Modeling and Lighting Interior Spaces using Reflected Natural Light
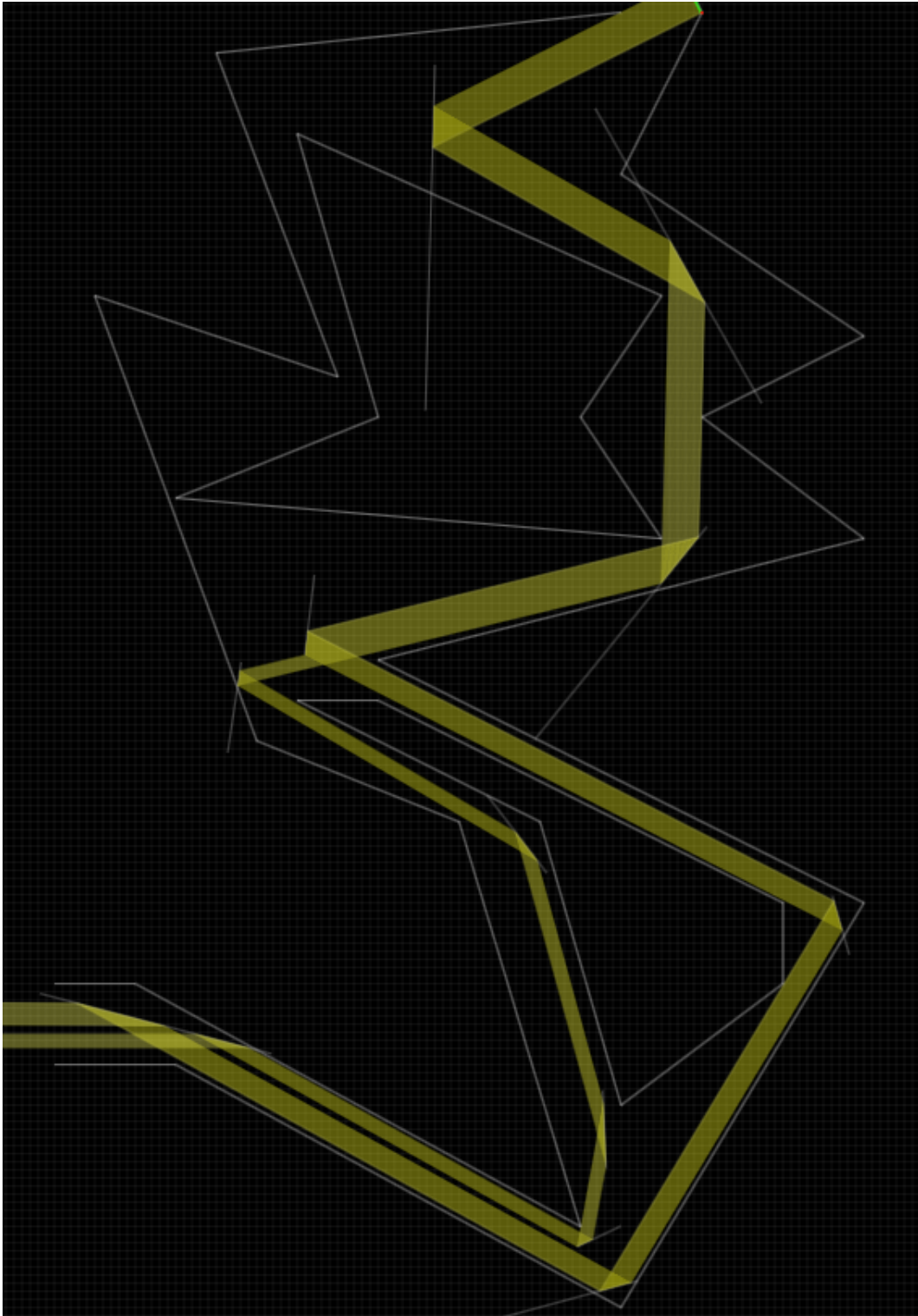
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1 Introduction

1.1 Premise

- Study aims to find optimal mirror placement for minimum decrease in intensity as light travels throughout the cave. This will be achieved by mapping the cave's geometry and simulating the travel of light throughout the cave as a vector.

1.2 Assumptions

In Order for a solution to be formed, a set of conditions must be assumed.

- The given specifications do not list whether the cave is horizontal or vertical, so it will be assumed that the cave described is traversed horizontally. This also implies that in all diagrams and depictions, the cave is being viewed from a 'top-down' view.

- The mirrors and walls of the cave are perfectly parallel to the floor of the cave and extend upwards with an undefined height. This simplifies modeling and can easily be altered to fit revised specifications, such as only needing to light the floor of the cave.

- Either light does not decrease in intensity or increase in area according to the inverse square law, or the change is negligible. The suns rays have traveled so far that they can be considered effectively parallel and therefore will not diverge. **find a source for this**

- mirrors will reflect light across their entire surface, even at the very tips of their edges.

- mirrors are perfectly flat and do not distort or affect light beams in any other way than reflecting them

- While the entry vector has no width, it will be assumed that light will enter the cave through the entire entrance. Each point along the entrance will be the beginning of its own vector, with equal direction to the entry vector. This assumption allows the

- Light will enter the cave parallel to the ground and of equal intensity from floor to ceiling.

1.3 Observations

- Vectors can be modeled on the Cartesian plane and translated without affecting their properties.

- Light can be modeled as a relative position vector with origin at a mirror surface

- Light will reflect so that angle of incidence = angle of refraction.

- Light will not diverge however contaminants in the air may decrease the intensity of light. Distance light travels in cave must me minimized

- Mirrors are not perfect and will only reflect a portion of light that hits them.

- Only the edges of each beam of light need to be found as any light that is within a beam will be traveling the same direction as the light at the edges. This allows intersections with mirrors and cave walls to be found without introducing unnecessary calculations.

- Since it is assumed that light will not diverge. the maximum size a mirror must be to reflect all the light hitting it will be 2 units, or the size of the cave's entrance.

- Clearly paths are not wide enough for a beam of 2 units to pass through them without a significant number of mirrors, therefore the beam may have to be split in order for them to be passed through the cave efficiently

- in the case of the beam being split, the edges of each beam will be found and each

1.4 Translation

- **move this to translation** This angle can be found by first calcualting the *dot product* and then using it to find the acute angle between the vecotrs. Using the calculated acute angles, subtract the

- As mentioned, mirrors are not perfect. The amount of light lost when a reflection occurs can be modelded as an exponential, $I = \text{Efficiency}^x$, where I is intensity of light, n is the number of mirrors, and efficiency is the percentage efficiency of the mirror in decimal form. Clearly adding more mirrors will lead to exponential losses in intensity.

- Vector addition can be used to join each given vector and form the walls of the cave and the obstacles

- Used Excel to do vector addition

- Took points from excel and inserted them as separate x and y list in desmos

- Graphed each point on list and joined points with lines.

- Imported Lists as points in phydemo.app

- Used the given lists and entry vector to draft a path through the cave

- clearly some sections of the cave are too narrow so split beam. More distance but drastic reduction in mirrors while maintianing full beam area

- translate mirrors from phyapp demo into lists of points for desmos

- graph linear equations from the lines formed between points (i.e. the locations of mirrors) and find intersections with initial beam of light

- trim mirrors to minimum size

- calculate angle of reflected beam

- repeat for all items and alter angles if a collision with the walls of the cave or an obstacle occurs

- if a colission occurs, then tweak mirror angle to correct and repeat

- verify light exiting cave is aligned with exit vector by measusing angle against entry vector

2 Solve

what do i put here exactly?

3 Evaluate

3.1 Extentions

- Use of Lenses or curved mirrors to focus or manipulate light

- Quantification of intensity and how factors such as distance and number of mirrors affect it in order to further optimize for maximum intensity.

- use of algortihms to find the most mathematically correct solution.

- Conversion into an optimisation problem

3.2 Reasonableness

- verified that solution was valid through visual inspection in desmos and through checking angle of exit vector

3.3 Strengths and Limitations of Solution

3.3.1 Strengths

- No light was lost through absoption into the cave walls

- the solution used the minimum amount of mirrors found to be required

3.3.2 Limitations

- Low tolerance for error in mirror placement in case of physical instalation, which is imminent considering the context of the task

- Solution is not very refined or automated. There are many steps that require manual intervention and this process is easily repeatable for other cave geometries

4 Conclusion