CEE 598: Uncertainty Quantification

Assignment Five

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Imports and Set Up

```
In [1]: import numpy as np
import scipy as sp
import matplotlib.pyplot as plt
import seaborn as sns
import pytest
import chaospy as cp
import pandas as pd
```

References

https://chaospy.readthedocs.io/en/master/tutorial.html (https://chaospy.readthedocs.io/en/master/tutorial.html)

Task One

Using the three-term recurrence relation, write a generic code that evaluates the n-th order one-dimensional Hermite and Legendre polynomials, denoted by $P_n(x)$, at a prescribed numerical value for x. The code can be written in the form of a single function that is called with a prescribed type of polynomial (either Hermite or Legendre). Name your function evaluate_1D_polynomial. So, the function will be called as follows

evaluate_1D_polynomial(x,n,polynomial_type).

Using this function, plot the Hermite and Legendre polynomials of order 0, 1, 2, 3. For Hermite polynomials, set the plotting range x to be [-3, 3].

Task Two

Multi-dimensional polynomial bases are just the product of one-dimensional polynomials. Based on your one-dimensional polynomial code, **evaluate_1D_polynomial**, write a code that evaluates the i-th d-dimensional Hermite or Legendre polynomial, denoted by $\Psi_i(x)$, at a given numerical vector sample $x=x_{i=1}^d$. The function will be called as follows

polynomial_value = evaluate_multiD_polynomial(x,d,i,polynomial_type)

Using this function, generate the (surface) plots of 2D Hermite and Legendre polynomials with i = 0, 1, 2, 3. For Hermite polynomials, set the plotting range of x_1 and x_2 to be [-3, 3].

Note

For the relationship between a multi-dimensional index, i, and its corresponding combination of one-dimensional degrees, e.g. (2,1,0,1), you could use the convention shown on Slide 6 of March 31 Lecture.

Task Three

In this code verification task, verify your codes by testing whether it can separately recover the following two target functions (intentionally chosen to be polynomial):

$$f(x_1,\ldots,x_2)=6+2x_1^2+0.2x_1^3+2.3x_1x_2-1.5x_2^2-0.8x_3 \ g(y_1,y_2)=-15+0.05y_2^2+3.2y_1y_2+0.3y_2^2$$

Consider all the 3 x variables to be standard normal and the 2 y variables to be uniform random variables in [0,1], use the corresponding orthogonal polynomials. To do the verification, use multidimensional quadrature using tensor product. For 1D quadrature rules, use Gauss-Hermite quadrature points for normal random variables and Gauss-Legendre quadrature points for uniform random variables. These quadrature points and their weights can be easily found on the Internet. You should choose the number of quadrature points and explain your choices.

General Solution Approach

Per the assignment guidelines, I have ultimately chosen approach (3), utilizing open-source codes to perform tasks 1 and 2, and verified using task 3. I had initially attempted approach (2), but am most satisfied with the verificiation of task 3 utilizing approach (3). For the library, I have chosen to use the Python library ChaosPy, which I found through online searches and comparisons of available options. As seen in the code below, the approach for Chaospy is relatively clean and straightforward, requiring only a few hours of review and practice to implement successfully with required variations. In the spirit of this assignment, I have also written several helper functions included with this assignment, which I found useful in understanding the results produced by ChaosPy and in comparing my results to those expected per task 3. These functions were particularly important for the first reason, as the danger of applying an unknown third-party library is that it is often difficult to understand if it is functioning correctly and in the intended way.

Per slide 6 of lecture 17, we consider the general approach to be:

- 1. Choose the polynomial type
- 2. Write the polynomial representation for parameters
- 3. Pick the polynomial order for response
- 4. Write the polynomial representation for response
- 5. Calculate the unknown coefficients

$$u_i = \sum_{q=1}^{N_q} f(ar{x}^q) \psi_i(ar{x}^q) w^q$$

I have simplified most of these steps within wrappers for the ChaosPy library, which still require inputs for (1) the polynomial type and (3) the polynomial order for the response. I have written the code to be easily modified to take in arbitrary simulations for the systems being modeled, but have also written my wrappers to directly input matrix representations of the polynomial functions for easy comparison.

While ChaosPy supports a vast variety of polynomial types, per the problem prompt I have focused on normal distributions (evaluated using Hermite polynomials) and uniform distributions (evaluated using Legendre polynomials). Because the ChaosPy library is well established, I first solved for the multi-dimensional polynomial, and then bulit the ability to indvidually extract out and filter the one-dimensional polynomials. I feel that this approach most cleanly allows utilization of the library. Runtime is very fast for the examples of case three.

```
In [2]: # Use ChasosPy to define the distributions for the problem. Multiple distributions
    are supported by defualt.
    distribution_x = cp.J(cp.Normal(),cp.Normal())
    distribution_y = cp.J(cp.Uniform(0,1),cp.Uniform(0,1))
```

For simplicity in comparing results, I have chosen to create a data structure for storing polynomials. The datastructure, contained within a Pandas DataFrame, has a column of coefficients, followed by an arbitrary number of numbered columns representing variables (for instance x_1), the value of which is the power to which this coefficient should be taken for the given term, scaled by the row's coefficient.

```
In [3]: coefs_x = [6,2,0.2,2.3,-1.5,-0.8]
x1_x = [0,2,3,1,0,0]
x2_x = [0,0,0,1,2,0]
x3_x = [0,0,0,0,0,1]
df_x = pd.DataFrame({"Coefficient":coefs_x,0:x1_x,1:x2_x,2:x3_x})
df_x
```

Out[3]:

```
In [4]: coefs_y = [-15, 0.05, 3.2, 0.3]
        y1 y = [0,0,1,0]
        y2_y = [0, 2, 1, 2]
        df_y = pd.DataFrame({"Coefficient":coefs_y,0:y1_y,1:y2_y})
```

Out[4]:

	Coefficient	0	1
0	-15.00	0	0
1	0.05	0	2
2	3.20	1	1
3	0.30	0	2

Helper Functions for ChaosPy

```
In [5]:
        mmm
        Takes the dataframe representation of coefficients and variable orders and allows t
        his to be treated like
        an equation, taking inputs and returning the evaluation. Very simple but I think a
        pretty clean
        way to represent the models used in task three. Most importantly, makes it much eas
        ier to evaluate
        ChaosPy polynomials in my opinion.
        Inputs:
        coefsDF (Pandas DataFrame) -> a data structure I created for this assignment where
        the first column
                                      is the coefficient of each term, and each subsequent
        numbered column
                                      is a variable index
        varsArray (list or numpy array) -> the coordinates at which the function is being e
        valuated
        Returns:
        valueToReturn (float) -> The value of the function represented by coefsDF at the co
        ordinates represented
                                by varsArray
        11 11 11
        def matrixToEquation(coefsDF, varsArray):
            valueToReturn = 0.0
            for i,row in coefsDF.iterrows():
                rowValue = row["Coefficient"]
                for j, var in enumerate(varsArray):
                    rowValue *= np.power(var,row[j])
                valueToReturn += rowValue
            return valueToReturn
```

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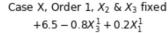
```
In [6]: # this is kludgy, but pass the two coefficinent matrices and an array of variables
        # the place which is (min, max) is the study (non-fixed) variable and the other valu
        es are fixed
        def plotComparison(correctCoefs,generatedCoefs,arr,title='',nSamples=100):
            correctEvaluations = []
            generatedEvaluations = []
            indexOfVariable = [i for i in range(len(arr)) if type(arr[i]) == tuple][0]
            lowerBound = arr[indexOfVariable][0]
            upperBound = arr[indexOfVariable][1]
            varValues = np.linspace(lowerBound, upperBound, nSamples)
            for varValue in varValues:
                variableInput = []
                for varLoc, varVal in enumerate(arr):
                    if varLoc == indexOfVariable:
                        variableInput.append(varValue)
                    else:
                        variableInput.append(varVal)
                correctEvaluation = matrixToEquation(correctCoefs, variableInput)
                generatedEvaluation = matrixToEquation(generatedCoefs,variableInput)
                correctEvaluations.append(correctEvaluation)
                generatedEvaluations.append(generatedEvaluation)
            fig,ax = plt.subplots(figsize=(10,5))
            ax.plot(varValues, correctEvaluations, label="Correct")
            ax.scatter(varValues,generatedEvaluations,label="Test",marker="*",color="red",a
        lpha=0.5)
            ax.set title(title)
            ax.legend()
```

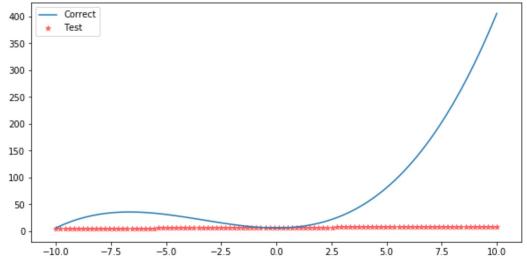
```
In [7]: | """
        Creates a pretty-print string representation of the polynomial represented by the p
        andas dataframe,
        written to look nice in LaTex. The cutoff will drop (from printing, not from analy
        zing) any coefficient
        with an absolute value less than the cutoff. Coefficients are rounded for printing
        based upon rounding.
        def convertDFGeneratedToEquation(df Generated, variableName="X", cutoff=0.001, roundin
        g=3):
            df Generated Filtered = df Generated[np.abs(df Generated["Coefficient"]) >= 0.0
        01]
            variables = list(df Generated.columns)[1:]
            strRepresentation = ""
            for i,row in df Generated Filtered.iterrows():
                if row["Coefficient"] >= 0:
                    term = f"+{round(row['Coefficient'], rounding)}"
                else:
                    term = f"{round(row['Coefficient'], rounding)}"
                for variable in variables:
                    if row[variable] != 0:
                        term += f"{variableName}_{variable+1}^{int(row[variable])}" # the v
        ariable + 1 is to be congruent with the 1-based indexing of the assignment
                strRepresentation += term
            return strRepresentation
```

```
In [8]: | """
        This function implements task three directly, with the examples below demonstrating
        how it can be
        used to implement tasks one and two.
        distribution (Pandas DataFrame) -> a data structure I created for this assignment w
        here the first column
                                      is the coefficient of each term, and each subsequent
        numbered column
                                       is a variable index
        simulationDistribution (Pandas DataFrame) -> The same data structure as above to re
        present the polynomials
                                                      being modeled. Please note that it is
        very easy to replace this
                                                      with an actual simulation, or any gene
        rator of choice.
        order (int) -> The order to be evaluated. As noted in the discussion, order < 2 pr
        oduces unpredictable results
        sampleRule (string) -> The polynomial type, including "gaussian", "gauss legendre"
        Returns:
        df Generated (Pandas DataFrame) -> a data structure I created for this assignment w
        here the first column
                                       is the coefficient of each term, and each subsequent
        numbered column
                                       is a variable index
        def generatePolynomialSurrogate(distribution, simulationDistribution, order, sampleRul
        e="gauss legendre"):
            orthogonal expansion = cp.orth ttr(order, distribution)
            samples,weights = cp.generate quadrature(order,distribution,rule=sampleRule)
            solves = np.array([matrixToEquation(simulationDistribution,sample) for sample i
        n samples.T])
            approx model = cp.fit regression(orthogonal expansion, samples, solves)
            nVars = approx model.exponents.shape[1]
            dataDict = {'Coefficient':approx model.coefficients}
            for varIndex in range(0, nVars):
                dataDict[varIndex] = approx model.exponents[:,varIndex]
            df Generated = pd.DataFrame(dataDict)
            return df Generated
```

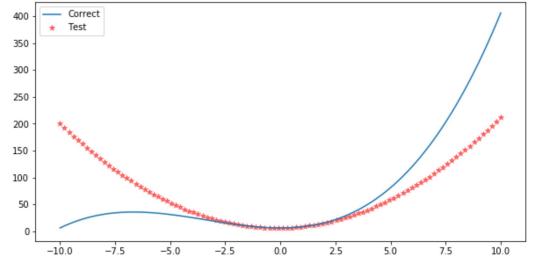
Equation X

```
In [9]: df_Generated = generatePolynomialSurrogate(distribution_x,df_x,1,sampleRule="gaussi
an")
    plotComparison(df_x,df_Generated,[(-10,10),0,0],title=f"Case X, Order 1, $x_2$ & $X
    _3$ fixed\n${convertDFGeneratedToEquation(df_Generated)}$")
```

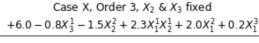


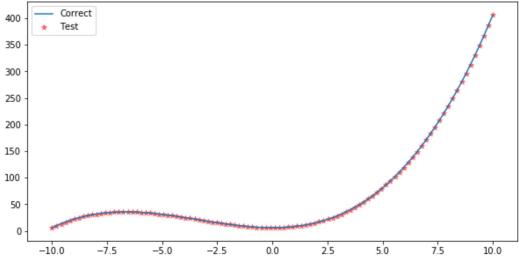


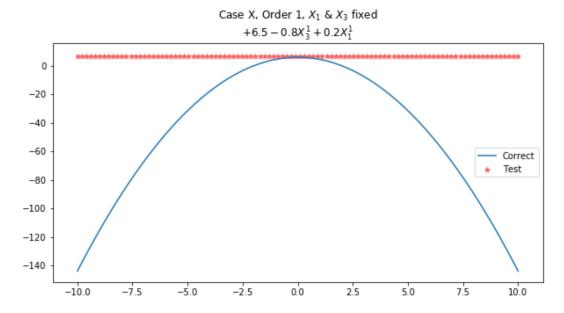
Case X, Order 2, $X_2 \& X_3$ fixed +6.0 - 0.8 X_3^1 - 1.5 X_2^2 + 0.6 X_1^1 + 2.3 $X_1^1X_2^1$ + 2.0 X_1^2

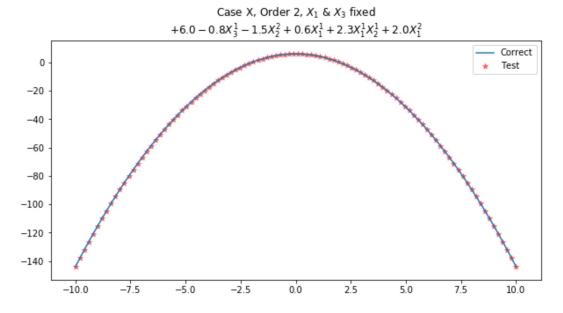


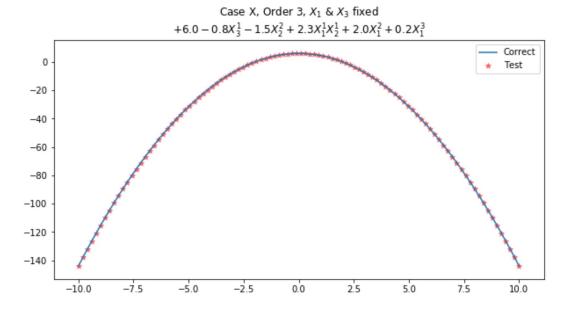
```
In [11]: df_Generated = generatePolynomialSurrogate(distribution_x,df_x,3,sampleRule="gaussi
an")
    plotComparison(df_x,df_Generated,[(-10,10),0,0],title=f"Case X, Order 3, $X_2$ & $X
    _3$ fixed\n${convertDFGeneratedToEquation(df_Generated)}$")
```











Equation Y

