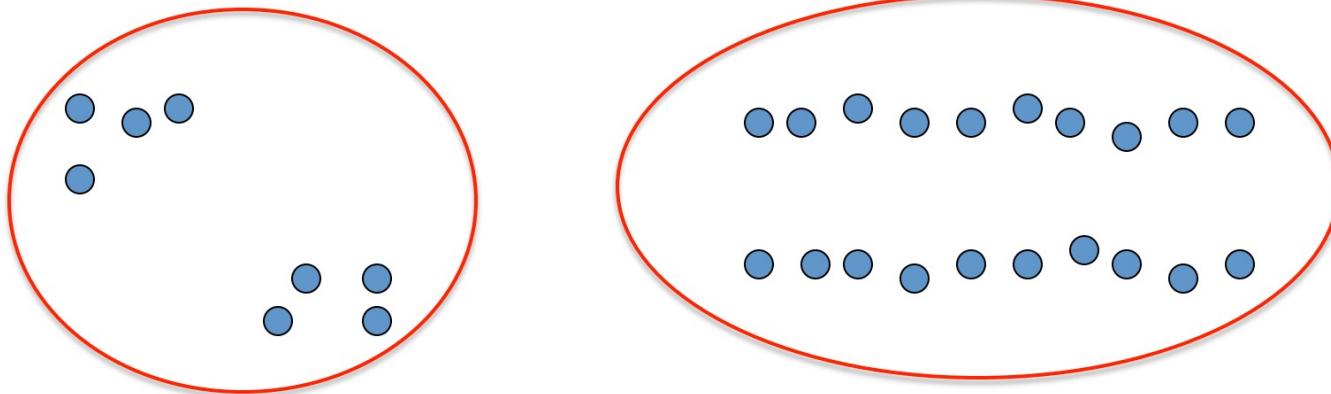
the task of grouping a set of objects in such a way that objects in the same group (called a cluster) are more similar (in some sense) to each other than to those in other groups (clusters)



Clustering



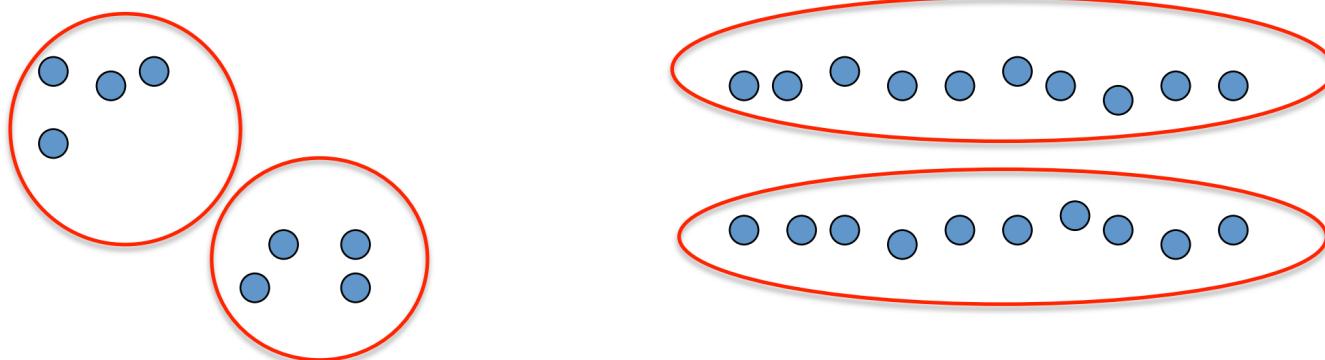
the task of grouping a set of objects in such a way that objects in the same group (called a cluster) are more similar (in some sense) to each other than to those in other groups (clusters)



Clustering



the task of grouping a set of objects in such a way that objects in the same group (called a cluster) are more similar (in some sense) to each other than to those in other groups (clusters)



Clustering is challenging... because how would you describe similarity?

Image segmentation

Goal: Identify groups of pixels that go together



Image segmentation

Goal: Identify groups of pixels that go together

Psychologists identified series of factors that predispose set of elements to be grouped (by human visual system)

"I stand at the window and see a house, trees, sky. Theoretically I might say there were 327 brightnesses and nuances of colour. Do I have "327"? No. I have sky, house, and trees."

Max Wertheimer, Psychologist (1880-1943)

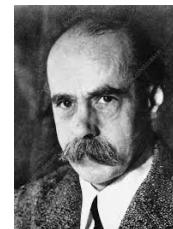
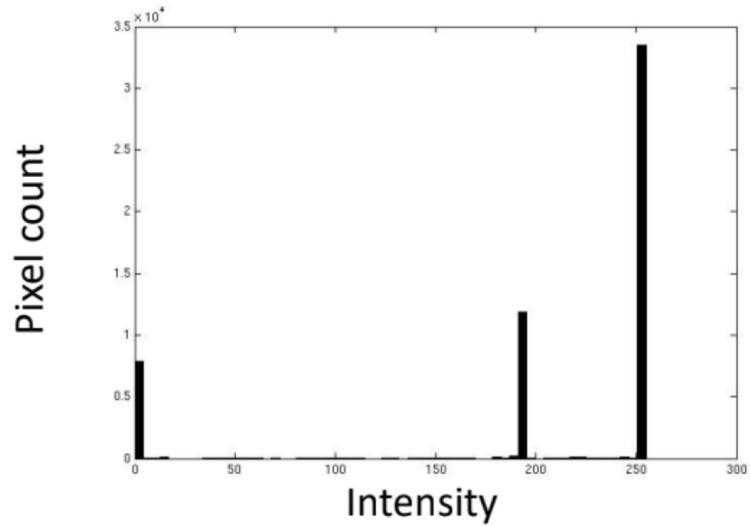
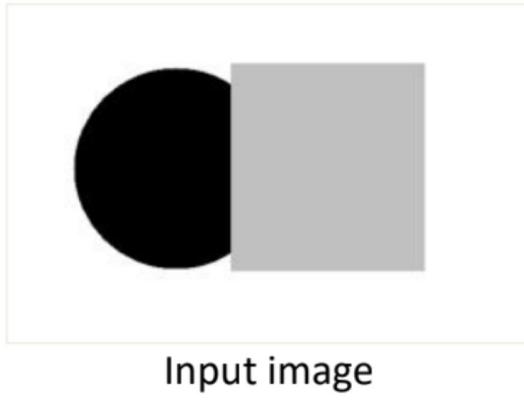


Image segmentation



Input image

Image segmentation



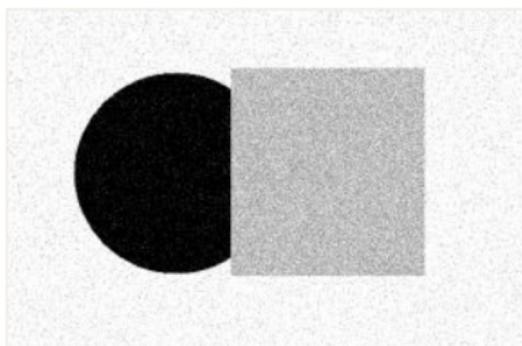
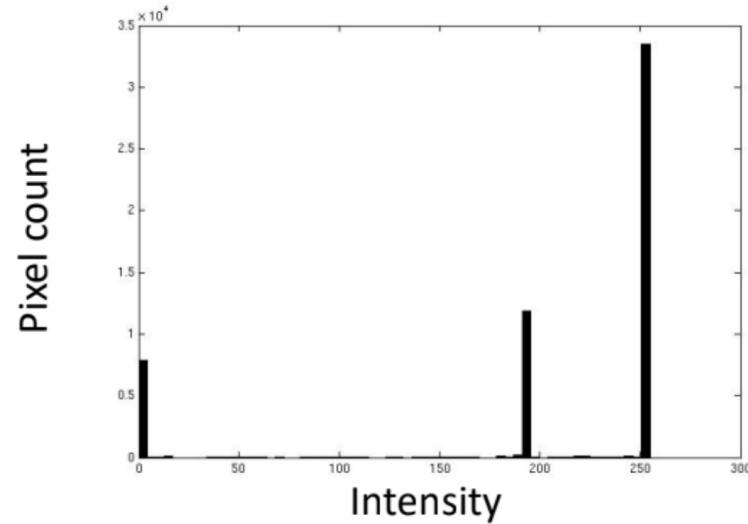
Intensities define the three groups.

- Segment the image based on the intensity feature.
- What if the image isn't quite so simple?

Image segmentation



Input image



Input image

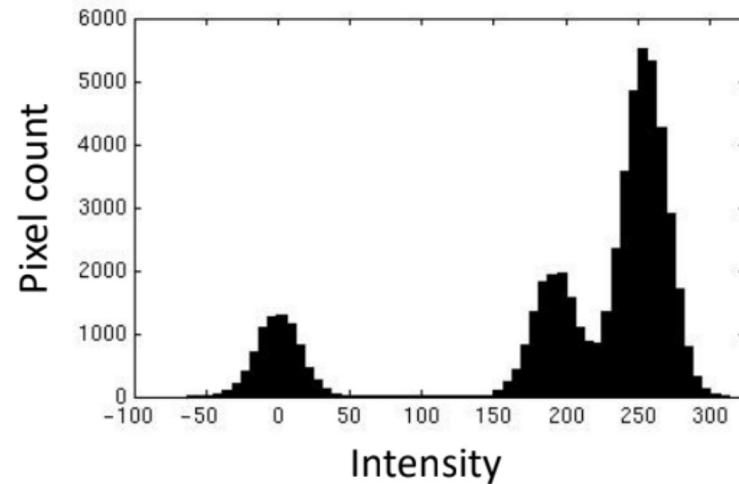
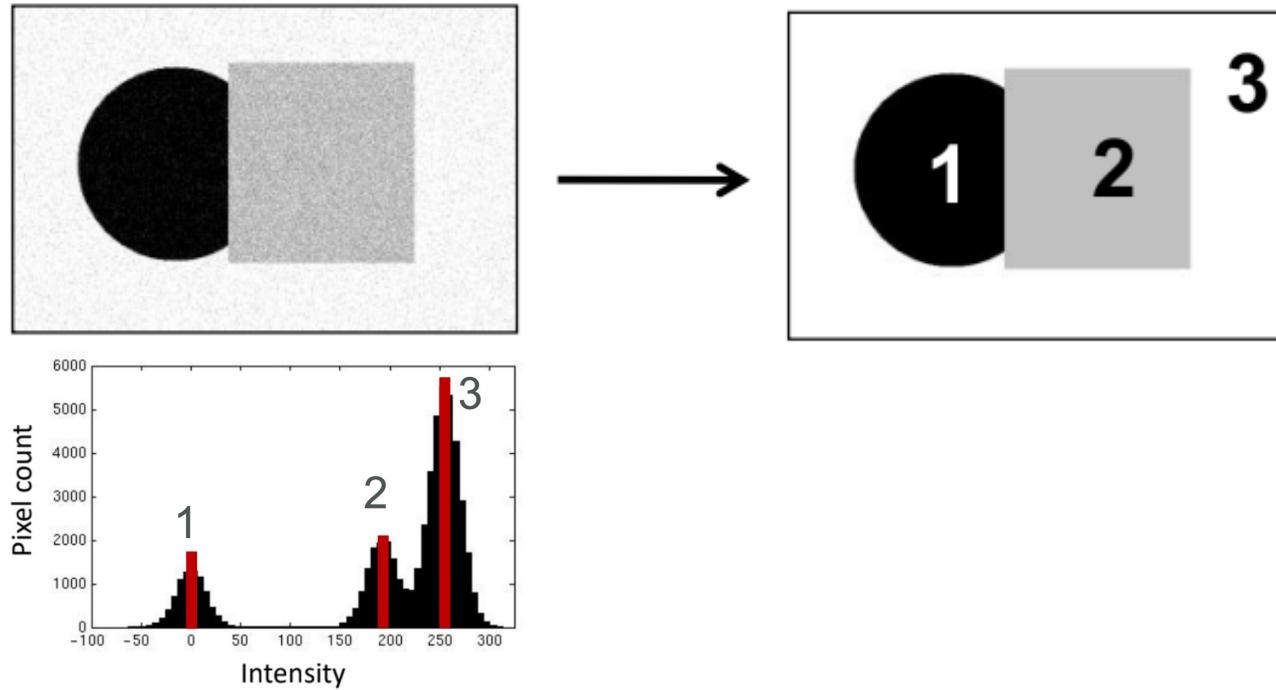


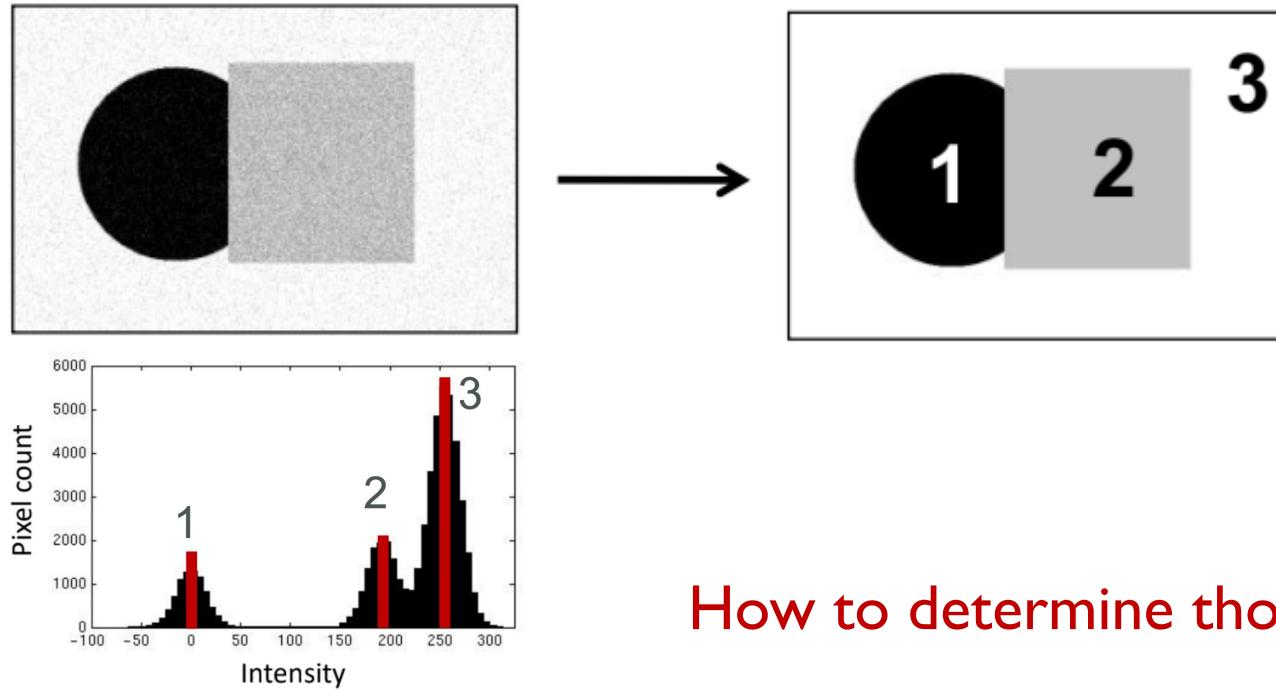
Image segmentation



Step 1: Choose three “centers” as the representative intensities;

Step 2: Label every pixel according to which of these centers it is nearest to

Image segmentation

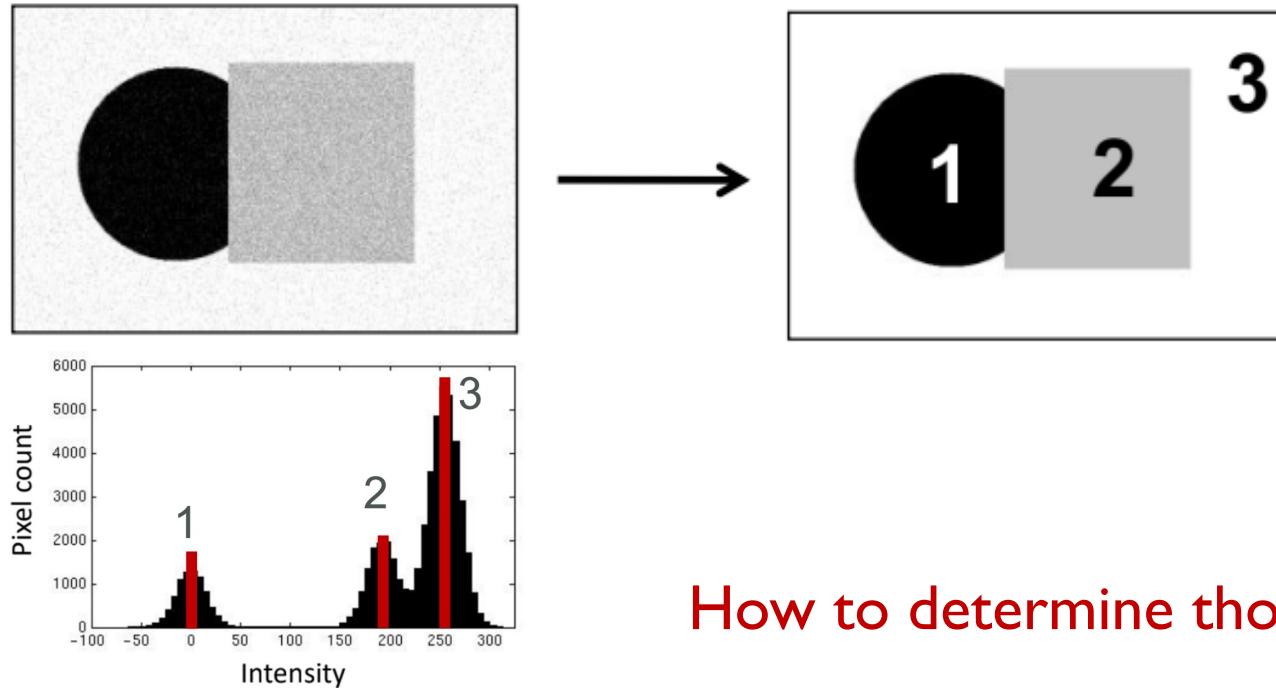


How to determine those centers?

Step 1: Choose three “centers” as the representative intensities;

Step 2: Label every pixel according to which of these centers it is nearest to

Image segmentation



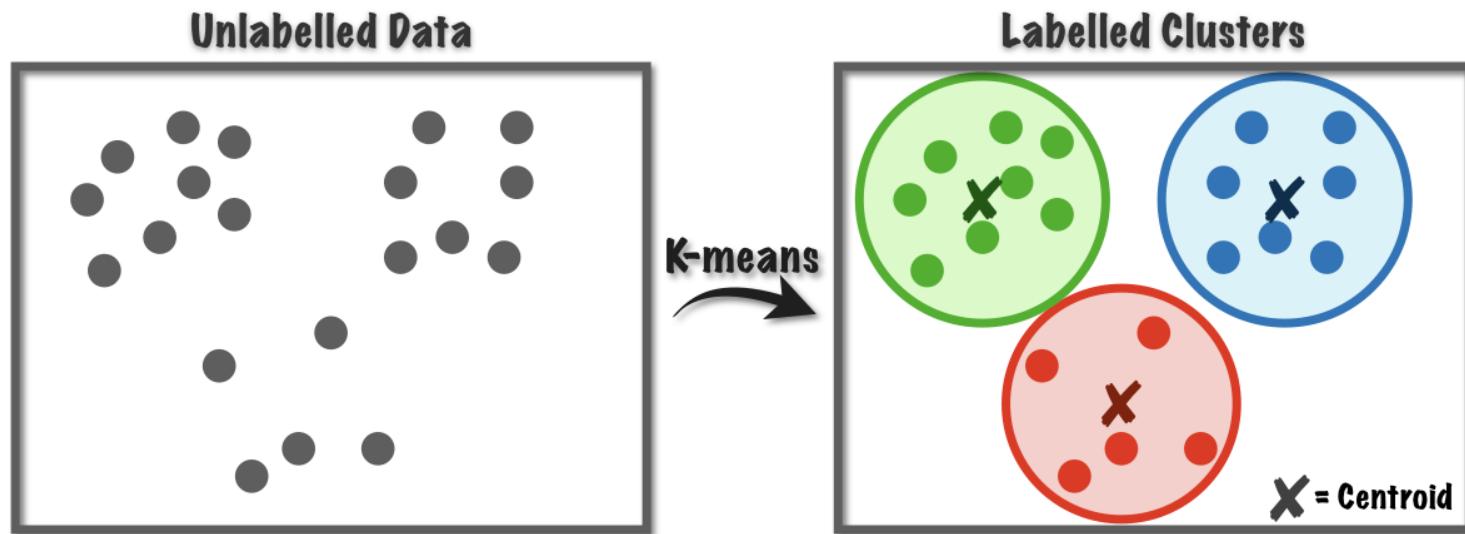
How to determine those centers?

Best cluster centers are those that minimize Sum of Square Distance (SSD) between all points and their nearest cluster center

$$SSD(c_1, c_2, c_3) = \sum_{x_i} \min_j (x_i - c_j)^2$$

What will we learn today?

K-means clustering

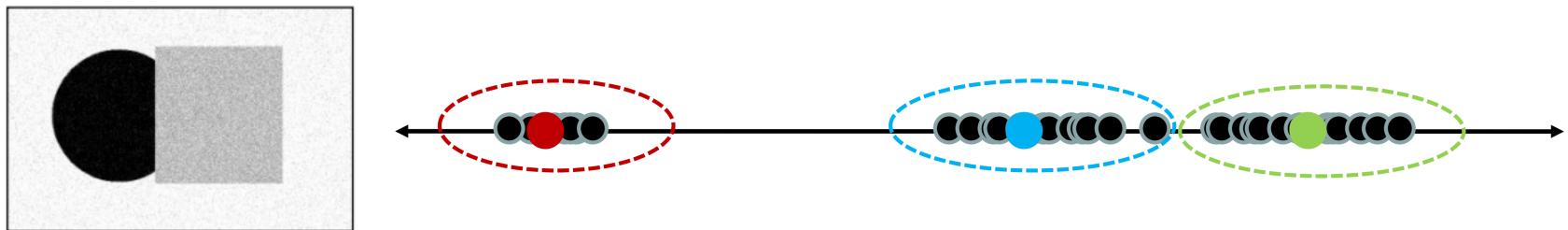


K-means clustering

Goal: cluster to minimize variance in data given clusters

$$\mathbf{c}^* = \arg \min_{\mathbf{c}} \sum_{x_i} \min_j (x_i - c_j)^2$$

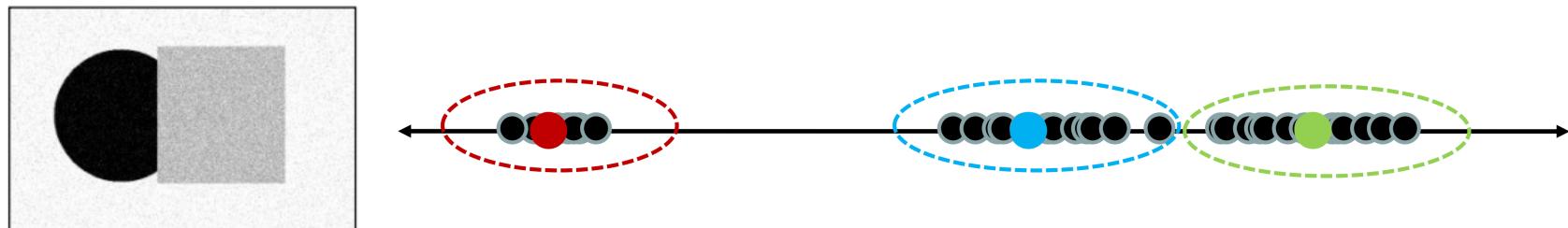
↑ ↑ ↑
find cluster center membership assignment data center



K-means clustering

With this objective, it is a “chicken and egg” problem:

- If we knew the cluster centers, we could allocate points to groups by assigning each to its closest center
- If we knew the group memberships, we could get the centers by computing the mean per group



K-means clustering: Optimization

Goal: cluster to minimize variance in data given clusters

$$\mathbf{c}^* = \arg \min_{\mathbf{c}} \sum_{x_i} \min_j (x_i - c_j)^2$$


$$\mathbf{c}^*, \delta^* = \arg \min_{\mathbf{c}, \delta} \sum_{x_i} \sum_{c_j} \delta_{i,j} (x_i - c_j)^2$$

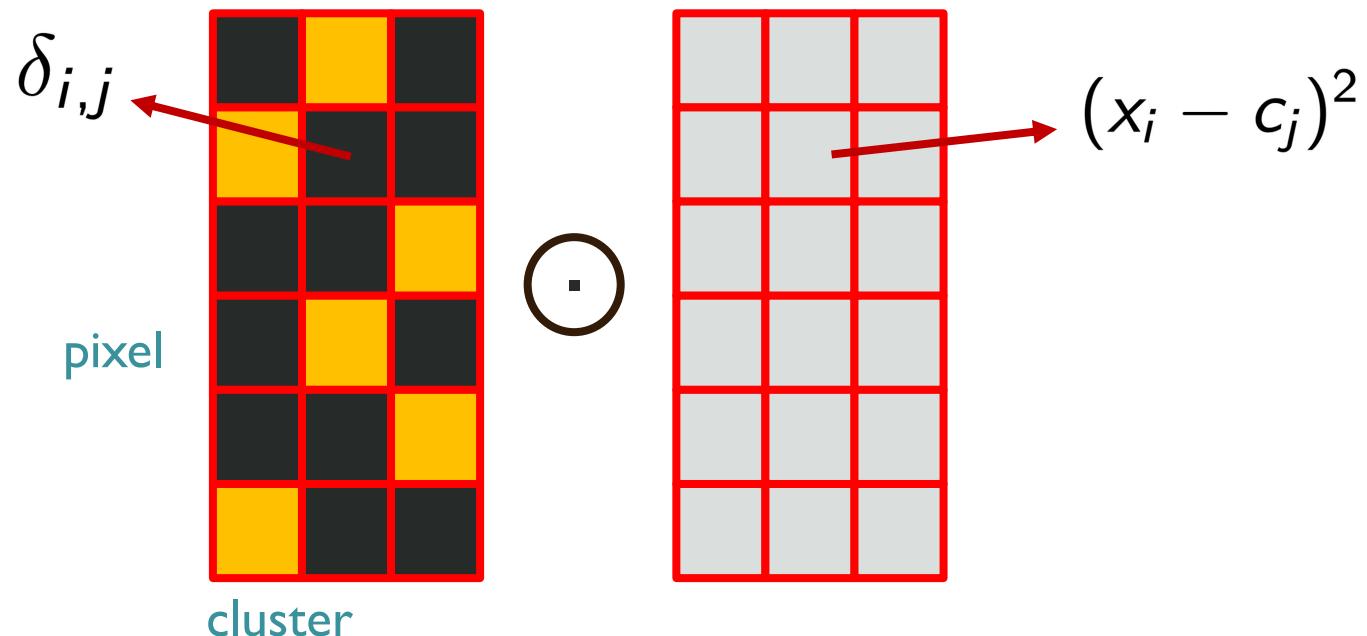
$$\delta \in \{0, 1\}^{N \times K}, \delta 1 = 1$$

membership matrix

K-means clustering: Optimization

Goal: cluster to minimize variance in data given clusters

$$\mathbf{c}^*, \delta^* = \arg \min_{\mathbf{c}, \delta} \sum_{x_i} \sum_{c_j} \delta_{i,j} (x_i - c_j)^2 \quad \delta \in \{0, 1\}^{N \times K}, \delta \mathbf{1} = 1$$



K-means clustering: Iterative algorithm

$$\mathbf{c}^*, \delta^* = \arg \min_{\mathbf{c}, \delta} \sum_{x_i} \sum_{c_j} \delta_{i,j} (x_i - c_j)^2 \quad \delta \in \{0, 1\}^{N \times K}, \delta \mathbf{1} = 1$$

1. Initialize: cluster centers
2. Assign each point to the closest center

$$\delta^{(t)} = \arg \min_{\delta} \sum_{x_i} \sum_{c_j^{(t-1)}} \delta_{i,j} (x_i - c_j^{(t-1)})^2$$

3. Update cluster centers as the mean of the points

$$\mathbf{c}^{(t)} = \arg \min_{\mathbf{c}} \sum_{x_i} \sum_{c_j} \delta_{i,j}^{(t)} (x_i - c_j)^2$$

4. Repeat Step 2-3 till stopped



K-means clustering: Iterative algorithm

$$\mathbf{c}^*, \delta^* = \arg \min_{\mathbf{c}, \delta} \sum_{x_i} \sum_{c_j} \delta_{i,j} (x_i - c_j)^2 \quad \delta \in \{0, 1\}^{N \times K}, \delta \mathbf{1} = 1$$

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Solution: $\delta_{i,j^*} = 1$, when $j^* = \arg \min_j (x_i - c_j)^2$

3. Update cluster centers as the mean of the points

$$\mathbf{c}^{(t)} = \arg \min_{\mathbf{c}} \sum_{x_i} \sum_{c_j} \delta_{i,j}^{(t)} (x_i - c_j)^2$$



$$\text{Solution: } c_j^{(t)} = \frac{1}{\sum_i \delta_{i,j}^{(t)}} \sum_i x_i \delta_{i,j}^{(t)}$$

4. Repeat Step 2-3 till stopped



K-means clustering: Iterative algorithm

$$\mathbf{c}^*, \delta^* = \arg \min_{\mathbf{c}, \delta} \sum_{x_i} \sum_{c_j} \delta_{i,j} (x_i - c_j)^2 \quad \delta \in \{0, 1\}^{N \times K}, \delta \mathbf{1} = 1$$

1. Initialize: cluster centers Random/ K-means++

2. Assign each point to the closest center

$$\delta^{(t)} = \arg \min_{\delta} \sum_{x_i} \sum_{c_j^{(t-1)}} \delta_{i,j} (x_i - c_j^{(t-1)})^2$$


Solution: $\delta_{i,j^*} = 1$, when $j^* = \arg \min_j (x_i - c_j)^2$

3. Update cluster centers as the mean of the points

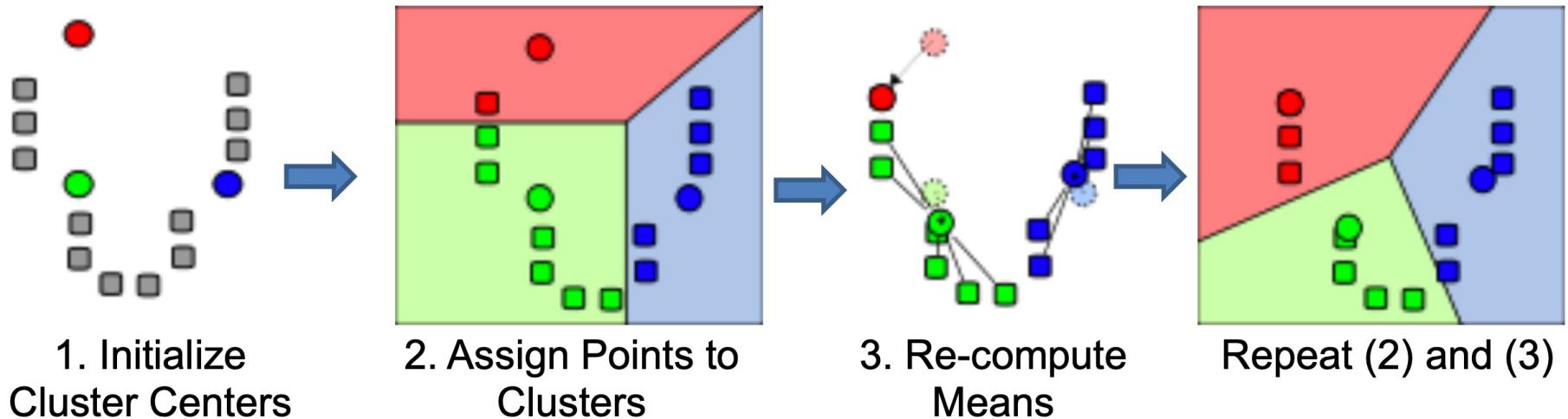
$$\mathbf{c}^{(t)} = \arg \min_{\mathbf{c}} \sum_{x_i} \sum_{c_j} \delta_{i,j}^{(t)} (x_i - c_j)^2 \quad \leftrightarrow \quad \text{Solution: } c_j^{(t)} = \frac{1}{\sum_i \delta_{i,j}^{(t)}} \sum_i x_i \delta_{i,j}^{(t)}$$

4. Repeat Step 2-3 till stopped

Convergence analysis

K-means clustering: Iterative algorithm

$$\mathbf{c}^*, \delta^* = \arg \min_{\mathbf{c}, \delta} \sum_{x_i} \sum_{c_j} \delta_{i,j} (x_i - c_j)^2 \quad \delta \in \{0, 1\}^{N \times K}, \delta 1 = 1$$



K-means clustering for segmentation

Original Image



Segmented Image when K = 6



K-means clustering for segmentation



Original image



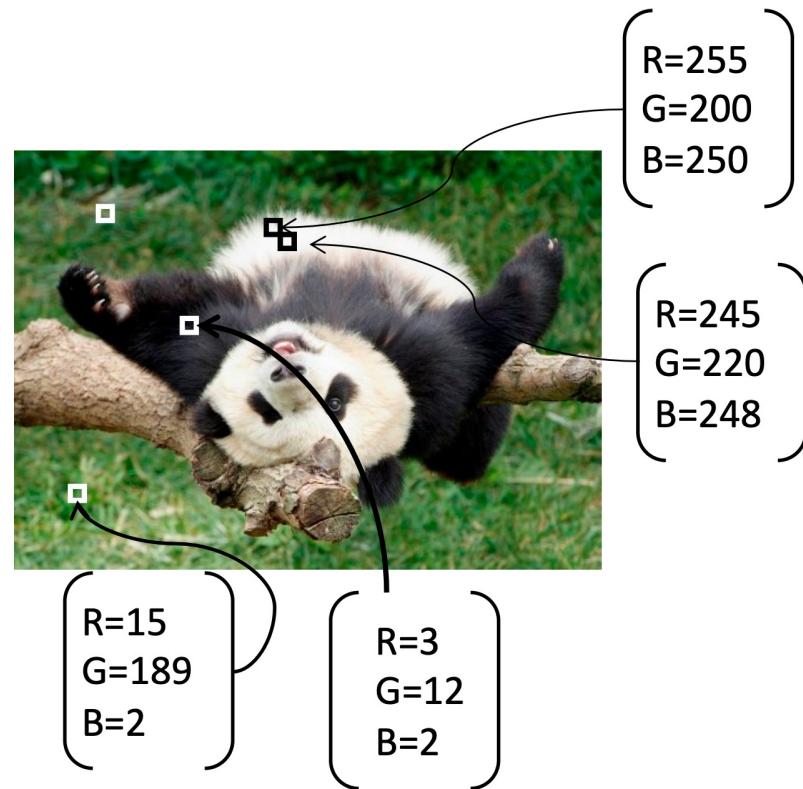
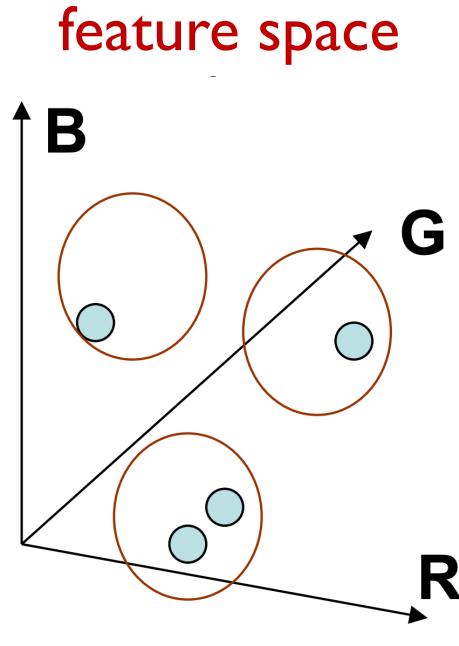
2 clusters



3 clusters

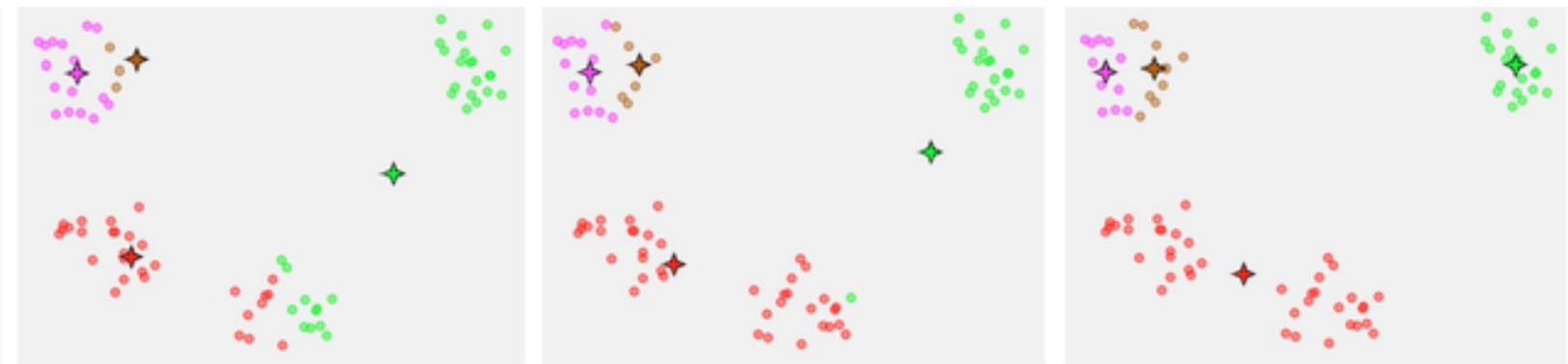
K-means clustering for segmentation

Depending on what we choose as the **feature space**, we can group pixels in different ways



K-means clustering: Issues

- Converge to local minimum



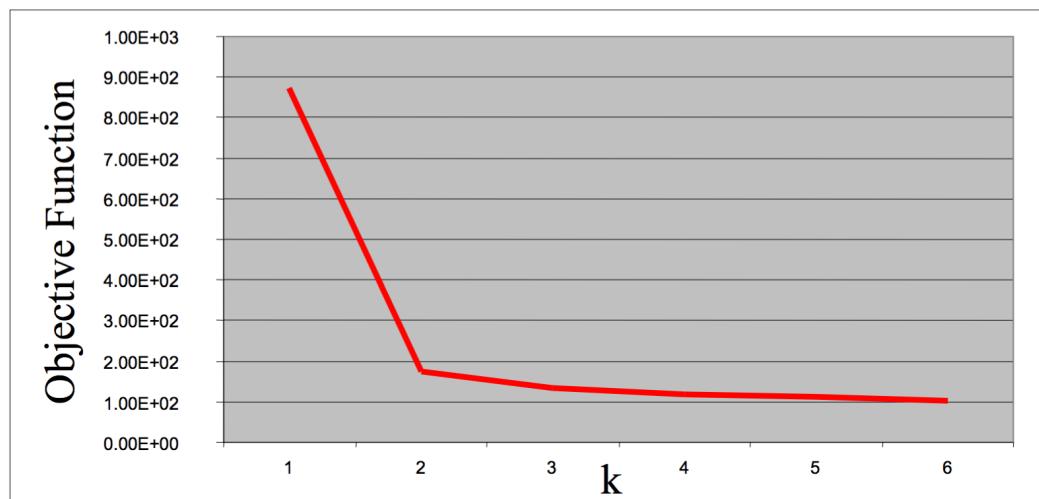
Solution: Initialize multiple times!

K-means clustering: Issues

- Need to pick the number of centers K

We can plot the objective function values for k equals 1 to 6...

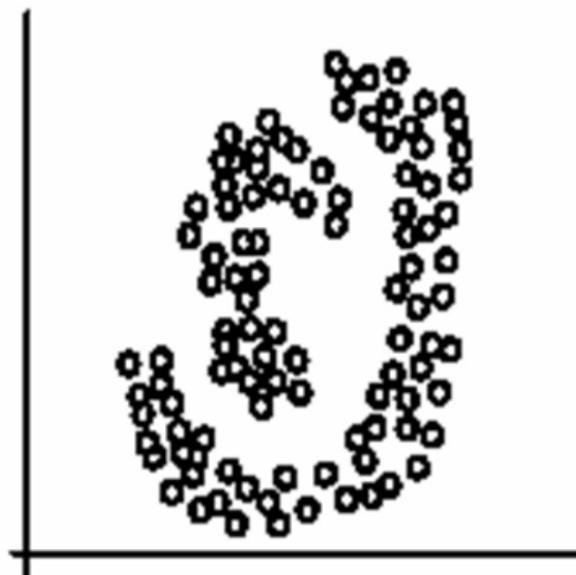
The abrupt change at $k = 2$, is highly suggestive of two clusters in the data. This technique for determining the number of clusters is known as “knee finding” or “elbow finding”.



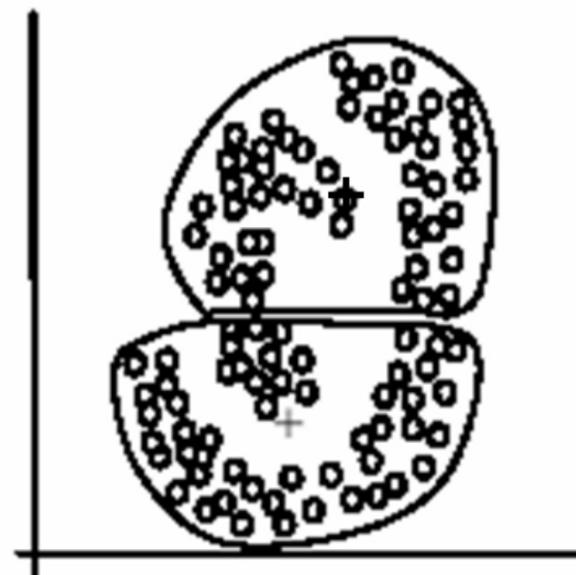
Solutions: Try different numbers of clusters and look at performance!

K-means clustering: Issues

- Wrong similarity metric



(A): Two natural clusters



(B): k -means clusters

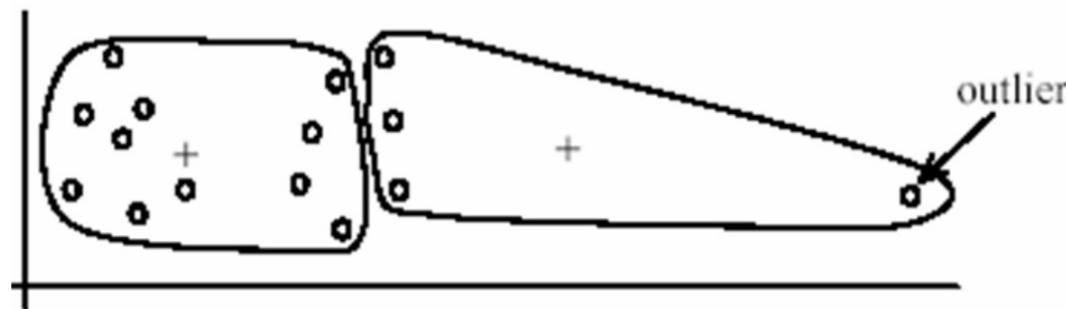
Solutions: Adaptive similarity metric!

K-means clustering: Issues

- Sensitive to outliers



(B): Ideal clusters



Solutions: Consider density!

K-means clustering

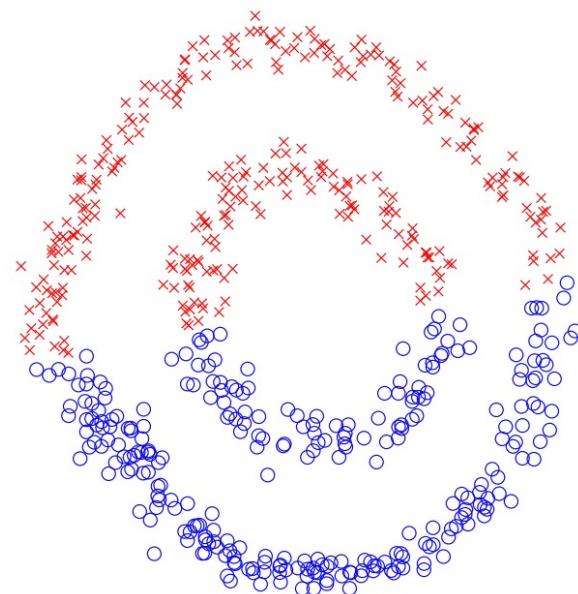
Pros

- Finds cluster centers that minimize conditional variance
- Simple and fast, Easy to implement

Cons

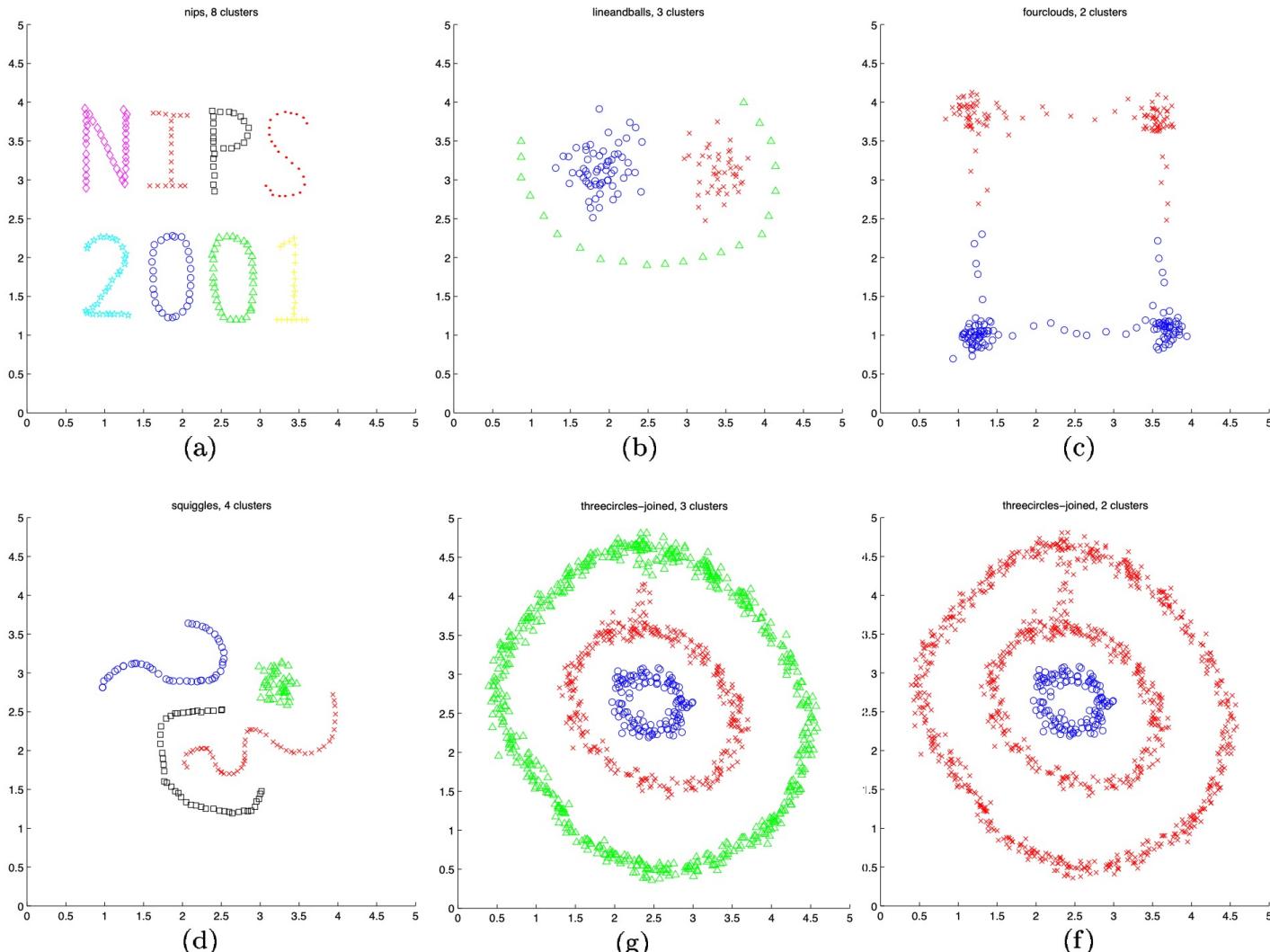
- Prone to local minima
- Need to choose K
- Sensitive to outliers
- All clusters have the same parameters (e.g., distance measure is non -adaptive)

K-means clustering



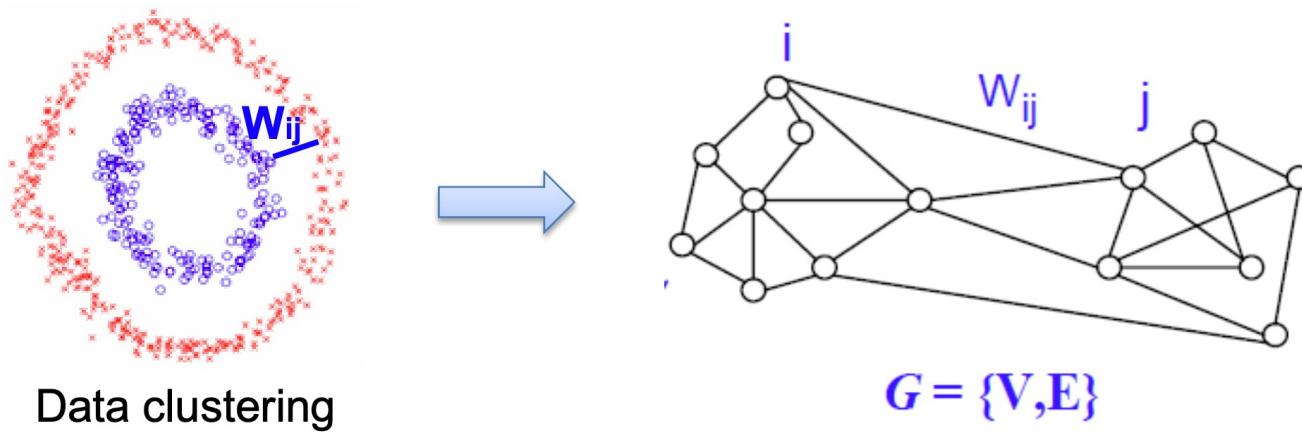
two circles, 2 clusters

Spectral clustering



Spectral clustering

Group points based on links in a graph

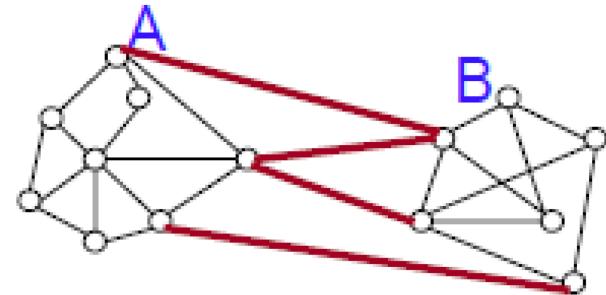


$$W_{ij} = e^{\frac{\|x_i - x_j\|^2}{2\sigma^2}}$$

Spectral clustering

Min-cut: Partition graph into two sets A and B such that weight of edges connecting vertices in A to vertices in B is minimum.

$$\text{cut}(A, B) := \sum_{i \in A, j \in B} w_{ij}$$



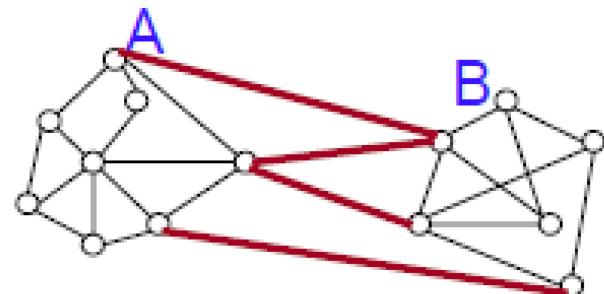
Notations

- $W = (w_{ij})$ adjacency matrix of the graph
- $d_i = \sum_j w_{ij}$ degree of a vertex
- $D = \text{diag}(d_1, \dots, d_n)$ degree matrix
- $|A|$ = number of vertices in A
- $\text{vol}(A) = \sum_{i \in A} d_i$

Spectral clustering

Min-cut: Partition graph into **two nonoverlapping** sets A and B such that weight of edges connecting vertices in A to vertices in B is minimum.

$$\text{cut}(A, B) := \sum_{i \in A, j \in B} w_{ij}$$



$$\text{Ncut}(A, B) := \text{cut}(A, B) \left(\frac{1}{\text{vol}(A)} + \frac{1}{\text{vol}(B)} \right)$$

$$\text{vol}(A) = \sum_{i \in A} d_i$$

Spectral clustering

Min-cut: Partition graph into **two nonoverlapping** sets A and B such that weight of edges connecting vertices in A to vertices in B is minimum.

$$\text{Ncut}(A, B) := \text{cut}(A, B) \left(\frac{1}{\text{vol}(A)} + \frac{1}{\text{vol}(B)} \right)$$

$$= \frac{\mathbf{f}^T \mathbf{L} \mathbf{f}}{\mathbf{f}^T \mathbf{D} \mathbf{f}} \quad \mathbf{f} = [f_1 \ f_2 \ \dots \ f_n]^T \text{ with } f_i = \begin{cases} \frac{1}{\text{vol}(A)} & \text{if } i \in A \\ -\frac{1}{\text{vol}(B)} & \text{if } i \in B \end{cases}$$

- $W = (w_{ij})$ adjacency matrix of the graph
- $d_i = \sum_j w_{ij}$ degree of a vertex
- $D = \text{diag}(d_1, \dots, d_n)$ degree matrix
- $L = D - W$

Spectral clustering

Min-cut: Partition graph into **two nonoverlapping** sets A and B such that weight of edges connecting vertices in A to vertices in B is minimum.

$$f' L f = f' D f - f' W f$$

$$L = D - W$$

Spectral clustering

Min-cut: Partition graph into **two nonoverlapping** sets A and B such that weight of edges connecting vertices in A to vertices in B is minimum.

$$\begin{aligned} \mathbf{f}' \mathbf{L} \mathbf{f} &= \mathbf{f}' \mathbf{D} \mathbf{f} - \mathbf{f}' \mathbf{W} \mathbf{f} & \mathbf{L} &= \mathbf{D} - \mathbf{W} \\ &= \sum_i d_i f_i^2 - \sum_{i,j} f_i f_j w_{ij} \\ &= \frac{1}{2} \left(\sum_i \left(\sum_j w_{ij} \right) f_i^2 - 2 \sum_{ij} f_i f_j w_{ij} + \sum_j \left(\sum_i w_{ij} \right) f_j^2 \right) \\ &= \frac{1}{2} \sum_{ij} w_{ij} (f_i - f_j)^2 = \sum_{i \in A, j \in B} w_{ij} \left(\frac{1}{\text{vol}(A)} + \frac{1}{\text{vol}(B)} \right)^2 \end{aligned}$$

$$\mathbf{f} = [f_1 \ f_2 \ \dots \ f_n]^T \text{ with } f_i = \begin{cases} \frac{1}{\text{vol}(A)} & \text{if } i \in A \\ -\frac{1}{\text{vol}(B)} & \text{if } i \in B \end{cases}$$

Spectral clustering

Min-cut: Partition graph into **two nonoverlapping** sets A and B such that weight of edges connecting vertices in A to vertices in B is minimum.

$$\mathbf{f}^T \mathbf{D} \mathbf{f} = \sum_j d_i f_i^2 = \sum_{i \in A} \frac{d_i}{\text{vol}(A)^2} + \sum_{j \in B} \frac{d_i}{\text{vol}(B)^2} = \frac{1}{\text{vol}(A)} + \frac{1}{\text{vol}(B)}$$

$$\mathbf{f} = [f_1 \ f_2 \ \dots \ f_n]^T \text{ with } f_i = \begin{cases} \frac{1}{\text{vol}(A)} & \text{if } i \in A \\ -\frac{1}{\text{vol}(B)} & \text{if } i \in B \end{cases}$$

Spectral clustering

Min-cut: Partition graph into **two nonoverlapping** sets A and B such that weight of edges connecting vertices in A to vertices in B is minimum.

$$\text{Ncut}(A, B) := \text{cut}(A, B) \left(\frac{1}{\text{vol}(A)} + \frac{1}{\text{vol}(B)} \right)$$

$$\begin{aligned} &= \frac{\mathbf{f}^T \mathbf{L} \mathbf{f}}{\mathbf{f}^T \mathbf{D} \mathbf{f}} \\ &= \frac{\sum_{i \in A, j \in B} w_{ij} \left(\frac{1}{\text{vol}(A)} + \frac{1}{\text{vol}(B)} \right)^2}{\frac{1}{\text{vol}(A)} + \frac{1}{\text{vol}(B)}} \end{aligned}$$

Spectral clustering

minimize

$$\text{Ncut}(A, B) = \frac{\mathbf{f}^T \mathbf{L} \mathbf{f}}{\mathbf{f}^T \mathbf{D} \mathbf{f}}$$

subject to

$$\mathbf{f} = [f_1 \ f_2 \ \dots \ f_n]^T \text{ with } f_i = \begin{cases} \frac{1}{\text{vol}(A)} & \text{if } i \in A \\ -\frac{1}{\text{vol}(B)} & \text{if } i \in B \end{cases}$$



Relax the constraint

minimize

$$\text{Ncut}(A, B) = \frac{\mathbf{f}^T \mathbf{L} \mathbf{f}}{\mathbf{f}^T \mathbf{D} \mathbf{f}}$$

subject to

$$\mathbf{f}^T \mathbf{D} \mathbf{1} = 0$$

Spectral clustering

minimize

$$\text{Ncut}(A, B) = \frac{\mathbf{f}^T \mathbf{L} \mathbf{f}}{\mathbf{f}^T \mathbf{D} \mathbf{f}}$$

subject to

$$\mathbf{f}^T \mathbf{D} \mathbf{1} = 0$$

second eigenvector of generalized eigendecomposition problem

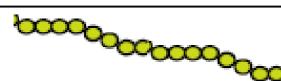
$$\mathbf{L}\mathbf{f} = \lambda \mathbf{D}\mathbf{f}$$

min-cut solution (binary)



Approximation

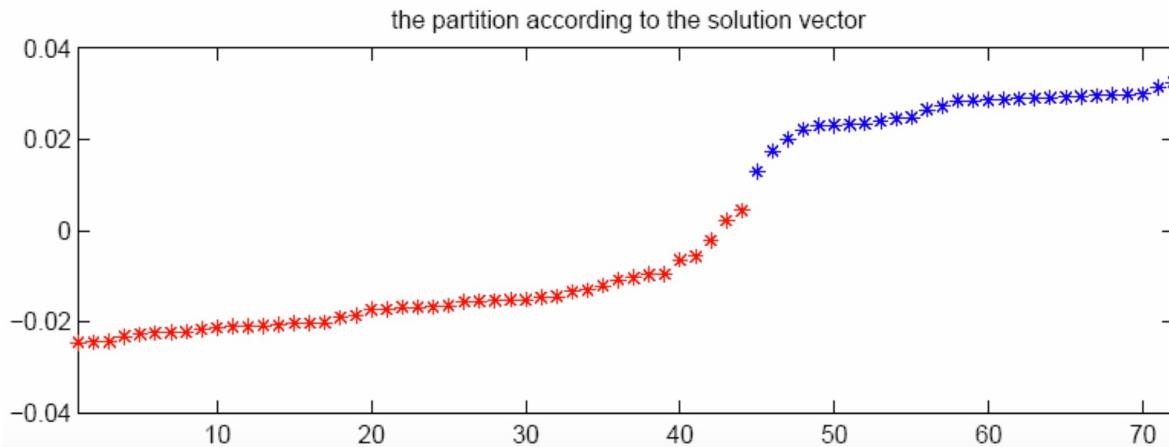
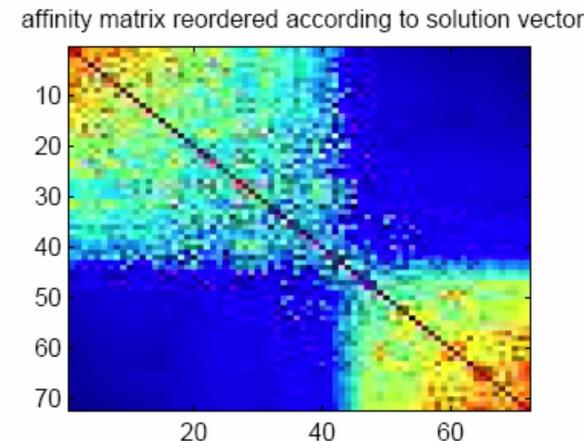
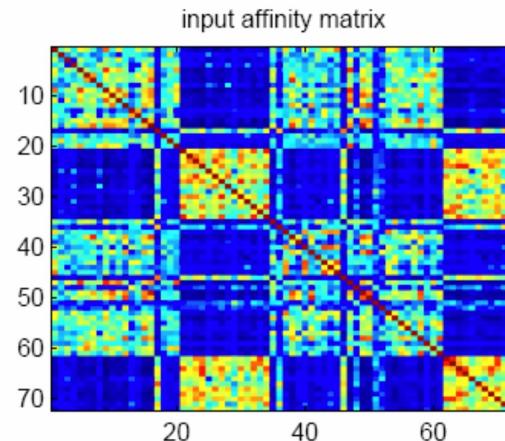
spectral clustering solution



Spectral clustering

Example:

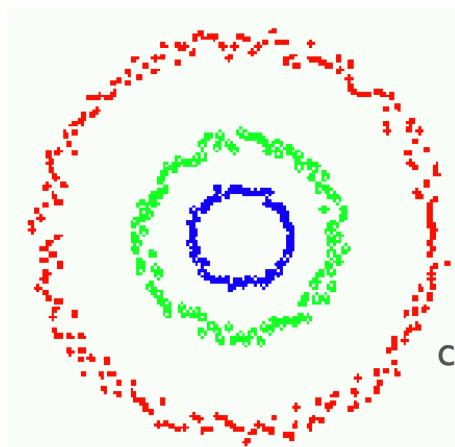
block-wise matrix -> eigenvector with positive / negative elements



Spectral clustering

How to partition a graph into k clusters?

graph modeling + k-means



Graph
construction

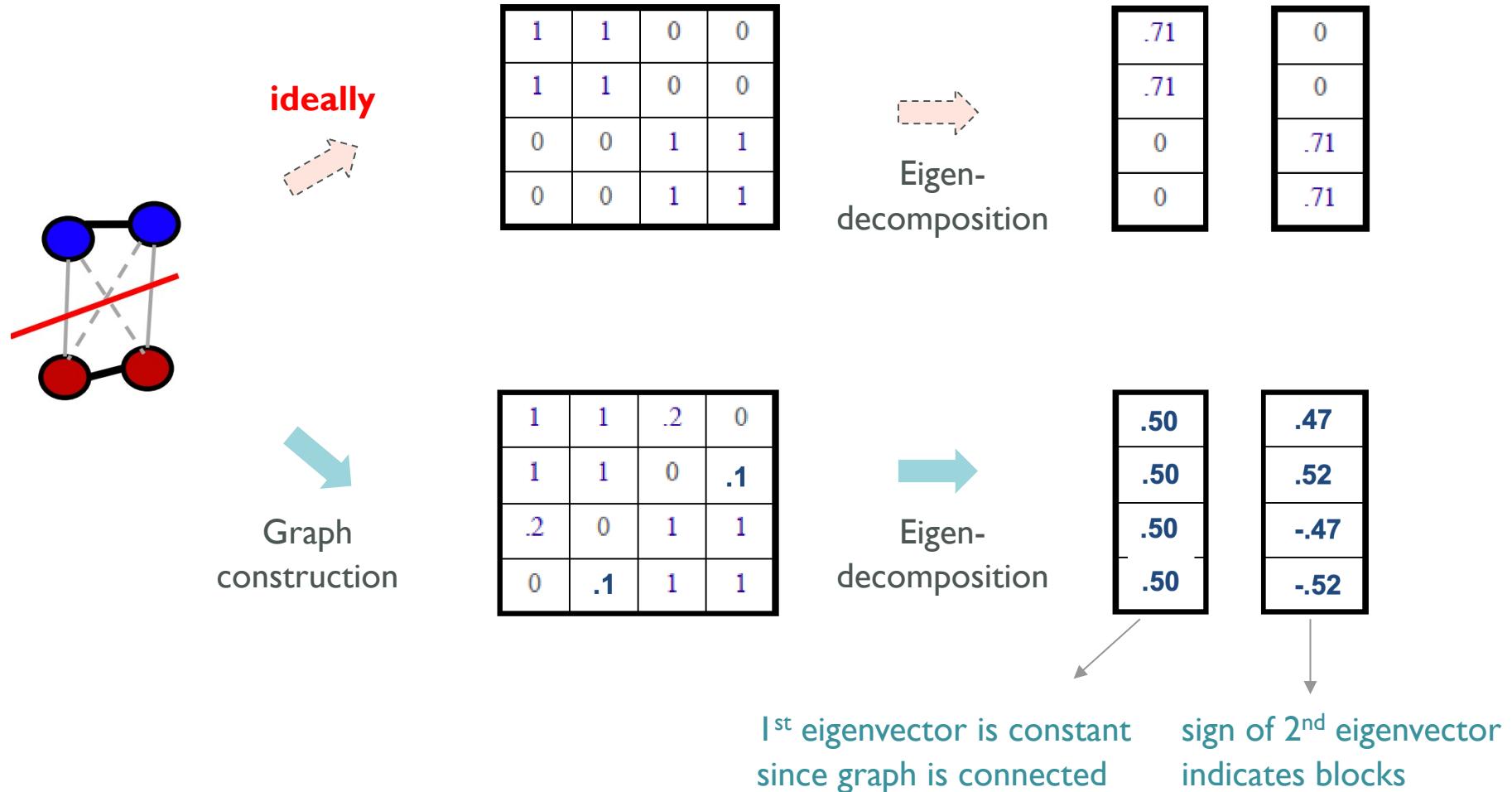
$$L = \begin{pmatrix} L_1 & & & \\ & \ddots & 0 & \\ & 0 & L_2 & \\ & & & \ddots \\ & & 0 & L_3 \end{pmatrix}$$

Eigen-decomposition

A diagram illustrating the eigenvalue decomposition of a matrix. On the left, a vertical vector with entries 1, 0, 0, ..., 0 is shown. An arrow points to the right, where the same vector is shown next to a diagonal matrix with the same entries. This represents the transformation of a general vector into its eigenvectors.

block-wise matrix -> eigenvectors with
nonoverlapping nonzero indices

Spectral clustering

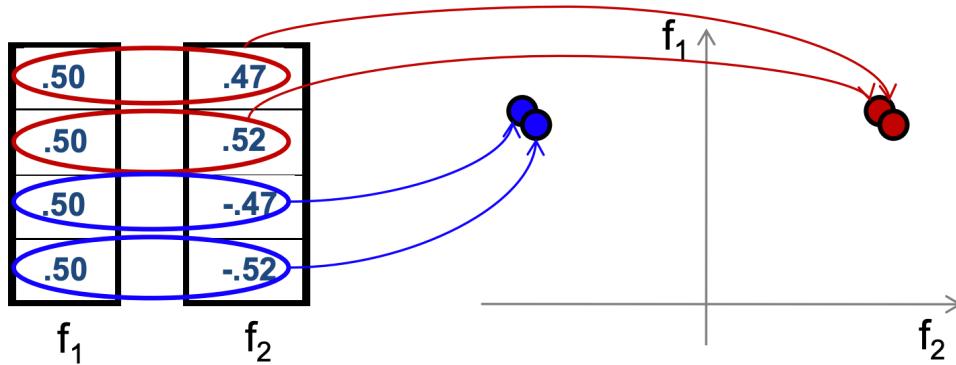


Spectral clustering

Can put data points into blocks using eigenvectors:

1	1	.2	0
1	1	0	.1
.2	0	1	1
0	.1	1	1

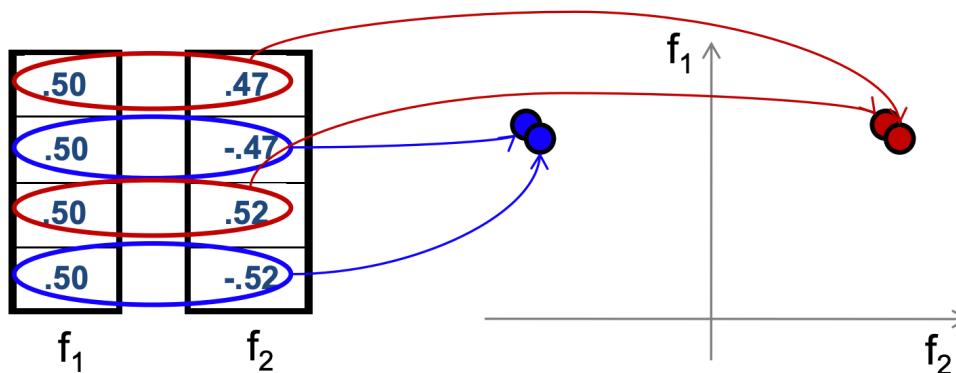
W



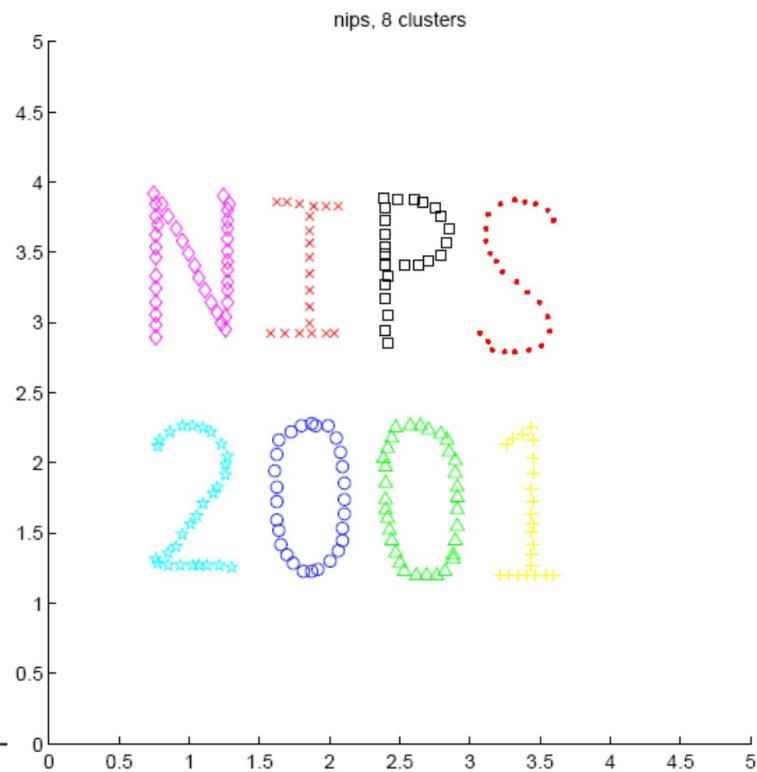
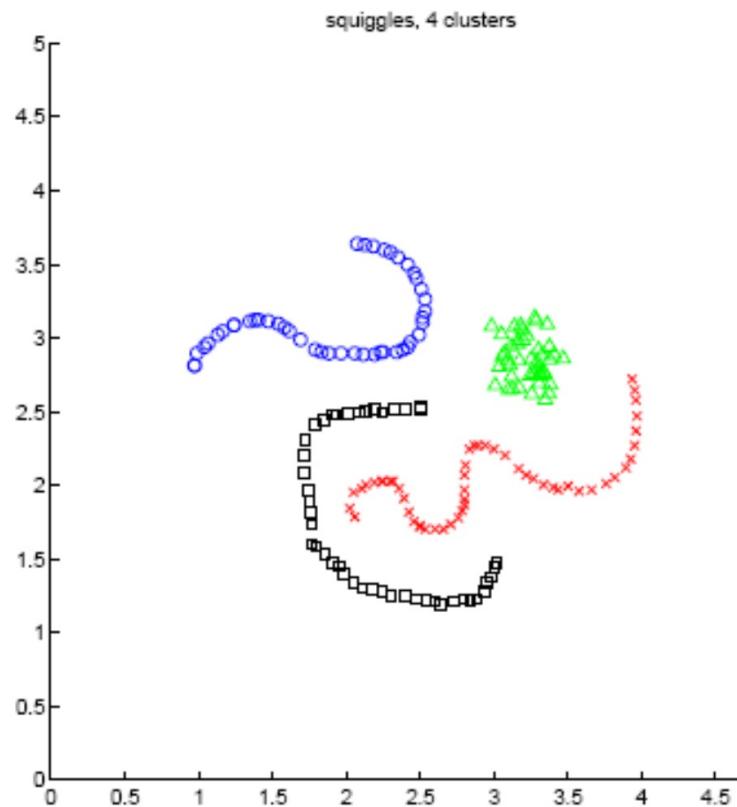
Embedding is same regardless of data ordering:

1	.2	1	0
.2	0	1	1
1	1	0	.1
0	1	.1	1

W

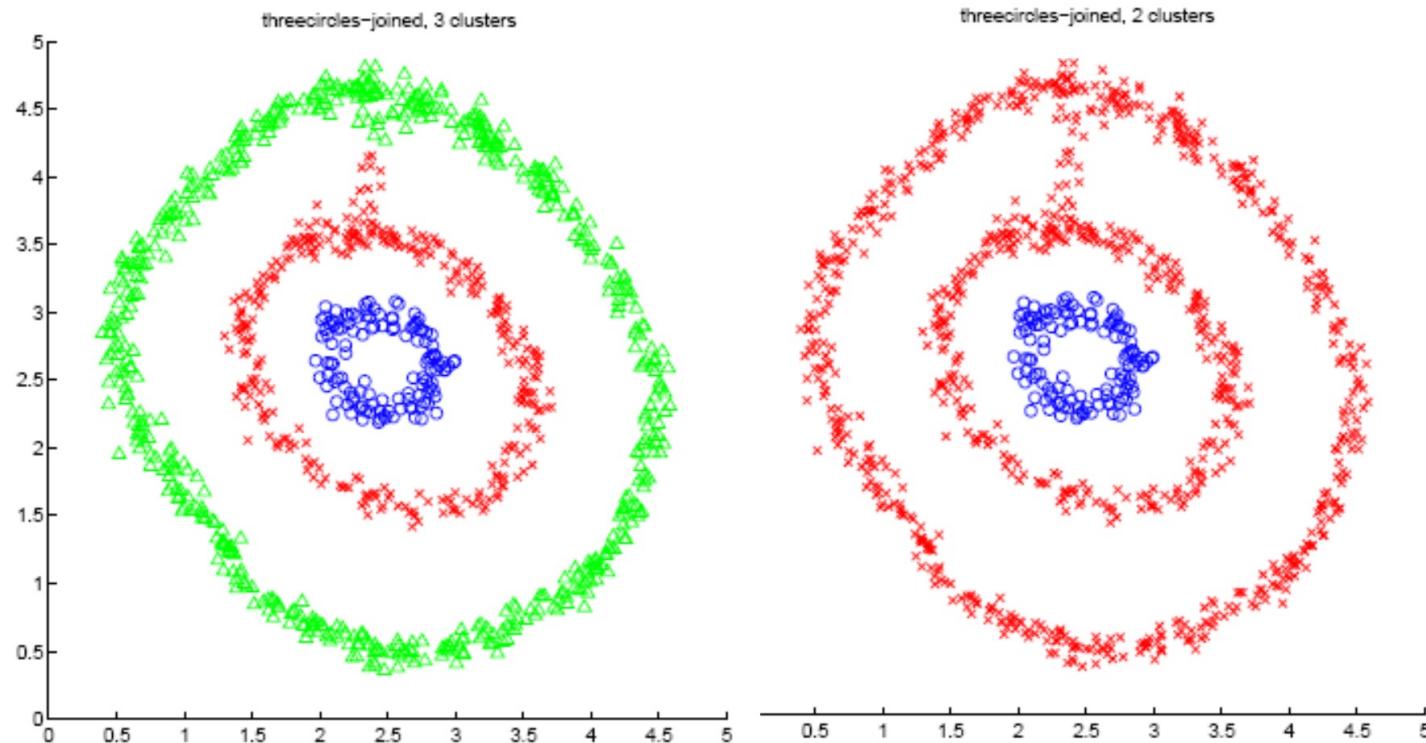


Spectral clustering



Spectral clustering

How to determine the number of clusters K?

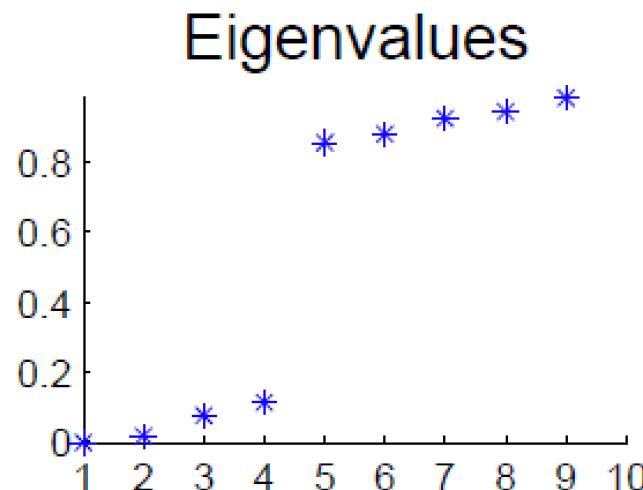


Spectral clustering

How to determine the number of clusters K?

Most stable clustering is usually given by the value of k that maximizes the eigengap (difference between consecutive eigenvalues)

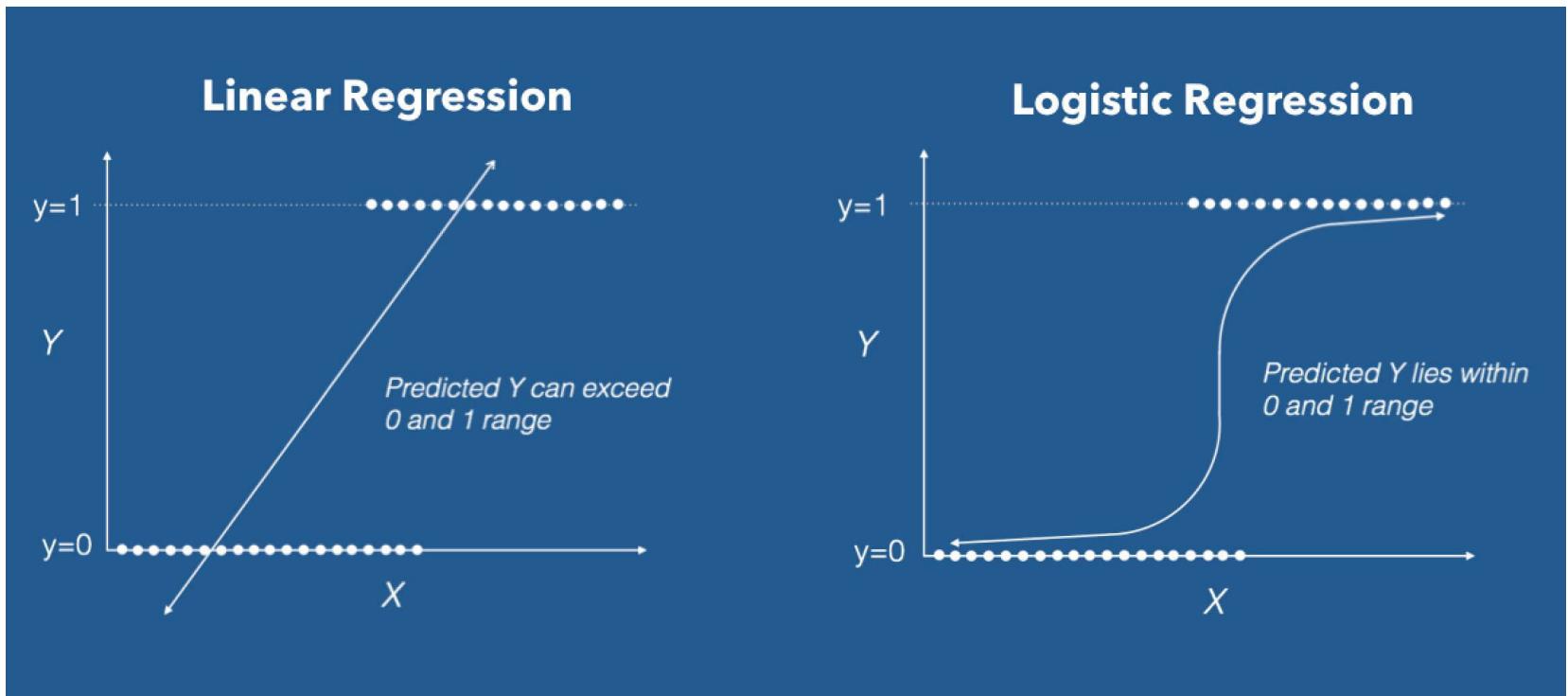
$$\Delta_k = |\lambda_k - \lambda_{k-1}|$$



Spectral clustering

- Algorithms that cluster points using eigenvectors of matrices derived from the data
- Useful in hard non-convex clustering problems
- Obtain data representation in the low-dimensional space that can be easily clustered
- Variety of methods that use eigenvectors of unnormalized or normalized Laplacian, differ in how to derive clusters from eigenvectors, k-way vs repeated 2-way
- Empirically very successful

Next lecture: Logistic regression



Thank you very much!

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