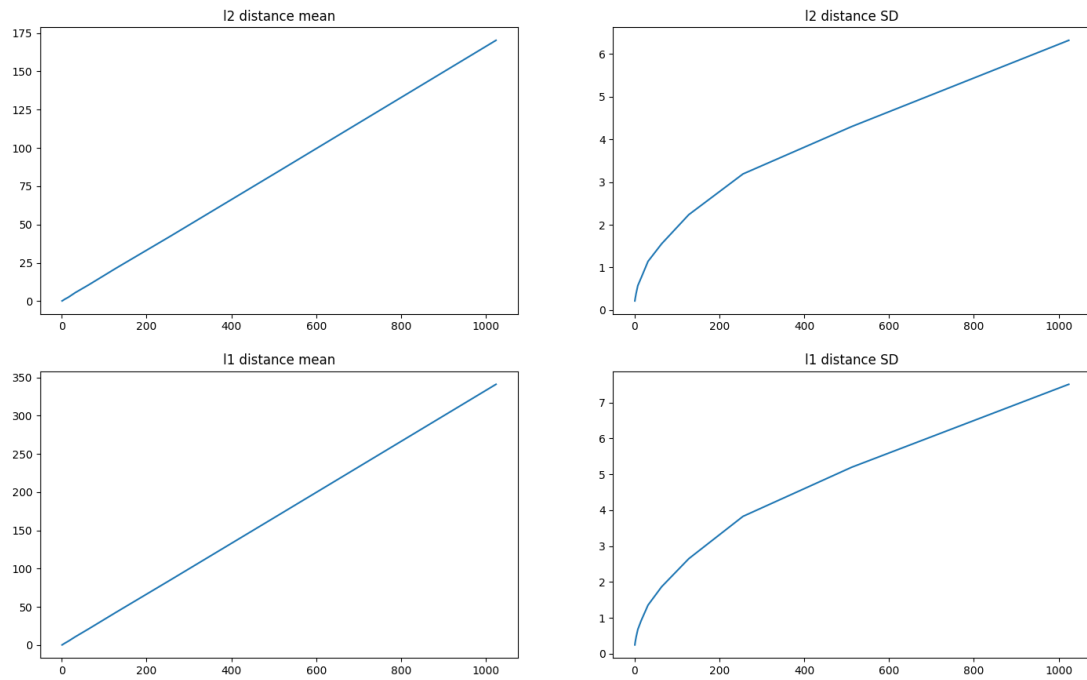


Q1

a)



$$\begin{aligned}
 b) \quad E[R] &= E[z_1 + \dots + z_d] \\
 &= E[z_1] + \dots + E[z_d] \\
 &= d \times \left(\frac{1}{6}\right) \\
 &= d/6
 \end{aligned}$$

Since x_i, y_i are independently sampled for each i , z_i and z_j are independent for $i \neq j$

$$\Rightarrow \text{Var}[R] = \text{Var}[z_1 + \dots + z_d]$$

$$\begin{aligned}
&= \text{Var}[z_1] + \dots + \text{Var}[z_d] \\
&= d \times \frac{7}{180} \\
&= 7d/180
\end{aligned}$$

c) i) Let R be the Euclidean distance

then E is: $R - E[R] \leq d$

$$\text{ii) } P(R - E[R] \leq d) = 1 - P(R - E[R] > d)$$

$$= 1 - P(R - E[R] \geq d)$$

(since E is a conti. random variable)

$$\geq 1 - \frac{\text{Var}[R]}{d^2}$$

$$\text{iii) then } P(E) \geq 1 - \frac{7d/180}{d^2}$$

$$= 1 - \frac{7}{180d}$$

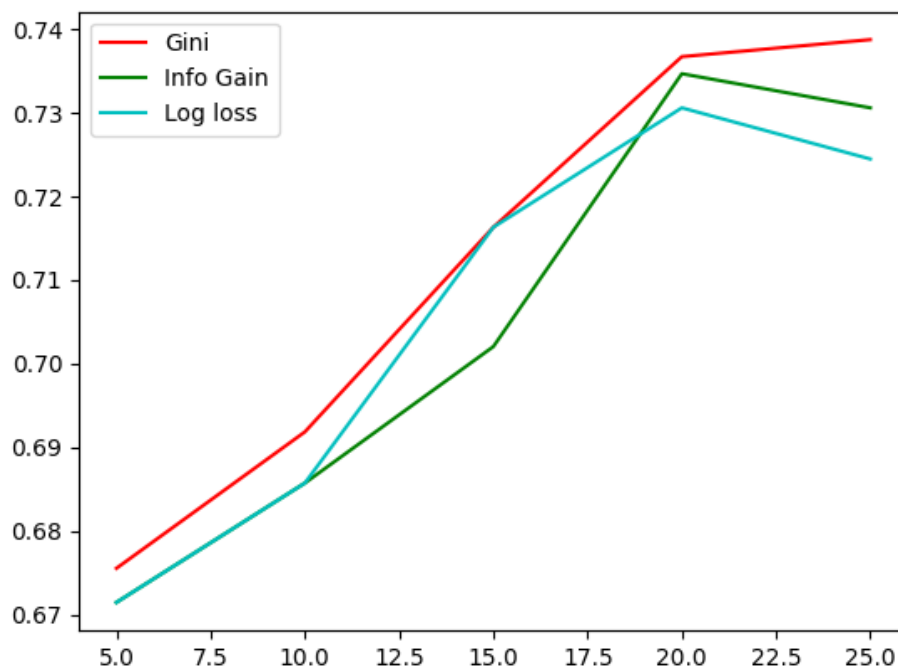
$$\Rightarrow \lim_{d \rightarrow \infty} P(E) \geq \lim_{d \rightarrow \infty} 1 - \frac{7}{180d} = 1$$

so as $d \rightarrow \infty$, $P(E) = 1$, so any distance is d
away from its expectation

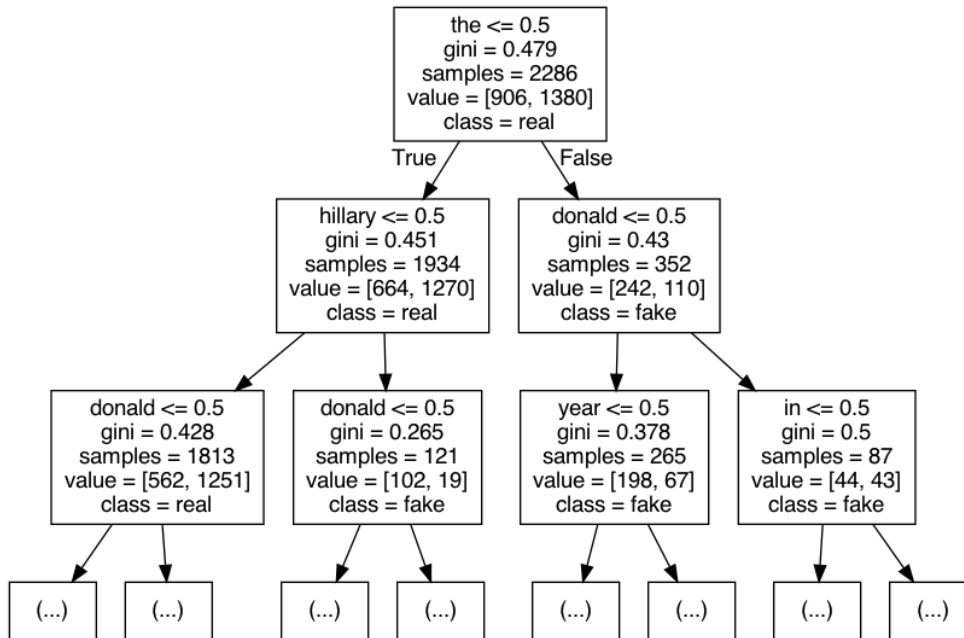
Q2. b) Function output :

```
Gini: score = 0.6755102040816326, depth = 5
Information gain: score = 0.6714285714285714, depth = 5
Log loss: score = 0.6714285714285714, depth = 5
Gini: score = 0.6918367346938775, depth = 10
Information gain: score = 0.6857142857142857, depth = 10
Log loss: score = 0.6857142857142857, depth = 10
Gini: score = 0.7163265306122449, depth = 15
Information gain: score = 0.7020408163265306, depth = 15
Log loss: score = 0.7163265306122449, depth = 15
Gini: score = 0.736734693877551, depth = 20
Information gain: score = 0.7346938775510204, depth = 20
Log loss: score = 0.7306122448979592, depth = 20
Gini: score = 0.7387755102040816, depth = 25
Information gain: score = 0.7306122448979592, depth = 25
Log loss: score = 0.7244897959183674, depth = 25
```

Plot :



c) Gini w/ depth 25 achieved the highest accuracy



d) The keywords are selected from
 $\{ \text{"the"}, \text{"hillary"}, \text{"trumps"}, \text{"donald"} \}$

Their IG are as follows :

IG(Y|X) is 0.04570772617653496 for the keyword the
IG(Y|X) is 0.04268249633366705 for the keyword hillary
IG(Y|X) is 0.03711785532105771 for the keyword trumps
IG(Y|X) is 0.04197422322376332 for the keyword donald

Q3.

$$a) \quad \frac{\partial J}{\partial w_{j'}} = \frac{1}{2N} \cdot \frac{\partial \left(\sum_{i=1}^N (y^{(i)} - t^{(i)})^2 \right)}{\partial w_{j'}} \quad \rightarrow = \sum_{j=1}^D w_j x_j^{(i)} + b$$

$$= \frac{1}{2N} \cdot \frac{\partial \left(\sum_{i=1}^N \left(\sum_{j=1}^D w_j x_j^{(i)} + b - t^{(i)} \right)^2 \right)}{\partial w_{j'}}$$

$$= \frac{1}{2N} \cdot 2 \sum_{i=1}^N \left(\sum_{j=1}^D w_j x_j^{(i)} + b - t^{(i)} \right) (x_{j'}^{(i)})$$

$$= \frac{1}{N} \cdot \sum_{i=1}^N \underbrace{\left(\sum_{j=1}^D w_j x_j^{(i)} + b \right)}_{= y^{(i)}} (x_{j'}^{(i)}) - t^{(i)} (x_{j'}^{(i)})$$

$$= \frac{1}{N} \cdot \sum_{i=1}^N (y^{(i)} - t^{(i)}) (x_{j'}^{(i)}) \quad (1)$$

$$\frac{\partial R}{\partial w_{j'}} = \frac{\partial \left(\sum_{j=1}^D \alpha_j |w_j| + \frac{1}{2} \sum_{j=1}^D \beta_j w_j^2 \right)}{\partial w_{j'}} \quad \rightarrow := f(w_j) = \begin{cases} w_j, & w_j > 0 \\ 0, & w_j = 0 \\ -w_j, & w_j < 0 \end{cases}$$

$$= \begin{cases} \text{if } w_{j'} > 0: \frac{\partial \left(\sum_{j=1}^D \alpha_j w_j + \frac{1}{2} \sum_{j=1}^D \beta_j w_j^2 \right)}{\partial w_{j'}} \\ \quad = \alpha_{j'} + \beta_{j'} w_{j'} \quad (2) \end{cases}$$

$$\text{if } w_{j'} = 0: = 0 \quad (3)$$

$$\text{if } w_{j'} < 0: \frac{\partial \left(-\sum_{j=1}^D \alpha_j w_j + \frac{1}{2} \sum_{j=1}^D \beta_j w_j^2 \right)}{\partial w_{j'}}$$

$$= -\alpha_j' + \beta_j' w_j' \quad (4)$$

So $\frac{\partial J_{\text{reg}}^{d/\beta}(w)}{\partial w_j'}$ is:

if $w_j' = 0$: $\frac{1}{N} \cdot \sum_{i=1}^N (y^{(i)} - t^{(i)}) (x_{j'}^{(i)})$

if $w_j' > 0$: $\frac{1}{N} \cdot \sum_{i=1}^N (y^{(i)} - t^{(i)}) (x_{j'}^{(i)}) + \alpha_j' + \beta_j' w_j'$

if $w_j' < 0$: $\frac{1}{N} \cdot \sum_{i=1}^N (y^{(i)} - t^{(i)}) (x_{j'}^{(i)}) - \alpha_j' + \beta_j' w_j'$

$$\frac{\partial J}{\partial b} = \frac{1}{2N} \cdot \frac{\partial}{\partial b} \left[\sum_{i=1}^N \left(y^{(i)} - t^{(i)} \right)^2 \right] / \frac{\partial}{\partial b}$$

\downarrow
 $\sum_{j=1}^D w_j x_j + b$

$$= \frac{1}{2N} \cdot \sum_{i=1}^N 2 \left(\sum_{j=1}^D w_j x_j + b - t^{(i)} \right)$$

$$= \frac{1}{N} \cdot \sum_{i=1}^N (y^{(i)} - t^{(i)})$$

Let $\alpha > 0$ be the learning rate, so overall:

if $w_j' > 0$: $w_j' \leftarrow w_j' - \alpha \left(\frac{1}{N} \cdot \sum_{i=1}^N (y^{(i)} - t^{(i)}) (x_{j'}^{(i)}) + \alpha_j' + \beta_j' w_j' \right)$

$$\Leftrightarrow w_j' \leftarrow w_j' - \frac{\alpha}{N} \sum_{i=1}^N (y^{(i)} - t^{(i)}) (x_{j'}^{(i)}) - \alpha_j' \alpha - \alpha \beta_j' w_j'$$

$$\Leftrightarrow w_{j'} \leftarrow w_{j'}(1 - \alpha\beta_{j'}) - \frac{\alpha}{N} \sum_{i=1}^N (y^{(i)} - t^{(i)})(x_{j'}^{(i)}) - \alpha_j \alpha$$

$$b \leftarrow b - \frac{\alpha}{N} \sum_{i=1}^N (y^{(i)} - t^{(i)})$$

if $w_{j'} = 0$: $w_{j'} \leftarrow w_{j'} - \alpha \left(\frac{1}{N} \cdot \sum_{i=1}^N (y^{(i)} - t^{(i)})(x_{j'}^{(i)}) \right)$

$$\Leftrightarrow w_{j'} \leftarrow w_{j'} - \frac{\alpha}{N} \sum_{i=1}^N (y^{(i)} - t^{(i)})(x_{j'}^{(i)})$$

$$b \leftarrow b - \frac{\alpha}{N} \sum_{i=1}^N (y^{(i)} - t^{(i)})$$

if $w_{j'} < 0$: $w_{j'} \leftarrow w_{j'} - \alpha \left(\frac{1}{N} \cdot \sum_{i=1}^N (y^{(i)} - t^{(i)})(x_{j'}^{(i)}) - \alpha_j + \beta_{j'} w_{j'} \right)$

$$\Leftrightarrow w_{j'} \leftarrow (1 - \alpha\beta_{j'}) w_{j'} - \frac{\alpha}{N} \sum_{i=1}^N (y^{(i)} - t^{(i)})(x_{j'}^{(i)}) + \alpha \alpha_j$$

$$b \leftarrow b - \frac{\alpha}{N} \sum_{i=1}^N (y^{(i)} - t^{(i)})$$

This is called weight decay possibly because for cases $w_{j'} < 0$ and $w_{j'} > 0$, the update rule for $w_{j'}$ contains the term $(1 - \alpha\beta_{j'}) w_{j'}$.

$$\alpha > 0 \text{ and } \beta_{j'} \geq 0, \text{ so } (1 - \alpha\beta_{j'}) w_{j'} \leq w_{j'}$$

\Rightarrow within the update rule, the weight $w_{j'}$ decays to a

lesser term.

b) $\lambda_1 = 0$

$$\Rightarrow J_{\text{reg}}^{\beta}(\omega) = \frac{1}{2N} \cdot \sum_{i=1}^N (y^{(i)} - t^{(i)})^2 + \frac{1}{2} \sum_{j=1}^D \beta_j \omega_j^2$$

Note: for the sake of consistency^{to 3a)}, in my notations I swapped j and j' defined in the question

$$\begin{aligned} \Rightarrow \frac{\partial J_{\text{reg}}^{\beta}(\omega)}{\partial \omega_{j'}} &= \frac{1}{2N} \cdot \sum_{i=1}^N 2(y^{(i)} - t^{(i)})(x_{j'}^{(i)}) + \beta_{j'} \omega_{j'} \\ &= \frac{1}{N} \cdot \underbrace{\sum_{i=1}^N \left(\sum_{j=1}^D (\omega_j x_j^{(i)}) - t^{(i)} \right) (x_{j'}^{(i)})}_{\text{to 3a)}} + \beta_{j'} \omega_{j'} \\ &= \sum_{i=1}^N \sum_{j=1}^D (\omega_j x_j^{(i)}) x_{j'}^{(i)} - \sum_{i=1}^N t^{(i)} x_{j'}^{(i)} \\ &= \sum_{j=1}^D \sum_{i=1}^N \frac{1}{N} \omega_j x_j^{(i)} x_{j'}^{(i)} - \frac{1}{N} \sum_{i=1}^N t^{(i)} x_{j'}^{(i)} + \beta_{j'} \omega_{j'} \end{aligned}$$

Define the indicator function $I(j) = \begin{cases} 0 & \text{if } j \neq j' \\ 1 & \text{if } j = j' \end{cases}$

$$\begin{aligned} &= \sum_{j=1}^D \sum_{i=1}^N \frac{1}{N} \omega_j x_j^{(i)} x_{j'}^{(i)} + I(j) \beta_j \omega_j - \frac{1}{N} \sum_{i=1}^N t^{(i)} x_{j'}^{(i)} \\ &= \sum_{j=1}^D \left(\frac{1}{N} \sum_{i=1}^N x_j^{(i)} x_{j'}^{(i)} + I(j) \beta_j \right) \omega_j - \frac{1}{N} \sum_{i=1}^N t^{(i)} x_{j'}^{(i)} \end{aligned}$$

$$\text{so } A_{jj'} = \frac{1}{N} \sum_{i=1}^N x_j^{(i)} x_{j'}^{(i)} + I(j) \beta_j$$

$$C_{j'} = \frac{1}{N} \sum_{i=1}^N t^{(i)} x_{j'}^{(i)}$$

c) Note that $X = \begin{pmatrix} x_1^{(1)} & x_2^{(1)} & \dots & x_D^{(1)} \\ \vdots & \vdots & & \vdots \\ x_1^{(N)} & x_2^{(N)} & \dots & x_D^{(N)} \end{pmatrix}$

$$\text{Then } A = \underbrace{\begin{pmatrix} \frac{1}{N} \sum_{i=1}^N x_1^{(i)} x_1^{(i)} & \dots & \frac{1}{N} \sum_{i=1}^N x_1^{(i)} x_D^{(i)} \\ \vdots & \ddots & \vdots \\ \frac{1}{N} \sum_{i=1}^N x_D^{(i)} x_1^{(i)} & \dots & \frac{1}{N} \sum_{i=1}^N x_D^{(i)} x_D^{(i)} \end{pmatrix}} + \begin{pmatrix} \beta_1 & & 0 \\ & \ddots & \\ 0 & & \beta_D \end{pmatrix}$$

$$= \frac{1}{N} \begin{pmatrix} x_1^{(1)} x_1^{(1)} + \dots + x_1^{(N)} x_1^{(N)} & \dots & x_1^{(1)} x_D^{(1)} + \dots + x_1^{(N)} x_D^{(N)} \\ \vdots & \ddots & \vdots \\ x_D^{(1)} x_1^{(1)} + \dots + x_D^{(N)} x_1^{(N)} & \dots & x_D^{(1)} x_D^{(1)} + \dots + x_D^{(N)} x_D^{(N)} \end{pmatrix}$$

$$\text{let } \vec{x}_i = \begin{pmatrix} x_i^{(1)} \\ \vdots \\ x_i^{(N)} \end{pmatrix} : \quad = \frac{1}{N} \begin{pmatrix} \vec{x}_1 \cdot \vec{x}_1 & \dots & \vec{x}_1 \cdot \vec{x}_D \\ \vdots & \ddots & \vdots \\ \vec{x}_D \cdot \vec{x}_1 & \dots & \vec{x}_D \cdot \vec{x}_D \end{pmatrix}$$

$$= \frac{1}{N} \underbrace{\begin{pmatrix} -\vec{x}_1 & - \\ \vdots & \\ -\vec{x}_D & - \end{pmatrix}}_{X^T} \underbrace{\begin{pmatrix} \vec{x}_1 & \dots & \vec{x}_D \\ | & & | \end{pmatrix}}_X$$

$$= \frac{1}{N} X^T X + \begin{pmatrix} \beta_1 & \dots & 0 \\ 0 & \dots & \beta_D \end{pmatrix}$$

$$C = \frac{1}{N} \begin{pmatrix} x_1^{(1)} & \dots & x_1^{(N)} \\ \vdots & \ddots & \vdots \\ x_D^{(1)} & \dots & x_D^{(N)} \end{pmatrix} \begin{pmatrix} t^{(1)} \\ \vdots \\ t^{(N)} \end{pmatrix}$$

$$= \frac{1}{N} X^T \vec{t} \quad \text{for target vector } \vec{t} = \begin{pmatrix} t^{(1)} \\ \vdots \\ t^{(N)} \end{pmatrix}$$

$$\text{then } A\vec{w} - C = 0$$

$$\Rightarrow \left[\frac{1}{N} X^T X + \begin{pmatrix} \beta_1 & \dots & 0 \\ 0 & \dots & \beta_D \end{pmatrix} \right] \vec{w} - \frac{1}{N} X^T \vec{t} = 0$$

$$\Rightarrow \left[X^T X + N \begin{pmatrix} \beta_1 & \dots & 0 \\ 0 & \dots & \beta_D \end{pmatrix} \right] \vec{w} = X^T \vec{t}$$

$$\Rightarrow \vec{w} = \left[X^T X + N \begin{pmatrix} \beta_1 & \dots & 0 \\ 0 & \dots & \beta_D \end{pmatrix} \right]^{-1} X^T \vec{t}$$

assuming that $X^T X + N \begin{pmatrix} \beta_1 & \dots & 0 \\ 0 & \dots & \beta_D \end{pmatrix}$ is invertible