# Noà Samarelli

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### **EDUCATION**

Columbia University

New York, NY

## MS in Mechanical Engineering with Elective Concentration in Robotics and Control

Expected Dec 2021

• GPA: 4.0/4.0

• Coursework: Data Science for Mechanical Systems, Intro to Robotics, Digital Manufacturing, Nano Optics Sensing & Actuation

## **University of Birmingham**

Birmingham, UK

## BEng in Mechanical Engineering

Jul 2019

• First-class Honors Student, GPA: 4.0/4.0

· Coursework: Engineering Materials, Manufacturing Systems, C Language, Mechanical Design, CFD and FEA

#### PROFESSIONAL EXPERIENCE

Hardware Intern San Francisco, CA

Cruise

May 2021 – Present

- Designed and manufactured sensor calibration stations with time optimization of 25%, cost of 3%, and accuracy of 10%
- Implementing BOMs, MIs and design drawings for supplier mass scale production
- Performed data and statistical analysis to assess pass or fail criteria for short ToF Lidar sensor technology

## Mechanical Design Engineer

New York, NY

Vessel Technologies

Jan 2021 - May 2021

- Designed modular apartments to achieve technical solutions to the global housing crisis
- Fabricated and optimized structural designs performing FEA analysis to minimize expenses and enhance user experience

### **Infotrading SAS**

Rome, IT

Junior Engineer Sep 2019 - Jun 2020

• Identified smart home and office products, implementing & supporting deployment of IR, thermal, and radar microwave and radio sensing technology to combine alarm functions with automation and personalized access control

Contact Design Hong Kong

\*\*Robotics Intern\*\* Jun - Aug 2018

\* Directed team of 3 in R&D for proof of concept for an automated robotic vending machine, with robotic arm of 3 DOF and XX

- Utilized Fusion 360 to create model drawings and animations for parts distributors and future investors
- Implemented low-cost sourcing strategy to achieve a cost reduction of 7% and a 10% increase in product efficiency

Polygon Technologies

Tzur Yigal, IL

Manufacturing Intern

Jul - Aug 2017

- Tested industrial manufacturing machines' final assembly to increase production speed by 3%, automated guided vehicles to improve route implementation by 2%, and drone satellites to improve underwater resistance by 1.7%
- Collaborated with Caja Robotics, implementing warehouses' automation technologies, to enhance robotic performance by 2%

## ACADEMIC EXPERIENCE

## **Graduate Teaching Assistant – Human Centered Design & Innovation**

New York, NY

Columbia University

Jan 2021 - May 2021

- Managed a full class of graduate students (~40) as they develop and design capstone project on innovative transportation methods
- Lead lectures on prototyping, design fidelity and other tools to resonate how well and idea resonates with stakeholders

## Graduate Research Assistant - Food Digital Manufacturing

New York, NY

Columbia University - Creative Machines Lab

Sep 2020 – Present

- Developing breakthrough techniques for 3D food printing and cooking using blue and infrared laser technologies
- Designing, optimizing, and slicing 3D CAD food models to allow additive manufacturing production using Solidworks and Slic3r

### Research Assistant - Robotics Tactile Sensing Technology

Birmingham, UK

University of Birmingham

Sep 2018 - May 2019

- Developed robotic fingers with tactile sensing technology based on optical fiber sensors (FBG) for robotics disassembly by exploring KUKA disassembly technologies as key enabler for autonomous remanufacturing
- Refined experiment's accuracy up until FBG sensitivity of 9.103  $\mu\varepsilon$ , concluding with overall research error of 9%

### **SKILLS**

- Italian (Proficient); Chinese (Intermediate); French (Intermediate); Hebrew (Beginner); Spanish (Beginner)
- C, Python, Solidworks, Fusion 360, MATLAB, Ansys, Abaqus, Slic3r, 3D Printing, Laser Cutting, OpenSCAD, nTop, Inspire