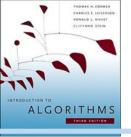


Introduction to Algorithms 11. Augmenting Data Structures

Hyungsoo Jung





Dynamic order statistics

OS-Select(i, S): returns the ith smallest element in the

dynamic set *S*.

OS-RANK(x, S): returns the rank of $x \in S$ in the sorted

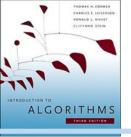
order of 5's elements.

IDEA: Use a red-black tree for the set *S*, but keep subtree sizes in the nodes.

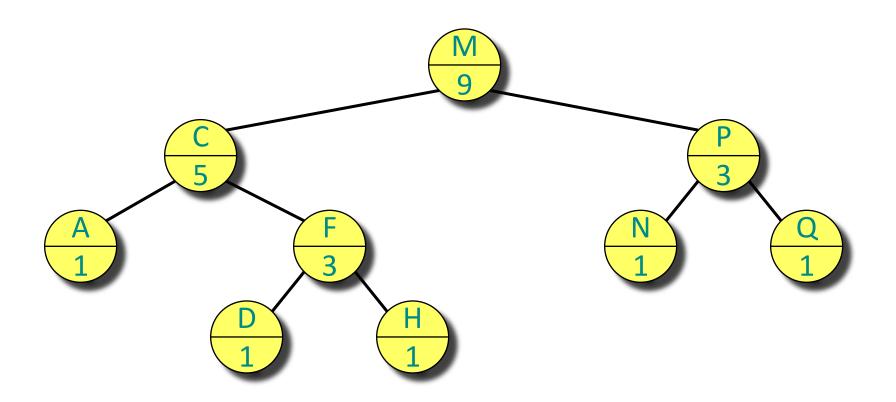
Notation for nodes:





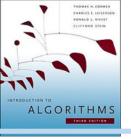


Example of an OS-tree



size[x] = size[left[x]] + size[right[x]] + 1

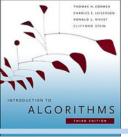




Selection

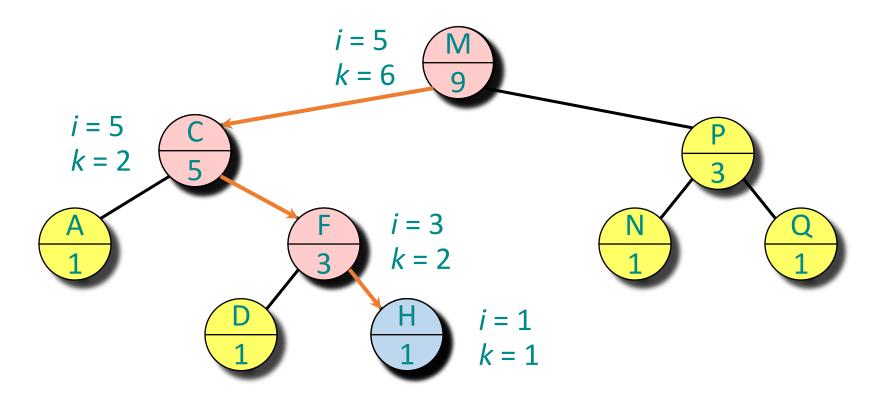
```
Implementation trick: Use a sentinel (dummy record)
for NIL such that size[NIL] = 0.
  OS-Select(x, i) > ith smallest element in the
                       subtree rooted at x
     k \leftarrow size[left[x]] + 1 \triangleright k = rank(x)
     if i = k then return x
     if i < k
        then return OS-SELECT(left[x], i)
        else return OS-SELECT(right[x], i-k)
  (OS-RANK is in the textbook.)
```





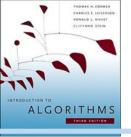
Example

OS-SELECT(root, 5)



Running time = $O(h) = O(\lg n)$ for red-black trees.





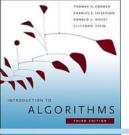
Data structure maintenance

- Q. Why not keep the ranks themselves in the nodes instead of subtree sizes?
- A. They are hard to maintain when the red-black tree is modified.

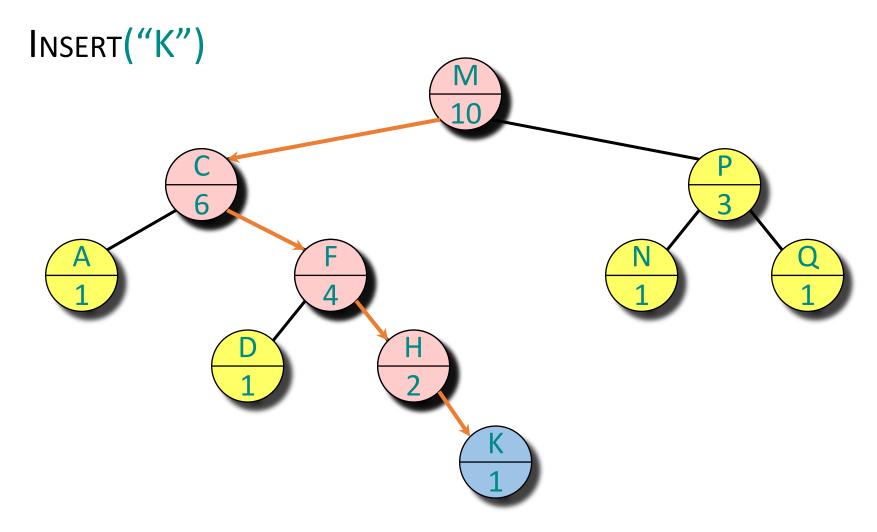
Modifying operations: INSERT and DELETE.

Strategy: Update subtree sizes when inserting or deleting.

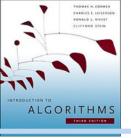




Example of insertion



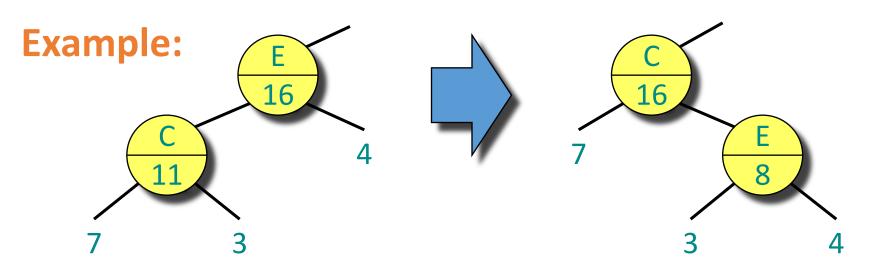




Handling rebalancing

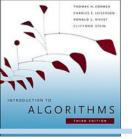
Don't forget that RB-INSERT and RB-DELETE may also need to modify the red-black tree in order to maintain balance.

- Recolorings: no effect on subtree sizes.
- Rotations: fix up subtree sizes in O(1) time.



 \therefore RB-Insert and RB-Delete still run in $O(\lg n)$ time.





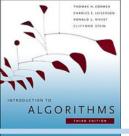
Data-structure augmentation

Methodology: (e.g., order-statistics trees)

- 1. Choose an underlying data structure (red-black trees).
- 2. Determine additional information to be stored in the data structure (*subtree sizes*).
- 3. Verify that this information can be maintained for modifying operations (*RB-INSERT*, *RB-DELETE don't forget rotatio ns*).
- 4. Develop new dynamic-set operations that use the inform ation (OS-SELECT and OS-RANK).

These steps are guidelines, not rigid rules.





Interval trees

Goal: To maintain a dynamic set of intervals, such as time intervals.

$$i = [7, 10]$$

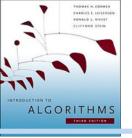
$$low[i] = 7 \longrightarrow 10 = high[i]$$

$$5 \longrightarrow 11 \qquad 17 \longrightarrow 19$$

$$4 \longrightarrow 8 \qquad 15 \longrightarrow 18 \quad 22 \longrightarrow 23$$

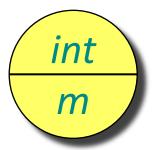
Query: For a given query interval *i*, find an interval in the set that overlaps *i*.



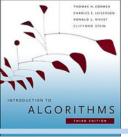


Following the methodology

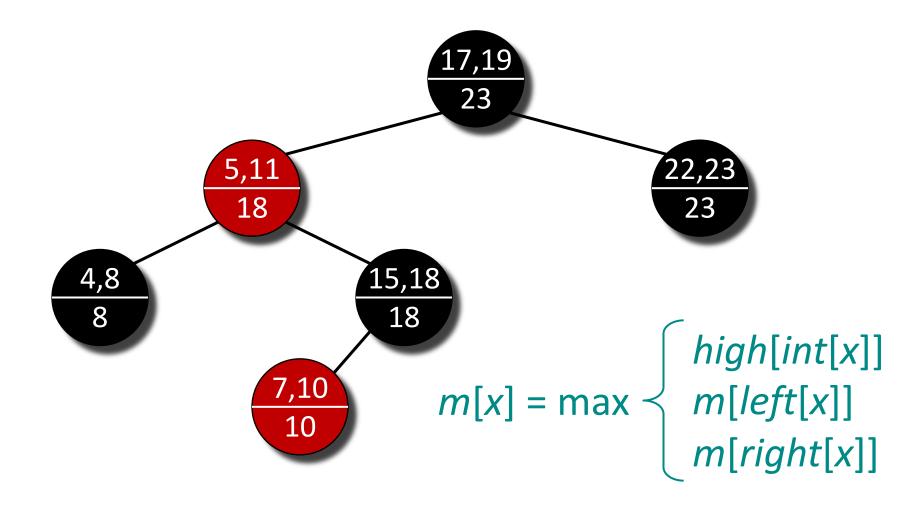
- 1. Choose an underlying data structure.
 - Red-black tree keyed on low (left) endpoint.
- 2. Determine additional information to be stored in the data structure.
 - Store in each node x the largest value m[x] in the subtree rooted at x, as well as the interval int[x] corresponding to the key.



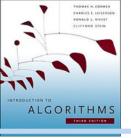




Example interval tree

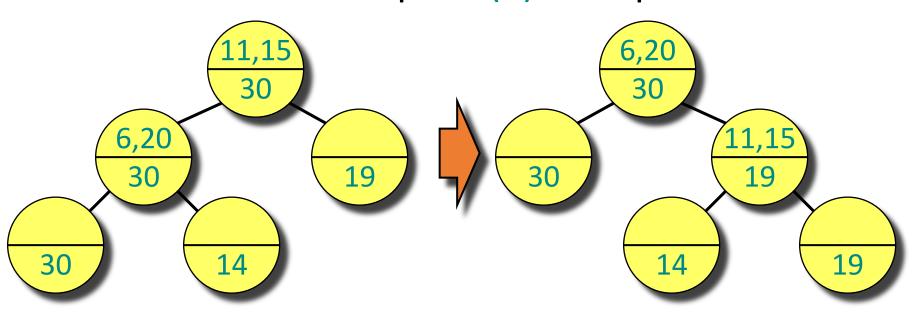






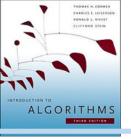
Modifying operations

- 3. Verify that this information can be maintained for modifying operations.
 - INSERT: Fix m's on the way down.
 - Rotations Fixup = O(1) time per rotation:



Total Insert time = $O(\lg n)$; Delete similar.



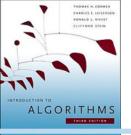


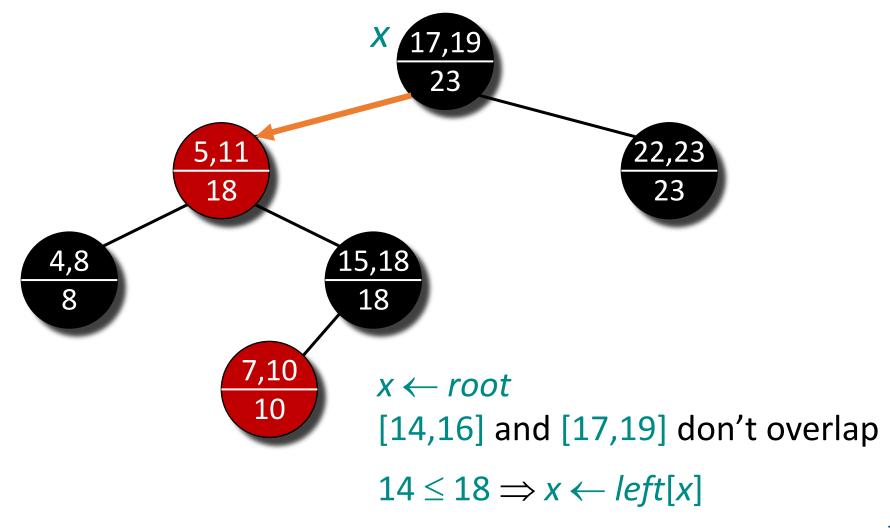
New operations

4. Develop new dynamic-set operations that use the information.

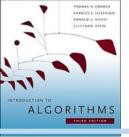
```
INTERVAL-SEARCH(i)
    x \leftarrow root
    while x \neq NIL and (low[i] > high[int[x]])
                             or low[int[x]] > high[i]
       do \triangleright i and int[x] don't overlap
            if left[x] \neq NIL and low[i] \leq m[left[x]]
                then x \leftarrow left[x]
                else x \leftarrow right[x]
    return x
```

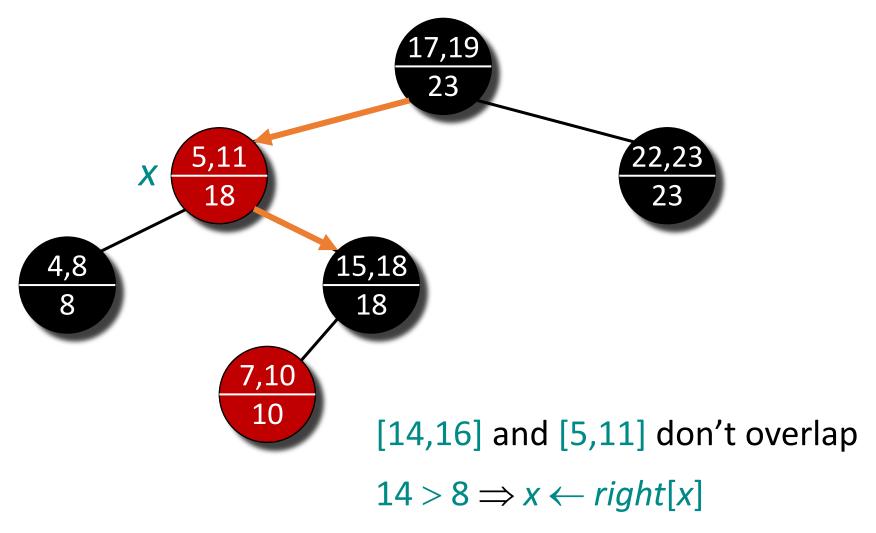




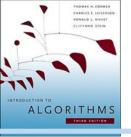


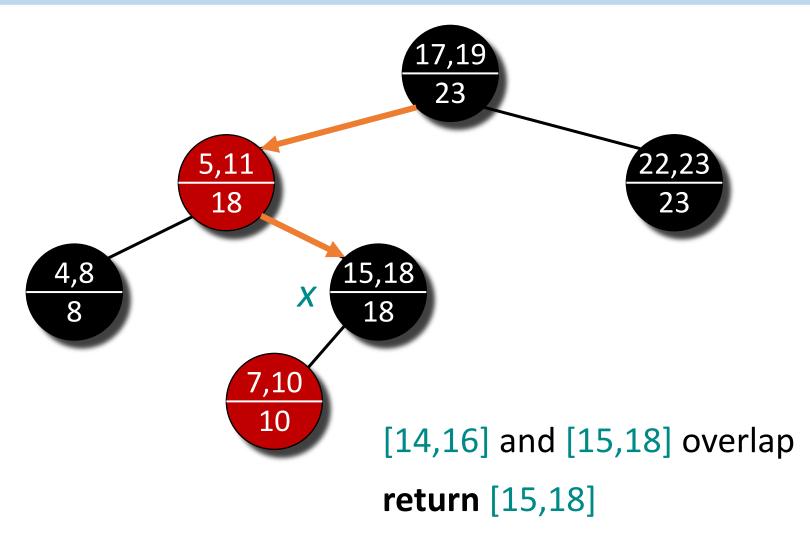




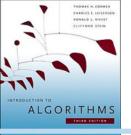


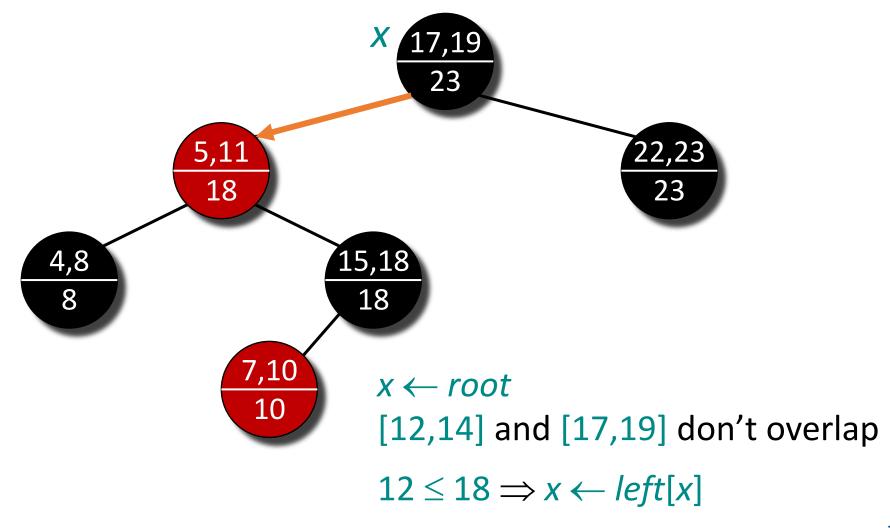




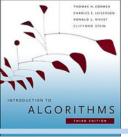


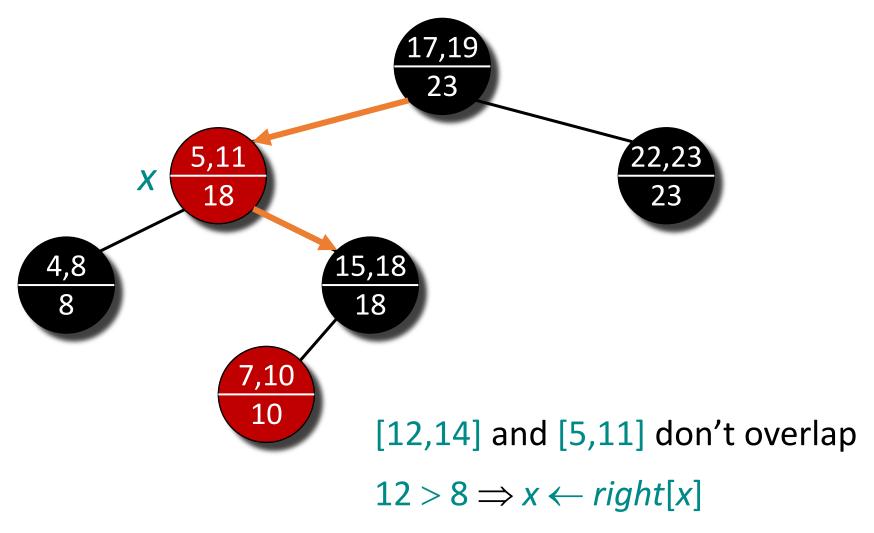




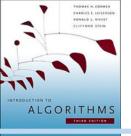


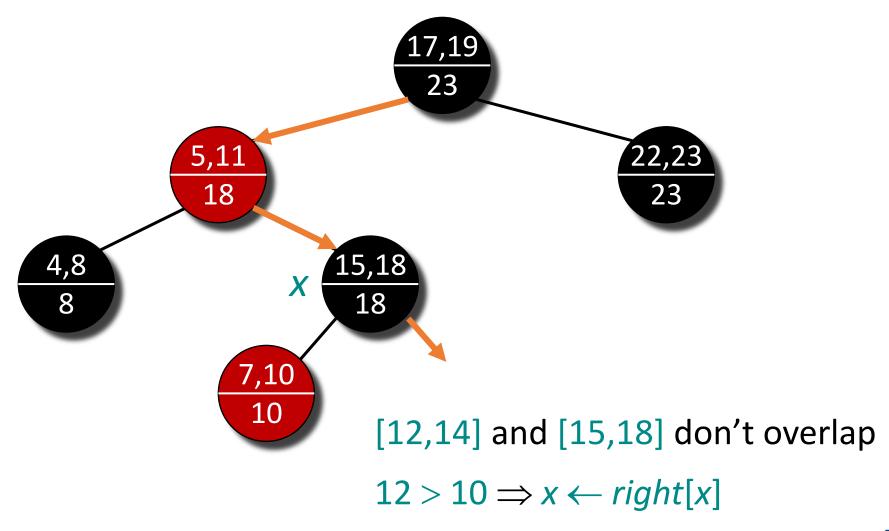




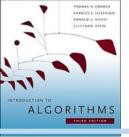


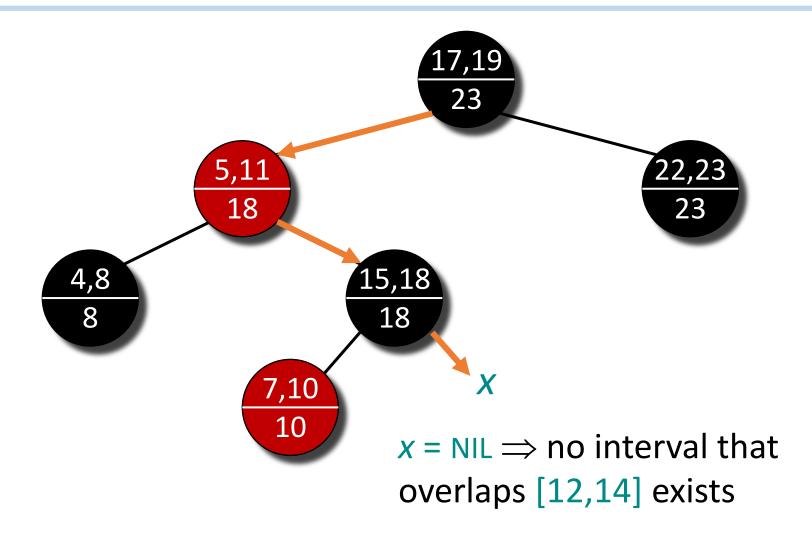




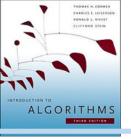












Analysis

Time = O(h) = $O(\lg n)$, since Interval-Search does constant work at each level as it follows a simple path down the tree.

List *all* overlapping intervals:

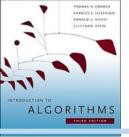
- Search, list, delete, repeat.
- Insert them all again at the end.

Time = $O(k \lg n)$, where k is the total number of overlapping intervals.

This is an *output-sensitive* bound.

Best algorithm to date: $O(k + \lg n)$.





Correctness

Theorem. Let L be the set of intervals in the left subtree of node x, and let R be the set of intervals in x's right subtree.

If the search goes right, then

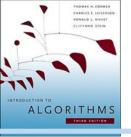
```
\{i' \in L : i' \text{ overlaps } i\} = \emptyset.
```

If the search goes left, then

```
\{i' \in L : i' \text{ overlaps } i\} = \emptyset
\Rightarrow \{i' \in R : i' \text{ overlaps } i\} = \emptyset.
```

In other words, it's always safe to take only 1 of the 2 children: we'll either find something, or nothing was to be found.





Correctness proof

Proof. Suppose first that the search goes right.

- If left[x] = NIL, then we're done, since $L = \emptyset$.
- Otherwise, the code dictates that we must have low[i] > m[left[x]]. The value m[left[x]] corresponds to the high endpoint of some interval $j \in L$, and no other interval in L can have a larger high endpoint than high[j].

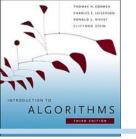
$$high[j] = m[left[x]]$$

$$i$$

$$low(i)$$

• Therefore, $\{i' \in L : i' \text{ overlaps } i\} = \emptyset$.

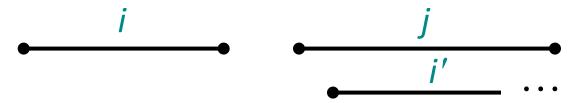




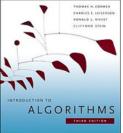
Proof (continued)

Suppose that the search goes left, and assume that $\{i' \in L : i' \text{ overlaps } i\} = \emptyset$.

- Then, the code dictates that $low[i] \le m[left[x]] = high[j]$ for some $j \in L$.
- Since $j \in L$, it does not overlap i, and hence high[i] < low[j].
- But, the binary-search-tree property implies that for all $i' \in R$, we have $low[j] \le low[i']$.
- But then $\{i' \in R : i' \text{ overlaps } i\} = \emptyset$.







Thank You

