## Why we multiply by batch size in the gradient hook of EKFAC

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Whatever loss function we take, for a given mini-batch the loss function is of the form

$$L(\theta) = \frac{1}{N_{batch}} \sum_{i} L_i(\theta), \tag{1}$$

where i indexes the data points in each mini-batch, and  $L_i$  is the contribution to the loss of the  $i^{th}$  data point.

When we use automatic differentiation to take the derivative of the loss function with respect to the parameter vector  $\theta$ , what we are computing is  $\frac{dL}{d\theta}$ . This is fine if we're already averaging over the mini-batch, but if we want to store the individual loss-function values for each data point to compute later (and possibly average after further computation), what we need to store, for each data point, is  $\frac{dL_i}{d\theta}$ . Since we don't have access to this directly, i.e. the gradient which is passed through backpropagation comes from the total loss function  $L(\theta)$  rather than  $L_i(\theta)$ , when we save this gradient for future computation, we must multiply by  $N_{batch}$  so we are saving  $\nabla L_i(\theta)$ , and not  $\nabla L_i(\theta)/N_{batch}$ .