Final Review Part II

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August 4, 2019

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Overview

Reference: VV255 Lecture Slides by Professor Jing, Professor Olga, VV255 TA Group18SU, Demidovich, and Stewart's Textbook

- Tips for Final
- 2 Triple: Iterate
- Surface Integral

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Typical Questions. Part A

Description

- All the questions shall be answered properly in part A.
- No difficult questions presented here. Well understand those questions appeared in Slides!
- Calculate the double integral. Especially the technique of Change of variables. Identify the boundary, and carefully conduct the calculation.
- ② Using Iterated integral to represent the triple integral, in different manner (from dxdydz to dzdydx, for example). Tell the difference between the double/triple integral and the iterate integral!
- Tell the conservative field (★) and apply its property to calculate the corresponding line integral. Apply the FTL.
- Apply Divergence theorem or Stoke's theorem.

Typical Questions. Part B

Description

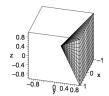
- Choose 4 from 6. Only counts the HIGHEST scores.
- Integrated problems mainly involves the part after surface integral.
- Properly parametrize the surface to calculate the surface integral.
- Oerive the vector field (e.g. heat flow) properly for calculating the surface integral. (Potentially physical concept and memorize the typical vector field appeared in the Text Book!)
- Apply Stoke's to represent the surface integral of a curl as the line integral to simplify the problem.
- Well understand the spherical coordinates and apply it to solve some integrated problems.

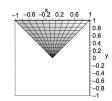
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- For each of the following regions E, express the triple integral $\iiint_E f(x, y, z) dV$ as an iterated integral in Cartesian coordinates.
- E is the box $[0,2] \times [-1,1] \times [3,5]$ Solution:

$$\iiint_E f(x,y,z)dV = \int_0^2 \int_{-1}^1 \int_3^5 f(x,y,z)dzdydx$$

2 E is the pyramid with vertices (0,0,0),(1,1,1),(1,1,-1),(-1,1,1), and (-1,1,-1) **Solution:**





Solution (Continued):

Top function: z=y (plane passing through (0, 0, 0), (1, 1, 1), and (1, 1, 1))

Bottom function: z=y (plane passing through (0, 0, 0), (1, 1, 1), and (1, 1, 1))

$$\iiint_{E} f(x, y, z) dV = \iint_{D} \int_{-y}^{y} f(x, y, z) dz dA$$
$$= \int_{0}^{1} \int_{-y}^{y} \int_{-y}^{y} f(x, y, z) dz dx dy$$

You can see more examples in the worksheet.



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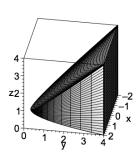
Consider the integral

$$\iiint_{E} f(x,y,z)dV = \int_{-2}^{2} \int_{x^{2}}^{4} \int_{0}^{y} f(x,y,z)dzdydx$$

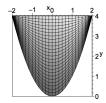
(a) Sketch the region E. (b) Write the other five iterated integrals which represent $\iiint_E f(x, y, z) dV$

Solution:

(a)



Solution(Continued):



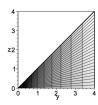


Figure: Left: The image of E on xy-plane; Right: The image of E on yz-plane

If we project E onto xy-plane, then the top function is z = y, and the bottom function is z = 0, as given in the question. In the order of dz dx dy,

$$\iiint_E f(x,y,z)dV = \int_0^4 \int_{-\sqrt{y}}^{\sqrt{y}} \int_0^y f(x,y,z)dzdxdy$$

Solution(Continued):

If we project E onto yz-plane, then the front function is $x = \sqrt{y}$, and the back function is x = -sqrty, as given in the question. In the order of dx dy dz,

$$\iiint_E f(x,y,z)dV = \int_0^4 \int_z^4 \int_{-\sqrt{y}}^{\sqrt{y}} f(x,y,z)dxdydz$$

In the order of dx dz dy,

$$\iiint_{E} f(x,y,z)dV = \int_{0}^{4} \int_{0}^{y} \int_{-\sqrt{y}}^{\sqrt{y}} f(x,y,z)dxdydz$$



Surface Integral: Concept Overview

Basic Classification

- Parametrization of the surface; parametrized surface; Spherical coordinates; Cylindrical coordinates; Rotation surface.
- Piecewise smooth surfaces.
- Oriented and orientable (smooth) surfaces; positive and negative orientation.
- Closed surface.

Surface Integral

- Surface Integral for a Parametric Surface. Surface integral of scalar function; surface integral of vector fields.
- 2 Derive some typical vector fields.
- Apply Stoke's and Divergence theorem. (covered later)

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Parametric Surface

Def. Parametric surface

The vector function together with the domain D,

$$\overline{r}(u,v) = x(u,v)\mathbf{e}_x + y(u,v)\mathbf{e}_y + z(u,v)\mathbf{e}_z$$

is called a parametric surface. And \overline{r} is a parametrisation of S. Actually we have obtained the Surfaces Described by Vector Functions.

Special Parametrization: explicit z

For the surface given by the equation as

$$S = g(x, y)$$

we can find the special parametrization as

$$\overline{r}(u,v) = u\overline{i} + v\overline{j} + g(u,v)\overline{k}$$

Special Parametrization: Spherical and Cylindrical

Spherical Coordinates: example

The sphere

$$x^2 + y^2 + z^2 = a^2$$

could parametrized as

$$\overline{r}(\theta,\phi) = a\sin\phi\cos\theta\overline{i} + a\sin\phi\sin\theta\overline{j} + a\cos\phi\overline{k}$$
$$0 \le \theta \le 2\pi, \quad 0 \le \phi \le \pi$$

Cylindrical Coordinates: example

The cylinder

$$x^2 + y^2 = a^2, 0 \le z \le b$$

could be parametrized as

$$\overline{r}(z,\theta) = a\cos\theta\overline{i} + a\sin\theta\overline{j} + z\overline{k}$$

 $0 \le z \le b, \quad 0 \le \theta \le 2\pi$

Parametric Surface

Def. Smooth Parametric surface

A parametric surface is smooth provided the following two conditions:

- **1** The partial derivatives, $\frac{\partial \bar{r}}{\partial u}$ and $\frac{\partial \bar{r}}{\partial v}$ are continuous
- ② The cross product between partial derivatives is non-zero in the interior of the domain of $\overline{r}(u,v)$

$$\frac{\partial \overline{r}}{\partial u} \times \frac{\partial \overline{r}}{\partial v} \neq \mathbf{0}$$

Actually, it means that the surface normal vector depends continuously on the points on the surface.

Def. Piecewise Smooth Surface

A piecewise smooth surface consists of finitely many smooth surface.

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Oriented and Orientable

Description. Two-Sided and One-sided

Two-sided: Across the boundary the surface normal vector \overline{n} is undefined.

One-sided: Everywhere \overline{n} could be well defined.

Def. Oriented Smooth Surface

A smooth surface S is said to be orientable if S is two-sided, and non-orientable if S is a one-sided surface.

An oriented surface is a surface S and a vector function \overline{n} that witnesses the fact that S is orientable.

Orientation

Def. Orientation

If \overline{n} witnesses the fact that S is orientable, then we say that \overline{n} is an orientation of S, where there are two orientations in total, positive orientation:

$$\overline{\mathbf{n}_1} = \frac{\overline{\mathbf{r}_u} \times \overline{\mathbf{r}_v}}{|\overline{\mathbf{r}_u} \times \overline{\mathbf{r}_v}|}$$

negative orientation: $\overline{\mathbf{n}_2} = -\overline{\mathbf{n}_1}$

Orientation for Surface explicitly defined by equation

For the surface defined by the equation, we have the orientation as

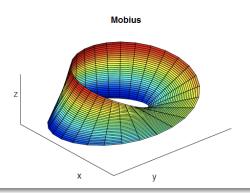
$$\Phi(x,y,z)=0$$

$$\mathbf{n}_1 = \frac{\nabla \Phi}{|\nabla \Phi|} \Longrightarrow \nabla \Phi = \mathbf{r}_u \times \mathbf{r}_v$$

Orientation: for fun

Illustrate some non-orientable surfaces.

Solution: Mobius strip or Klein bottle.



Surface Integral

Def. of a scalar-valued function

Suppose S is a smooth parametric surface defined by $\overline{r}(u,v)$ over D and f(x,y,z) is a continuous function, then the surface integral of f over S is defined to be

$$\iint_{S} f(x, y, z) dS = \iint_{\mathcal{R}} f(\overline{r}(u, v)) |\overline{r}_{u} \times \overline{r}_{v}| dA$$

Def. of a vector field

Suppose \overline{F} is a continuous vector field and S is an oriented smooth surface, then

$$\iint_{\mathcal{S}} \overline{F} \cdot \overline{n} \ dS = \iint_{\mathcal{S}} \overline{F} \cdot d\overline{S} = \iint_{D} \overline{F}(\overline{r}(u, v)) \cdot (\overline{r}_{u} \times \overline{r}_{v}) \ dA$$

is known also as the flux integral of \overline{F} across S.

Surface Integral: Type I

Special case: explicit z parametrization

If the surface is z = g(x, y)

$$|\overline{r}_x \times \overline{r}_y| = \sqrt{\left(\frac{\partial g}{\partial x}\right)^2 + \left(\frac{\partial g}{\partial y}\right)^2 + 1}$$

Application: Surface Area

Let S be a smooth surface that is parametrized by

$$\mathbf{r}(u, v)$$
, where $(u, v) \in \mathcal{D}$

where D is a region in the uv- plane, then the surface area of S is

$$A(S) = \iint_{\mathcal{R}} |\overline{r}_u \times \overline{r}_v| \, dA = \iint_{S} dS$$

Surface Integral: Type II

For Piecewise-smooth S

$$\iint_{S} \vec{F} \cdot d\vec{S} = \iint_{S_{1}} \vec{F} \cdot d\vec{S} + \dots + \iint_{S_{n}} \vec{F} \cdot d\vec{S}$$

Orientation

- Default: just given parametrization of the surface ⇒ Assume positive oriented. (where the normal is outward)
- ② Given Description: "inward" for negative and "outward" for positive.

Heat Flow

Provided u(x, y, z) be the temperature at a point (x, y, z), then the temperature gradient, a.k.a. heat flow \overline{F} can be represented as,

$$\overline{F} = -K\nabla u$$

Heat Flow

Provided u(x, y, z) be the temperature at a point (x, y, z), then the temperature gradient, a.k.a. heat flow \overline{F} can be represented as,

$$\overline{F} = -K\nabla u$$

where K is an experimentally determined constant called the conductivity of the substance.

And

$$\iint_{S} F \cdot d\overline{S}$$

is the total rate of heat flow or flux across the surface S.



Exercises

Surface Integral. Type I

Example: Evaluate the surface integral $\iint_S yzdS$, where S is the helicoid with vector equation $\vec{R}(u,v) = \langle u\cos v, u\sin v, v \rangle$, $0 \le u \le 1$, $0 \le v \le \pi$.

Surface Integral. Type II and the spherical coordinates

Find the outward flux of $\vec{F}(x, y, z) = \langle z, y, x \rangle$ across the sphere $x^2 + y^2 + z^2 = 1$.

Surface Integral. Heat Flow

Example: The temperature at the point (x,y,z) in a substance with conductivity K=6.5 is $T(x,y,z)=2(x^2+y^2)$. Find the rate of heat flow inward across the cylindrical surface $x^2+y^2=6$ for $0 \le z \le 4$.