

M.S. Math Bootcamp: Probability & Statistics

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Outline

1. Probability
2. Random Variables
3. Discrete Random Variables
4. Continuous Random Variables
5. Expectation
6. Joint Distributions
7. Parameter Estimation

Acknowledgements

Most of the material in these slides was adapted from *Mathematical Statistics & Data Analysis*, 3rd ed., by John A. Rice, as well as *Statistical Inference*, 2nd ed., by Casella and Berger.

Please do not distribute these slides.

Probability

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 - A single element of Ω is denoted ω , e.g. $\omega \in \Omega$.

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- An *event* E is a subset of Ω , i.e. $E \subseteq \Omega$.
- Two events E_1, E_2 are said to be *disjoint* if their intersection is the empty set $E_1 \cap E_2 = \emptyset$.

Probability Measure (Informal)

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$$P : \{\text{subsets of } \Omega\} \rightarrow [0, 1]$$

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- $P(\Omega) = 1$
- $P(\emptyset) = 0$
- If A_1, A_2 disjoint, then $P(A_1 \cup A_2) = P(A_1) + P(A_2)$ (this extends to countable sums).

Independent Events

- Given a sample space Ω and a probability measure P , we say two events E_1, E_2 are independent if

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- There can be many different probability measures associated with the same space Ω !
- However, in “reality” only one probability measure is used at any given time.

Example: Die Roll

- We have $\Omega = \{1, 2, 3, 4, 5, 6\}$.
- Consider the probability measure defined as follows:
 - $P(\{1\}) = P(\{2\}) = P(\{3\}) = \frac{1}{9}$
 - $P(\{4\}) = P(\{5\}) = P(\{6\}) = \frac{2}{9}$

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 - $P(\{1, 5\}) = P(\{1\} \cup \{5\}) = P(\{1\}) + P(\{5\}) = \frac{1}{9} + \frac{2}{9} = \frac{1}{3}$.
 - $P(\{2, 3, 6\}) = P(\{2\} \cup \{3\} \cup \{6\}) = \frac{1}{9} + \frac{1}{9} + \frac{2}{9} = \frac{4}{9}$

Conditional Probability

Let A, B be two events with $P(B) \neq 0$. Then the conditional probability of A given B is defined as

$$P(A \mid B) = \frac{P(A \cap B)}{P(B)}$$

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Conditional Probability: Example

- Consider two experiments
 - Whether or not the person buys a cup a coffee.
 - Whether or not the person buys a second cup of coffee.
- The sample space for each of the two experiments is $\Omega = \{(Y, Y), (Y, N), (N, Y), (N, N)\}$
- Suppose probabilities are known to be

First Cup/Second Cup	N	Y	Total
N	.5	0	.5
Y	.05	.45	.5
Total	.55	.45	1

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- Compute $P(A | B)$ and $P(B | A)$.

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- Let A be the event that a person buys a second cup of coffee.
- Compute $P(A | B)$ and $P(B | A)$.
- $P(A | B) = \frac{P(A \cap B)}{P(B)} = \frac{.45}{.50} = .9$

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- Compute $P(A | B)$ and $P(B | A)$.
- $P(B | A) = \frac{P(A \cap B)}{P(A)} = \frac{.45}{.45} = 1.0$

“And” Events

We can manipulate the conditional probability formula

$$P(A | B) = \frac{P(A \cap B)}{P(B)}$$

to calculate

$$P(A \cap B) = P(A | B)P(B)$$

Law of Total Probability

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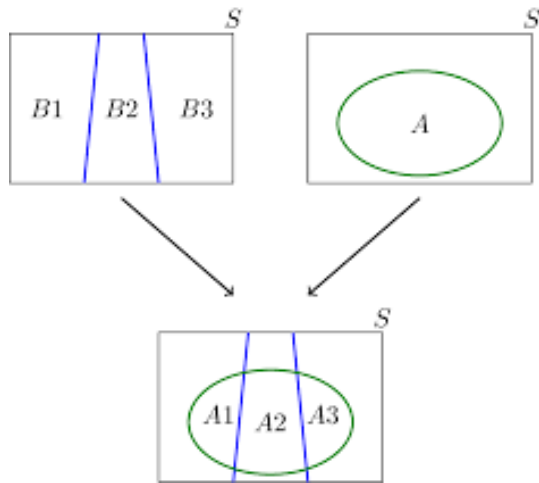
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- Then

$$\begin{aligned} P(A) &= \sum_{i=1}^n P(A \mid B_i)P(B_i) \\ &= \sum_{i=1}^n P(A \cap B_i) \end{aligned}$$

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- I pick two balls. Let R_2 be the event I pick red on my second draw. Let R_1 be the event I pick red on my first draw, B_1 be the event I pick blue on my first draw.
- The sample space for this experiment of picking two balls is

$$\Omega = \{(\text{blue}, \text{blue}), (\text{blue}, \text{red}), (\text{red}, \text{blue}), (\text{red}, \text{red})\}$$

Law of Total Probability: Example

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- I pick two balls. Let R_2 be the event I pick red on my second draw.
- Then

$$\begin{aligned}P(R_2) &= P(R_2 \mid B_1)P(B_1) + P(R_2 \mid R_1)P(R_1) \\&= \frac{7}{13} \cdot \frac{1}{2} + \frac{6}{13} \cdot \frac{1}{2}\end{aligned}$$

Bayes' Rule

Bayes' Rule tells us that

$$P(A | B) = \frac{P(B | A)P(A)}{P(B)}$$

Bayes' Rule Derivation

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$$P(A \mid B) = \frac{P(A \cap B)}{P(B)} = \frac{P(B \cap A)}{P(B)} = \frac{P(B \mid A)P(A)}{P(B)}$$

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- Let T denote the event that a subject tells the truth; let L denote the event that a subject lies.
- Let $+$ be the event that the machine flags the subject, $-$ be the event that the machine doesn't.
- The underlying sample space being considered here is

$$\Omega = \{(\text{lie}, \text{flagged}), (\text{lie}, \text{not flagged}), (\text{truth}, \text{flagged}), (\text{truth}, \text{not flagged})\}$$

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- Suppose that

$$P(+ \mid L) = .88$$

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$$P(- \mid T) = .86$$

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- Most people have no reason to lie, so generally $P(T) = .999$, $P(L) = .001$.

Try It

Given the information

$$P(+ \mid L) = .88$$

$$P(- \mid T) = .86$$

$$P(T) = .999$$

$$P(L) = .001$$

Compute $P(T \mid +)$ using Bayes' Rule.

Try It

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$$P(T | +) = \frac{P(+ | T)P(T)}{P(+)}$$

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Compute $P(T | +)$ using Bayes' Rule.

$$P(T | +) = \frac{P(+ | T)P(T)}{P(+)} = \frac{P(+ | T)P(T)}{P(+ | L)P(L) + P(+ | T)P(T)}$$

Try It

Given the information

$$P(+ | L) = .88 \implies P(- | L) = .12$$

$$P(- | T) = .86 \implies P(+ | T) = .14$$

$$P(T) = .999$$

$$P(L) = .001$$

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Compute $P(T | +)$ using Bayes' Rule.

$$\frac{P(+ | T)P(T)}{P(+ | L)P(L) + P(+ | T)P(T)} = \frac{.14 \cdot .999}{.88 \cdot .001 + .14 \cdot .999} = .994$$

Random Variables

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Note how this is different from a probability distribution, which is a function

$$P : \{\text{subsets of } \Omega\} \rightarrow [0, 1]$$

Induced Probability Distribution

Given a random variable X and a probability distribution P on sample space $\{\text{subsets of } \Omega\}$, P_X is an induced probability distribution on sample space \mathbb{R}

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This notation is really confusing, though, so we just write $P(X \in A)$. We call P_X the *distribution of X* .

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- So $\omega = 2, 3, 6$ result in $X \in [2, 3]$.
- Therefore

$$P_X([2, 3]) = P(\{2, 3, 6\}) = 0.5$$

Try It

Consider a sample space $\Omega = \{1, 2, 3, 4\}$ with probability measure

$$P(\{1\}) = .5$$

$$P(\{2\}) = .25$$

$$P(\{3\}) = .125$$

$$P(\{4\}) = .125$$

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Let $X(\omega) = \omega^2 - 5$.

Find $P(X \in [4, \infty))$.

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Let $X(\omega) = \omega^2 - 5$.

Find $P(X \in [4, \infty))$.

Only $\omega = 3$ and $\omega = 4$ result in $X(\omega) \in [4, \infty)$. So we want

$$P(\{3, 4\}) = .25$$

Cumulative Distribution Function

- The *cumulative distribution function* or *cdf* of a random variable X is a function $F_X : \mathbb{R} \rightarrow [0, 1]$ given by

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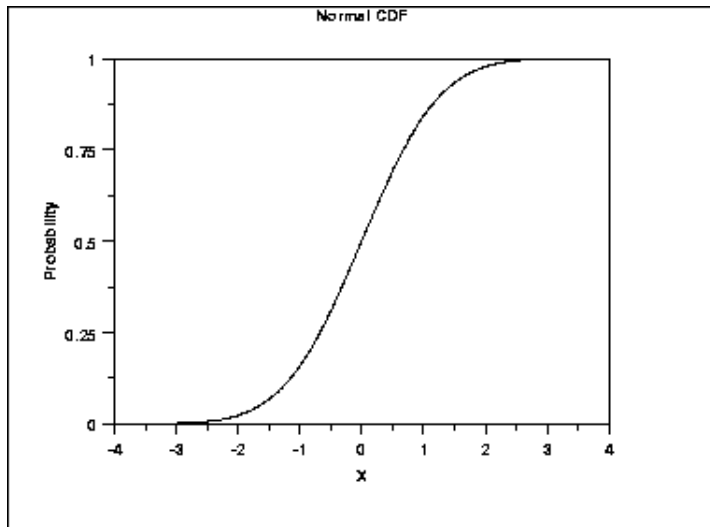
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- The cdf completely characterizes the distribution of X .
- The cdf is monotonically increasing.

Cumulative Distribution Function



Discrete Random Variables

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- The underlying probability space Ω is a useful theoretical concept.
- However, in practice we don't care about Ω because we don't observe the results of the underlying experiment.
- We only observe random variable X , and so we only care about the distribution of X . From now on, P will denote distributions of a random variable.

Abstract \rightarrow Practical

- $\Omega = \{\text{all possible underlying financial market conditions tomorrow}\}$

Abstract \rightarrow Practical

- $\Omega = \{\text{all possible underlying financial market conditions tomorrow}\}$
- $X : \Omega \rightarrow \mathbb{R}$ is a function that returns the stock price of Nvidia at close tomorrow.
In other words, $X(\omega)$ is a deterministic function of ω .

Discrete Random Variables

- Some random variable X only take on finitely (or countably many) values like $1, 2, 3, 4, \dots$. These are called *discrete random variables*.
- Most discrete random variables *count* the number of occurrences of something.

Bernoulli Random Variable

- A *Bernoulli* random variable X with parameter p is such that

$$\begin{cases} P(X = 1) = p \\ P(X = 0) = 1 - p \end{cases}$$

Binomial Random Variable

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- The random variable $X = \#$ of successes has a *binomial distribution*.
- A binomial distribution has

$$P(X = k) = \binom{n}{k} p^k (1 - p)^{n-k}$$

Poisson Random Variable

A Poisson random variable with parameter $\lambda > 0$ has distribution

$$P(X = k) = \frac{\lambda^k}{k!} e^{-\lambda}$$

for $k = 1, \dots, \infty$.

Continuous Random Variables

Continuous Random Variables

- More generally, a random variable X can take on a continuous range of values in \mathbb{R} .
 - The height of a random person (in inches).
 - The value of company (in dollars)
 - The degree of improvement of a pharmaceutical drug.

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- More generally, a random variable X can take on a continuous range of values in \mathbb{R} .
 - The height of a random person (in inches).
 - The value of company (in dollars)
 - The degree of improvement of a pharmaceutical drug.
- In situations like these, we want to know $P(X \in [a, b])$, $P(X > a)$, $P(X < b)$, etc.

Density

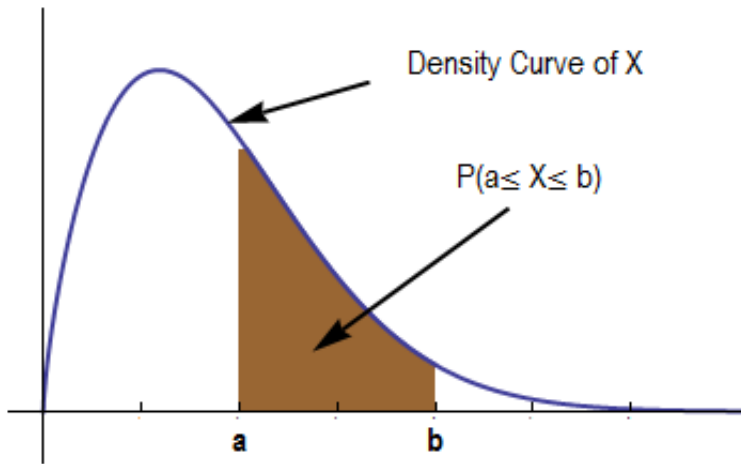
- The distribution of a continuous random variable X is often given to us in the form of a **density** function which we call $p(x)$.

Density

- The distribution of a continuous random variable X is often given to us in the form of a **density** function which we call $p(x)$.
- The density $p(x)$ gives probabilities via the relation

$$P(X \in [a, b]) = \int_a^b p(x) dx$$

Why Area?



Food For Thought

Given density curve $p(x)$,

- How would I calculate $P(X > b)$?

Food For Thought

Given density curve $p(x)$,

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Uniform Random Variable

A *uniform* random variable on the interval $[a, b]$ has density function

$$p(x) = \begin{cases} \frac{1}{b-a}, & x \in [a, b] \\ 0, & x \notin [a, b] \end{cases}$$

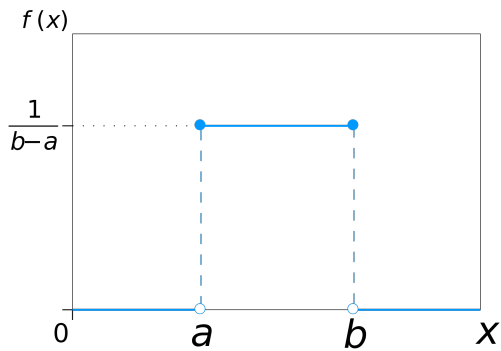


Image Source: https://en.wikipedia.org/wiki/Continuous_uniform_distribution

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Note

How do the following quantities differ?

$$P(X > 5) \quad \text{vs} \quad P(X \geq 5)$$

Exponential Random Variable

An *exponential* random variable (with parameter $\lambda > 0$) has density function

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$$\int_0^2 2e^{-2x} dx = -e^{-2x} \Big|_0^2 = -e^{-4} + 1$$

Normal Random Variable

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We often denote such a random variable as $X \sim \mathcal{N}(\mu, \sigma^2)$.

The Distribution Zoo

`https://ben18785.shinyapps.io/distribution-zoo/`

Expectation

Discrete R.V's

The expectation of a discrete random variable is defined as

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We also call $\mathbb{E}(X)$ the *mean* of X , which is often denoted μ .

Discrete R.V Example

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Suppose X has distribution

$$P(X = 1) = .5$$

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Then $\mathbb{E}(X) = 1(.5) + 2(.25) + 3(.2) + 4(.05) = 1.8$

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$$\mathbb{E}(X) = .999(-5) + .001(1000) = -\$3.995$$

Continuous R.V's

If X is a continuous random variable with density $p(x)$, then we define

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$$E(X) = \int_{-\infty}^{\infty} x \frac{1}{10} dx = \int_0^{10} x \frac{1}{10} dx = \frac{x^2}{20} \Big|_0^{10} = 5$$

Expectation of Functions of R.V's

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- Suppose tomorrow comes and the price turns out to be \$70.
- I may want to calculate $\mathbb{E}((X - 70)^2)$, i.e. the mean squared error of my estimate, to improve my model for the future.

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- Let X be a discrete random variable on $0, 1, 2$ with probabilities $\frac{1}{2}, \frac{3}{8}, \frac{1}{8}$, respectively.

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$$\mathbb{E}(X^2) = 0^2 \cdot \frac{1}{2} + 1^2 \cdot \frac{3}{8} + 2^2 \cdot \frac{1}{8} = \frac{7}{8}$$

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- Why is this? Because integration is linear.

$$\int_a^b \alpha f(x) + \beta g(x) dx = \alpha \int_a^b f(x) + \beta \int_a^b g(x)$$

Variance

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In words, the variance of a r.v. is “*the average squared distance between X and its mean*”.

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There's a lot of symbols in the formula above. It's easier to remember that $\mathbb{E}(X)$ is just a constant, μ , and rewrite as

$$\text{Var}(X) = \mathbb{E}[X - \mu]^2$$

Joint Distributions

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We're interested in quantities of the form

$$P(X = x, Y = y)$$

for discrete random variables and

$$P(X \in [a, b], Y \in [c, d])$$

for continuous random variables.

Joint Distribution

The notation with the comma

$$P(X = x, Y = y), P(X \in [a, b], Y \in [c, d])$$

is shorthand for denoting that both of these occur simultaneously.

Joint Density

Continuous random variables have a *joint density* $p(x, y)$ that satisfies

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and

$$P((X, Y) \in A) = \int \int_A p(x, y) dx dy$$

for any set $A \subseteq \mathbb{R}^2$.

Independence

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Two continuous r.v.'s X, Y are independent if their joint density factors into a product of their marginal densities, i.e.

$$p(x, y) = p(x)p(y).$$

Expectation

For any function $g : \mathbb{R}^2 \rightarrow \mathbb{R}$ we define

$$\mathbb{E}(g(X, Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x, y) p(x, y) dx dy$$

Covariance

The *covariance* between two random variables X, Y is

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Fact: If random variables X, Y are independent, then $\text{Cov}(X, Y) = 0$.

Parameter Estimation

Statistical Estimation (Informal)

Classical statistical frameworks consist of three main components.

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An *estimator* $\hat{\theta}(X_1, \dots, X_n)$ is a function of the data whose value we hope is close to θ .

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2. If we pick an eligible voter at random from the population, their support on this issue can be modeled as $\text{Bernoulli}(p)$.
3. We sample 1,078 eligible voters, and find that 670 support term limits. A natural estimator is

$$\hat{p} = \frac{\# \text{ in favor}}{\# \text{ polled}} = \frac{670}{1078} \approx .622$$

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2. With known standard deviation σ , assume a randomly selected can has a number of calories distributed as $\mathcal{N}(\mu, \sigma^2)$.
3. The FDA samples 178 cans for testing, and computes the number of calories in each with a high-precision instrument. A natural estimator is

$$\hat{\mu} = \frac{1}{178} \sum_{i=1}^{178} X_i$$

where X_i is the number of calories in can number i .

Observations About Estimators (Informal)

(Informal) Definition: An *estimator* $\hat{\theta}$ is a real-valued function of random variable X , i.e.

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Here's an alternative perspective. As $X : \Omega \rightarrow \mathbb{R}$, an estimator $\hat{\theta}(X)$ is the *composition of functions* that is itself a random variable:

$$\hat{\theta}(X) : \Omega \rightarrow \mathbb{R}$$

We can thus talk about the distribution, expectation, variance etc. of the estimator $\hat{\theta}(X)$.

Lots of Data?

- If we have many random variables, suppose each $X_i : \Omega \rightarrow \mathbb{R}$ for $i = 1, \dots, n$. Then the estimator

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takes in all n numbers and outputs a single number.

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- Define a new underlying sample space $\tilde{\Omega} = \Omega \times \Omega \times \dots \times \Omega$. Then

$$\hat{\theta}(X_1, \dots, X_n) : \tilde{\Omega} \rightarrow \mathbb{R}$$

is a random variable defined on this new sample space.

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3. What is $P(|\hat{\theta} - \theta| > \epsilon)$?

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3. The FDA samples 178 cans for testing, and computes the number of calories in each with a high-precision instrument. Call these numbers X_1, \dots, X_{178} .
4. We will consider the estimator

$$\hat{\mu} = \frac{1}{178} \sum_{i=1}^{178} X_i.$$

Try It: Questions About $\hat{\mu}$

1. Assuming each $X_i \sim \mathcal{N}(\mu, \sigma^2)$ and the random variables are independent, for $\hat{\mu} = \frac{1}{178} \sum_{i=1}^{178} X_i$ calculate $\mathbb{E}(\hat{\mu})$.
2. Calculate $\text{Var}(\hat{\mu})$ (you will need to use the fact that for independent random variables Y, Z , we have $\text{Var}(\alpha Y + \beta Z) = \alpha^2 \text{Var}(Y) + \beta^2 \text{Var}(Z)$.)

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By linearity, we have

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Calculate $\text{Var}(\hat{\mu})$ (you will need to use the fact that for independent random variables Y, Z , we have $\text{Var}(\alpha Y + \beta Z) = \alpha^2 \text{Var}(Y) + \beta^2 \text{Var}(Z)$, the variance of a $\mathcal{N}(\mu, \sigma^2)$ is σ^2 .)

Using the fact given

$$\begin{aligned}\text{Var}(\hat{\mu}) &= \text{Var}\left(\frac{1}{178} \sum_{i=1}^{178} X_i\right) \\ &= \text{Var}\left(\frac{X_1}{178} + \frac{X_2}{178} + \cdots + \frac{X_{178}}{178}\right)\end{aligned}$$

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Likelihood Function

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- Let X be a continuous random variable with density function p parameterized by parameter θ .
 - Denoted $p_{\theta}(x)$.
- The *likelihood function* is defined as

$$\mathcal{L}(\theta) = p_{\theta}(x)$$

- Viewed as a function of θ , rather than x .

Problem Formulation

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- Data X is generated from some distribution, parameterized by θ .
 - E.g., $X \sim \mathcal{N}(\theta, 1)$.
- We observe X , but θ is unknown.
- Maximum likelihood estimation (MLE) picks $\hat{\theta}$ to estimate θ as

$$\hat{\theta} = \arg \max \mathcal{L}(\theta)$$

Easy Example: $\mathcal{N}(\theta, 1)$

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- Suppose you observe $X = 10$. What value of θ maximizes the likelihood function?

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Now we differentiate with respect to θ .

$$\begin{aligned} \frac{d}{d\theta} \mathcal{L}(\theta) &= \frac{d}{d\theta} p_{\theta}(x) = \frac{d}{d\theta} \frac{1}{\sqrt{2\pi}} e^{-\frac{(10 - \theta)^2}{2}} \\ &= \frac{1}{\sqrt{2\pi}} e^{-\frac{(10 - \theta)^2}{2}} \cdot (10 - \theta) = 0 \end{aligned}$$

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We don't need to actually observe X . More generally if the random variable $X = x$ after the experiment is performed, then

$$\begin{aligned} \frac{d}{d\theta} \mathcal{L}(\theta) &= \frac{\partial}{\partial \theta} p_{\theta}(x) = \frac{\partial}{\partial \theta} \frac{1}{\sqrt{2\pi}} e^{-\frac{(x - \theta)^2}{2}} = \\ &= \frac{1}{\sqrt{2\pi}} e^{-\frac{(x - \theta)^2}{2}} \cdot (x - \theta) = 0 \end{aligned}$$

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Typical Example

- Suppose $X_1, \dots, X_n \stackrel{iid}{\sim} \mathcal{N}(\theta, 1)$. What is the MLE of θ ?
- We want

$$\begin{aligned} & \frac{\partial}{\partial \theta} \frac{1}{(2\pi)^{\frac{n}{2}}} e^{-\frac{1}{2} \sum_{i=1}^n (x_i - \theta)^2} \\ &= \frac{1}{(2\pi)^{\frac{n}{2}}} e^{-\frac{1}{2} \sum_{i=1}^n (x_i - \theta)^2} \cdot \left(-\sum_{i=1}^n x_i - \theta \right) \\ &= \frac{1}{(2\pi)^{\frac{n}{2}}} e^{-\frac{1}{2} \sum_{i=1}^n (x_i - \theta)^2} \cdot \left(n\theta - \sum_{i=1}^n x_i \right) = 0 \end{aligned}$$

Typical Example

Clearly, to have

$$\frac{1}{(2\pi)^{\frac{n}{2}}} e^{-\frac{1}{2} \sum_{i=1}^n (x_i - \theta)^2} \cdot \left(n\theta - \sum_{i=1}^n x_i \right) = 0$$

we must have

$$\begin{aligned} \left(n\theta - \sum_{i=1}^n x_i \right) &= 0 \\ \implies \theta &= \frac{1}{n} \sum_{i=1}^n x_i = \bar{x} \end{aligned}$$

The End