

Unitree application

basic skills

 $\label{eq:Real-time} \textit{Real-time image transmission, visual tracking, SLAM navigation, 3D simulation control}$

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Analog controls

Used to familiarize yourself with the basic manipulation of the robot

A1 and Aliengo models can be switched

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object tracking

Machine Vision, Lock Tracking

People or things can be framed

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depth camera

Depth perspective, knowing far and near

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human identification

Dog's eyes also know people

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SLAM navigation

Used to familiarize yourself with the basic manipulation of the robot

Automatic map building, where to go

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iOS version (beta)

The iOS version needs to install TestFlight first Install TestFlight to get the beta version

Go1 installation link

Android version (beta)

The Android test version can be downloaded from the link below After downloading, you need to unzip and install it yourself

Go1 installation link

 Unitree
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The target Aliengo battery 4D LiDAR L1

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