
CS3DS19 - Data Science Algorithms and Tools

Major Coursework

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Task 0: Exploratory Data Analysis

In this section, we will try to get familiarize ourselves with the given dataset, with the ultimate goal of designing an appropriate pre-processing process, necessary for our future workflows. It is noteworthy that a normalisation process is absent from our EDA, this is because, normalisation/standardization will be explained and applied on Task2

Missing values detection

The first part of EDA is the Missing values detection. We used the output of the statistics node, (output contains 'No of Missing' per variable) and we sum for all the variables, by using 'Group By' Node. The results along with the node configurations are given below. Based on the findings we can safely ignore a missing values pre-preprocessing step

Workflow and node configurations for missing values detection

Duplicate detection

The second part of EDA is the duplicate values detection and removal. Our logic is rather simple, we applied a 'Duplicate Row Filter' into the dataset, and we counted the number of rows of this result, if the number of rows remains unchanged, then we do not have duplicates. The results suggest that, indeed, there is no duplicate entries, so its safe to ignore a duplicate filter as a pre-processing step

Workflow and node configurations for duplicate detection

Outliers detection

Our third part of our EDA, contains the detection of outliers. We need to carefully thing about outliers, because one of the limitations of our chosen clustering algorithm of choice. One of K-Means limitations are the sensitivity to outliers [?].

How to detect outliers

Assuming an underlying approximate normal distribution on every of our variables, we will use the famous 68-95-99 empirical rule[1] to detect outliers. Part of 68-95-99 rule states that, 99.7% of the data, lies within the range $\mu \pm 3 \cdot \sigma$, where μ is the variable mean and σ is the standard deviation. It is rather simple to detect for outliers with the following method. We will use the output of the 'Statistics' node(columns 'max', 'min', 'mean', 'stddev'), and by using a simple mathematical formula, we can determine if, for a given variable, $\max > \mu + 3 \cdot \sigma$ or $\min < \mu - 3 \cdot \sigma$

Results

The next figure displays the variables that may contain outliers. We can see that 8 out of 14 variables contain outliers. We can visualize those suspected variables with box plots, to visually verify our findings

Workflow and node configurations for outliers detection

'Class' to string

The last step of our EDA, is to transform 'class' column, from an integer column, into a string column. This is essential to be handled as a categorical variable by the color manager, PCA, normalization and etc. This can be easily achieved with the following small workflow and the node configuration is given below

Our Pre-processing strategy

Given our EDA, we now have a clear strategy for the initial data cleansing, and processing. The following workflow will be transformed into a metanode, and will be included into every workflow from now on. A noteworthy mention, is the fact that the 'numeric outliers' strategy is to remove the outlier rows.

Task 1

Task 1.1 : Generate plot1

The workflow to generate plot1 is given below And the configurations of the nodes with descriptions are given below Finally, the plot1 is given below

Task 1.2 : Generate plot2

The workflow to generate plot2 is given below Apart from the clustering algorithm adopted(K-Means), there is no significant changes with the workflow from the previous task, please see task1.1 for an overall review of the workflow. The Newly introduced nodes configurations, as well as the descriptions are given below

Finally, the plot2 is given below

Introduction to K-Means clustering algorithm

K-Means is a heuristic method for grouping similar items in a form of clusters. K is number of clusters and is pre-determined. By heuristic we mean that the algorithm does not produce absolute optimal solutions, but approximations with an given accuracy. By similarity ,on purely numeric data, we usually mean a geometric distance metric. 3 of the most widely accepted geometric metrics for determining similarity are Euclidean, Manhattan and Minkowski distances.

K-Means Algorithm

K-Means is an heuristic algorithm that repeats 2 distinct steps to converge into an acceptable solution. We will explain K-Means with a hands-on example. Let the following fictional 1D Data, $k = 3$ Let initialize $k = 3$ initial random estimated cluster centroids Now, the repetitive process, First, we should calculate the distances of any given point from each of the $k = 3$ estimated cluster centroids, and then assign the given datapoint into the cluster with the closest centroid. Here X_1 will be assigned on the blue cluster(M_1) After the calculation is finished for all the datapoints, the clustering should look like the following figure We now calculate the centroids of the clusters. the centroids do not need to be actual datapoints, they can lie on any point on the plane We repeat steps 2,3,until we end up with an acceptable solution We can quantify the quality of a solution(i.e quantify if the given solution is acceptable), by using Sum of Squared errors statistic(SSE). K-Means terminates when SSE converges into a value. SEE is explained in detail on Task 1.5

Task 1.3 : Compare plot1 and plot2

The main point of interest in the figures above, is the fact that, the clustering algorithm(K-Means, $k=3$) failed to appropriately partition the data, and recognise the classes provided by the dataset, This phenomenon can be explained due to the absence of the standardization process, something that will be explained in the next Task. The exact scale of the problem cannot be appropriately assessed with only those two plots though, we will need to examine the distribution of the classes in each cluster, something that will be done on the next task(Task 1.4)

Task 1.4 : plot3a,plot3b,plot3c

The workflow to generate the requested plots is given below The majority of the workflow is identical to workflows of task1.1 and task1.2, so please refer to those tasks for a detailed explanations of those nodes. The major difference is on the display section. There, we use 3 row filters(one per cluster) to filter the datapoints that were assigned on each cluster. Hence in the first plot, we have all the datapoints assigned to cluster0 and vice versa. The node configurations with the necessary filters are given below Finally, the generated plots are given in the next figure. It becomes apparent that the clusters generated are composing an meaningless clustering solution. Under ideal circumstances, each cluster will had a vast majority of each of the classes, with some to none variation due to outliers or errors, Using histograms we can visualize the extend of the issue This is the result of the lack of a normalization process, something that we will explain on the next task.

Task 1.5 : Cluster Validity Measure

For our cluster validity measure, we will explain and intepret WSS (Within cluster sum of squares) and BSS (Between cluster sum of squares). The workflow for generating the cluster validity measures is given below The majority of the workflow is identical to workflows of task1.1 to task1.4, so please refer to those tasks for a detailed explanations of those nodes. The Major Difference is on the repeat process and on the intepretation proccess. The newly introduced nodes configurations are given below, along with a short explanation

Prerequisites for explaining WSS ans BSS

Before our attempt of explaining WSS and BSS, it is essential to explain SSE (Sum of Square estimate of Errors). SSE is an evaluation metric with a plethora of applications in statistics and predictive analytics[?]. It is used to evaluate a model's performance against a training set[?]. The logic behind SSE is rather simple in nature. Let X an random variable and a model $y = \bar{X}$ We can evaluate our model's performance, by calculating the Sum of Errors, where 'error' in this case, is the distance of the observed variable from the responce of our model (i.e the mean \bar{X}), as follows Unfortunately, our evaluation metric has a fatal flaw, it allows for error's to 'cancel out' simply because they are placed beneath our model's line. It can be proven that, for the case of $y = \bar{X}$ SE is always 0. For other models(in higher dimensions, where corellation of the involved variables is not 1), it may not be zero, but the fatal flaw remains, by cancelling errors we severely underestimate the errors involved. A more appropriate approach could be to square the distances, that would give us the Sum of Squared Errors (SSE)

WSS and BSS Inner-Workings

In the world of Clustering models performance evaluation, SSE is translated into two distinct but related ideas[?], WSS and BSS

WSS

WSS or Within Cluster Sum of Squares is a clustering model performance evaluation function. Our 'model' in this case is the cluster centroid and the error is the distance for each datapoint from the cluster centroid. WSS can be evaluated with the following formula[?] Where k , the number of clusters involved, C_i the individual cluster and m_i , the given cluster centroid.

BSS

BSS or Between Cluster Sum of Squares is a clustering model performance evaluation function, just like WSS. Our 'model' in this case is the overall data mean and the error is the distance of each cluster's centroid to the overall mean. BSS can be evaluated with the following formula[?] Where k , the number of clusters involved, C_i the individual cluster and m_i , the given cluster centroid.

Interpretation

A good clustering solution, would involve well separated clusters, with low WSS to BSS ratio[?]. As K-Means is a heuristic based algorithm, we will not analyse WSS and BSS of a single K-Means run, but rather we will analyse their behaviour after a sequence of 100 runs. It is rather obvious, that the WSS/BSS Ratio is quite small, something that indicates well separated clusters(i.e a good clustering solution). However, a single cluster validity measure on its own, is insufficient to provide enough evidence for a meaningful clustering. Taking into consideration our observations from Task 1.3 and Task 1.4, this clustering [?]is not meaningful, as it produces wrong clusters. This is something that can be explained due to absence of Normalisation/Standardization process, something that we will analyse on Task 2

Task 2

The importance of Normalization

Let the following figure with some of the statistics for Proline and Ash variables K-Means is a geometric algorithm, that uses a distance(proximity) metric to evaluate the similarity between datapoints. Having one or more variables with significantly greater range of values, will cause this variable to have greater influence on the clustering, producing biased results.

How Normalization solves the problem?

Normalization solves the aforementioned issue by transforming all the variables in question, within the range [0-1], without affecting the scales of the distances. Normalization is described with the following formula

Changes in the workflows

The only change to apply normalization, is on our pre-processing node. Everything else will be the same. Keep note that the 'normalization' node follows the 'min-max' normalization, with min=0 and max=1. The 'class' variable is automatically excluded.

New Plots

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Compare and Contrast

The standard Lorem Ipsum passage, used since the 1500s

”Lorem ipsum dolor sit amet, consectetur adipiscing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur. Excepteur sint occaecat cupidatat non proident, sunt in culpa qui officia deserunt mollit anim id est laborum.” Section 1.10.32 of ”de Finibus Bonorum et Malorum”, written by Cicero in 45 BC

References

- [1] *Grafarend, E. (2006). Linear and nonlinear models (p. 553). Berlin, New York, N.Y.: Walter de Gruyter*
- [2] *Shannon, C., 1948. A Mathematical Theory of Communication. Bell System Technical Journal, 27(3), pp.379-423.*
- [3] *Shanker M, Hu MY, Hung MS, Effect of Data Standardization on Neural Network Training*
<https://www.sciencedirect.com/science/article/pii/S0305048396000102>