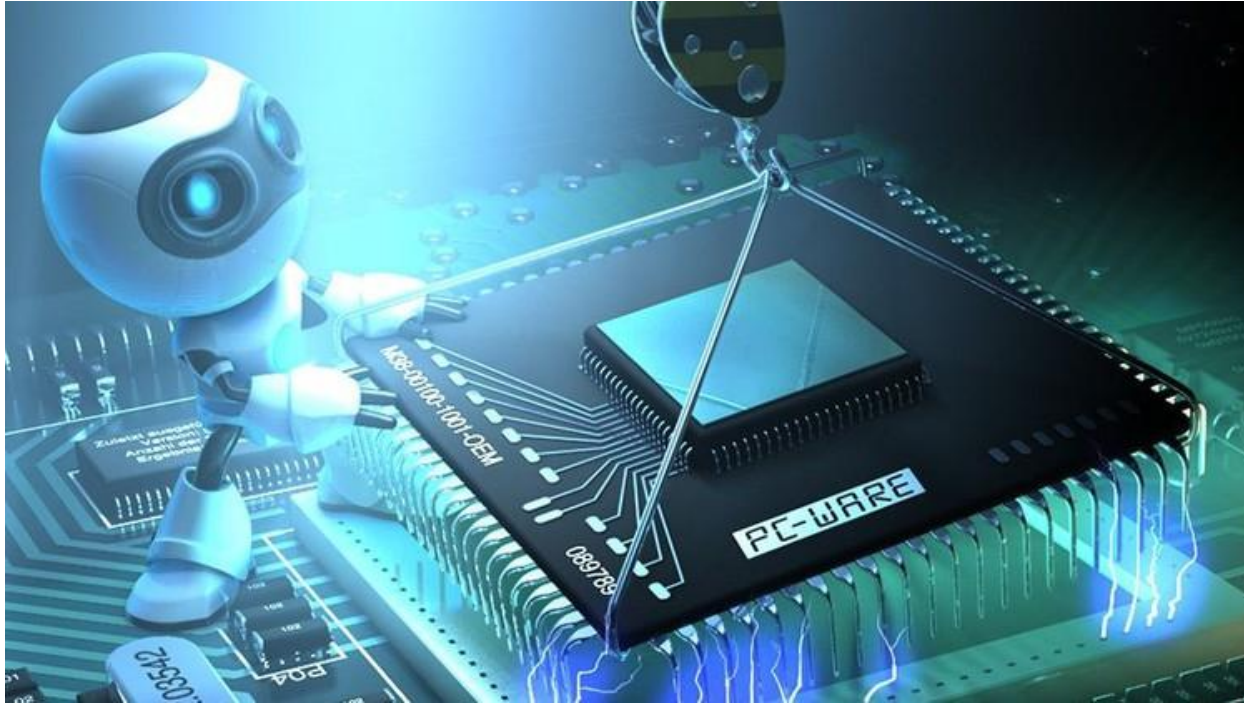
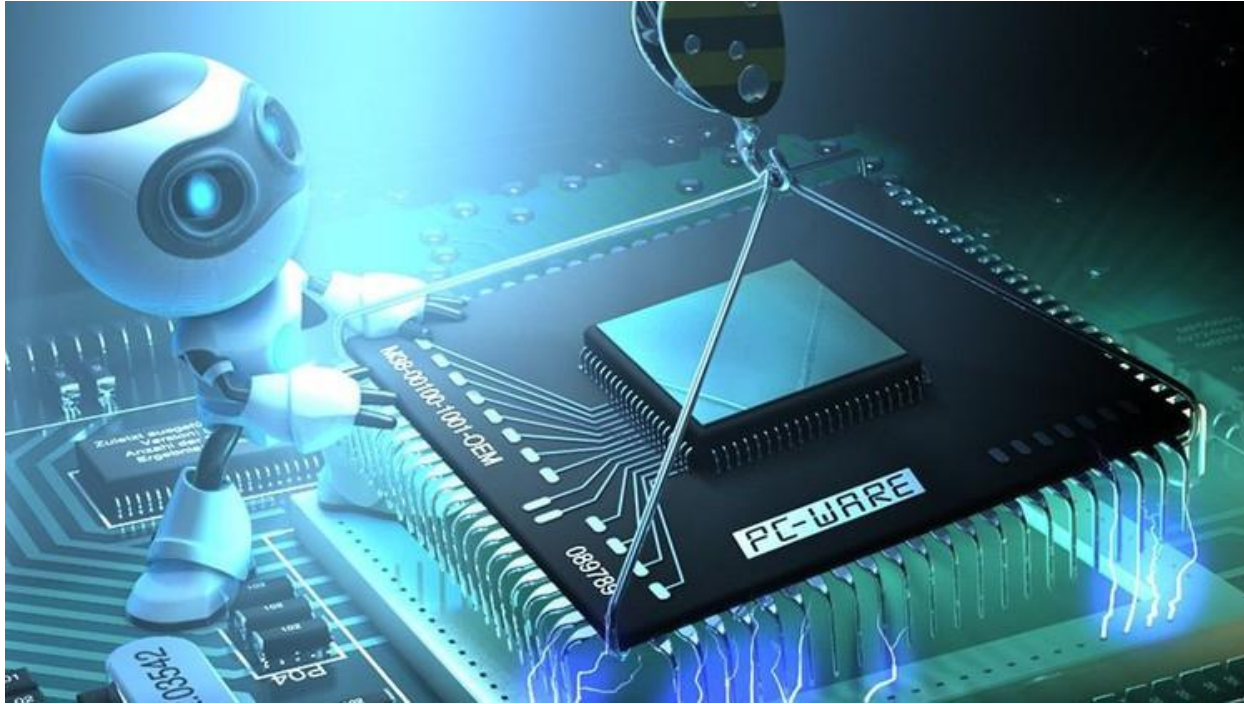


# Laboratory Session 2



# Practise - Problem 3



# Practise - Problem 3



## 3. Translate the Swap routine to x86 assembler.

```
void Swap(S1 v[], int i, int j) {  
  
    int tmp;  
    int *aux;  
    char s;  
  
    s      = v[i].c;  
    v[i].c = v[j].c;  
    v[j].c = s;  
  
    tmp     = v[i].k;  
    v[i].k = v[j].k;  
    v[j].k = tmp;  
  
    aux     = v[i].m;  
    v[i].m = v[j].m;  
    v[j].m = aux;  
}
```



# Practise - Problem 3



3.

Part 1/3

```
.text
```

```
    .align 4
```

```
    .globl Swap
```

```
    .type Swap,@function
```

```
Swap:
```

```
    # preparation for subroutine management
```

```
    push %ebp
```

```
    movl %esp, %ebp
```

```
    subl $12, %esp
```

```
    movl 8(%ebp), %ebx
```

```
    movl 12(%ebp), %eax
```

```
    movl 16(%ebp), %edx
```

```
    # we have 3 local variables (tmp,aux,s) + padding
```

```
    # @v
```

```
    # i
```

```
    # j
```

x86

# Practise - Problem 3



3.

Part 2/3

**# Swap v[i].c and v[j].c**

```
mov (%ebx,%eax,12), %al
mov (%ebx,%edx,12), %dl
mov %dl, (%ebx,%eax,12)
mov %al, (%ebx,%edx,12)
```

```
# %al = v[i].c
# %dl = v[j].c
# v[i].c = v[j].c
# v[j].c = s
```

**# Swap v[i].k and v[j].k**

```
mov 4(%ebx,%eax,12), %eax
mov 4(%ebx,%edx,12), %edx
mov %edx, 4(%ebx,%eax,12)
mov %eax, 4(%ebx,%edx,12)
```

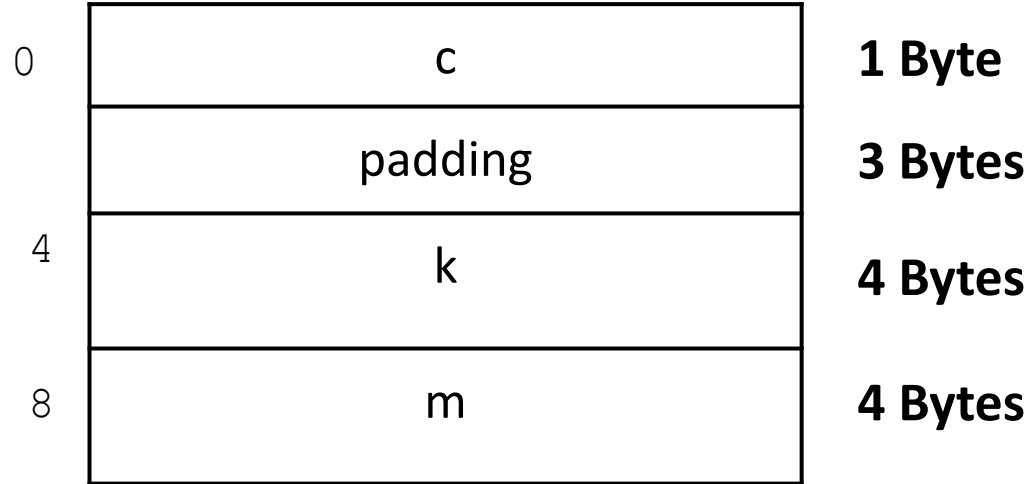
```
# %eax = v[i].k
# %edx = v[j].k
# v[i].k = v[j].k
# v[j].k = tmp
```

x86

# Previous Study - Problem 1



```
typedef struct {  
    char c;  
    int k;  
    int *m;  
} S1;
```



Total size of struct S1: **12 bytes**

# Practise - Problem 3



3.

Part 3/3

**# Swap v[i].m and v[j].m**

```
mov 8(%ebx,%eax,12), %eax
mov 8(%ebx,%edx,12), %edx
mov %edx, 8(%ebx,%eax,12)
mov %eax, 8(%ebx,%edx,12)
```

```
# eax = v[i].m
# edx = v[j].m
# v[i].m = v[j].m
# v[j].m = aux
```

**# Function epilogue**

```
mov %ebp, %esp
pop %ebp
ret
```

