Lecture 16 1. Parametrized surfaces - A parametrised surface, is the image of DER2 under a per map C: D ---> 183 where G(u,v) = (Gx(u,v), y(u,v), Z(u,v))Ex A cylinder of radius 1, x2+y2=1 is parametrized by G(0,2) = (cos0, sin0,2) when D=[0,211]x1R Ex A sphere of radius R G(O, +) = (RcosOsin +, Rsin Osin +, Rcos+) $D = [0, 2\pi] \times [0\pi]$ Exercise parametrise du ellipsoid x2 + 22 + 52 = 1 A torus (inner adius 1, outer radius 3)

To parametrise let ep 0 be angle from x axis and y and angle on ralated circle G(0, q) = ((2+cosq)cos0, (2+cosq)sino, sinq). - We will assume G has cent. partial decenderivatives. - Weraidh as - If G(u,u) = (x(u,u), y(u,u), =(u,u)) - we we would & like to understand the tangent vectors at a point G(u,u) EIR's