

Lecture 24

Boundaries of 3D regions

- If $E \subseteq \mathbb{R}^3$ is a region in three dimensional space, its boundary, ∂E , is a closed surface.
- Recall a surface S is closed if $\partial S = \emptyset$.
so $\partial \partial E = \emptyset$.
- We give the surface ∂E an ~~an~~ orientation called the boundary orientation by choosing the normal vector pointing away from E .
- Points on the boundary are "limiting points".
i.e. if we are inside the region E and we start moving, and we reach a point where we would exit the region if we kept going, that means we are on the boundary.

Ex The ball $\{x^2 + y^2 + z^2 \leq 1\}$ has boundary the sphere $\{x^2 + y^2 + z^2 = 1\}$ with normal pointing away from the origin.

Thm (Divergence Theorem)

Let E be a three dimensional region in \mathbb{R}^3 ~~and~~ with smooth boundary ∂E . Then

$$\iint_{\partial E} \underline{F} \cdot d\underline{S} = \iiint_E \operatorname{div}(\underline{F}) dV$$

Rmk - This thm is useful in both directions

- If $\operatorname{div}(\underline{F}) = 0$, then

$$\iint_{\partial E} \underline{F} \cdot d\underline{S} = \iiint_E 0 dV = 0.$$

- Be careful though! Let $\underline{F} = \frac{1}{r^3} \langle x, y, z \rangle$

where $r = x^2 + y^2 + z^2$. Then $\operatorname{div}(\underline{F}) = 0$ but

if $S =$ sphere of radius 1 then

$$\iint_S \underline{F} \cdot d\underline{S} = \iint_S \frac{1}{r^3} \langle x, y, z \rangle \cdot d\underline{S}$$

$$= \int_0^\pi \int_0^{2\pi} \langle \cos\theta \sin\phi, \sin\theta \sin\phi, \cos\phi \rangle \cdot \langle \cos\theta \sin\phi, \sin\theta \sin\phi, \cos\phi \rangle \sin\phi d\theta d\phi$$

$$= \int_0^\pi \int_0^{2\pi} \sin\phi d\theta d\phi$$

$$= 2\pi \left[-\cos\phi \right]_0^\pi = 4\pi \neq 0$$

So what went wrong? Well \underline{F} is not defined at all points of E (i.e. at $(0,0,0)$.)

Summary

- We have learnt about various types of integrals

$$\int_a^b f(x) dx, \int_C \underline{F} d\underline{r}, \iint_S \underline{F} \cdot d\underline{r}, \iiint_E \varphi dV$$

- Four main theorems of the course

* FTC (for conservative vector fields)

* Green's Theorem

* Stokes' Theorem

* Divergence Theorem

- These theorems summarise the interaction of integrals over regions + their boundaries using the various "derivatives" we have learnt:

1D

functions

$\frac{d}{dx}$

functions

FTC

If $\underline{F} = \frac{df}{dx}$ then

$$\int_a^b f dx = F(b) - F(a)$$

2D

functions

∇

vector fields

curl

functions

FTC

If $\underline{F} = \nabla f$ then

$$\int_C \underline{F} \cdot d\underline{r} = f(Q) - f(P)$$

Green's

If $f = \text{curl}(\underline{F})$ then

$$\iint_D f dA = \int_{\partial D} \underline{F} \cdot d\underline{r}$$

3D

functions

∇

vector fields

curl

vector fields

div

functions

FTC

If $\underline{E} = \nabla \psi$ then

$$\int_C \underline{E} \cdot d\underline{r} = \psi(Q) - \psi(P)$$

Stokes'

If $\underline{E} = \text{curl}(\underline{A})$

$$\iint_S \underline{E} \cdot d\underline{S} = \int_{\partial S} \underline{A} \cdot d\underline{r}$$

Divergence.

If $f = \text{div}(\underline{A})$

$$\iiint_E f dV = \iint_{\partial E} \underline{A} \cdot d\underline{S}$$

4D

functions

?

?(vector fields)

?

?

?

?(vector fields)

?

functions