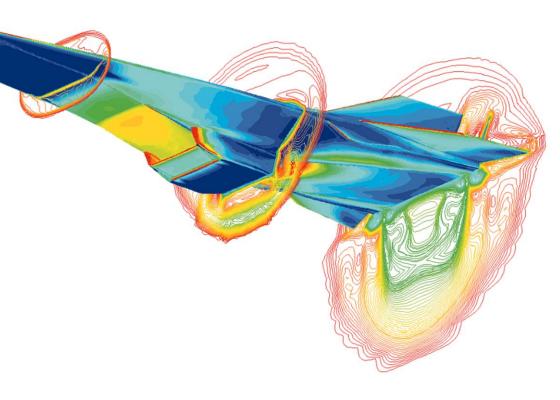
Conservation Laws of Fluid Dynamics

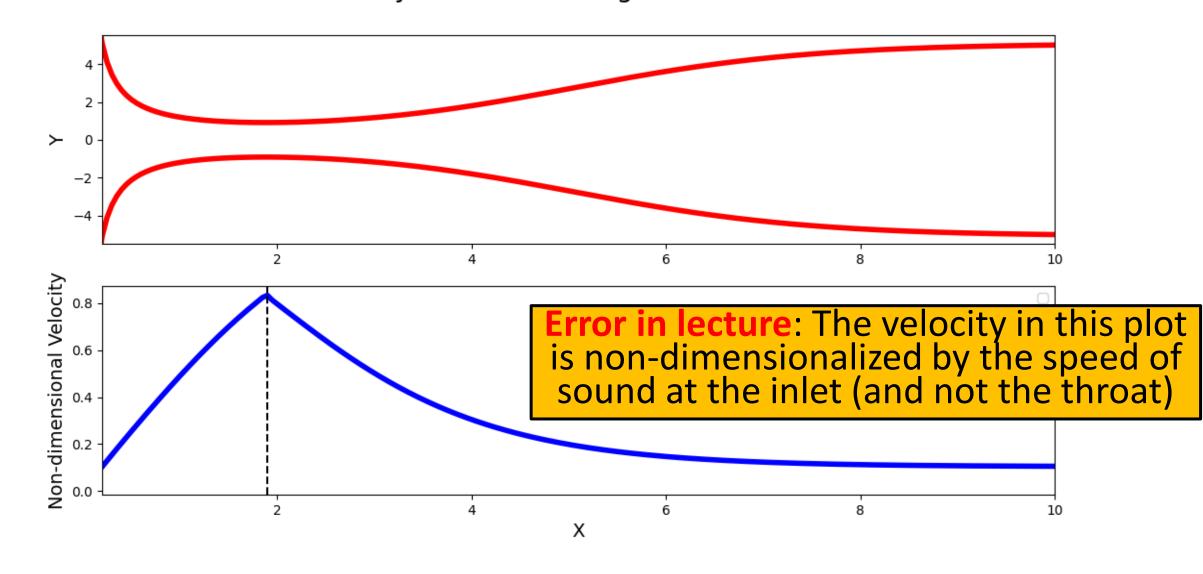
SEBASTIAN THOMAS

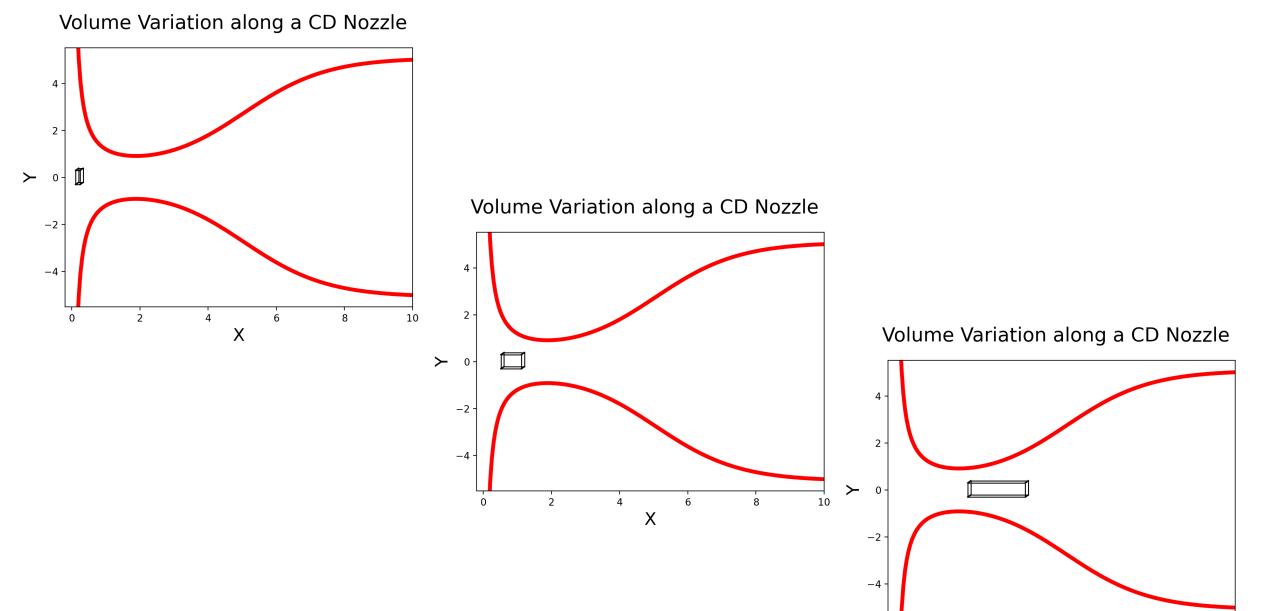


Two Vital Concepts

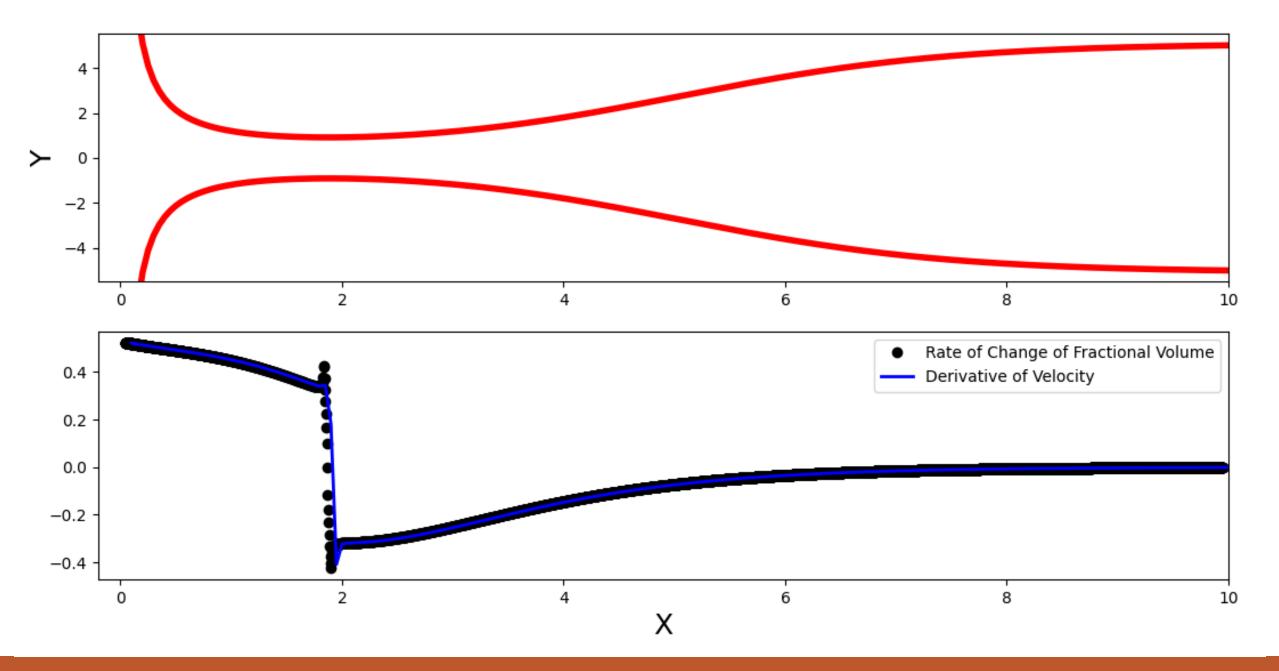
- Divergence
- Substantial Derivative

Velocity Variation through a CD Nozzle

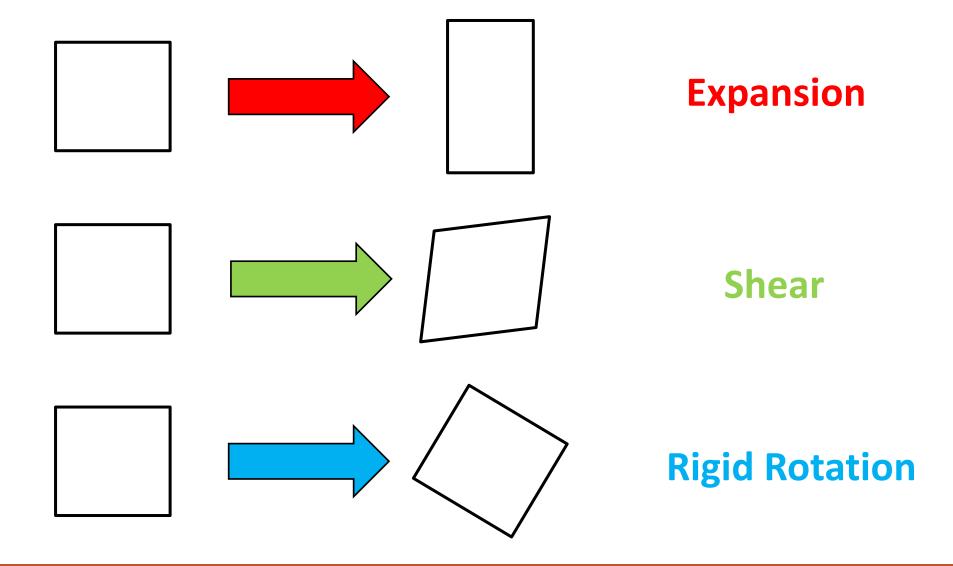


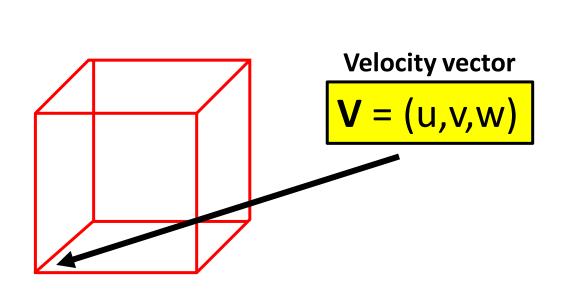


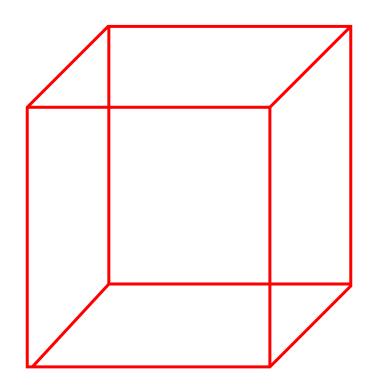
Χ



What about higher dimensions?







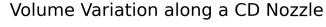
$$Vol_t = dx*dy*dz$$

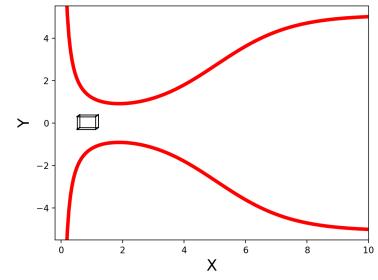
$$Vol_{t+dt} = (dx+u_x dxdt)*(dy+v_y dydt)*(dz+w_z dzdt)$$

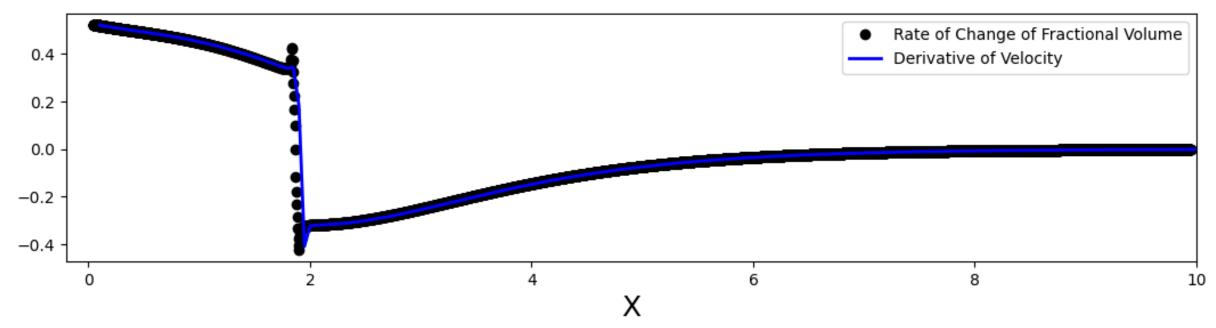
$$\frac{\text{Vol}_{t+dt}\text{-Volt}}{\text{Vol}_t*\text{dt}} = u_x + v_y + w_z$$

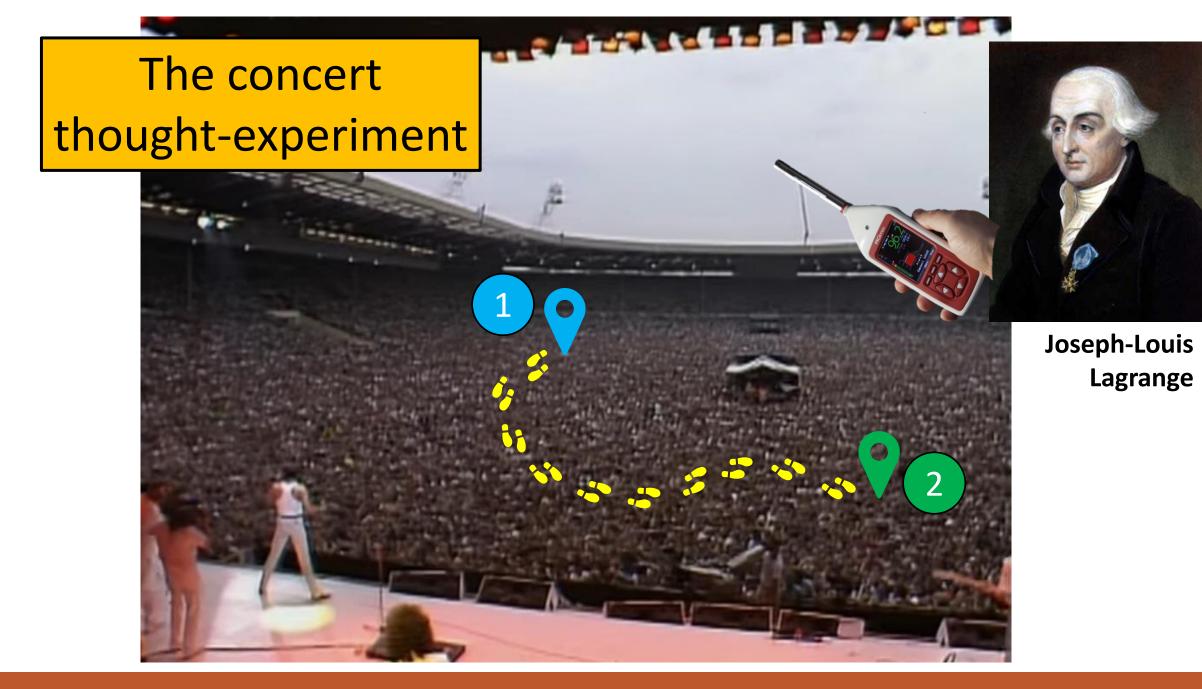


∇.V is simply the fractional rate of change of volume









Taylor Series

$$f = f(x)$$

$$f(b) = f(a) + (b-a)f'(a) + \frac{(b-a)^2}{2!}f''(a) + \frac{(b-a)^3}{3!}f'''(a) + \cdots$$

Multi-variate Taylor Series Expansion

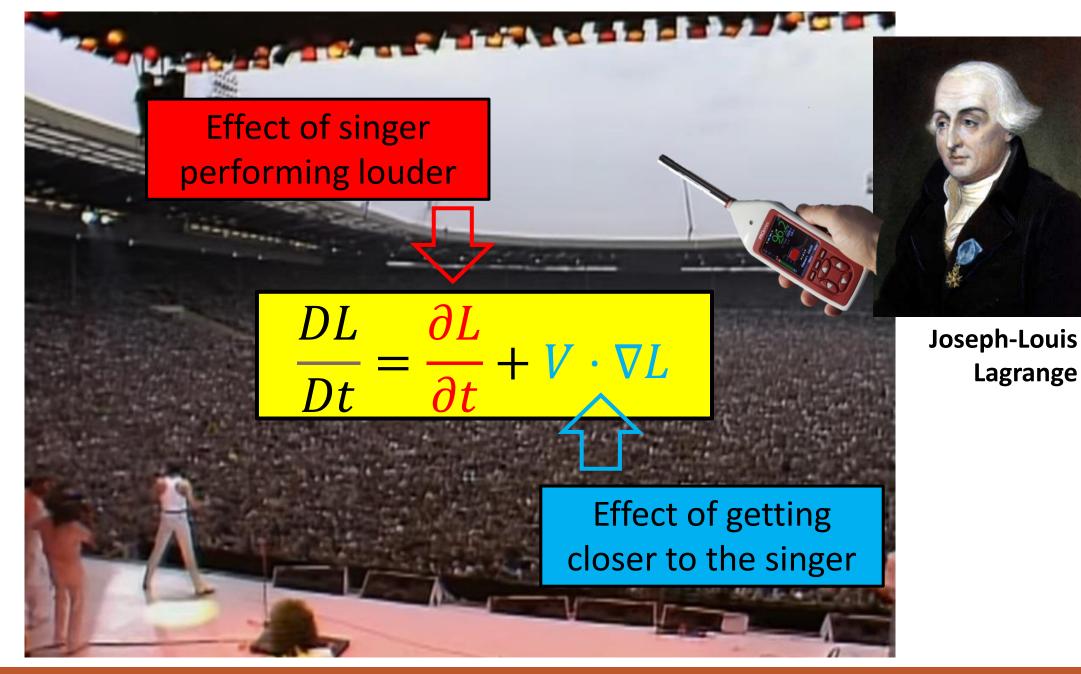
$$L = L(x, y, t)$$

$$L_2 = L_1 + \frac{\partial L}{\partial t}(t_2 - t_1) + \frac{\partial L}{\partial x}(x_2 - x_1) + \frac{\partial L}{\partial y}(y_2 - y_1) + \cdots$$

The Substantial Derivative

$$\frac{DL}{Dt} = \frac{\partial L}{\partial t} + V \cdot \nabla L$$

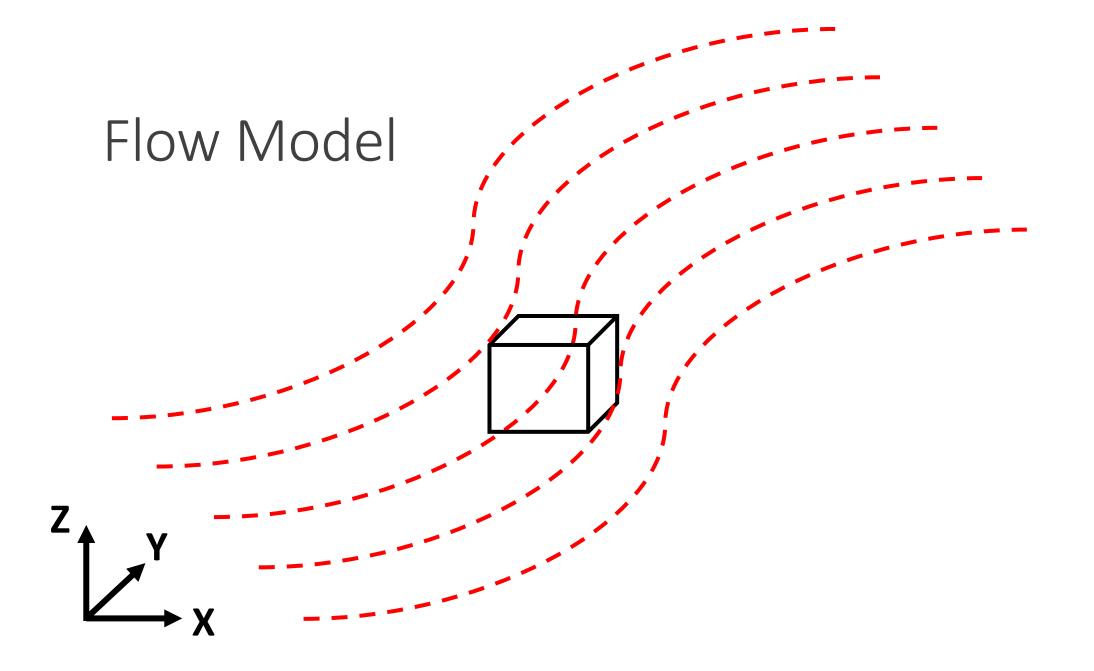
The concept of the 'substantial' (or 'material') derivative arises in fluid dynamics when a quantity is being measured inside a control volume that moves with the fluid



Lagrange

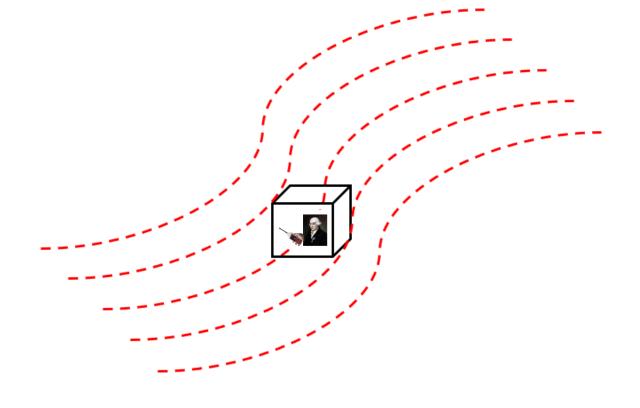
Conservation Laws

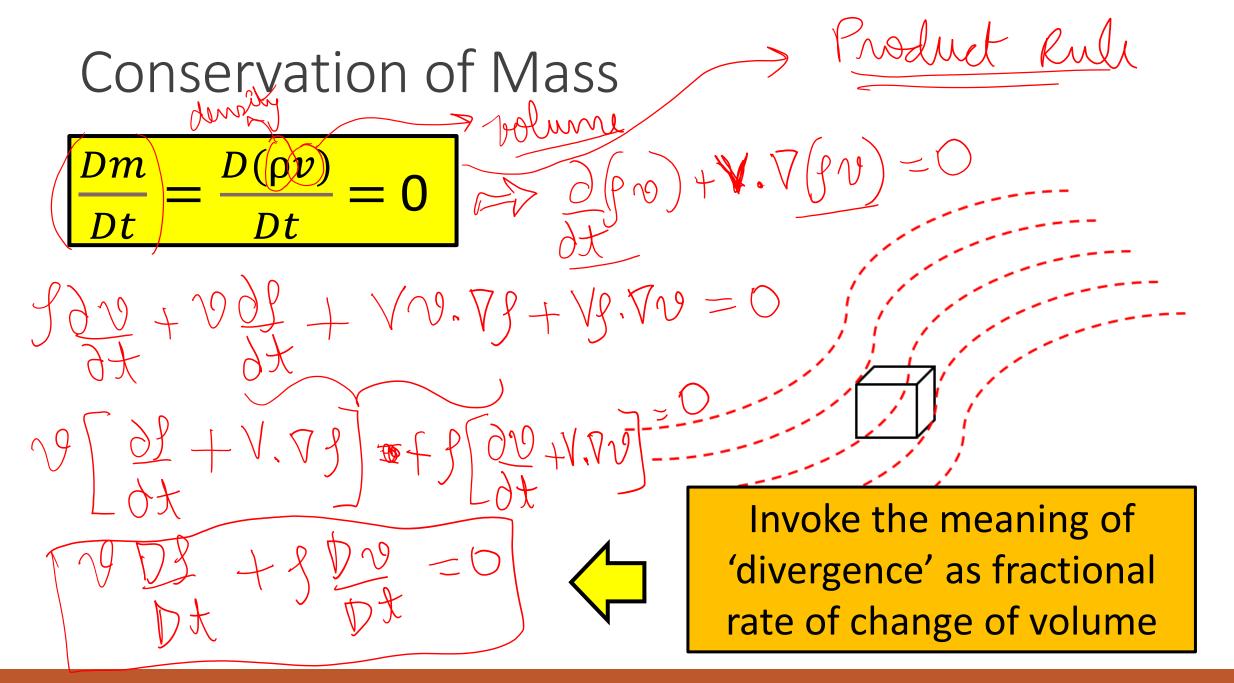
- For any fluid element, three laws are inviolable:
 - Mass is conserved
 - The rate of change of momentum is equal to the force applied
 - Energy is conserved



Conservation of Mass

- The mass of the fluid element – as it moves through the fluid remains constant
- In other words, the substantial derivative of mass is zero



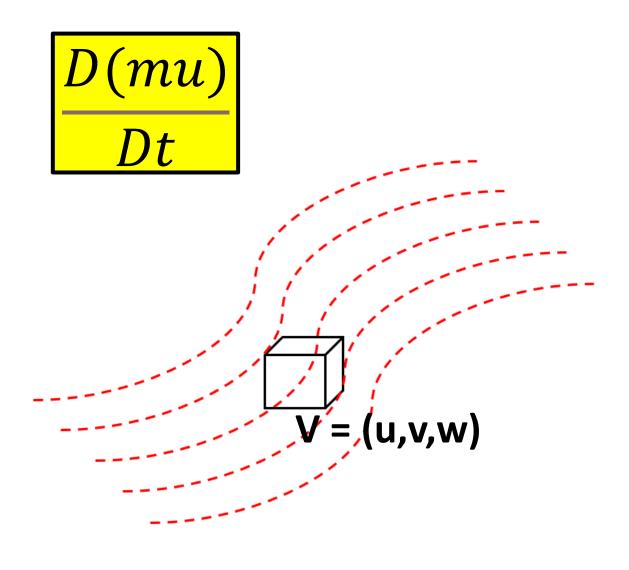


Conservation of Mass

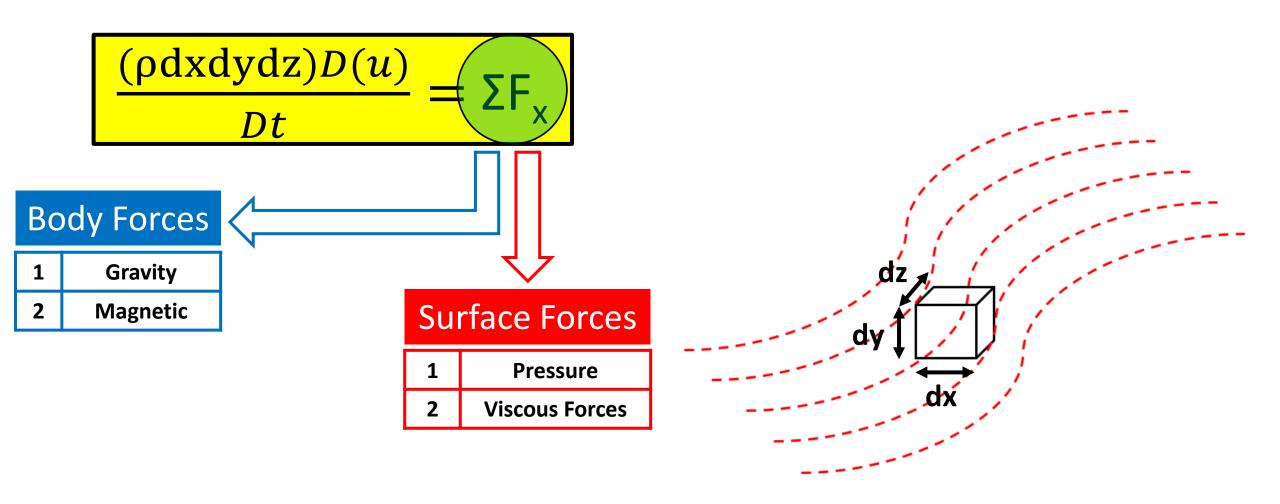
$$\frac{D\rho}{Dt} + \rho \nabla \cdot \mathbf{V} = 0$$

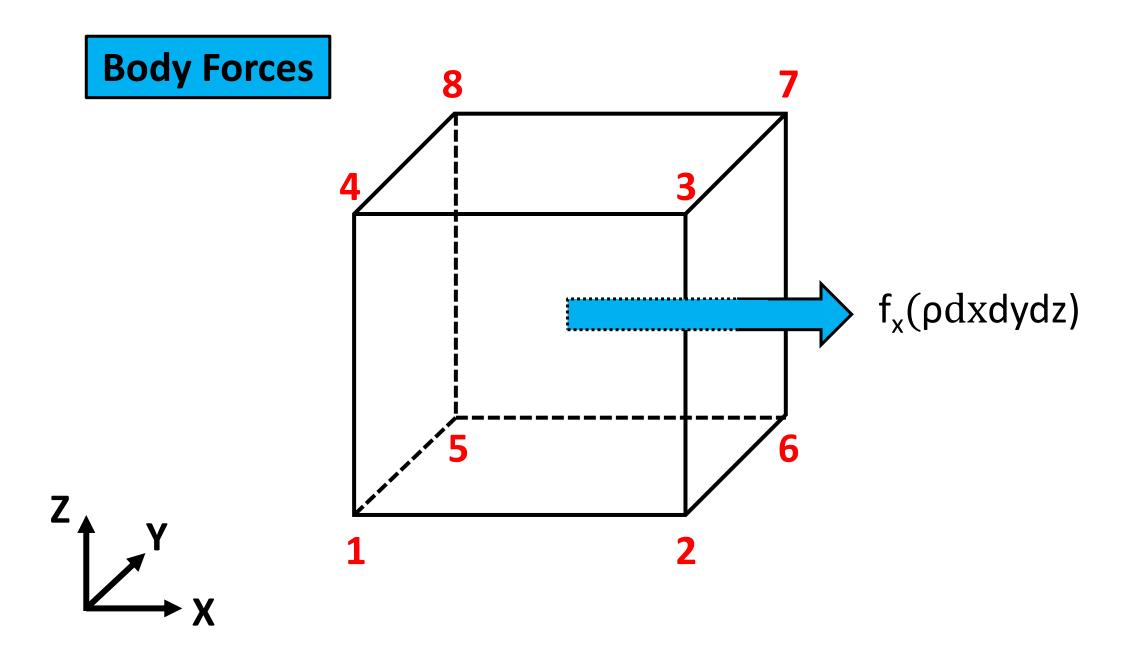
 The rate at which the momentum of the fluid element changes in the X direction — as it moves through the fluid – is equal to the total force acting on it in the X direction

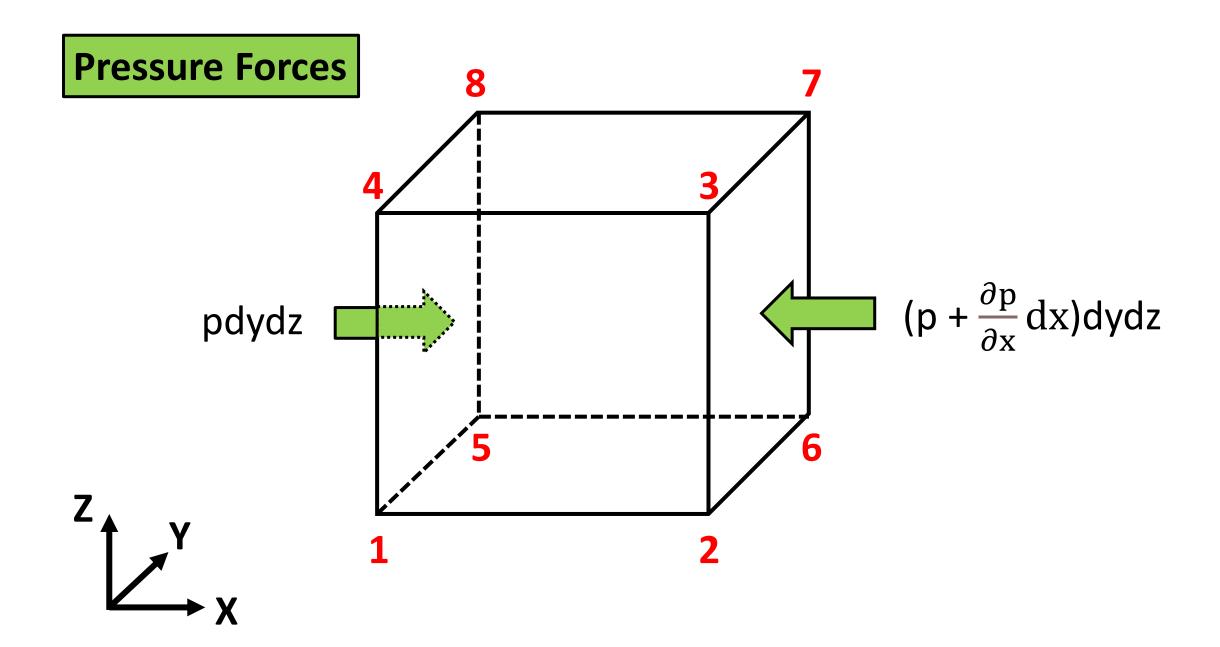


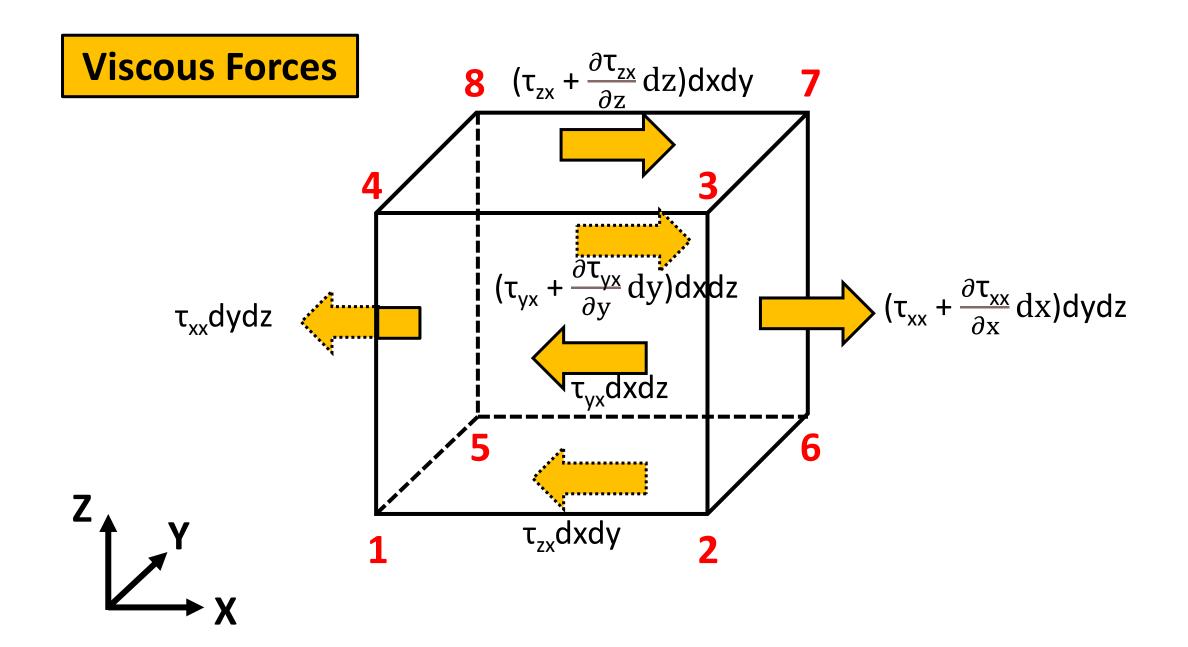


$$\frac{D(mu)}{Dt} = \Sigma F_{x}$$









$$\frac{\frac{(\rho dxdydz)D(u)}{Dt}}{\frac{\partial \tau_{yx}}{\partial y} dxdydz} = \frac{\partial p}{\partial x} dxdydz + \frac{\partial \tau_{xx}}{\partial x} dxdydz + \frac{\partial \tau_{yx}}{\partial z} dxdydz + \frac{\partial \tau_{zx}}{\partial z} dxdydz + f_{x}(\rho dxdydz)$$

$$\frac{\rho D(u)}{Dt} = -\frac{\partial p}{\partial x} + \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} + f_{x}\rho$$

$$\frac{\rho D(u)}{Dt} = -\frac{\partial p}{\partial x} + \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} + f_{x}\rho$$

$$\frac{\rho D(v)}{Dt} = -\frac{\partial p}{\partial y} + \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} + f_y \rho$$

$$\frac{\rho D(w)}{Dt} = -\frac{\partial p}{\partial z} + \frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \tau_{zz}}{\partial z} + f_z \rho$$

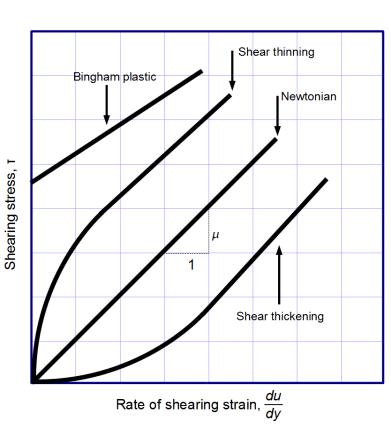
Newtonian Fluid

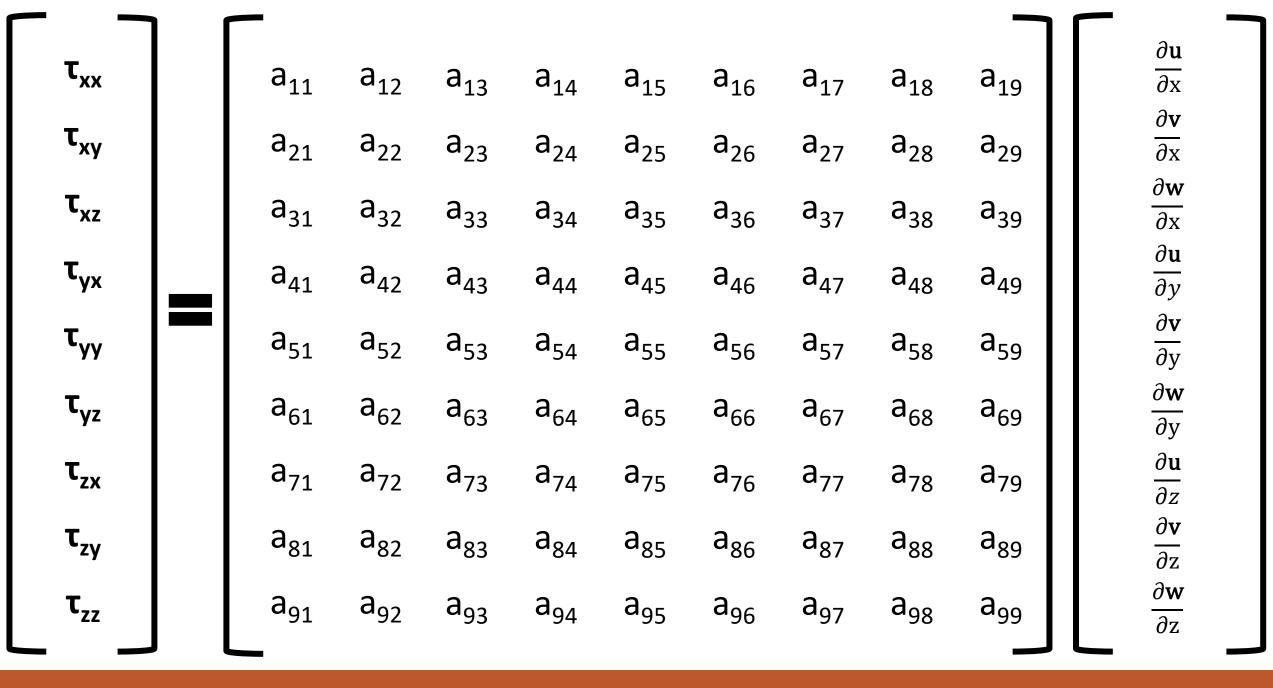
Newtonian fluids exhibit a linear relationship between viscous stress and velocity gradients

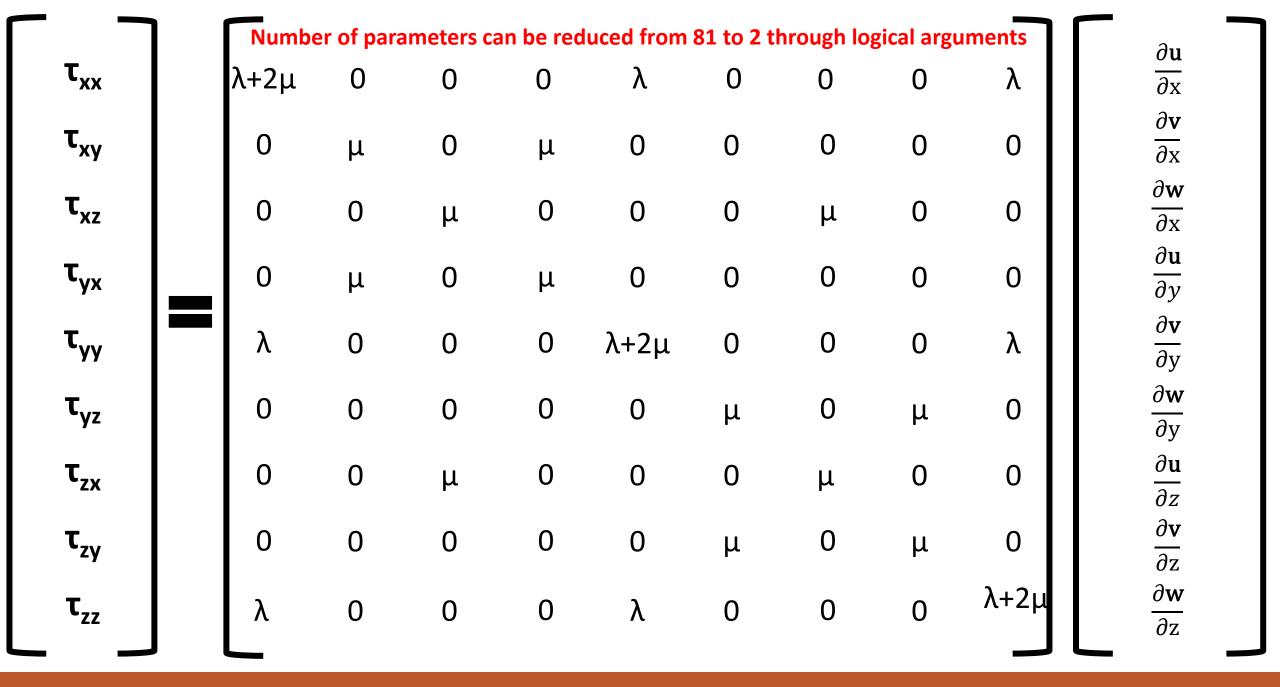
$$\frac{\rho D(u)}{Dt} = -\frac{\partial p}{\partial x} + \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} + f_{x}\rho$$

$$\frac{\rho D(v)}{Dt} = -\frac{\partial p}{\partial y} + \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} + f_y \rho$$

$$\frac{\rho D(w)}{Dt} = -\frac{\partial p}{\partial z} + \frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \tau_{zz}}{\partial z} + f_z \rho$$

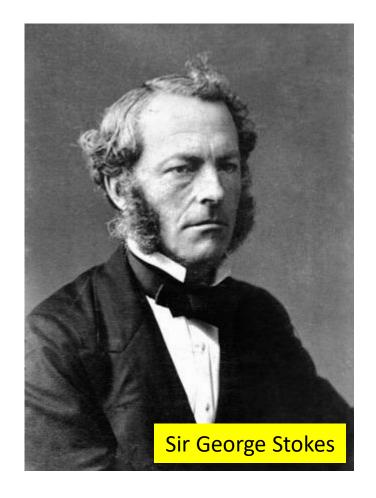






Stokes' Hypothesis

$$\lambda = -\frac{2}{3}\mu$$



Viscous Stresses

$$\tau_{xx} = \frac{2\mu}{3} \left[2 \frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} - \frac{\partial w}{\partial z} \right]$$

$$\tau_{yy} = \frac{2\mu}{3} \left[-\frac{\partial u}{\partial x} + 2 \frac{\partial v}{\partial y} - \frac{\partial w}{\partial z} \right]$$

$$\tau_{zz} = \frac{2\mu}{3} \left[-\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} + 2 \frac{\partial w}{\partial z} \right]$$

$$\tau_{xy}, \tau_{yx} = \mu \left[\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right]$$

$$\tau_{xz}, \tau_{zx} = \mu \left[\frac{\partial w}{\partial x} + \frac{\partial u}{\partial z} \right]$$

$$\tau_{yz},\tau_{zy} = \mu \left[\frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right]$$

$$\tau_{yx} = \mu \left[\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right] \qquad \tau_{zx} = \mu \left[\frac{\partial w}{\partial x} + \frac{\partial u}{\partial z} \right]$$

$$\frac{\rho D(u)}{Dt} = -\frac{\partial p}{\partial x} + \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{xx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} + f_{x}\rho$$

$$\tau_{xx} = \frac{2\mu}{3} \left[2 \frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} - \frac{\partial w}{\partial z} \right]$$

$$\rho \frac{\partial u}{\partial t} + V \cdot \nabla u = -\frac{\partial p}{\partial x} + \frac{2\mu}{3} \frac{\partial}{\partial x} \left[2 \frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} - \frac{\partial w}{\partial z} \right] + \mu \frac{\partial}{\partial y} \left[\frac{\partial v}{\partial x} + \frac{\partial u}{\partial z} \right] + \mu \frac{\partial}{\partial y} \left[\frac{\partial v}{\partial x} + \frac{\partial u}{\partial z} \right] + f_x \rho$$

$$\rho \left[\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right] = -\frac{\partial p}{\partial x} + \frac{2\mu}{3} \frac{\partial}{\partial x} \left[2 \frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} - \frac{\partial v}{\partial y} \right]$$

$$\frac{\partial w}{\partial z} \left[+ \mu \frac{\partial}{\partial y} \left[\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right] + \mu \frac{\partial}{\partial z} \left[\frac{\partial w}{\partial x} + \frac{\partial u}{\partial z} \right] + f_x \rho$$

$$\rho \left[\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right] = -\frac{\partial p}{\partial x} + \frac{2\mu}{3} \frac{\partial}{\partial x} \left[2 \frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} - \frac{\partial w}{\partial z} \right] + \mu \frac{\partial}{\partial y} \left[\frac{\partial v}{\partial x} + \frac{\partial u}{\partial z} \right] + \mu \frac{\partial}{\partial z} \left[\frac{\partial w}{\partial x} + \frac{\partial u}{\partial z} \right] + f_x \rho$$

$$\rho \left[\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right] = -\frac{\partial p}{\partial y} + \mu \frac{\partial}{\partial x} \left[\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right] + \frac{2\mu}{3} \frac{\partial}{\partial y} \left[-\frac{\partial u}{\partial x} + 2 \frac{\partial v}{\partial y} - \frac{\partial v}{\partial y} \right] + \frac{\partial w}{\partial z} \left[\frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right] + f_y \rho$$

$$\rho \left[\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right] = -\frac{\partial p}{\partial z} + \mu \frac{\partial}{\partial x} \left[\frac{\partial w}{\partial x} + \frac{\partial u}{\partial z} \right] + \mu \frac{\partial}{\partial y} \left[\frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right] + \frac{\partial w}{\partial z} \left[-\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} + 2 \frac{\partial w}{\partial z} \right] + f_z \rho$$

A Much More Convenient Form

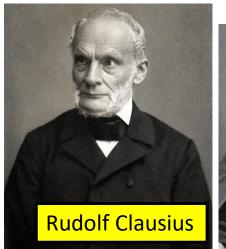
$$\frac{\rho D(u)}{Dt} = -\frac{\partial p}{\partial x} + \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} + f_{x}\rho$$

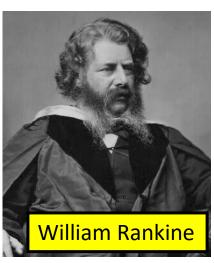
$$\frac{\rho D(v)}{Dt} = -\frac{\partial p}{\partial y} + \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} + f_y \rho$$

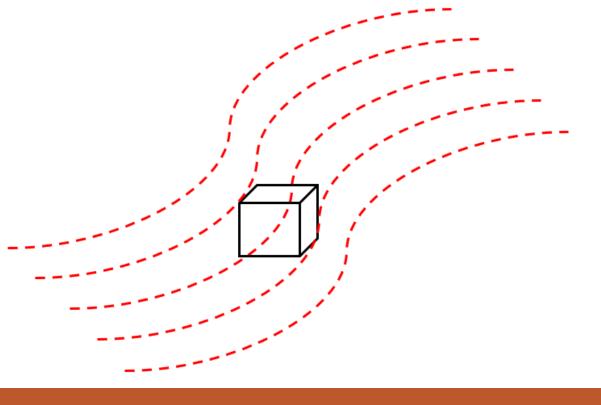
$$\frac{\rho D(w)}{Dt} = -\frac{\partial p}{\partial z} + \frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \tau_{zz}}{\partial z} + f_z \rho$$

Conservation of Energy

 The rate at which the energy of the fluid element changes – as it moves through the fluid – is equal to the rate of work done on it and the rate at which energy is transferred into it

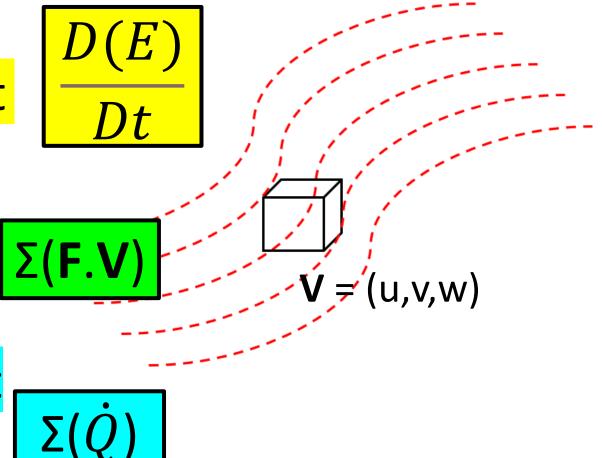




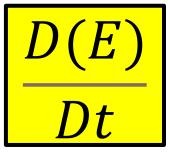


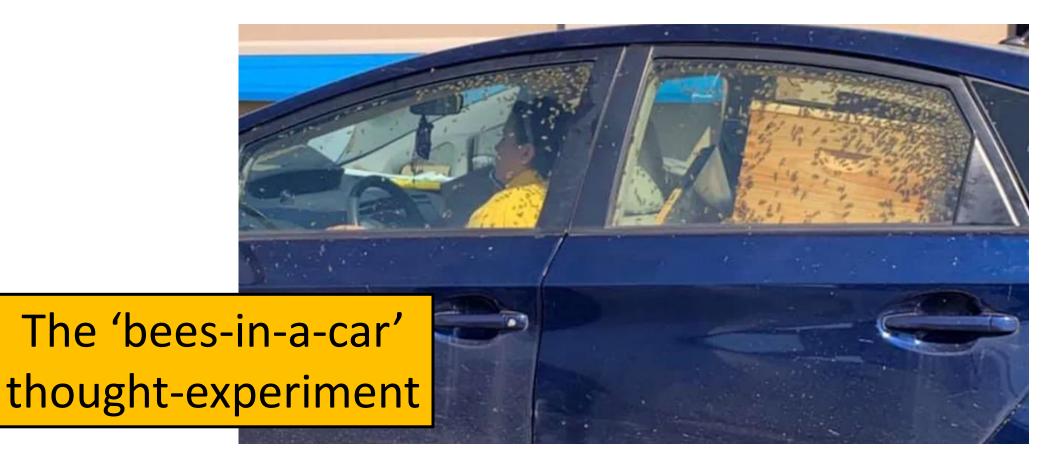
Conservation of Energy

 The rate at which the energy of the fluid element changes – as it moves through the fluid - is equal to the rate of work done on it and the rate at which energy is transferred into it



$$\frac{D(E)}{Dt} = \Sigma(\mathbf{F}.\mathbf{V}) + \Sigma(\dot{Q})$$





Source: Josh Dutton, "'That's crazy': Baffling photo of woman driving a car full of bees," Yahoo News Australia, 22 March 2021



Energy of the bees

Energy due to the bees flapping their wings



Energy due to the bees flying around within the car

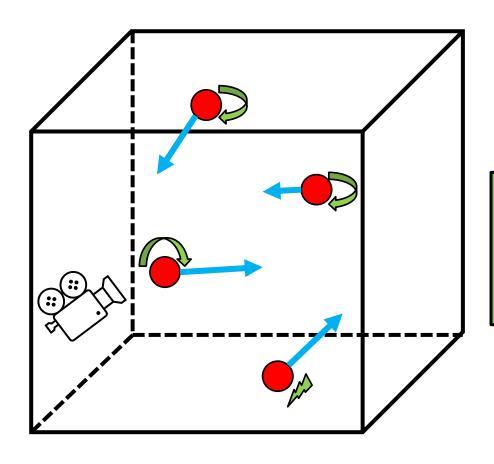


Energy due to the car's motion

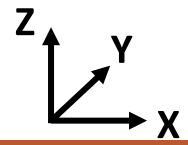
"INTERNAL" ENERGY

KINETIC ENERGY

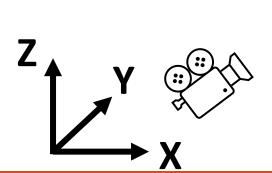
Atoms/Molecules have translational velocities as measured in the reference frame attached to the moving volume

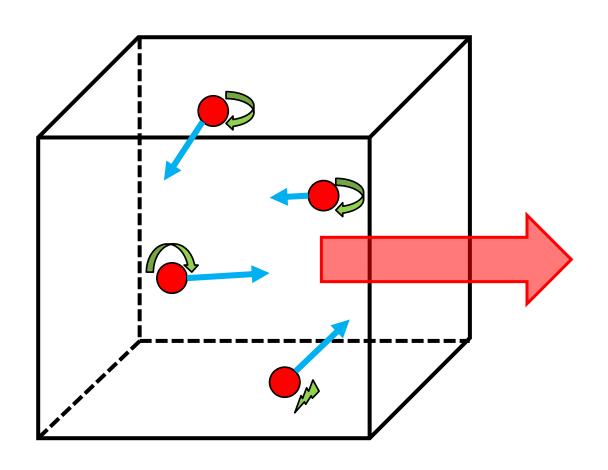


Molecules can also have rotational and vibrational energy

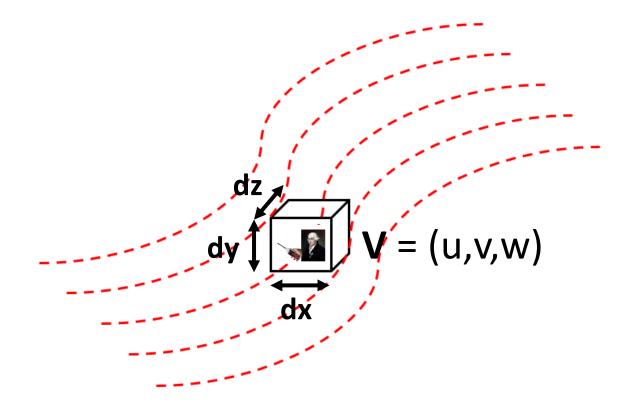


Atoms/Molecules can also have kinetic energy due to moving *en masse*





$$\frac{D(E)}{Dt} = \frac{D(me + \frac{1}{2}m|\mathbf{V}|^2)}{Dt}$$



Internal Energy

$$e = function(T, p)$$



'Calorically perfect gas'

$$e = c_v T$$

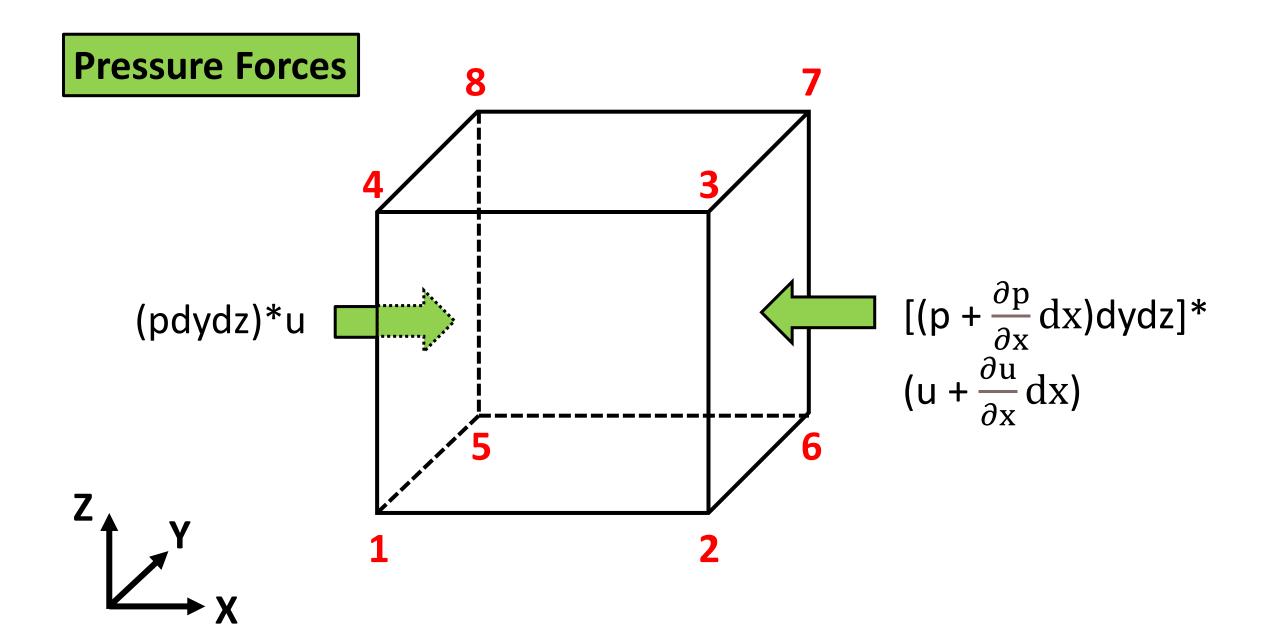


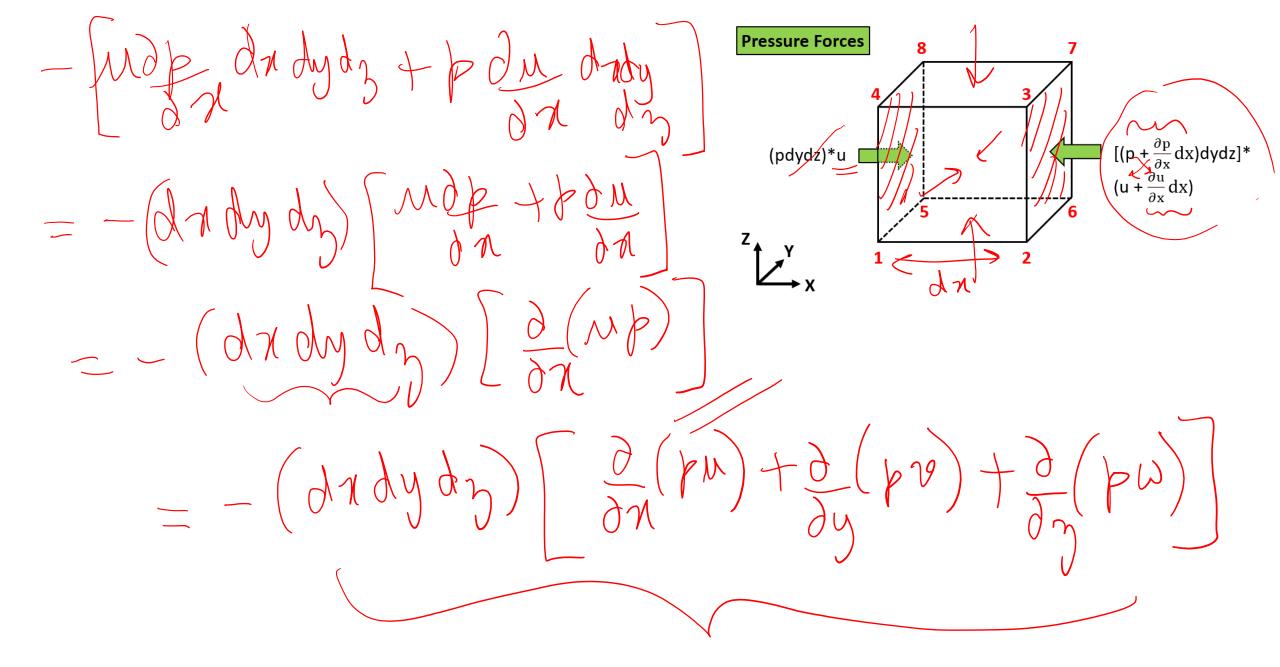
'Ideal gas'

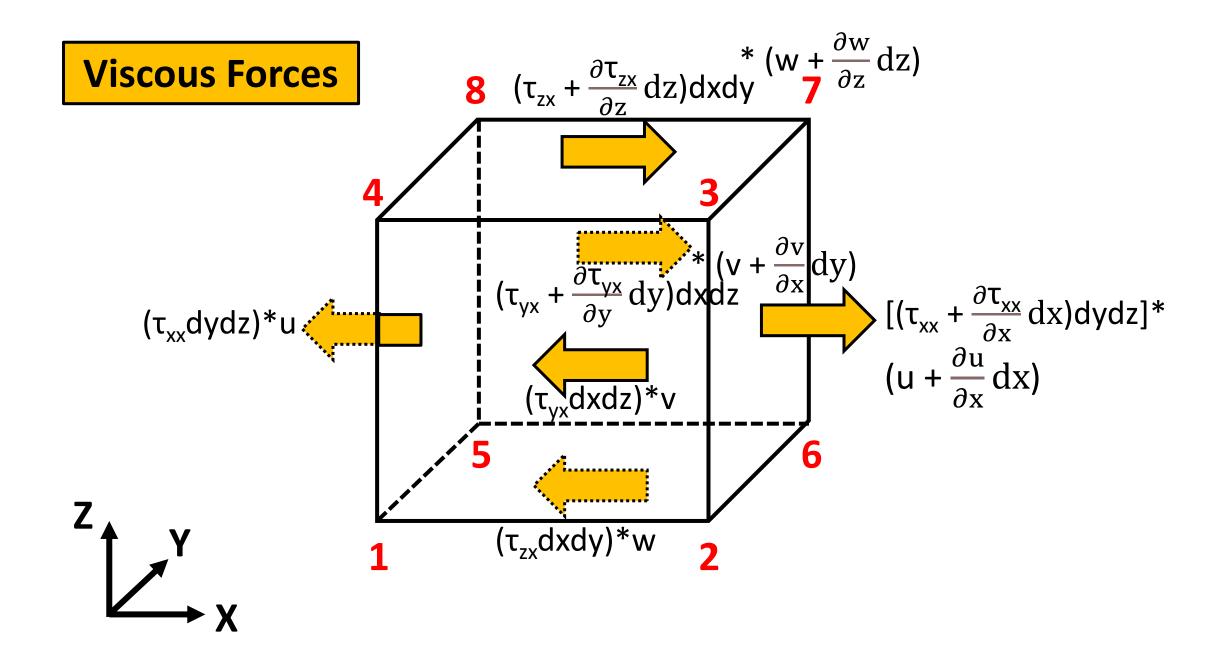
$$e = \frac{p}{(\gamma - 1)\rho}$$

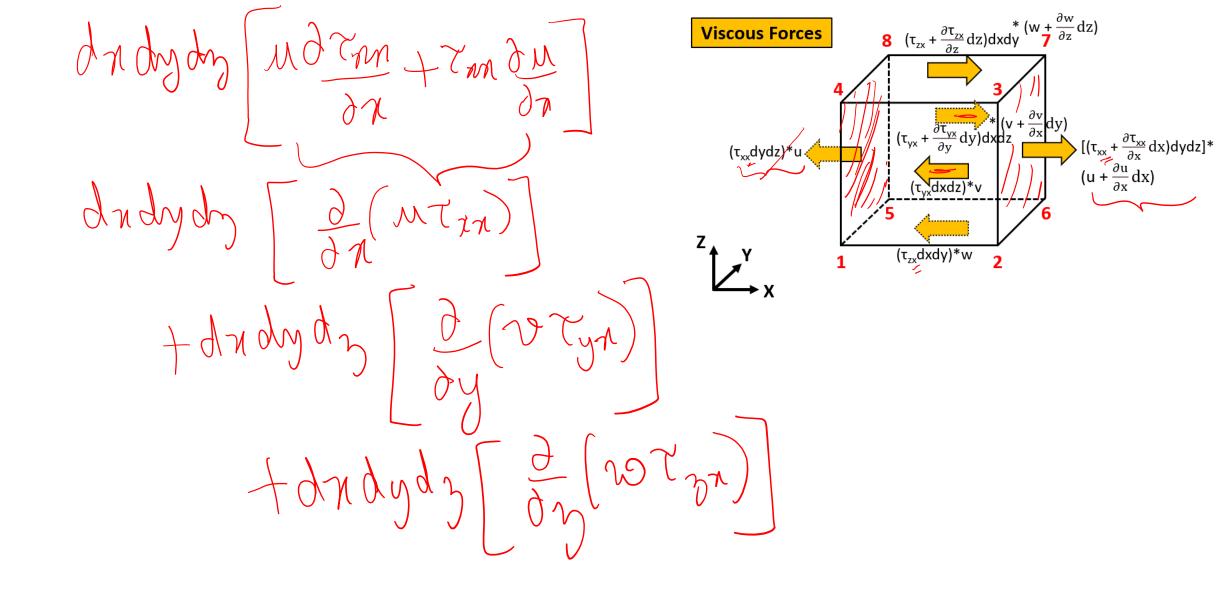
$$\frac{D(e + \frac{1}{2}|\mathbf{V}|^2)}{Dt}$$

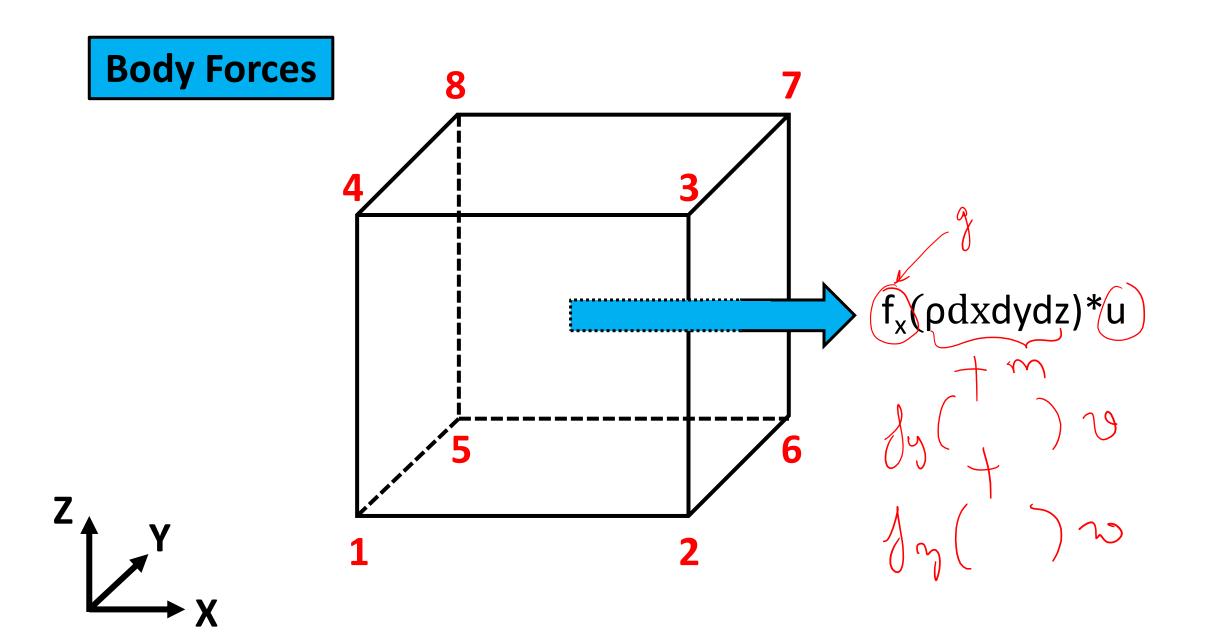
$$\frac{D(E)}{Dt} \neq \Sigma(\mathbf{F}.\mathbf{V}) + \Sigma(\dot{Q})$$







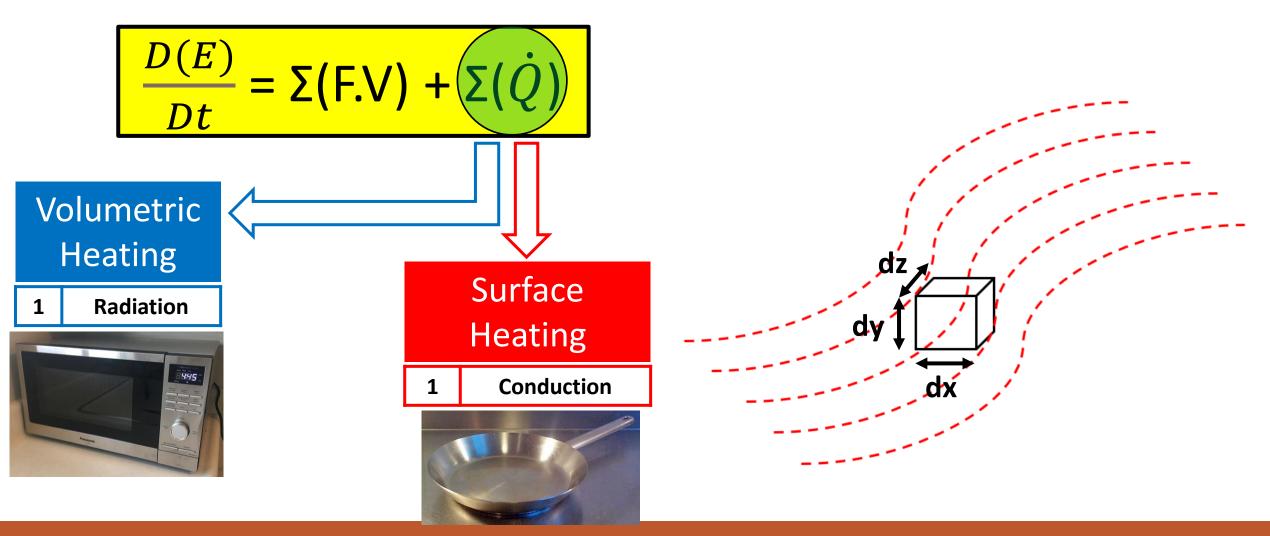


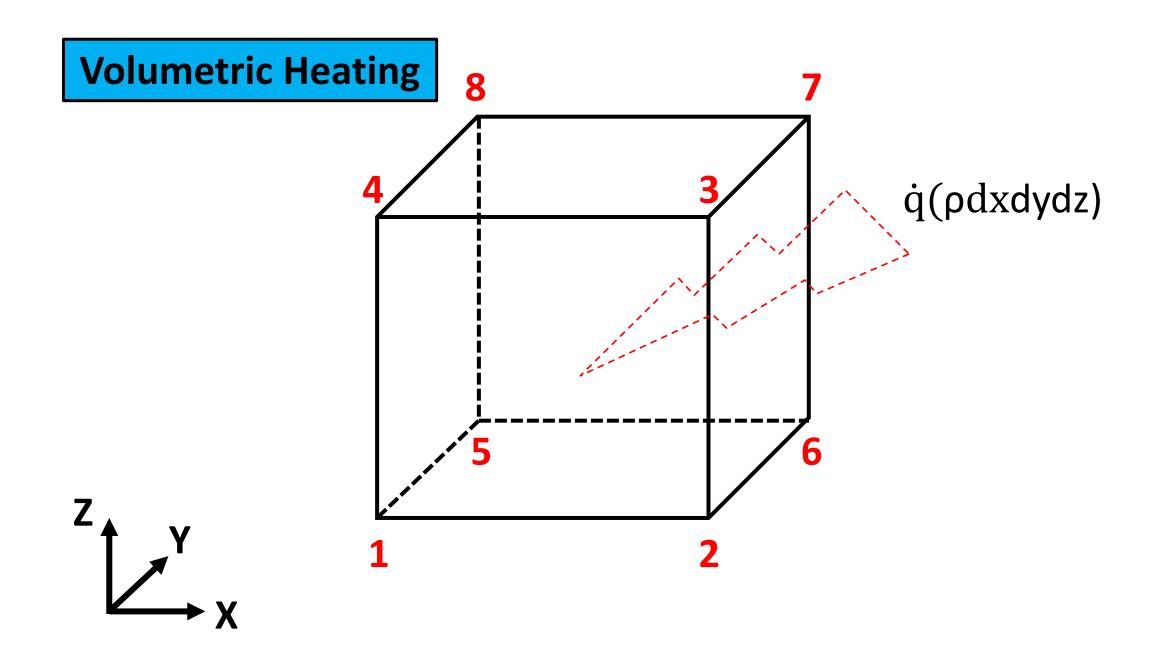


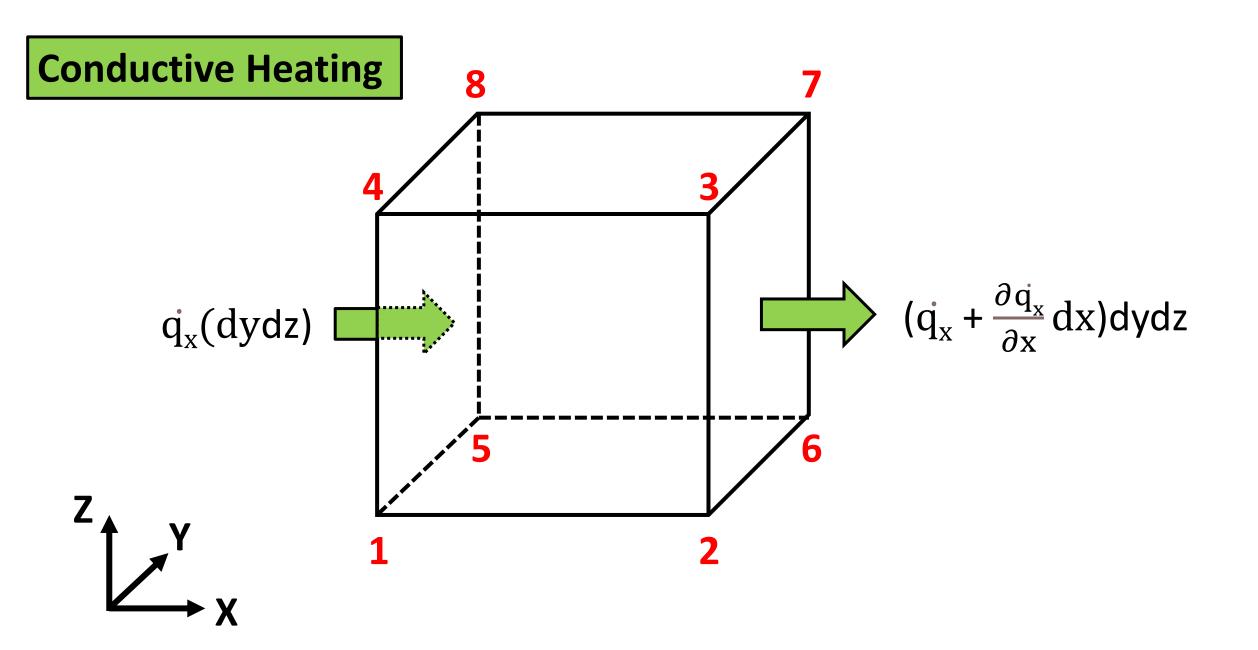
$$\frac{D(e + \frac{1}{2}|\mathbf{V}|^2)}{Dt}$$

$$\frac{D(E)}{Dt} \neq \mathbf{\Sigma}(\mathbf{F}.\mathbf{V}) + \mathbf{\Sigma}(\dot{Q})$$

$$\begin{aligned} & (\rho dx dy dz) \left[-\frac{\partial (pu)}{\partial x} - \frac{\partial (pv)}{\partial y} - \frac{\partial (pw)}{\partial z} + \frac{\partial (\tau_{xx} u)}{\partial x} + \frac{\partial (\tau_{yx} u)}{\partial y} + \frac{\partial (\tau_{zx} u)}{\partial z} + \frac{\partial (\tau_{xy} v)}{\partial z} + \frac{\partial (\tau_{xy} v)}{\partial z} \right] \\ & + \frac{\partial (\tau_{yy} v)}{\partial y} + \frac{\partial (\tau_{zy} v)}{\partial z} + \frac{\partial (\tau_{xz} w)}{\partial z} + \frac{\partial (\tau_{yz} w)}{\partial z} + \frac{\partial (\tau_{zz} w)}{\partial z} + f_x u + f_y v + f_z w \right] \end{aligned}$$







$$(\rho dxdydz) \frac{D(e + \frac{1}{2}|\mathbf{V}|^2)}{Dt}$$

$$(dxdydz)[-\frac{\partial q_x}{\partial x} - \frac{\partial q_y}{\partial y} - \frac{\partial q_z}{\partial z} + \rho \dot{q}]$$

$$D(E) = \Sigma(\mathbf{F}.\mathbf{V}) + \Sigma(\dot{Q})$$

$$D(E) = \Sigma(\mathbf{F}.\mathbf{V}) + \Sigma(\dot{Q})$$

$$\begin{aligned} & (\rho dx dy dz) \left[-\frac{\partial (pu)}{\partial x} - \frac{\partial (pv)}{\partial y} - \frac{\partial (pw)}{\partial z} + \frac{\partial (\tau_{xx}u)}{\partial x} + \frac{\partial (\tau_{yx}u)}{\partial y} + \frac{\partial (\tau_{zx}u)}{\partial z} + \frac{\partial (\tau_{xy}v)}{\partial z} + \frac{\partial (\tau_{xy}v)$$

Fourier's Law

$$\dot{\mathbf{q}}_{\mathbf{x}} = -k \frac{\partial T}{\partial \mathbf{x}}$$



$$\frac{D(e + \frac{1}{2}|\mathbf{V}|^2)}{Dt}$$

$$(\mathsf{dxdydz}) \left[\frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial x} \right) + \frac{\partial}{\partial y} \left(k \frac{\partial T}{\partial y} \right) + \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \rho \dot{q} \right]$$

$$\frac{D(E)}{Dt} \neq \Sigma(F.V) + \Sigma(\dot{Q})$$

$$\begin{aligned} & (\text{dxdydz}) [\frac{\partial (\text{pu})}{\partial x} + \frac{\partial (\text{pv})}{\partial y} + \frac{\partial (\text{pw})}{\partial z} + \frac{\partial (\tau_{xx}u)}{\partial x} + \frac{\partial (\tau_{$$

$$(\rho dxdydz) \frac{D(e + \frac{1}{2}|\mathbf{V}|^2)}{Dt} = (dxdydz) \left[\frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial x} \right) + \frac{\partial}{\partial y} \left(k \frac{\partial T}{\partial y} \right) + \frac{\partial}{\partial y} \left(k \frac{\partial T}{\partial y} \right) + \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \rho \dot{q} \right] + (dxdydz) \left[-\frac{\partial(pu)}{\partial x} - \frac{\partial(pv)}{\partial y} - \frac{\partial(pw)}{\partial z} + \frac{\partial(pw)}{\partial z} \right] + \frac{\partial(\tau_{xx}u)}{\partial x} + \frac{\partial(\tau_{yx}u)}{\partial y} + \frac{\partial(\tau_{zx}u)}{\partial z} + \frac{\partial(\tau_{xy}v)}{\partial z} + \frac{\partial(\tau_{yy}v)}{\partial z} + \frac{\partial(\tau_{zy}v)}{\partial z} + \frac{\partial(\tau_{zy}v)}{\partial z} + \frac{\partial(\tau_{zz}w)}{\partial z} + \frac{\partial($$

$$\frac{\rho D\left(e + \frac{1}{2}|\mathbf{V}|^{2}\right)}{Dt} = \frac{\partial}{\partial x}\left(k\frac{\partial T}{\partial x}\right) + \frac{\partial}{\partial y}\left(k\frac{\partial T}{\partial y}\right) + \frac{\partial}{\partial z}\left(k\frac{\partial T}{\partial z}\right) + \frac{\partial}{\partial z}\left(k\frac{\partial T}{\partial z}\right) + \frac{\partial}{\partial z}\left(\frac{\partial D}{\partial x}\right) + \frac{\partial^{2}(Du}{\partial x} - \frac{\partial^{2}(Du)}{\partial y} - \frac{\partial^{2}(Du)}{\partial z} + \frac{\partial^{2}(Du}{\partial x} + \frac{\partial^{2}(Du}{\partial x}) + \frac{\partial^{2}(Du}{\partial y} + \frac{\partial^{2}(Du}{\partial y}) + \frac{\partial^{2}(Du}{\partial z} + \frac{\partial^{2}(Du}{\partial x}) + \frac{\partial^{2}(Du}{\partial y} + \frac{\partial^{2}(Du}{\partial y}) + \frac{\partial^{2}(Du}{\partial y} + \frac{\partial^{2}(Du}{\partial y}) + \frac{\partial^{2}(Du}{\partial z} + \frac{\partial^{2}(Du}{\partial z}) + \frac{\partial^{2}(Du}{\partial z}) + \frac{\partial^{2}(Du}{\partial z} + \frac{\partial^{2}(Du}{\partial z}) + \frac{\partial^{2}(Du}{\partial z} + \frac{\partial^{2}(Du}{\partial z}) + \frac{\partial^{2}(Du}{\partial z}) + \frac{\partial^{2}(Du}{\partial z} + \frac{\partial^{2}(Du}{\partial z}) + \frac{\partial^{2}(Du}{\partial z} + \frac{\partial^{2}(Du}{\partial z}) + \frac{\partial^{2}(Du}{\partial$$

Hierarchy of Fluid Dynamical Models

SEBASTIAN THOMAS

$$\frac{D\rho}{Dt} + \rho \nabla . \mathbf{V} = 0$$

$$\frac{\rho D(u)}{Dt} = -\frac{\partial p}{\partial x} + \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} + f_{x}\rho$$

$$\frac{\rho D(v)}{Dt} = -\frac{\partial p}{\partial y} + \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} + f_y \rho$$

$$\frac{\rho D(w)}{Dt} = -\frac{\partial p}{\partial z} + \frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \tau_{zz}}{\partial z} + f_z \rho$$

$$\frac{\rho D\left(e + \frac{1}{2}|\mathbf{V}|^{2}\right)}{Dt} = \frac{\partial}{\partial x}\left(k\frac{\partial T}{\partial x}\right) + \frac{\partial}{\partial y}\left(k\frac{\partial T}{\partial y}\right) + \frac{\partial}{\partial z}\left(k\frac{\partial T}{\partial z}\right) + \rho\dot{q} - \frac{\partial(pu)}{\partial x} - \frac{\partial(pv)}{\partial y} - \frac{\partial(pw)}{\partial z} + \frac{\partial(\tau_{xx}u)}{\partial z} + \frac{\partial(\tau_{xx}u)}{\partial x} + \frac{\partial(\tau_{xx}u)}{\partial z} + \frac{\partial(\tau_{xy}v)}{\partial z} + \frac{\partial(\tau_{xy}v)}{\partial z} + \frac{\partial(\tau_{xz}w)}{\partial z} + \frac{\partial(\tau_{xz}w)}{\partial z} + \frac{\partial(\tau_{xz}w)}{\partial z} + \frac{\partial(\tau_{xx}u)}{\partial z} + \rho\left(fxu + fyv + fzw\right)$$

$$e = C_v T$$

$$p = \rho RT$$

$$\tau_{xx} = \frac{2\mu}{3} \left[2 \frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} - \frac{\partial w}{\partial z} \right]$$

$$\tau_{xy}, \tau_{yx} = \mu \left[\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right]$$

$$\tau_{yy} = \frac{2\mu}{3} \left[-\frac{\partial u}{\partial x} + 2 \frac{\partial v}{\partial y} - \frac{\partial w}{\partial z} \right]$$

$$\tau_{xz}, \tau_{zx} = \mu \left[\frac{\partial w}{\partial x} + \frac{\partial u}{\partial z} \right]$$

$$\tau_{zz} = \frac{2\mu}{3} \left[-\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} + 2 \frac{\partial w}{\partial z} \right]$$

$$\tau_{yz}, \tau_{zy} = \mu \left[\frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right]$$

$$\frac{D()}{Dt} = \frac{\partial()}{\partial t} + \mathbf{V} \cdot \nabla()$$

$$\mu = \mu_{ref} \left(\frac{T}{T_{ref}}\right)^{3/2} \left[\frac{T_{ref} + S}{T + S}\right]$$

List of unknowns

Unknowns	Appearance(s)
ρ	Mass, Momentum, Energy, Ideal Gas
р	Momentum, Ideal Gas
u, v, w	Mass, Momentum, Energy
Т	Energy, Ideal Gas
е	Energy, Linear function of temperature
μ	Function of temperature ('Sutherland's Law')

The Case for Simplification

Simplify the Navier-Stokes equations whenever justifiable!







The problem you're simulating

