3027020 - Noah Kuntner - Bemacs

Starting off I import numpy, torch, torchvision and through torchvision I am able to access the data of the CIFAR10-dataset.

Additionally, I use torch's linear functional and nn and matplotlib.pyplot for plotting purposes.

```
In [3]: import numpy as np
               import torch
               import torchvision
               import torchvision.transforms as transforms
               import torch.nn.functional as F
               import torch.nn as nn
               import matplotlib.pyplot as plt
               # Import transforms' use is typical for Pytorch
               transform = transforms.Compose([transforms.ToTensor(),
                        transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5))])
               trainset = torchvision.datasets.CIFAR10(root="C:/Users/noah /Thesis/Pytorch", trainset = torchvision.datasets.CIFAR10(root="C:/Users/noah /Thesis/Pytorch")
                                                                                         download=False, transform=transform)
               trainloader = torch.utils.data.DataLoader(trainset, batch size=4,
                                                                                             shuffle=True, num workers=2)
               testset = torchvision.datasets.CIFAR10(root="C:/Users/noah /Thesis/Pytorch", trai
                                                                                       download=False, transform=transform)
               testloader = torch.utils.data.DataLoader(testset, batch size=4,
                                                                                           shuffle=False, num workers=2)
               classes = ("plane", "car", "bird", "cat", "deer", "dog", "frog", "horse", "ship"]
```

Plotting through Matplotlib the various predicted labels of random iterations.

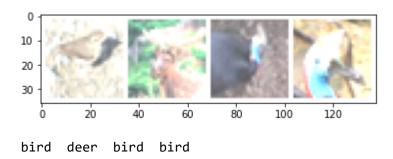
```
In [4]: def imshow(img):
    img = img / 1.5 + 1
    npimg = img.numpy()
    plt.imshow(np.transpose(npimg, (1, 2, 0)))
    plt.show()

# iterating over the data
dataiter = iter(trainloader)
images, labels = dataiter.next()

#create the grid
imshow(torchvision.utils.make_grid(images))
#print out the images with its respective labels based on the
#previously assigned classes

print("".join("%5s " % classes[labels[j]] for j in range(4)))
```

Clipping input data to the valid range for imshow with RGB data ([0..1] for flo ats or [0..255] for integers).



Building the convolutional neural network:

```
In [5]: class Net(nn.Module):
            def __init__(self):
                super(Net, self).__init__()
                #creation of the Convolutional Layer
                self.conv1 = nn.Conv2d(3, 6, 5)
                self.pool = nn.MaxPool2d(2, 2)
                self.conv2 = nn.Conv2d(6, 16, 5)
                self.pool = nn.MaxPool2d(2, 2)
                self.fc1 = nn.Linear(16 * 5 * 5, 120)
                self.fc2 = nn.Linear(120, 84)
                self.fc3 = nn.Linear(84, 84)
                self.fc4 = nn.Linear(84, 10)
            def forward(self, x):
                # forwarding part of the neural network; using self.pool()
                # the above parts of teh module are being called in conjuction with
                # rectifier linear unit and the linear functional
                x = self.pool(F.relu(self.conv1(x)))
                x = self.pool(F.relu(self.conv2(x)))
                x = x.view(-1, 16 * 5 * 5)
                # Rectifier linear unit
                x = F.relu(self.fc1(x))
                x = F.relu(self.fc2(x))
                x = F.relu(self.fc3(x))
                x = self.fc4(x)
                return x
        net = Net()
```

Now one may train the model:

```
In [6]: import torch.optim as optim
        # Using CrossEntropy and defining optimizer through the imported torch.optim
        criterion = nn.CrossEntropyLoss()
        optimizer = optim.SGD(net.parameters(), lr=0.001, momentum=0.9)
        for epoch in range(2):
            running loss = 0.0
            for i, data in enumerate(trainloader, 0):
                #obtaining all the inputs of the training data
                inputs, labels = data
                # using zero_grad() to set to null al parameter gradients
                optimizer.zero_grad()
                #output the loss backward to be able to analyze the logic
                outputs = net(inputs)
                loss = criterion(outputs, labels)
                loss.backward()
                optimizer.step()
                running loss += loss.item()
                if i % 2000 == 1999:
                                        # print every 2000 mini-batches
                    print("[%d, %5d] loss: %.3f" %
                          (epoch + 1, i + 1, running_loss / 2000))
                    running_loss = 0.0
        print("Training done")
```

```
[1, 2000] loss: 2.302
[1, 4000] loss: 2.162
[1, 6000] loss: 1.832
[1, 8000] loss: 1.680
[1, 10000] loss: 1.592
[1, 12000] loss: 1.517
[2, 2000] loss: 1.465
[2, 4000] loss: 1.440
[2, 6000] loss: 1.370
[2, 10000] loss: 1.349
[2, 12000] loss: 1.321
Training done
```

Now one may test the model's performance

Accuracy of the network on the 10000 test images: 53.35%

```
In [ ]:
```