

On the Ability of Graph Neural Networks to Model Interactions Between Vertices

Noam Razin

Joint work with Tom Verbin & Nadav Cohen

Tel Aviv University



Learning on Graphs and Geometry Reading Group

16 January 2023

Outline

- 1 Expressivity in Graph Neural Networks (GNNs)
- 2 Theory: Quantifying Ability of GNNs to Model Interactions
 - Formalizing Interaction via Separation Rank
 - Analyzed GNN Architecture
 - Characterizing Strength of Modeled Interaction
- 3 Application: Expressivity Preserving Edge Sparsification
- 4 Conclusion

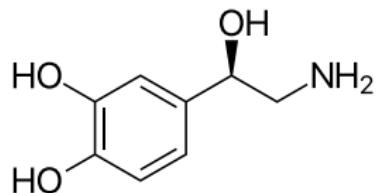
Graph Neural Networks (GNNs)

Neural networks purposed for modeling interactions over graph data

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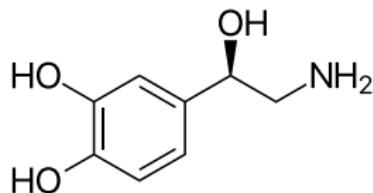
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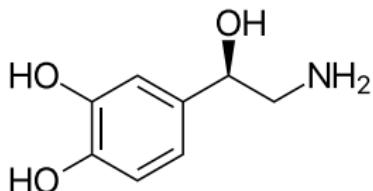
- Social networks — vertex prediction



Graph Neural Networks (GNNs)

Neural networks purposed for modeling interactions over graph data

- Molecular data — graph prediction



- Social networks — vertex prediction



- Many more applications: recommender systems, ETA prediction,...

Mathematical Theory of GNNs

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Challenge

Develop mathematical theory for GNNs

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Fundamental Question

Expressivity: which functions can GNNs realize?

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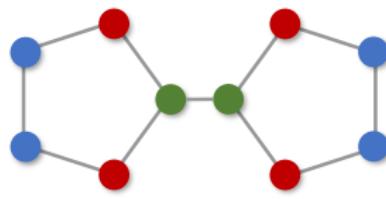
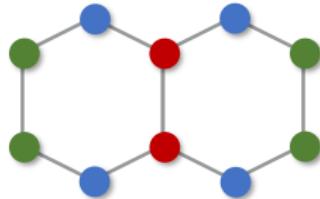
*functions **practically sized** GNNs can realize*

Existing Analyses of Expressivity

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(1) Ability to distinguish non-isomorphic graphs

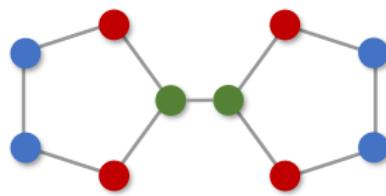
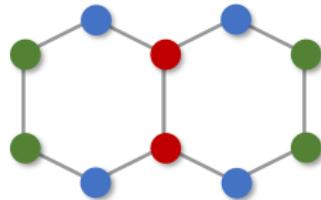
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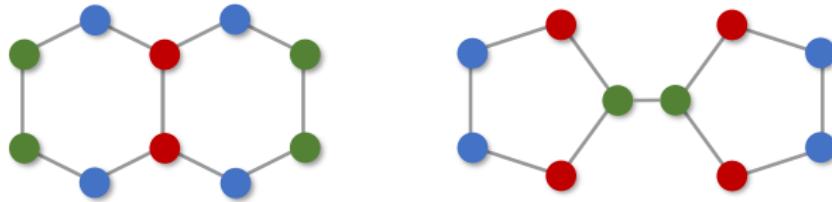
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(3) Computability of graph properties: shortest paths, diameter,...

(e.g. Dehmany et al. 2019, Garg et al. 2020, Loukas 2020, Chen et al. 2020)

Limitations of Existing Analyses

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Question

How do graph structure and GNN architecture affect interactions?

Promo: Our Contributions

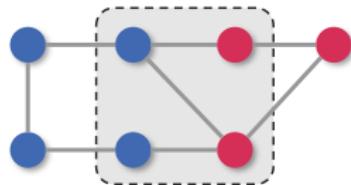
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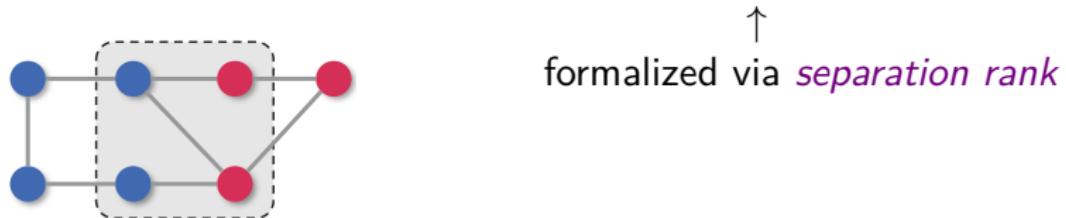
Characterize ability of certain GNNs to model interactions between vertices



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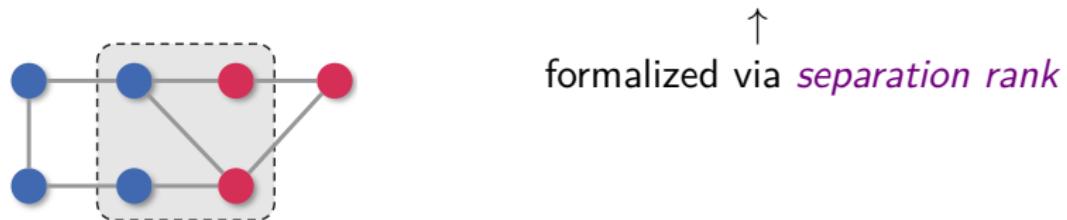
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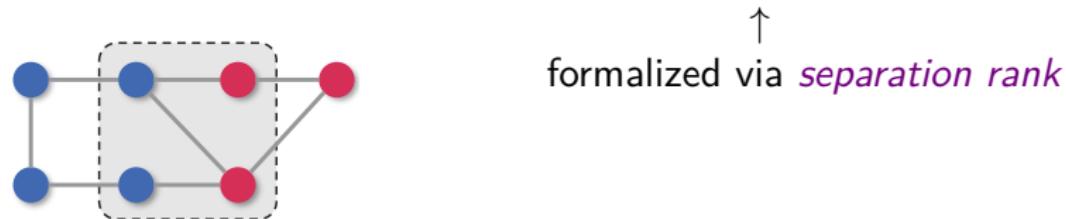


Practical Application

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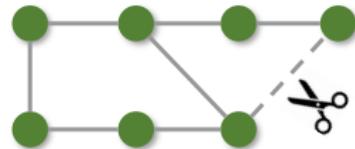
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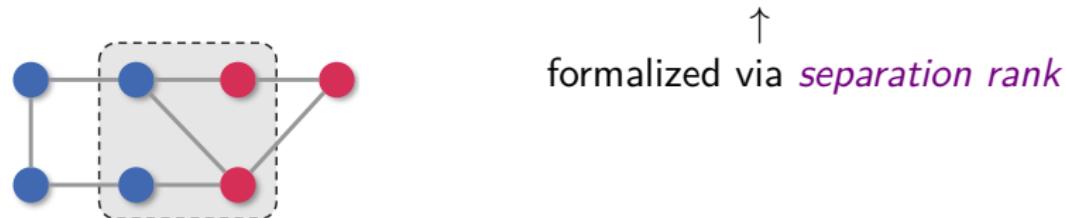
Use theory to derive an *edge sparsification* method preserving interactions



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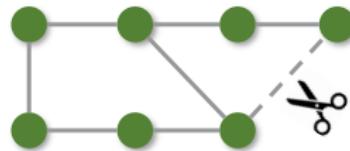
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It is simple, efficient, and outperforms alternative methods

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Known measure for interaction modeled across partition of input variables

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Let $f : (\mathbb{R}^D)^N \rightarrow \mathbb{R}$ and subset of variables $\mathcal{I} \subseteq [N]$

$$f \left(\underbrace{\begin{array}{c|c} \text{---} & \text{---} \\ \text{---} & \text{---} \\ \text{---} & \text{---} \end{array}}_{X_{\mathcal{I}}} \cdots \underbrace{\begin{array}{c|c} \text{---} & \text{---} \\ \text{---} & \text{---} \\ \text{---} & \text{---} \end{array}}_{X_{\mathcal{I}^c}} \right)$$

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$$\text{sep}(f; \mathcal{I}) := \min R \text{ s.t. } f(X) = \sum_{r=1}^R g_r(X_{\mathcal{I}}) \cdot \bar{g}_r(X_{\mathcal{I}^c})$$

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Higher $\text{sep}(f; \mathcal{I}) \implies$ stronger interaction between $X_{\mathcal{I}}$ and $X_{\mathcal{I}^c}$

Usages of Separation Rank

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- Measure of entanglement in quantum mechanics

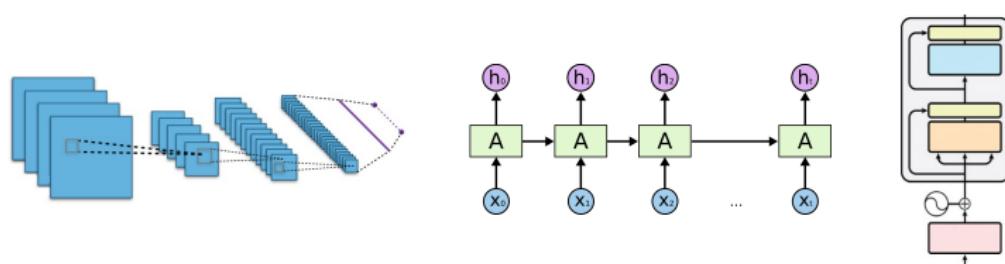


Usages of Separation Rank

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- Analyses of convolutional, recurrent, and self-attention NNs
(e.g. Cohen & Shashua 2017, Levine et al. 2018;2020, R et al. 2022)



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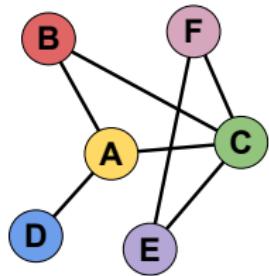
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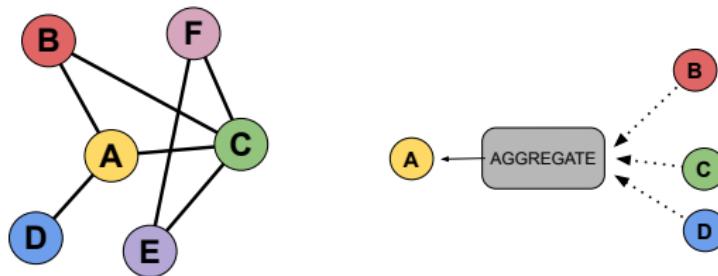
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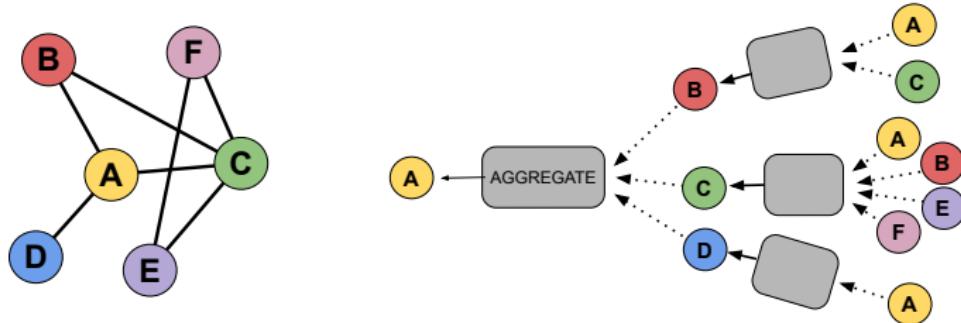
Inputs: graph $\mathcal{G} = (\mathcal{V}, \mathcal{E})$, vertex features $X = (x^{(1)}, \dots, x^{(|\mathcal{V}|)})$

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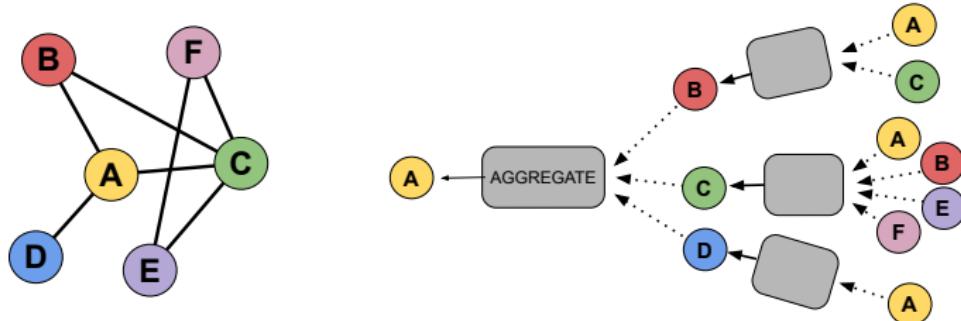
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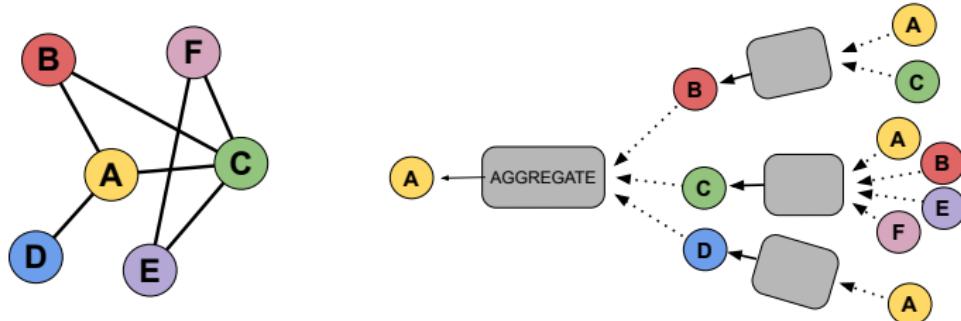
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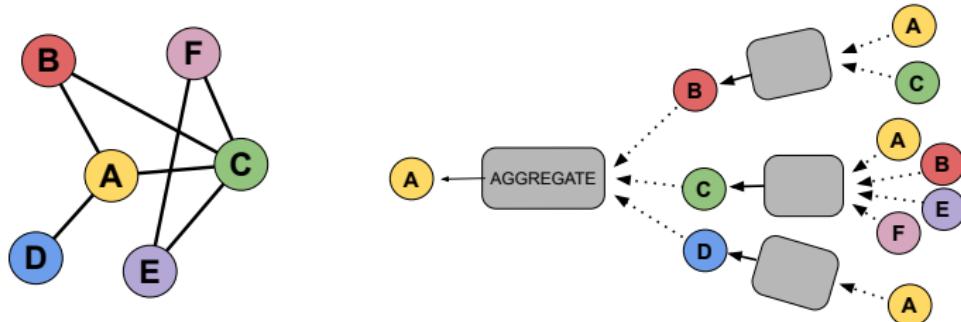


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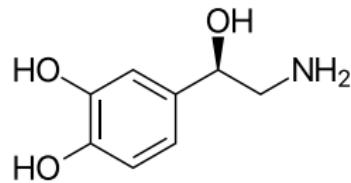
GNNs for Vertex vs Graph Prediction

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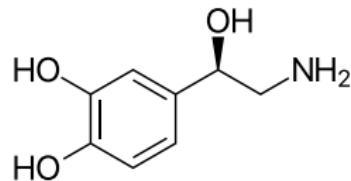
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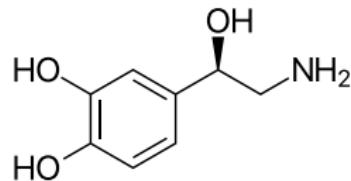


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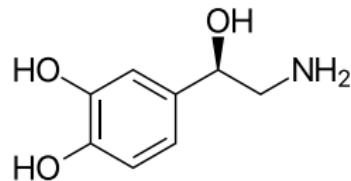
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Studying Modeled Interactions via Tensor Networks

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Prior work: study interactions for other NNs w/ polynomial non-linearity
(e.g. Cohen et al. 2016, Khrulkov et al. 2018, Levine et al. 2020, R et al. 2021;2022)

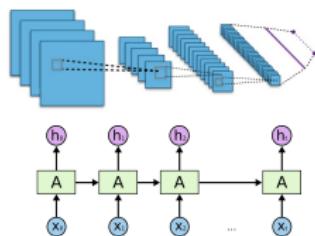
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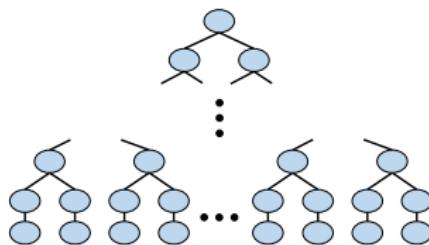
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Tensor networks



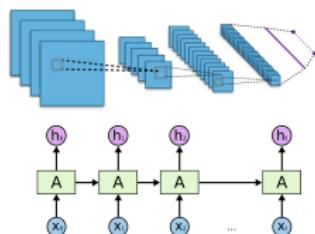
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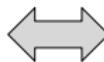
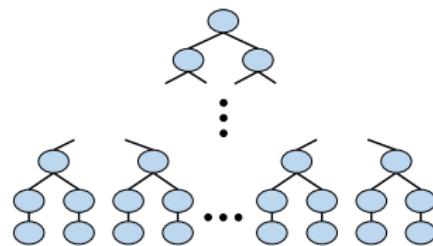
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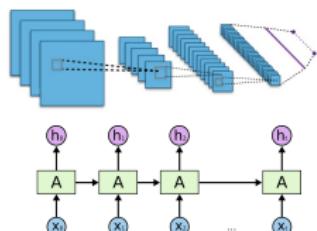
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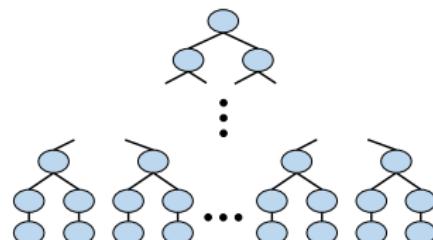
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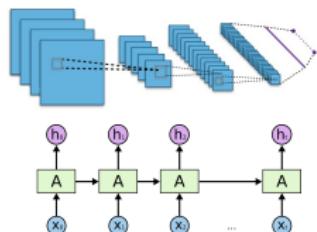
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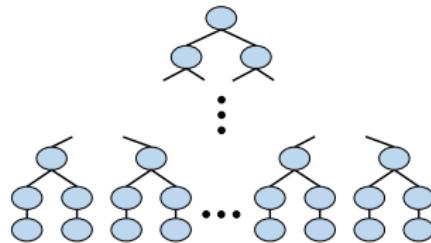
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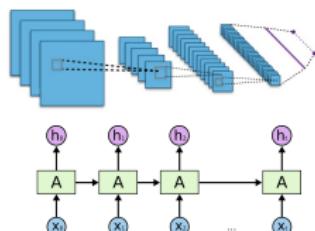
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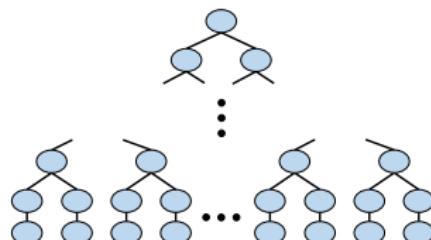
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- Insights and practical tools for more common models

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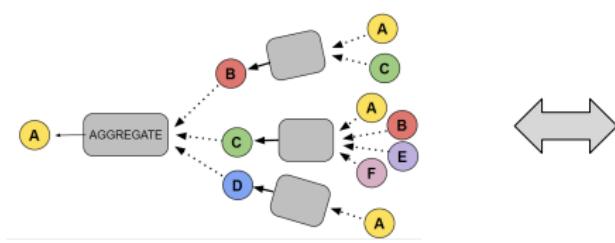
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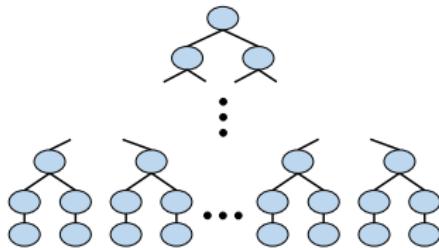
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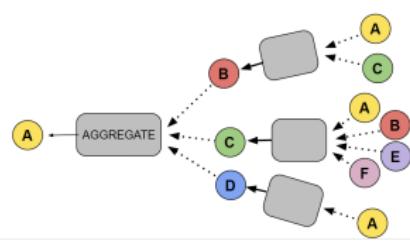


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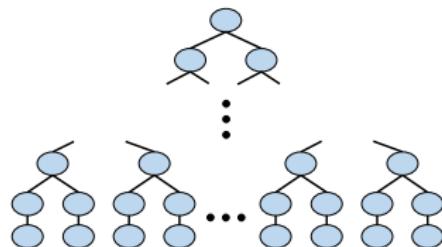
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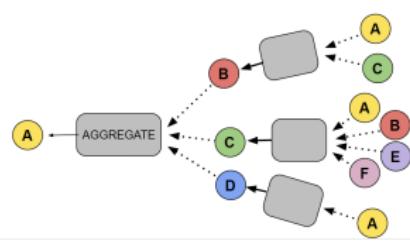
- Variant of the competitive Tensorized GNN (Hua et al. 2022)

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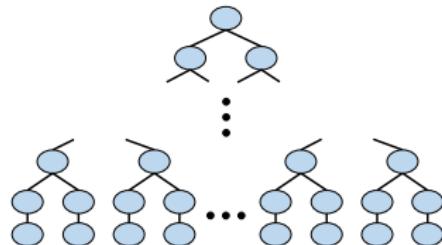
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GNNs w/ product aggregation



Tensor networks



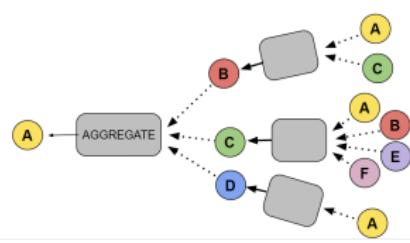
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GNNs With Product Aggregation

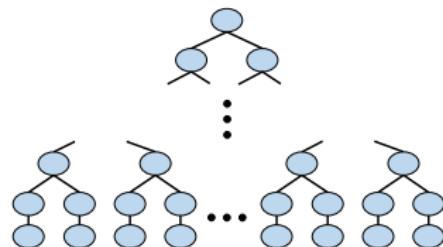
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- Based on theory: derive an **edge sparsification** algorithm

Outline

1 Expressivity in Graph Neural Networks (GNNs)

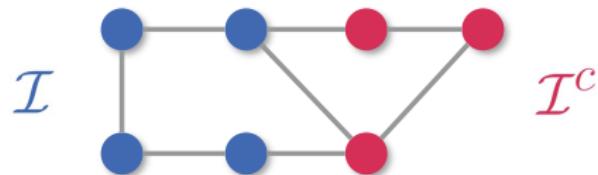
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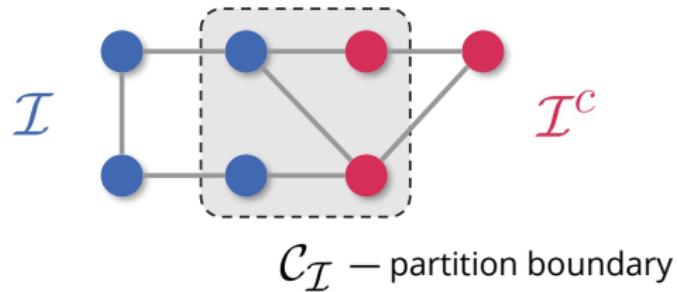
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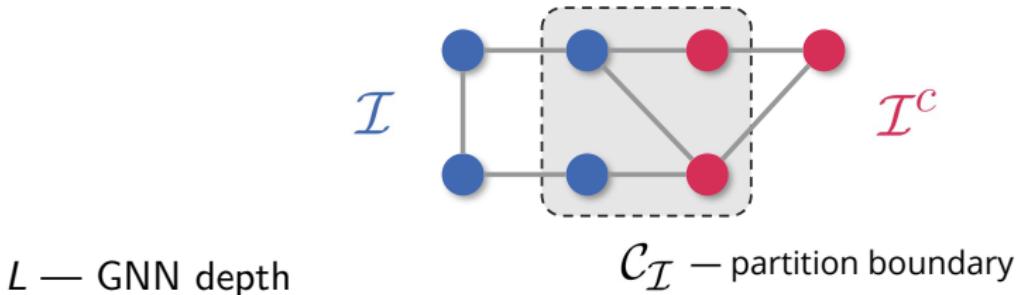
Walk Index (WI) of a Partition of Vertices



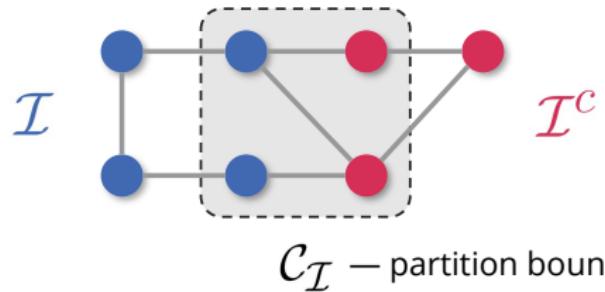
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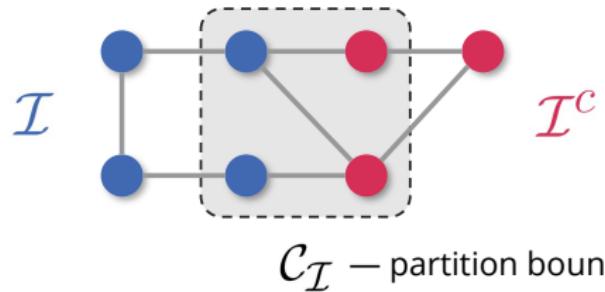
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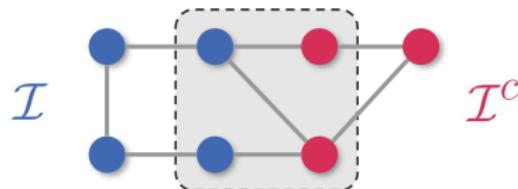
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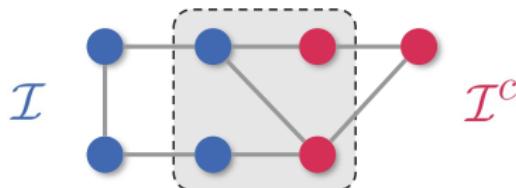


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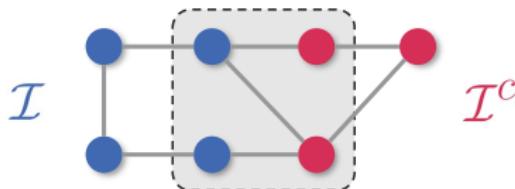
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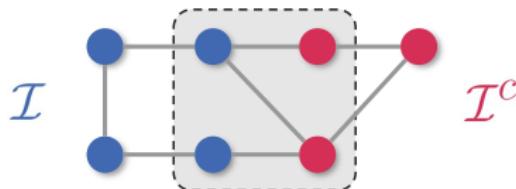
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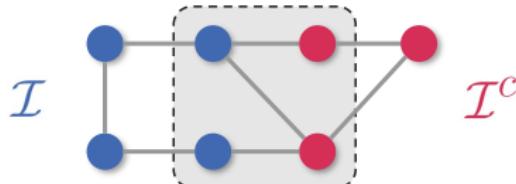
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Strength of interaction modeled across partition of vertices is determined by its walk index

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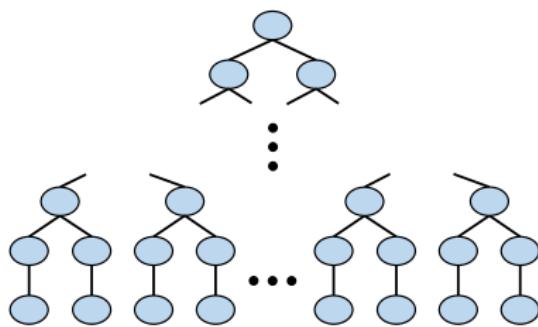
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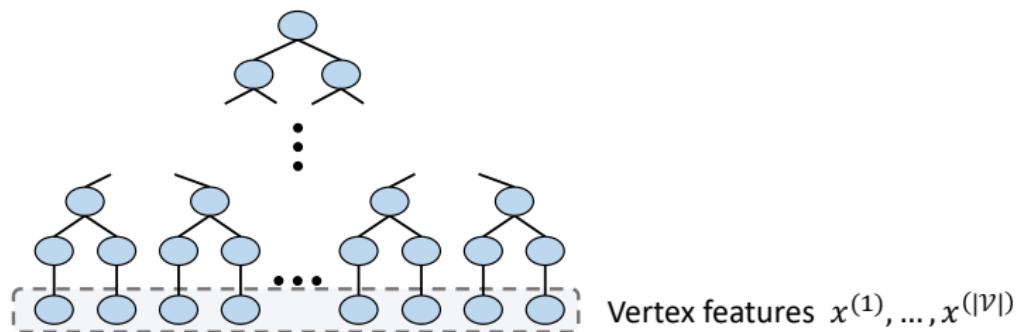


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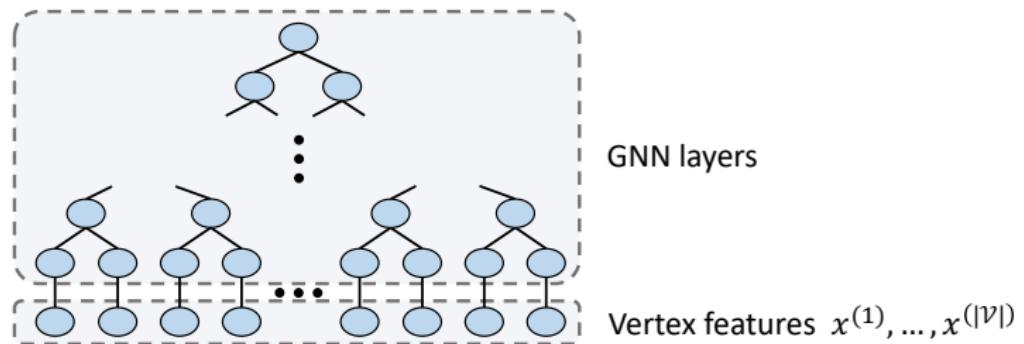


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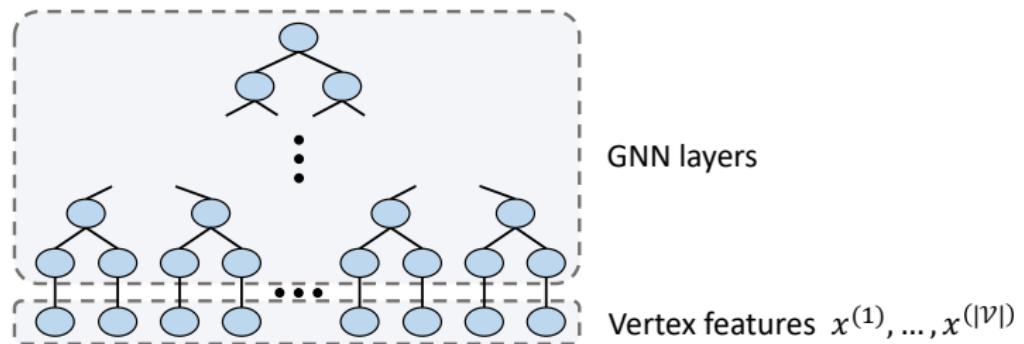


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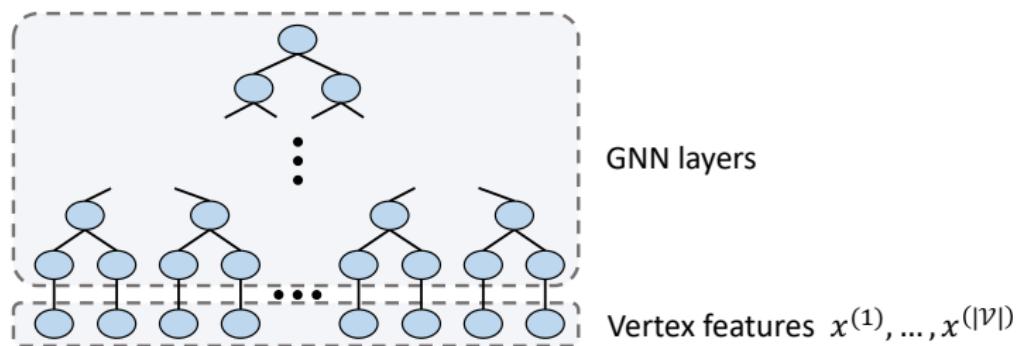
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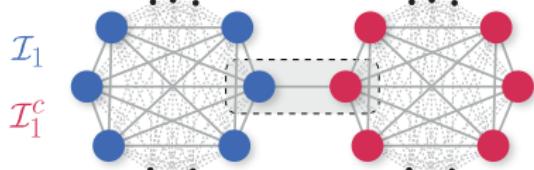
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↑
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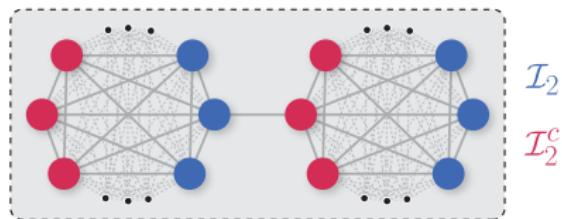
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low walk index

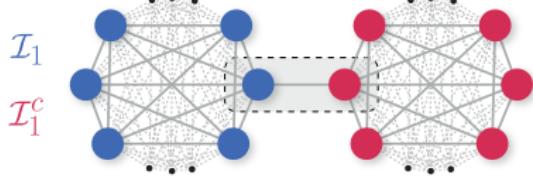


high walk index



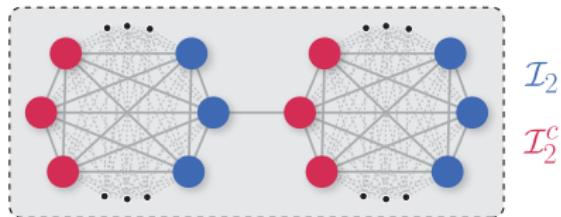
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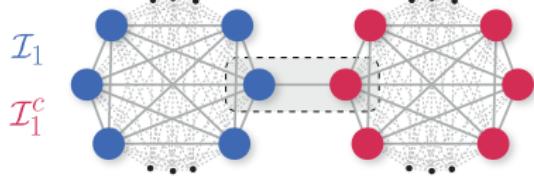
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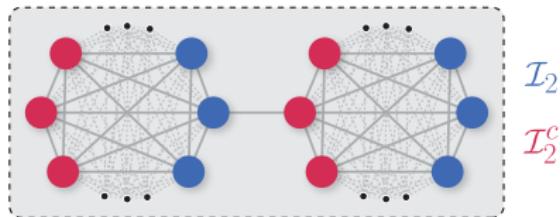
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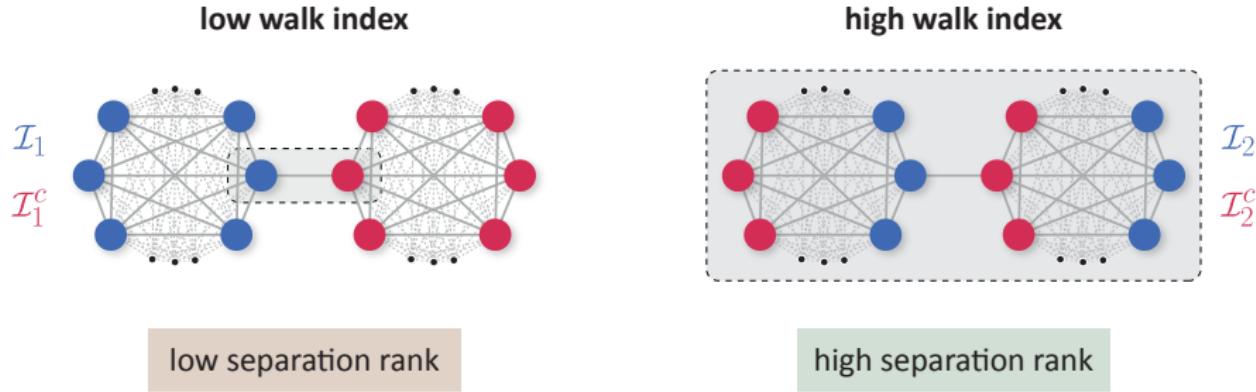
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GNNs can model stronger interactions across partitions with higher walk index

Implication of Main Result



GNNs can model stronger interactions across partitions with higher walk index

Formalizes intuition: more interconnected \implies stronger interaction

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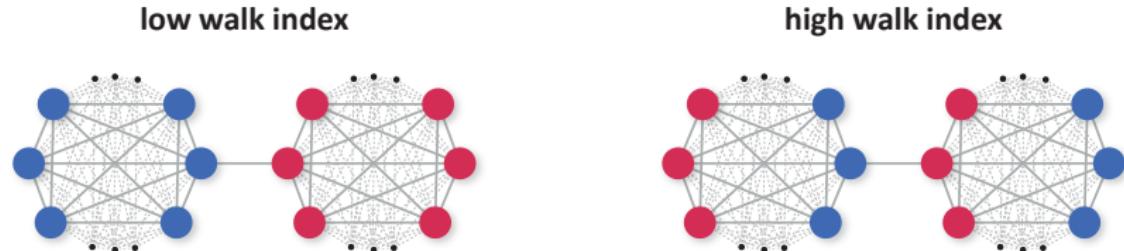
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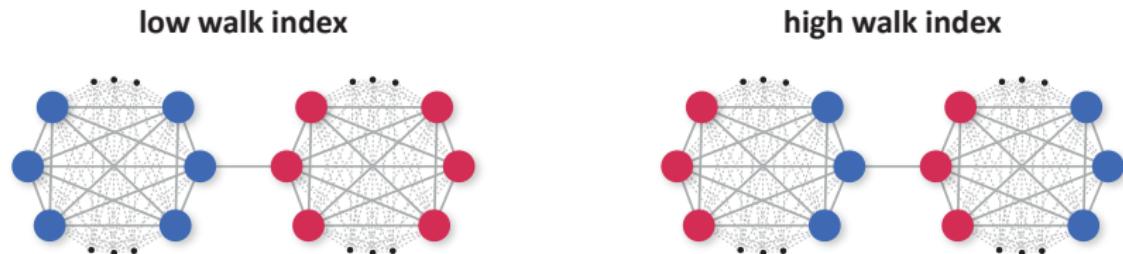
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blue vertices: patches of 1st image

red vertices: patches of 2nd image

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Experiment Results

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Experiment Results

		Partition Walk Index	
		Low	High
GCN	Train	70.4 ± 1.7	81.4 ± 2.0
	Test	52.7 ± 1.9	66.2 ± 1.1
GAT	Train	82.8 ± 2.6	88.5 ± 1.1
	Test	69.6 ± 0.6	72.1 ± 1.2
GIN	Train	83.2 ± 0.8	94.2 ± 0.8
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In accordance with our theory:

GNNs perform better on tasks entailing strong interactions across partitions with higher walk index

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Our theory \implies simple & effective recipe for pruning edges

General Walk Index Sparsification Scheme

Theory: walk index of $\mathcal{I} \subseteq \mathcal{V}$ key for modeling interaction across $\mathcal{I}, \mathcal{I}^c$

General Walk Index Sparsification Scheme

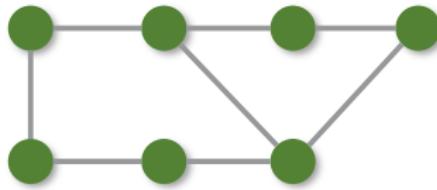
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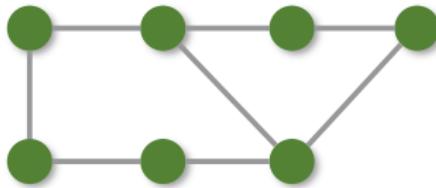
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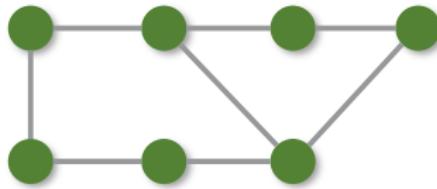


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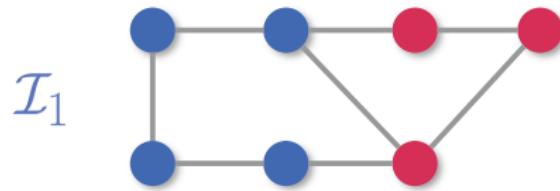
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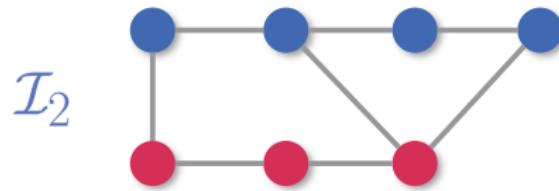
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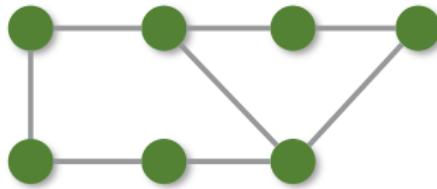
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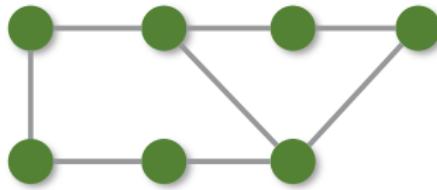
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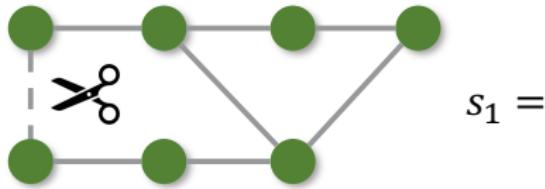
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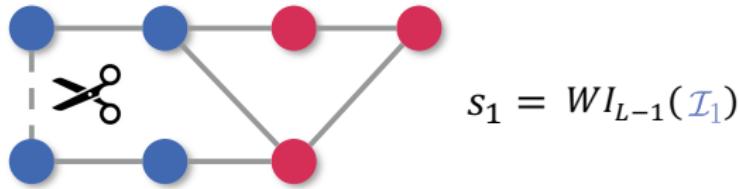
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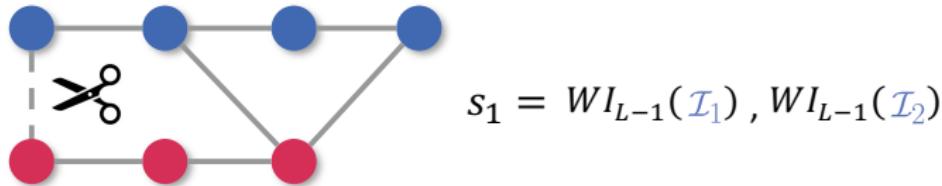
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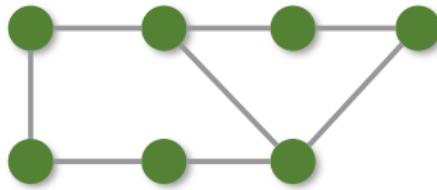
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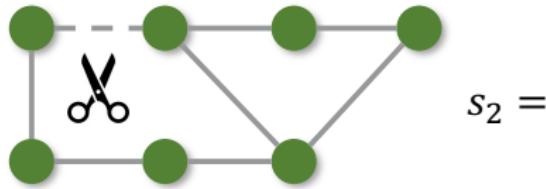
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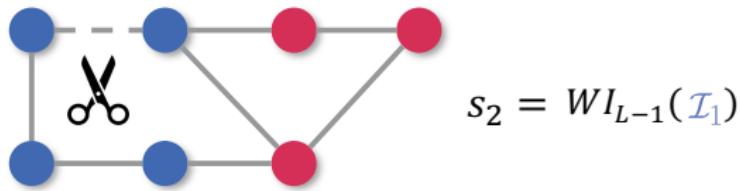
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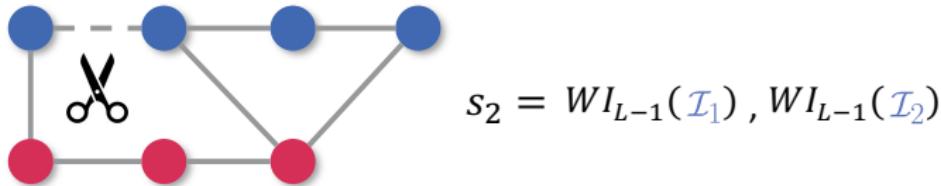
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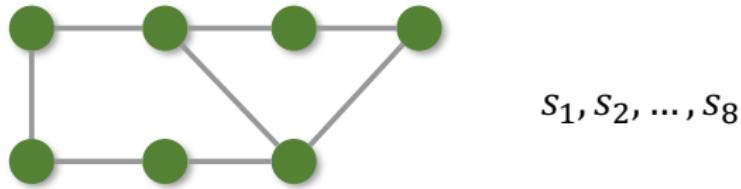
Algorithm: until desired # edges are removed:

- (1) Choose partitions $\mathcal{I}_1, \dots, \mathcal{I}_M$ to preserve modeled interactions for
- (2) Per edge, compute $(L - 1)$ -walk indices of $\mathcal{I}_1, \dots, \mathcal{I}_M$ after its removal

General Walk Index Sparsification Scheme

Theory: walk index of $\mathcal{I} \subseteq \mathcal{V}$ key for modeling interaction across $\mathcal{I}, \mathcal{I}^c$

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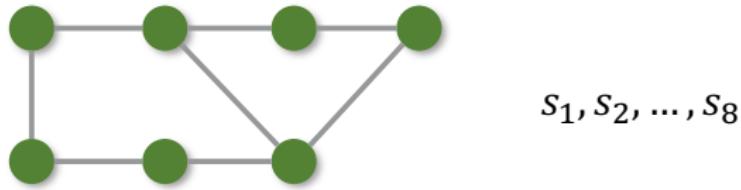
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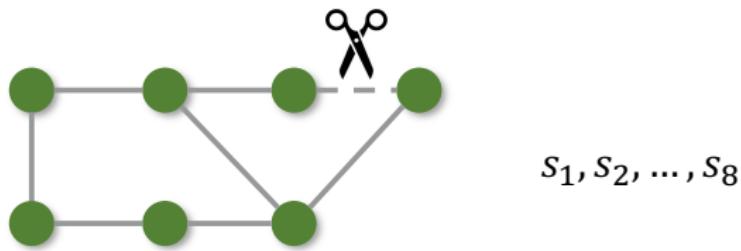
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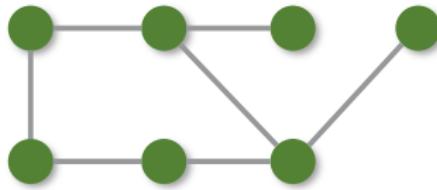
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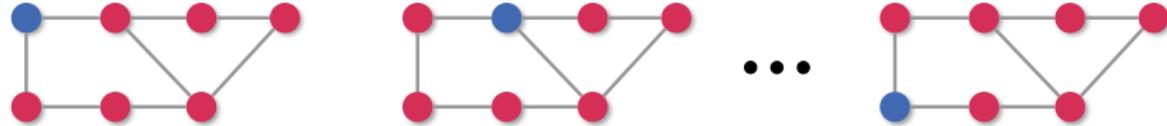
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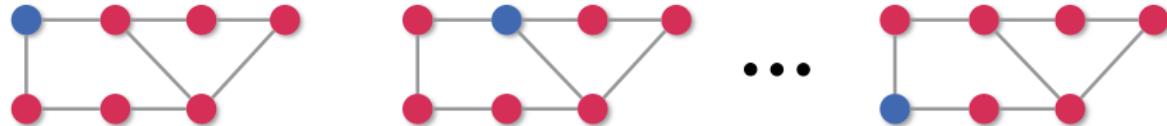


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- Order tuples by minimal entry, breaking ties using second smallest,...

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1-Walk Index Sparsification (1-WIS)

Particularly simple & efficient implementation

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(break ties via $\max\{\deg(i), \deg(j)\}$)

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Compare edge sparsification methods over standard benchmarks

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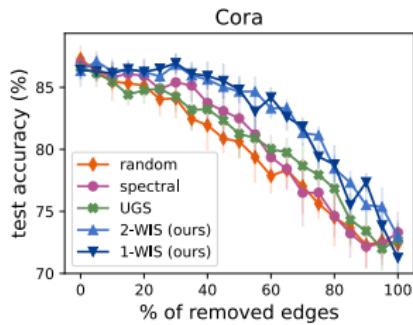
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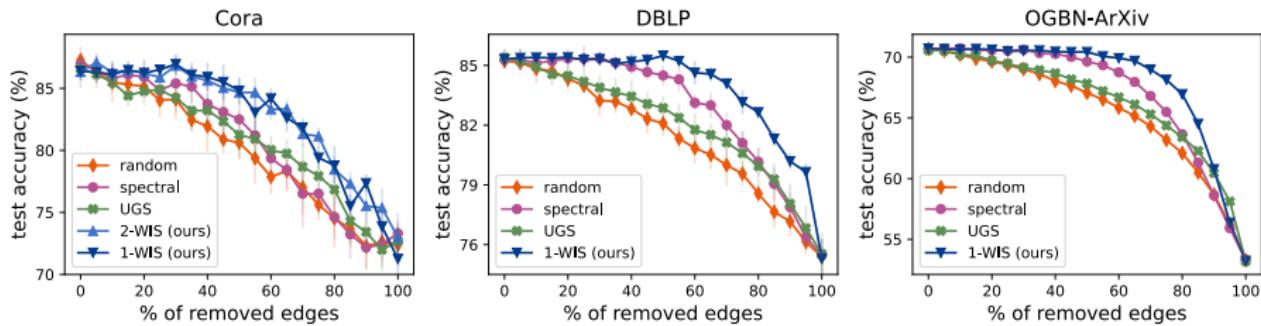
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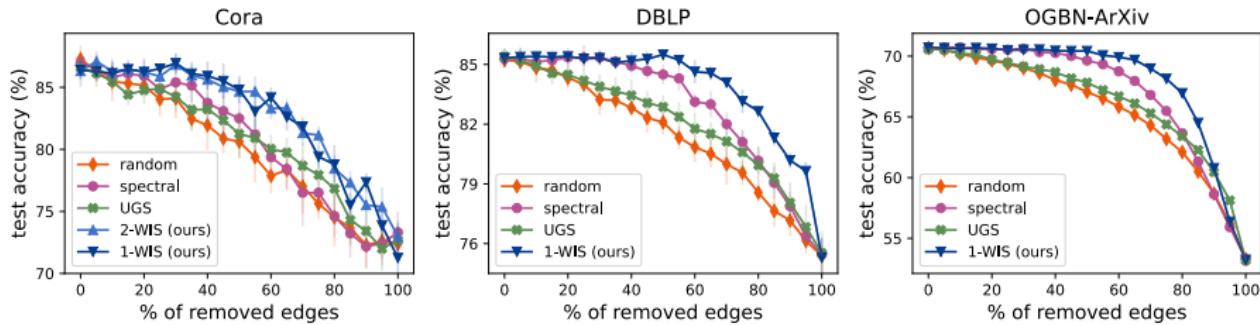
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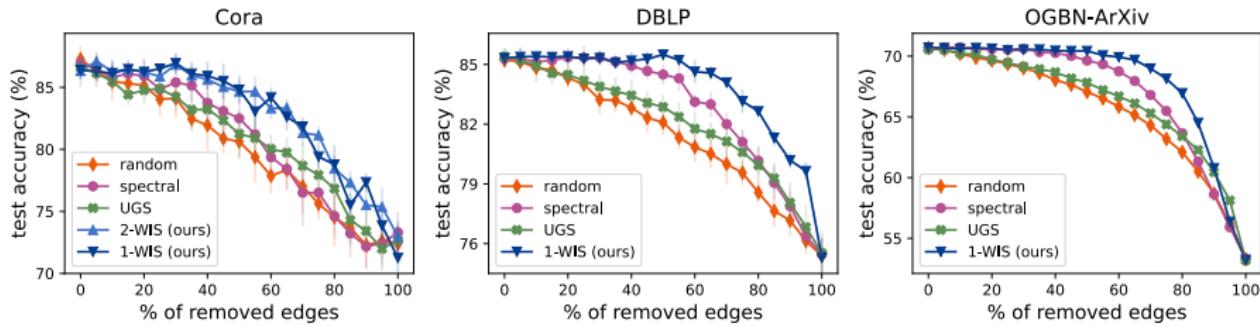
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Code: https://github.com/noamrazin/gnn_interactions

Outline

- 1 Expressivity in Graph Neural Networks (GNNs)
- 2 Theory: Quantifying Ability of GNNs to Model Interactions
 - Formalizing Interaction via Separation Rank
 - Analyzed GNN Architecture
 - Characterizing Strength of Modeled Interaction
- 3 Application: Expressivity Preserving Edge Sparsification
- 4 Conclusion

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- Improving performance of GNNs

Thank You!

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