## UNIVERSITY OF ILLINOIS AT URBANA-CHAMPAIGN

Department of Electrical and Computer Engineering

ECE 310 DIGITAL SIGNAL PROCESSING - FALL 2023

## Homework 3

## Profs. Do, Snyder, Moustakides

Due: Sep 15 on Gradescope

1. We are given the following impulse responses of LTI systems:

(a) 
$$h[n] = \delta[n] + 2\delta[n+2] - 3\delta[n-4]$$

(b) 
$$h[n] = \left(\frac{1}{3}\right)^n u[n+1] + \left(\frac{1}{2}\right)^n u[-(n+1)]$$

(c) 
$$h[n] = n\left(\frac{1}{3}\right)^n u[n-2] + \left(\frac{1}{2}\right)^n u[n+3]$$

(d)  $h[n] = \{A_1(z_1)^n + A_2(z_2)^n\}u[n]$ , where  $A_1, A_2, z_1, z_2$  are constant numbers not depending on n and  $A_1, A_2$  are not zero.

Using the definition and the properties of the  $\mathcal{Z}$ -transform, determine for each case the  $\mathcal{Z}$ -transform of the impulse response (transfer function) and the corresponding ROC.

2. We are given the  $\mathcal{Z}$ -transform pair

$$x[n] \stackrel{Z}{\leftrightarrow} X(z) = \frac{1}{1 - 0.5z^{-1}}, \text{ ROC} : |z| > 0.5, \text{ with } \alpha \neq 0.$$

Using the  $\mathcal{Z}$ -transform properties determine the  $\mathcal{Z}$ -transform and the corresponding ROC of the following sequences without computing x[n]:

- (a)  $y[n] = x[n n_0]$ , where  $n_0$  is a constant integer.
- (b) y[n] = n(n-1)x[n]
- (c)  $y[n] = \beta^n x[n]$ , where  $\beta \neq 0$  is a constant.
- (d) y[n] = x[n] \* x[-n]
- 3. Using the properties of the  $\mathcal{Z}$ -transform determine the signal x[n] that satisfies the following equations:
  - (a)  $x[-n] = \rho^n u[n]$
  - (b) nx[n] = 3x[n], with the  $\mathcal{Z}$ -transform of x[n] satisfying  $X(z)|_{z=1} = 1$
  - (c)  $x[n] = 1.3x[n-1] 0.4x[n-2] + \delta[n] + \delta[n-1]$ , where x[n] is rightsided
  - (d)  $(\frac{1}{2})^n x[n] = (1 (\frac{1}{3})^n) u[n]$