

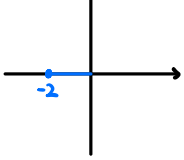
[1] (a) $2 \cdot e^{\frac{\pi}{3}j} + e^{-\frac{\pi}{3}j}$
 $= 1 + \sqrt{3}j - j$
 $= 1 + (\sqrt{3}-1)j$
 $r = \sqrt{1 + (\sqrt{3}-1)^2} = \sqrt{5-2\sqrt{3}} \approx 1.24$
 polar form: $\sqrt{5-2\sqrt{3}} e^{j\theta}$, $\arctan \theta = \frac{1}{\sqrt{3}-1} = \frac{\sqrt{3}+1}{2}$, $\theta = 36.21^\circ$

(b) $\frac{1+j}{1-2j} = \frac{(1+j)(1+2j)}{(1-2j)(1+2j)} = \frac{-1+3j}{5}$
 $r = \sqrt{(\frac{1}{5})^2 + (\frac{3}{5})^2} = \frac{\sqrt{10}}{5}$, $\theta = \arctan(\frac{3}{-1})$
 polar form: $\frac{\sqrt{10}}{5} e^{j\theta}$, $\theta = -71.56^\circ$

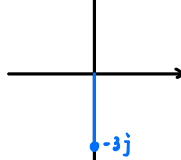
[2] $16z^3 + 2 = 0$, $z^3 = -\frac{1}{8}$

$z_1 = -0.5$ $z_2 = 0.25 + 0.433j$ $z_3 = 0.25 - 0.433j$
 $= \frac{1}{4} + \frac{\sqrt{3}}{4}j$ $= \frac{1}{4} - \frac{\sqrt{3}}{4}j$

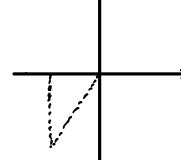
[3] (a) magnitude: 2 phase: π



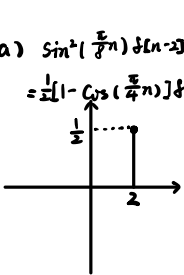
(b) magnitude: 3 phase: $\frac{3}{2}\pi$



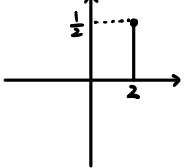
(c) magnitude: $\sqrt{(-3)^2 + (-4)^2} = 5$ phase: 4.067



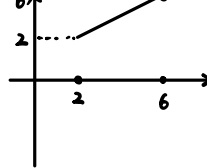
(d) $1 - e^{-\frac{\pi}{4}j} = 1 - \frac{\sqrt{2}}{2} - \frac{j\sqrt{2}}{2}$
 magnitude: 0.765
 phase: -1.107



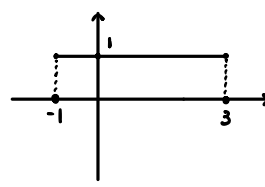
[4] (a) $\sin^2(\frac{\pi}{4}n) \delta[n-2]$
 $= \frac{1}{2} [1 - \cos(\frac{\pi}{2}n)] \delta[n-2]$



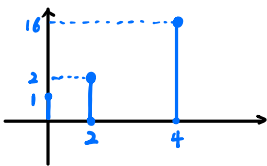
(b) $n(u[n-2] - u[n-6])$
 $n < 2: 0$ $2 \leq n < 6: n$ $n \geq 6: 0$



(c) $u[-n+3] = \begin{cases} 0 & n > 3 \\ 1 & n \leq 3 \end{cases}$ $u[n+1] = \begin{cases} 0 & n < -1 \\ 1 & n \geq -1 \end{cases}$



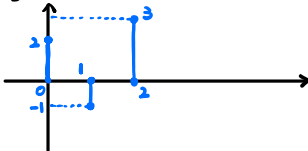
(d) $2^n \sum_{k=0}^2 \delta[n-2k] = 2^n (\delta[n] + \delta[n-2] + \delta[n-4])$



[5] (a) $x[n] = \{-\infty, 0, 2, 0, -1, 1, 3, 0, \dots\}$

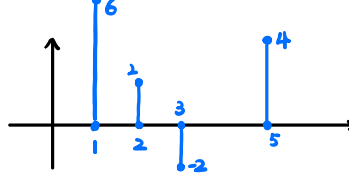
$= 2\delta[n+1] - \delta[n-1] + \delta[n-2] + 3\delta[n-3]$

(b) $y[n] = x[2n-1] = 2\delta[2n-1] - \delta[2n-3] + \delta[2n-5] + 3\delta[2n-7]$



(c) $v[n] = 2x[4-n]$

$= 4\delta[5-n] - 2\delta[3-n] + 2\delta[1-n] + 6\delta[-1-n]$



[6] (a) $y[n] = 3x[n] - x[n-1]$

Linear: let $z[n] = ax_1[n] + bx_2[n]$

$T(ax_1[n] + bx_2[n]) = 3z[n] - z[n-1]$
 $= aT(x_1[n]) + bT(x_2[n])$

the system is linear

time-invariant: $y[n-n_0] = 3x[n-n_0] - x[n-n_0-1]$

the system is time-invariant

causal: output not depend on future value

\Rightarrow the system is linear, time-invariant and causal

(b) $y[n] = x[n+2] + 2$

linear: $z[n] = ax_1[n] + bx_2[n]$

$T(z[n]) = z[n+2] + 2$
 $= ax_1[n+2] + bx_2[n+2] + 2$
 $\neq ax_1[n] + 2a + bx_2[n] + 2b$

not linear

time-invariant: $y[n-n_0] = x[n-n_0+2] + 2 \checkmark$

causal: depend on future value $x[n+2] \times$

the system is not linear, time-invariant, not causal. the system is linear, not time-invariant, causal.

(c) $y[n] = (n+1)x[n-1]$

linear: $z[n] = ax_1[n] + bx_2[n]$

$T(z[n]) = (n+1)z[n-1]$
 $= (n+1)[ax_1[n-1] + bx_2[n-1]]$
 $= a(n+1)x_1[n-1] + b(n+1)x_2[n-1]$
 $= aT(x_1[n]) + bT(x_2[n]) \checkmark$

time-invariant: $y[n-n_0] = (n-n_0+1)x[n-n_0-1] \times$

causal: not depend on future value \checkmark

$$(d) y[n] = |x[n^*]|$$

$$\text{linear: } z[n] = a x_1[n] + b x_2[n]$$

$$|z[n^*]| = |a x_1[n^*] + b x_2[n^*]| \\ \neq |a x_1[n^*]| + |b x_2[n^*]| \quad \times$$

$$\text{time-invariant: } y[n-n_0] = |x[n-n_0^*]| \quad \times$$

$$\text{causal: let } n=2, \quad y[2] = |x[16]|$$

depending on future value x

the system is not linear, not time-invariant, not causal.