

The UART Module

This chapter introduces the UART (Universal Asynchronous Receiver-Transmitter) module of Novix OS. UART is the primary way for the kernel to send and receive data to and from the host — it is our basic input/output device.

It is also used extensively throughout debugging, logging, and communication between the OS and QEMU console.

Function: `uart_getc`

```
long uart_getc(void);
```

Description:

Performs an SBI call to receive a single character from the UART input buffer. Returns -1 if no character is available.

Function: `uart_putc`

```
void uart_putc(char ch);
```

Description:

Sends a single character to the UART output using SBI call (extension ID 1).

Function: `uart_puts`

```
void uart_puts(const char *s);
```

Description:

Prints an entire string by repeatedly calling `uart_putc()` until a null terminator is reached.

Function: `uart_puthex8` / `uart_puthex8_prefixed`

```
void uart_puthex8(uint8_t val);  
void uart_puthex8_prefixed(uint8_t val);
```

Description:

Prints an 8-bit value in hexadecimal; the prefixed version adds "0x".

Function: `uart_puthex16` / `uart_puthex16_prefixed`

```
void uart_puthex16(uint16_t val);  
void uart_puthex16_prefixed(uint16_t val);
```

Description:

Prints a 16-bit value in hexadecimal; the prefixed version adds "0x".

Function: `uart_puthex32` / `uart_puthex32_prefixed`

```
void uart_puthex32(uint32_t val);  
void uart_puthex32_prefixed(uint32_t val);
```

Description:

Outputs a 32-bit value in hexadecimal format. The prefixed version includes "0x".

Function: `uart__puthex64` / `uart__puthex64__prefixed`

```
void uart__puthex64(uint64_t val);  
void uart__puthex64__prefixed(uint64_t val);
```

Description:

Prints a 64-bit value in hexadecimal; `__prefixed` adds "0x". Used for printing addresses and large integers.

Function: `uart__put__udec`

```
void uart__put__udec(uint64_t value);
```

Description:

Prints an unsigned integer in decimal format. Implemented manually without `libc`.

Function: `uart__put__dec`

```
void uart__put__dec(int64_t value);
```

Description:

Prints a signed integer with a leading minus sign if negative.

Function: `uart__puthex`

```
void uart__puthex(uint64_t value, int width);
```

Description:

Prints any integer value in hexadecimal format, padding zeros to match width.

Function: `uart__putpad`

```
void uart__putpad(uint64_t val, int base, int width, int zero_pad, int signed_val);
```

Description:

Flexible number formatting helper that supports padding, base, and signed output.

Function: `uart__printf`

```
void uart__printf(const char *fmt, ...);
```

Description:

Implements a minimal formatted print system supporting `%d`, `%u`, `%x`, `%p`, `%c`, `%s`, and padding options.

Function: `uart__cls`

```
void uart__cls(void);
```

Description:

Clears the terminal screen using ANSI escape sequences.

Function: `uart__set__color`

```
void uart__set__color(const char *ansi_code);
```

Description:

Sets ANSI color for terminal text (e.g. `"\x1b[31m"` for red).

Test Functions

Function: heap__test

Description:

Tests dynamic memory allocation by allocating and freeing several memory blocks.

Function: getc__test

Description:

Waits for a character input via UART, then echoes it to confirm UART RX/TX.

Function: date__time__test

Description:

Fetches and prints current time using `get_time()` and `compute_datetime()`.

Function: log__test

Description:

Demonstrates `LOG_INFO`, `LOG_WARN`, `LOG_ERR`, and `LOG_DEBUG` macros for kernel logging.

Function: kernel__main

Prototype

```
void kernel_main(void);
```

Parameters

- None.

Return Value

- None.
This function does not return — it contains an infinite loop to keep the kernel active.

Purpose

`kernel_main()` is the main entry point of the Novix OS kernel after the bootloader (`boot()` function) has set up the stack and transferred control.

It initializes the system's basic runtime environment and provides user feedback through UART output.

Detailed Description

1. Screen Initialization

The function starts by clearing the UART terminal screen using:

```
uart_cls();
```

This ensures that the kernel output starts from a clean display after boot.

2. Welcome Message

Next, a versioned welcome message is printed to the console:

```
uart_printf("Novix RISC-V 64 OS, (c) NovixManiac, Version 0.0.1\n\n");
```

This identifies the running OS and confirms successful control transfer from the bootloader.

3. Boot Feedback

The message "Booting ..." is printed using:

```
uart_puts("Booting ...\n");
```

This provides immediate user feedback that the kernel startup process has begun.

4. UART Input Test

The kernel performs a basic UART input test by calling:

```
getc_test();
```

This test prompts the user to type a key and echoes it back to verify both UART transmission and reception functionality.

5. Infinite Loop

Finally, the kernel enters an infinite loop:

```
for (;;) ;
```

This keeps the kernel running indefinitely, preventing control from returning to the bootloader and maintaining the system in an operational state.

Summary

The `kernel_main()` function is the central initialization point for the Novix kernel.

It demonstrates successful boot, performs a UART diagnostic, and transitions the system into its idle operational state.

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