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Maximum Mobility and Manipulation (M3) (Archived)

Robots hold great promise for amplifying human effectiveness in Defense operations. Compared to human beings and animals, however, the mobility and manipulation capability of present day robots is poor. In addition, design and manufacturing of current robotic systems are time consuming, and fabrication costs remain high. If these limitations were overcome, robots could assist in the execution of military operations far more effectively across a

The Maximum Mobility and Manipulation (M3) program is striving to create and demonstrate significant scientific and engineering advances in robotics that will:

- · Create a significantly improved scientific framework for the rapid design and fabrication of robot systems and greatly enhance robot mobility and
- Significantly improve robot capabilities through fundamentally new approaches to the engineering of better design tools, fabrication methods, and
 control algorithms. The M3 program covers scientific advancement across four tracks: design tools, fabrication methodologies, control methods,
 and technology demonstration prototypes.

| Autonomy | Energy | Robotics |

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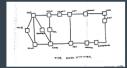
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