# ACM-ICPC Team Reference Document Tula State University (Basalova, Perezyabov, Provotorin)

C	ontents		7.1 Graph Implementation	12
			7.2 Graph Traversing	13
1	Tourslates	1	7.2 Graph Haversing	13
1	Templates	1	7.4 Connected Components	14
	1.1 C++ Template	1	7.4 Connected Components	14
	1.2 C++ Include	2		14
	1.3 Py Template	2	7.6 Bridges	15
			7.7 Articulation Points	
2	Data Structures	2	7.8 Kuhn	15
	2.1 Disjoint Set Union	2	7.9 Kruskal	16
	2.2 Segment Tree	2	7.10LCA (binary Lifting)	16
	2.3 Segment Tree Propagate	3	7.11LCA RMQ (seqtree)	16
	2.4 Treap	3	7.12 Maximum Flow	17
	2.5 Treap K	4	7.13 Eulerian Path	18
	2.6 Treap Universal	4	7.14 Eulerian Path Oriented	19
	2.7 Fenwick Tree	5	7.15 Shortest Paths	19
			8 Miscellaneous	20
3	Algebra	5	8.1 Ternary Search	20
	3.1 Primes Sieve	5		
	3.2 Factorization	5	4 55 1 .	
	3.3 Euler Totient Function	6	1 Templates	
	3.4 Greatest Common Divisor	6		
	3.5 Binary Operations	7	1.1 C++ Template	
	3.6 Matrices	7	-	
	3.7 Fibonacci	7	<pre>#include <bits stdc++.h=""></bits></pre>	
	3.8 Baby Step Giant Step	7	uning namanaga akdi	
	3.9 Combinations	7	using namespace std;	
	3.10 Permutation	8	// DEFINES	
	3.11 Fast Fourier Transform	8	<pre>#define precision(x) cout &lt;&lt; fixed &lt;&lt; setprecision(x);</pre>	
	3.12 Primitive Roots	9	<pre>#define fast cin.tie(0); ios::sync_with_stdio(0) #define all(x) x.begin(), x.end()</pre>	
	3.13 Number Decomposition	9	<pre>#define rall(x) x.rbegin(), x.rend()</pre>	
	3.14 Formulae	9	#define ff first #define ss second	
			// #define nl endl	
4	Geometry	10	#define nl "\n" #define sp " "	
	4.1 Vector	10	#define yes "Yes"	
	4.2 Planimetry	10	#define no "No"  #define int long long	
	4.3 Graham	10	3 1 3	
	4.4 Formulae	10		
			// CONSTANTS	
5	Stringology	11	const int INF = 1e18; // const int MOD = 1e9 + 7;	
	5.1 Z Function	11	// const int MOD = 998244353;	
	5.2 Manacher	11		
	5.3 Trie	11		
	5.4 Prefix Function	11	<pre>// FSTREAMS ifstream in("input.txt");</pre>	
	5.5 Suffix Array	12	ofstream out("output.txt");	
	5.5 Sumaruray	14		
6	Dynamic Programming	12	// RANDOM	
	6.1 Longest Increasing Subsequence	12	const int RMIN = 1, RMAX = 1e9;	
	6.2 Longest Common Subsequence	12	random_device rdev;	

```
mt19937_64 reng(rdev());
uniform\_int\_distribution < mt19937\_64: : result\_type > \ dist(RMIN)
     , RMAX);
// CUSTOM HASH
struct custom_hash {
   static uint64_t \stackrel{\cdot}{\text{splitmix64}}(uint64_t x) {
       // http://xorshift.di.unimi.it/splitmix64.c
       x += 0x9e3779b97f4a7c15;
       x = (x \land (x >> 30)) * 0xbf58476d1ce4e5b9;

x = (x \land (x >> 27)) * 0x94d049bb133111eb;

return x \land (x >> 31);
   }
   size_t operator()(uint64_t x) const {
   static const uint64_t FIXED_RANDOM = chrono::
             steady_clock::now().time_since_epoch().count();
       return splitmix64(x + FIXED_RANDOM);
   }
// USAGE EXAMPLES:
// unordered_set<long long, custom_hash> safe_set;
// unordered_map<long long, int, custom_hash> safe_map;
// gp_hash_table<long long, int, custom_hash>
      safe_hash_table;
// for pairs might be used like `3 * a + b` or `a ^ (b >>
     1)
// GLOBALS
// SOLUTION
void solve() {
// PREPROCESSING
void prepr() { }
// ENTRANCE
signed main()
   precision(15);
   fast;
prepr();
   int t = 1;
   cin >> t;
   while (t--) solve();
```

## 1.2 C++ Include

```
#include <iostream>
#include <iomanip>
#include <fstream>
#include <random>
#include <cmath>
#include <algorithm>
#include <string>
#include <vector>
#include <set>
#include <unordered_set>
#include <map>
#include <unordered_map>
#include <queue>
#include <deque>
#include <stack>
#include <list>
#include <bitset>
```

# 1.3 Py Template

```
from math import sqrt, ceil, floor, gcd
from random import randint
import sys

def inpt():
    return sys.stdin.readline().strip()

input = inpt

INF = int(1e18)
# MOD = int(1e9 + 7)
# MOD = 998244353

def solve():
    pass

t = 1
t = int(input())
for _ in range(t):
    solve()
```

## 2 Data Structures

# 2.1 Disjoint Set Union

```
// Theme: Disjoint Set Union
struct dsu {
   vector<int> p, size;
   dsu(int n) {
       p.assign(n, 0); size.assign(n, 0);
       for (int i = 0; i < n; i++) {
          p[i] = i;
           size[i] = 1;
       }
   }
   int get(int v) {
   if (p[v] != v) p[v] = get(p[v]);
       return p[v];
   void unite(int u, int v) {
       auto x = get(u), y = get(v);
       if (x == y) return;
if (size[x] > size[y]) swap(x, y);
       p[x] = y; size[y] += size[x];
};
```

# 2.2 Segment Tree

```
// Theme: Segment Tree
struct segtree {
    int size;
    vector<int> tree;

void init(int n) {
        size = 1;
        while (size < n) size <<= 1;
        tree.assign(2 * size - 1, 0);
}

void build(vector<int> &a, int x, int lx, int rx) {
        if (rx - lx == 1) {
            if (lx < a.size()) tree[x] = a[lx];
            return;
        }
        int m = (lx + rx) / 2;
        build(a, 2 * x + 1, lx, m);
        build(a, 2 * x + 2, m, rx);
        tree[x] = tree[2 * x + 1] + tree[2 * x + 2];
}</pre>
```

```
void build(vector<int> &a) {
        init(a.size());
        build(a, 0, 0, size);
    // Complexity: O(log(n))
    void set(int i, int v, int x, int lx, int rx) {
  if (rx - lx == 1) {
           tree[x] = v;
            return:
        int m = (lx + rx) / 2;
        if (i < m) set(i, v, 2 * x + 1, lx, m);
else set(i, v, 2 * x + 2, m, rx);
        tree[x] = tree[2 * x + 1] + tree[2 * x + 2];
    void set(int i, int v) {
    set(i, v, 0, 0, size);
    // Complexity: O(log(n))
    int sum(int 1, int r, int x, int lx, int rx) {
   if (1 <= lx && rx <= r) return tree[x];</pre>
        if (l \rightarrow = rx \mid | r \leftarrow lx) return 0;
        int m = (lx + rx) / 2;
        return sum(1, r, 2 * x + 1, lx, m) +
            sum(1, r, 2 * x + 2, m, rx);
    int sum(int 1, int r) {
        return sum(1, r, 0, 0, size);
};
```

## 2.3 Segment Tree Propagate

```
// Theme: Segment Tree With Propagation
struct segtree_prop {
   int size;
   vector<int> tree;
   void init(int n) {
       size = 1;
       while (size < n) size <<= 1;
       tree.assign(2 * size - 1, 0);
   void build(vector<int> &a, int x, int lx, int rx) {
       if (rx - lx == 1) {
           if (lx < a.size()) tree[x] = a[lx];
          return;
       int m = (lx + rx) / 2;
       build(a, 2 * x + 1, lx, m);
build(a, 2 * x + 2, m, rx);
tree[x] = tree[2 * x + 1] + tree[2 * x + 2];
   void build(vector<int> &a) {
       init(a.size());
       build(a, 0, 0, size);
   void push(int x, int lx, int rx) {
       if (rx - lx == 1) return;
       tree[2 * x + 1] += tree[x];
       tree[2 * x + 2] += tree[x];
       tree[x] = 0;
   // Complexity: O(log(n))
   void add(int v, int 1, int r, int x, int lx, int rx) {
       push(x, lx, rx);
if (rx <= l || r <= lx) return;</pre>
       if (1 <= lx && rx <= r) {
           tree[x] += v;
           return:
       int m = (lx + rx) / 2;
       add(v, 1, r, 2 * x + 1, 1x, m);
add(v, 1, r, 2 * x + 2, m, rx);
   void add(int v, int l, int r) {
       add(v, l, r, 0, 0, size);
```

```
// Complexity: O(log(n))
int get(int i, int x, int lx, int rx) {
   push(x, lx, rx);
   if (rx - lx == 1) return tree[x];
   int m = (lx + rx) / 2;
   if (i < m) return get(i, 2 * x + 1, lx, m);
   else return get(i, 2 * x + 2, m, rx);
}
int get(int i) {
   return get(i, 0, 0, size);
}
</pre>
```

## 2.4 Treap

```
// Theme: Treap (Tree + Heap)
// Node
struct node {
   int key, priorty;
   shared_ptr<node> left, right;
   node(int key, int priorty = INF) :
       key(key),
       priorty(priorty == INF ?
       reng() : priorty) { }
};
// Treap
struct treap {
   shared_ptr<node> root;
   treap() { }
   treap(int root_key, int root_priorty = INF) {
       root = shared_ptr<node>(new node(root_key,
            root_priorty));
   treap(shared_ptr<node> rt) {
       root = shared_ptr<node>(rt);
   treap(const treap &tr) {
       root = shared_ptr<node>(tr.root);
   // Complexity: O(log(N))
   pair<treap, treap> split(int k) {
  auto res = split(root, k);
  return { treap(res.ff), treap(res.ss) };
   pair<shared_ptr<node>, shared_ptr<node>> split(
       shared_ptr<node> rt, int k) {
if (!rt) return { nullptr, nullptr };
       else if (rt->key < k) {
   auto [rt1, rt2] = split(rt->right, k);
           rt->right = rt1;
           return { rt, rt2 };
       else {
           auto [rt1, rt2] = split(rt->left, k);
           rt->left = rt2;
          return { rt1, rt };
   }
   // Complexity: O(log(N))
   treap merge(const treap &tr) {
       root = shared_ptr<node>(merge(root, tr.root));
       return *this;
   shared_ptr<node> merge(shared_ptr<node> rt1, shared_ptr<
         node> rt2) {
       if (!rt1) return rt2;
       if (!rt2) return rt1
       if (rt1->priorty < rt2->priorty) {
           rt1->right = merge(rt1->right, rt2);
           return rt1;
       else {
           rt2->left = merge(rt1, rt2->left);
           return rt2;
```

```
}
};
```

# 2.5 Treap K

```
// Theme: Treap With Segments
struct node_k {
   int key, priorty, size;
   shared_ptr<node_k> left, right;
   node_k(int key, int priorty = INF):
       key(key),
       priorty(priorty == INF ?
       reng() : priorty),
size(1) { }
    friend int sz(shared_ptr<node_k> nd) {
       return (nd ? nd->size : 011);
   void upd() {
       size = sz(left) + sz(right) + 1;
};
// Treap
struct treap_k {
   shared_ptr<node_k> root;
   treap_k() { }
   treap_k(int root_key, int root_priorty = INF) {
       root = shared_ptr<node_k>(new node_k(root_key,
             root_priorty));
    treap_k(shared_ptr<node_k> rt) +
       root = shared_ptr<node_k>(rt);
   treap_k(const treap_k &tr) {
       root = shared_ptr<node_k>(tr.root);
    // Complexity: O(log(N))
   pair<treap_k, treap_k> split_k(int k) {
  auto res = split_k(root, k);
  return { treap_k(res.ff), treap_k(res.ss) };
   pair < shared\_ptr < node\_k > , \ shared\_ptr < node\_k > > \ split\_k (
          \verb| shared_ptr < \verb| node_k > rt, int k ) \{ \\
       share_printed=x1t, file k) {
if (!rt) return { nullptr, nullptr };
else if (sz(rt) <= k) return { rt, nullptr };
else if (sz(rt->left) + 1 <= k) {</pre>
           auto [rt1, rt2] = split_k(rt-)right, k - sz(rt-)
                 left) - 1);
           rt->right = rt1;
           rt->upd();
           return { rt, rt2 };
           auto [rt1, rt2] = split_k(rt->left, k);
           rt\rightarrow left = rt2;
           rt->upd():
           return { rt1, rt };
       }
    // Complexity: O(log(N))
   treap\_k \ merge\_k(const \ treap\_k \ \&tr) \ \{
       root = shared_ptr<node_k>(merge_k(root, tr.root));
       return *this:
   shared_ptr<node_k> merge_k(shared_ptr<node_k> rt1,
         shared_ptr<node_k> rt2) {
       if (!rt1) return rt2;
if (!rt2) return rt1;
        if (rt1->priorty < rt2->priorty) {
           rt1->right = merge_k(rt1->right, rt2);
            rt1->upd();
```

```
return rt1;
}
else {
    rt2->left = merge_k(rt1, rt2->left);
    rt2->upd();
    return rt2;
}
};
```

# 2.6 Treap Universal

```
// Theme: Treap (Tree + Heap)
// Supports both explicit and implicit keys (not
      simultaniously ofc)
// Core operations are all O(log n) average
mt19937 rna(378):
struct Node { int x, y, size; // "x" is key or payload, "y" is
         priority
   Node* left, * right;
   Node(int val): x(val), y(rng() % 1'000'000'000), size(1)
   , left(nullptr), right(nullptr) {}
};
int get_size(Node* root) {
    if (root == nullptr) return 0;
    return root->size:
void update(Node* root) {
     if (root == nullptr) return;
     root->size = get_size(root->left) + 1 + get_size(root->
      right);
// split by value (for explicit keys)
pair<Node*, Node*> split(Node* root, int v) {
    if (root == nullptr) return {nullptr, nullptr};
    if (root->x <= v) {
    auto res = split(root->right, v);
         root->right = res.first;
         update(root);
         return {root, res.second};
         auto res = split(root->left, v);
         root \rightarrow left = res.second;
         update(root):
         return {res.first, root};
    }
}
// split by size (for implicit keys)
pair<Node*, Node*> split_k(Node* root, int k) {
    if (root == nullptr) return {nullptr, nullptr};
     if (get_size(root) <= k) return {root, nullptr};</pre>
     if (k == 0) return {nullptr, root};
     int left_size = get_size(root->left);
    if (left_size >= k) {
   auto res = split_k(root->left, k);
         root->left = res.second;
         update(root);
         return {res.first, root};
    } else {
         auto res = split_k(root->right, k - left_size - 1);
         root->right = res.first;
         update(root);
         return {root, res.second};
    }
// merge for both explicit and implicit keys
Node* merge(Node* root1, Node* root2) {
    if (root1 == nullptr) return root2;
     if (root2 == nullptr) return root1;
    if (root1->y < root2->y) {
         root1->right = merge(root1->right, root2);
         update(root1);
         return root1;
         root2->left = merge(root1, root2->left);
```

```
update(root2);
    return root2;
}

// insert for explicit keys (use split_k for implicit keys)
Node* insert(Node* root, int v) {
    auto subs = split(root, v);
    return merge(merge(subs.first, new Node(v)), subs.
        second);
}

// debug helper
void print_node(Node* root, bool end = false) {
    if (root->left! = nullptr) print_node(root->left);
    cout << root->x << " ";
    if (root->right! = nullptr) print_node(root->right);
    if (end) cout << "\n";
}</pre>
```

#### 2.7 Fenwick Tree

```
// Theme: Fenwick Tree
// Core operations are O(log n)
struct Fenwick {
   vector<int> data:
   explicit Fenwick(int n) {
       data.assign(n + 1, 0);
   explicit Fenwick(vector<int>& arr): Fenwick(arr.size())
        for (int i = 1; i <= arr.size(); ++i) {
   add(i, arr[i - 1]);</pre>
       }
   }
   // Nested loops (also vector) for multi-dimensional.
          Also in add().
    // (x & -x) = last non-zero bit
   int sum(int right) {
       int res = 0;
for (int i = right; i > 0; i -= (i & -i)) {
           res += data[i];
       return res;
   int sum(int left, int right) {
       return sum(right) - sum(left - 1); // inclusion-
              exclusion principle
   void add(int idx, int x) \{
        for (int i = idx; i < data.size(); i += (i \& -i)) {
          data[i] += x;
   }
   // CONCEPT (didn't test it). Should work if all real
          values are non-negative.
   int lower_bound(int s) {
        int k = 0;
        int logn = (int)(log2(data.size() - 1) + 1); //
             maybe rewrite this line
        for (int b = logn; b \ge 0; --b) {
           if (k + (1 \leftrightarrow b) \leftrightarrow data.size() \&\& data[k + (1 \leftrightarrow b) \leftrightarrow data.size()) \&\& data[k + (1 \leftrightarrow b) \leftrightarrow data.size()]
                 b)] < s) {
               k += (1 << b);
               s -= data[k];
           }
       return k;
};
```

# 3 Algebra

### 3.1 Primes Sieve

```
// Theme: Prime Numbers
// Algorithm: Eratosthenes Sieve
// Complexity: O(N*log(log(N)))
// = 0 - Prime,
// != 0 - Lowest Prime Divisor
auto get_sieve(int n) {
   vector<int> sieve(n); // Sieve
sieve[0] = sieve[1] = 1;
   for (int i = 2; i * i < n; i++)
       if (!sieve[i])
  for (int j = i * i; j < n; j += i)</pre>
              sieve[j] = i;
   return sieve;
// Algorithm: Prime Numbers With Sieve
// Complexity: O(N*log(log(N)))
auto get_primes(int n) {
   vector<int> primes, sieve = get_sieve(n);
   for (int i = 2; i < sieve.size(); i++)
      if (!sieve[i])
          primes.push_back(i);
   return primes;
// Algorithm: Linear Algorithm
// Complexity: O(N)
// lp[i] = Lowest Prime Divisor
auto get_sieve_primes(int n, vector<int> &primes) {
   vector<int> lp(n);
   lp[0] = lp[1] = 1;
   for (int i = 2; i < n; i++) {
      if (!lp[i]) {
          lp[i] = i;
          primes.push_back(i);
       for (int j = 0; j < primes.size() && primes[j] <= lp[i] &&
                  i * primes[j] < n; j++)
          lp[i * primes[j]] = primes[j];
   return lp;
}
```

## 3.2 Factorization

```
// Theme: Factorization
// Algorithm: Trivial Algorithm
// Complexity: O(sqrt(N))
auto factors(int n) {
 vector<int> factors;
 for (int i = 2; i * i \leftarrow n; i++) {
   if (n % i)
    continue;
   while (n % i == 0)
    n /= i;
   factors.push_back(i);
 if (n != 1)
   factors.push_back(n);
 return factors:
// Algorithm: Factorization With Sieve
// Complexity: O(N*log(log(N)))
auto factors_sieve(int n) {
 vector<int> factors,
    sieve = get_sieve(n + 1);
```

```
while (sieve[n]) {
   factors.push_back(sieve[n]);
   n /= sieve[n];
 if (n != 1)
   factors.push_back(n);
 return factors;
}
// Algorithm: Factorization With Primes
// Complexity: O(sqrt(N)/log(sqrt(N)))
auto factors_primes(int n) {
 vector<int> factors.
     primes = get_primes(n + 1);
 for (auto &i : primes) \{
   if (i * i > n)
    break:
   if (n % i)
     continue;
   while (n \% i == 0)
     n /= i;
   factors.push_back(i);
 if (n != 1)
   factors.push_back(n);
 return factors;
// Algorithm: Ferma Test
// Complexity: O(K*log(N))
bool ferma(int n) {
 if (n == 2)
   return true:
 uniform_int_distribution<int> distA(2, n - 1);
 for (int i = 0; i < 1000; i++) {
   int a = distA(reng);
   if (gcd(a, n) != 1 ||
binpow(a, n - 1, n) != 1)
     return false;
 }
 return true;
}
// Algorithm: Pollard Rho Algorithm
// Complexity: O(N^{(1/4)})
int get_random_number(int 1, int r) \{
 random_device random_device;
 mt19937 generator(random_device());
 uniform_int_distribution<int> distribution(1, r);
 return distribution(generator);
}
int f(int x, int c, int n) {
return ((x * x + c) % n);
int ff(int n) {
 int g = 1;
 for (int i = 0; i < 5; i++) {
   int x = get_random_number(1, n);
int c = get_random_number(1, n);
   int h = 0;
   while (g == 1) {
     x = f(x, c, n) \% n;

int y = f(f(x, c, n), c, n) \% n;

g = gcd(abs(x - y), n);
     if (g == n) {
      g = 1;
     if (h > 4 * (int)pow(n, 1.0 / 4)) {
      break;
     }
```

```
if (g > 1) {
     return g;
   }
 return -1;
signed main() {
 // ...read n...
 vector<int> a;
 while (n > 1)
   int m = ff(n);
   if (m > 0) {
    n = n / m;
     a.push_back(m);
   } else {
     break;
   }
 }
 vector<int> ans;
 a.push_back(n);
 for (auto &it : a) {
   int i = 2;
   int m = it;
   while (i * i <= m) \{
if (m \% i == 0) \{
      ans.push_back(i);
       m = m / i;
     } else {
       i += 1;
     }
   ans.push_back(m);
 sort(all(ans));
```

#### 3.3 Euler Totient Function

```
// Theme: Euler Totient Function
// Algorithm: Euler Product Formula
// Complexity: O(sqrt(N))
// phi = n(1 - 1 / pi), i = 1,...
int phi(int n) {
  if (n == 1) return 1;
  auto f = factors(n);
  int res = n;
  for (auto &p : f)
    res -= res / p;
  return res;
}
```

#### 3.4 Greatest Common Divisor

```
// Theme: Greatest Common Divisor

// Algorithm: Simple Euclidean Algorithm
// Complexity: O(log(N))

int gcd(int a, int b) {
    while (b) {
        a %= b;
        swap(a, b);
    }
    return a;
}

// Algorithm: Extended Euclidean Algorithm
// Complexity: O(log(N))

// d = gcd(a, b)
// x * a + y * b = d
```

```
// returns {d, x, y}
vector<int> euclid(int a, int b) {
   if (!a) return { b, 0, 1 };
   auto v = euclid(b % a, a);
   int d = v[0], x = v[1], y = v[2];
   return { d, y - (b / a) * x, x };
}
```

# 3.5 Binary Operations

```
// Theme: Binary Operations
// Algorithm: Binary Multiplication
// Complexity: O(log(b))
int binmul(int a, int b, int p = 0) {
   int res = 0;
   while (b) {
      if (b & 1) res = p ? (res + a) % p : (res + a);
      a = p ? (a + a) % p : (a + a);
      b >>= 1;
   return res;
}
// Algorithm: Binary Exponentiation
// Complexity: O(log(b))
int binpow(int a, int b, int p = 0) {
   int res = 1:
   while (b) {
      if (b & 1) res = p ? (res * a) % p : (res * a);
      a = p ? (a * a) % p : (a * a);
   return res;
```

## 3.6 Matrices

```
// Theme: Matrix Opeations
template <typename T>
using row = vector<T>;
template <typename T>
using matrix = vector(vector(T>>);
// Algorithm: Matrix-Matrix Multiplication
// Complexity: O(N*K*M)
auto m_prod(matrix<int> &a, matrix<int> &b, int p = 0) {
   int n = a.size(), k = a[0].size(), m = b[0].size();
   matrix<int> res(n, row<int>(m)):
   for (int i = 0; i < n; i++)
      return res;
}
// Algorithm: Matrix-Vector Multiplication
// Complexity: O(N*M)
auto m_prod(matrix<int> &a, row<int> &b, int p = 0) {
   int n = a.size(), m = b.size();
   row<int> res(n);
   for (int i = 0; i < n; i++)
      for (int j = 0; j < m; j++)
  res[i] = p ? (res[i] + a[i][j] * b[j] % p) % p
  : (res[i] + a[i][j] * b[j]);</pre>
   return res;
}
// Algorithm: Fast Matrix Exponentiation
```

```
// Complexity: O(N^3*log(K))
auto m_binpow(matrix<int> a, int x, int p = 0) {
   int n = a.size();

   matrix<int> res(n, row<int>(n));
   for (int i = 0; i < n; i++) res[i][i] = 1;

   while (x) {
      if (x & 1) res = m_prod(res, a, p);
      a = m_prod(a, a, p);
      x >>= 1;
   }

   return res;
}
```

#### 3.7 Fibonacci

```
// Theme: Fibonacci Sequence

// Algorithm: Fibonacci Numbers With Matrix Exponentiation
// Complexity: O(log(N))

int fibonacci(int n) {
   row<int> first_two = { 1, 0 };
   if (n <= 2) return first_two[2 - n];

   matrix<int> fib(2, row<int>(2, 0));
   fib[0][0] = 1; fib[0][1] = 1;
   fib[1][0] = 1; fib[1][1] = 0;

   fib = m_binpow(fib, n - 2);
   row<int> last_two = m_prod(fib, first_two);
   return last_two[0];
}
```

# 3.8 Baby Step Giant Step

#### 3.9 Combinations

```
// Theme: Combination Number

// Algorithm: Online Multiplication-Division
// Complexity: O(k)

// C_n^k - from n by k
int C(int n, int k) {
  int res = 1;
```

```
for (int i = 1; i <= k; i++) {
    res *= n - k + i;
    res /= i;
}

return res;
}

// Algorithm: Pascal Triangle Preprocessing
// Complexity: O(N^2)

auto pascal(int n) {
    // C[i][j] = C_i+j^i
    vector<vector<int>> C(n + 1, vector<int>(n + 1, 1));
    for (int i = 1; i < n + 1; i++)
        for (int j = 1; j < n + 1; j++)
        C[i][j] = C[i - 1][j] + C[i][j - 1];

return C;
}</pre>
```

## 3.10 Permutation

```
// Theme: Permmutations

// Algorithm: Next Lexicological Permutation
// Complexity: O(N)

bool perm(vector<int> &v) {
   int n = v.size();

   for (int i = n - 1; i >= 1; i--) {
      if (v[i - 1] < v[i]) {
        reverse(v.begin() + i, v.end());

      int j = distance(v.begin(),
        upper_bound(v.begin() + i, v.end(), v[i - 1]));

      swap(v[i - 1], v[j]);
      return true;
    }
}

return false;
}</pre>
```

#### 3.11 Fast Fourier Transform

// Theme: Fast Fourier Transform

```
// Algorithm: Fast Fourier Transform (Complex)
// Complexity: O(N*log(N))
using cd = complex<double>:
const double PI = acos(-1);
auto fft(vector<cd> a, bool invert = 0) {
   // n = 2 ^ x
   int n = a.size();
   // Bit-Reversal Permutation (0000, 1000, 0100, 1100,
         0010, ...)
    for (int i = 1, j = 0; i < n; i++) {
        int bit = n \gg 1:
        for (; j \ge bit; bit >>= 1) j == bit;
        j += bit;
        if (i < j) swap(a[i], a[j]);</pre>
   for (int len = 2; len <= n; len <<= 1) {
   // Complex Root Of One</pre>
       double ang = 2 * PI / len * (invert ? -1 : 1);
       cd lroot(cos(ang), sin(ang));
        for (int i = 0; i < n; i += len) {
           cd root(1);
for (int j = 0; j < len / 2; j++) {
   cd u = a[i + j], v = a[i + j + len / 2] * root</pre>
               a[i + j] = (u + v);

a[i + j + len / 2] = (u - v);
```

```
root = (root * lroot);
       }
   }
    if (invert) {
        for (int i = 0; i < n; i++) a[i] /= n;
   return a;
}
// Module (7340033 = 7 * (2 ^ 20) + 1)
// Primitive Root (5 ^ (2 ^ 20) == 1 mod 7340033)
// Inverse Primitive Root (5 * 4404020 == 1 mod 7340033)
// Maximum Degree Of Two (2 ^ 20)
const int mod = 7340033;
const int proot = 5;
const int proot_1 = 4404020;
const int pw = 1 \iff 20;
// Algorithm: Discrete Fourier Transform (Inverse Roots)
// Complexity: O(N*log(N))
auto fft(vector<int> a, bool invert = 0) {
    // n = 2 ^ x
    int n = a.size();
   // Bit-Reversal Permutation (0000, 1000, 0100, 1100,
          0010, ...)
    for (int i = 1, j = 0; i < n; i++) {
        int bit = n \gg 1;
        for (; j \ge bit; bit \ge 1) j = bit; j + bit;
        if (i < j) swap(a[i], a[j]);</pre>
   for (int len = 2; len <= n; len <<= 1) {    // Primitive Root Or Inverse Root (Inverse
              Transform)
        int lroot = invert ? proot 1 : proot:
        // Current Primitive Root
       lroot = binpow(lroot, pw / len, mod);
        for (int i = 0; i < n; i += len) {
            int root = 1;
            for (int j = 0; j < len / 2; j++) {
               int u = a[i + j], v = a[i + j + len / 2] *
                     root % mod;
                a[i + j] = (u + v) \% \mod; \\ a[i + j + len / 2] = (u - v + mod) \% \mod; \\ root = (root * lroot) \% mod; 
       }
   }
    if (invert) {
        int _n = binpow(n, mod - 2, mod);
        for (int i = 0; i < n; i++) a[i] = (a[i] * _n) % mod
   }
   return a;
}
// Algorithm: Discrete Fourier Transform
// Complexity: O(N*log(N))
auto fft(vector<int> &a, bool invert = 0) {
    int n = a.size();
    // Bit-Reversal Permutation (0000, 1000, 0100, 1100,
   0010, ...) for (int i = 1, j = 0; i < n; i++) {
        int bit = n \gg 1;
        for (; j \ge bit; bit >>= 1) j -= bit;
        j += bit;
        if \; (i \; \langle \; j) \; swap(a[i], \; a[j]);
   }
    for (int len = 2; len <= n; len <<= 1) {
        // Current Primitive Root
        int lroot = binpow(proot, pw / len, mod);
```

```
for (int i = 0; i < n; i += len) {
    int root = 1;
    for (int j = 0; j < len / 2; j++) {
        int u = a[i + j], v = a[i + j + len / 2] *
            root % mod;
        a[i + j] = (u + v) % mod;
        a[i + j + len / 2] = (u - v + mod) % mod;
        root = (root * lroot) % mod;
    }
}

if (invert) {
    reverse(a.begin() + 1, a.end());
    int _n = binpow(n, mod - 2, mod);
    for (int i = 0; i < n; i++) a[i] = (a[i] * _n) % mod
    ;
}

return a;</pre>
```

#### 3.12 Primitive Roots

```
// Module (7 == 3 * (2 ^ 1) + 1)
// Primitive Root (3)
// Primitive Root {2 ^ 1} (6)
// Inverse Root {2 ^ 1} (6)
// Degree Of Two (2)

// const int mod = 7
// const int proot = 6
// const int proot_1 = 6
// const int pw = 1 << 1

// Module (13 == 3 * (2 ^ 2) + 1)
// Primitive Root (2)
// Primitive Root {2 ^ 2} (8)
// Inverse Root {2 ^ 2} (5)
// Degree Of Two (4)

// const int mod = 13
// const int proot = 8
// const int proot_1 = 5
// const int pw = 1 << 2</pre>
```

#### 3.13 Number Decomposition

```
// Theme: Integer Numbers Decomposition With Composite
     Module
// Module
// m = (p1 ^ m1) * (p2 ^ m2) * ... * (pn ^ mn)
// Prime Divisors Of Module
vector<int> p;
struct num {
      // GCD(x, m) = 1
   int x;
   // Powers Of Primes
   vector (int) a;
   num() : x(0), a(vector(int)(p.size())) { }
       // n = (p1 ^ a1) * (p2 ^ a2) * ... * (pn ^ an) * x
   num(int n) : x(0), a(vector < int > (p.size())) {
      if (!n) return;
      for (int i = 0; i < p.size(); i++) {
          int ai = 0;
          while (n \% p[i] == 0) {
            n /= p[i];
             ai++;
          a[i] = ai;
```

```
num operator*(const num &nm)
        vector<int> new_a(p.size());
for (int i = 0; i < p.size(); i++)
   new_a[i] = a[i] + nm.a[i];</pre>
        num res; res.a = new_a;
        res.x = x * nm.x % m;
        return res;
    num operator/(const num &nm) {
        vector<int> new_a(p.size());
        for (int i = 0; i < p.size(); i++)
new_a[i] = a[i] - nm.a[i];
        num res; res.a = new_a;
        int g = euclid(nm.x, m)[1];
        g += m; g %= m;
res.x = x * g % m;
        return res;
    int toint() {
        int res = x;
        for (int i = 0; i < p.size(); i++)</pre>
            res = res * binpow(p[i], a[i], m) % m;
        return res;
};
```

#### 3.14 Formulae

#### Combinations.

$$C_n^k = \frac{n!}{(n-k)!k!}$$

$$C_n^0 + C_n^1 + \dots + C_n^n = 2^n$$

$$C_{n+1}^{k+1} = C_n^{k+1} + C_n^k$$

$$C_n^k = \frac{n}{k} C_{n-1}^{k-1}$$

#### Striling approximation.

$$n! \approx \sqrt{2\pi n} \frac{n}{e}^n$$

## Euler's theorem.

$$a^{\phi(m)} \equiv 1 \bmod m$$
,  $gcd(a, m) = 1$ 

## Ferma's little theorem.

$$a^{p-1} \equiv 1 \mod p$$
,  $gcd(a, p) = 1$ ,  $p$  - prime.

#### Catalan number.

$$C_0 = 0, C_n = \sum_{i=0}^{n-1} C_i C_{n-1-i}$$

$$C_n = \frac{2(2n-1)}{n+1} C_{n-1}$$

$$C_n = \frac{(2n)!}{n!(n+1)!}$$

#### Arithmetic progression.

$$S_n = \frac{a_1 + a_n}{2} n = \frac{2a_1 + d(n-1)}{2} n$$

#### Geometric progression.

$$S_n = \frac{b_1(1-q^n)}{1-q}n$$

## Infinitely decreasing geometric progression.

$$S_n = \frac{b_1}{1-q}n$$

#### Sums.

$$\sum_{i=1}^{n} i = \frac{n(n+1)}{2},$$

$$\sum_{i=1}^{n} i^{2} = \frac{n(2n+1)(n+1)}{4},$$

$$\sum_{i=1}^{n} i^{3} = \frac{n^{2}(n+1)^{2}}{4},$$

$$\begin{array}{l} \sum_{i=1}^{n} i^4 = \frac{n(n+1)(2n+1)(3n^2+3n-1)}{30}, \\ \sum_{i=a}^{b} c^i = \frac{c^{b+1}-c^a}{c-1}, c \neq 1. \end{array}$$

# Geometry

### **Vector**

```
// Theme: Methematical 3-D Vector
template <typename T>
struct vec {
  T x, y, z;

vec(T x = 0, T y = 0, T z = 0) : x(x), y(y), z(z) { }
   vec<T> operator+(const vec<T> &v) const 
      return vec < T > (x + v.x, y + v.y, z + v.z);
   vec<T>operator-(const vec<T> &v) const {
      return vec<T>(x - v.x, y - v.y, z - v.z);
   \text{vec} < T > \text{operator} * (T \ k) \ \text{const} \ \{
      return vec < T > (k * x, k * y, k * z);
   friend vec<T> operator*(T k, const vec<T> &v) {
      return vec < T > (v.x * k, v.y * k, v.z * k);
   \text{vec}(T) = \frac{1}{T} k
      T operator*(const vec<T> &v) const {
      return x * v.x + y * v.y + z * v.z;
   vec<T> operator^(const vec<T> &v) const {
      return { y * v.z - z * v.y, z * v.x - x * v.z, x * v
           .y - y * v.x };
   auto operator <=> (const vec <T> &v) const = default;
   bool operator==(const vec<T> &v) const = default;
   T norm() const {
      return x * x + y * y + z * z;
   double abs() const {
      return sqrt(norm());
   double cos(const vec<T> &v) const {
      return ((*this) * v) / (abs() * v.abs());
   friend ostream &operator<<(ostream &out, const vec<T> &v
        ) {
      return out << v.x << sp << v.y << sp << v.z;
   friend istream &operator>>(istream &in, vec<T> &v) {
      return in >> v.x >> v.y >> v.z;
};
```

# **Planimetry**

```
// Theme: Planimetry Objects
// Point
template <typename T>
struct point {
   T x, y;
   point() : x(0), y(0) { }
point(T x, T y) : x(x), y(y) { }
// Rectangle
template <typename T>
struct rectangle {
   point<T> ld, ru;
   rectangle(const\ point<T>\ \&ld,\ const\ point<T>\ \&ru)\ :
       ld(ld), ru(ru) { }
};
```

#### 4.3 Graham

```
// Theme: Convex Hull
// Algorithm: Graham Algorithm
// Complexity: O(N*log(N))
auto graham(const vector(vec(int>> &points) {
    vec<int> p0 = points[0];
    for (auto p : points)
       if (p.y < p0.y ||
p.y == p0.y && p.x > p0.x)
p0 = p;
    for (auto &p : points) {
       p.x -= p0.x;
       p.y -= p0.y;
   sort(all(points), [] (vec<int> &p1, vec<int> &p2) {
   return (p1 ^ p2).z > 0 ||
           (p1 ^ p2).z == 0 && p1.norm() > p2.norm(); });
    vector<vec<int>> hull;
    for (auto &p : points) {
   while (hull.size() >= 2 &&
    (((p - hull.back()) ^ (hull[hull.size() - 1] - hull[
             hull.size() - 2]))).z >= 0)
            hull.pop_back();
       hull.push_back(p);
   }
    for (auto &p : hull) {
       p.x += p0.x;
       p.y += p0.y;
   return hull;
```

#### 4.4 Formulae

#### Triangles.

Radius of circumscribed circle:

$$R = \frac{abc}{4S}$$
.

Radius of inscribed circle:

$$r = \frac{S}{p}$$
.

Side via medians:

$$a = \frac{2}{3}\sqrt{2(m_b^2 + m_c^2) - m_a^2}$$

Median via sides:

$$m_a = \frac{1}{2}\sqrt{2(b^2+c^2)-a^2}$$
.

Bisector via sides:

$$l_a = \frac{2\sqrt{bcp(p-a)}}{b+c}$$

 $l_a = rac{2\sqrt{bcp(p-a)}}{b+c}.$  Bisector via two sides and angle:

$$l_a = \frac{2bc\cos\frac{\alpha}{2}}{b+c}.$$

Bisector via two sides and divided side:

$$l_a = \sqrt{bc - a_b a_c}$$
.

### Right triangles.

*a*, *b* - cathets, *c* - hypotenuse.

h - height to hypotenuse, divides c to  $c_a$  and

$$\begin{cases} h^2 = c_a \cdot c_b, \\ a^2 = c_a \cdot c, \\ b^2 = c_b \cdot c. \end{cases}$$

#### Quadrangles.

Sides of circumscribed quadrangle:

$$a+c=b+d.$$

```
Square of circumscribed quadrangle: S = \frac{Pr}{2} = pr. Angles of inscribed quadrangle: \alpha + \gamma = \beta + \delta = 180^{\circ}. Square of inscribed quadrangle: S = \sqrt{(p-a)(p-b)(p-c)(p-d)}.
```

#### Circles.

line.

```
Intersection of circle and line: \begin{cases} (x-x_0)^2+(y-y_0)^2=R^2\\ y=ax+b \end{cases} Task comes to solution of \alpha x^2+\beta x+\gamma=0, where \begin{cases} \alpha=(1+a^2),\\ \beta=(2a(b-y_0)-2x_0),\\ \gamma=(x_0^2+(b-y_0)^2-R^2). \end{cases} Intersection of circle and circle:
```

Intersection of circle and circle:  $\begin{cases} (x-x_0)^2 + (y-y_0)^2 = R_0^2 \\ (x-x_1)^2 + (y-y_1)^2 = R_1^2 \end{cases}$   $y = \frac{1}{2} \frac{(R_1^2 - R_0^2) + (x_0^2 - x_1^2) + (y_0^2 - y_1^2)}{y_0 - y_1} - \frac{x_0 - x_1}{y_0 - y_1} x$  Task comes to intersection of circle and

# 5 Stringology

#### 5.1 Z Function

#### 5.2 Manacher

```
// Theme: Palindromes

// Algorithm: Manacher Algorithm
// Complexity: O(N)

int manacher(const string &s) {
   int n = s.size();
   vector<int> d1(n), d2(n);

for (int i = 0, l = 0, r = -1; i < n; i++) {
    int k = i > r ? 1 : min(d1[l + r - i], r - i + 1);
    while (i + k < n && i - k >= 0 && s[i + k] == s[i - k]) k++;
   d1[i] = k;
   if (i + k - 1 > r) {
```

```
1 = i - k + 1;

r = i + k - 1;
   }
}
for (int i = 0, l = 0, r = -1; i < n; i++) {
    int k = i > r ? 0 : min(d2[1 + r - i + 1], r - i +
         1);
    while (i + k < n \&\& i - k - 1 >= 0 \&\& s[i + k] == s[i - k - 1]) k++;
    d2[i] = k;
    if (i + k - 1 > r) {
       1 = i - k;
       r = i + k - 1;
    }
}
int res = 0;
for (int i = 0; i < n; i++) {
   res += d1[i] + d2[i];
return res;
```

#### **5.3** Trie

```
// Theme: Trie
// Algorithm: Aho-Corasick
// Complexity: O(N)
struct trie {
   // Vertex
   struct vertex {
       vector<int> next;
       bool leaf;
   // Alphabet size
   static const int N = 26;
   // Maximum Vertex Number
   static const int MX = 2e5 + 1;
   // Vertices Vector
   vector<vertex> t;
   int sz;
   trie(): sz(1) {
       t.resize(MX):
       t[0].next.assign(N, -1);
   void add_str(const string &s) {
       int v = 0;
for (int i = 0; i < s.length(); i++) {</pre>
          char c = s[i] - 'a';
if (t[v].next[c] == -1) {
              t[sz].next.assign(N, -1);
              t[v].next[c] = sz++;
           v = t[v].next[c];
       t[v].leaf = true;
};
```

#### 5.4 Prefix Function

```
// Theme: Prefix function

// Algorithm: Knuth-Morris-Pratt Algorithm
// Complexity: O(N)

auto pref_func(const string &s) {
   int n = s.size();
   vector<int> pi(n);

   for (int i = 1; i < n; i++) {
      int j = pi[i - 1];

      while (j > 0 && s[i] != s[j]) j = pi[j - 1];
}
```

```
if (s[i] == s[j]) j++;
    pi[i] = j;
}
    return pi;
}
```

# 5.5 Suffix Array

```
// Theme: Suffix array
// Algorithm: Binary Algorithm With Count Sort
// Complexity: O(N*log(N))
void count_sort(vector<int> &p, vector<int> &c) {
   int n = p.size();
   vector<int> cnt(n), p_new(n), pos(n);
   for (auto &x : c) cnt[x]++;
   pos[0] = 0;
   for (int i = 1; i < n; i++)
      pos[i] = pos[i - 1] + cnt[i - 1];
   for (auto &x : p) {
      int i = c[x];
p_new[pos[i]] = x;
      pos[i]++;
   p = p_new;
}
auto suffix_array(const string &str) {
   string s = str + '$';
   int n = s.size();
   vector<int> p(n), c(n);
vector<pair<char, int>> a(n);
   for (int i = 0; i < n; i++) a[i] = { str[i], i };
   sort(a.begin(), a.end());
   for (int i = 0; i < n; i++) p[i] = a[i].second;
   c[p[0]] = 0;
   for (int i = 1; i < n; i++)
      c[p[i]] = c[p[i-1]] + (a[i].first != a[i-1].
            first);
   int k = 0:
   while ((1 << k) < n) {
      for (int i = 0; i < n; i++)
          p[i] = (p[i] - (1 << k) + n) % n;
      count_sort(p, c);
      vector<int> c_new(n);
      c_new[p[0]] = 0;
       for (int i = 1; i < n; i++) {
          pair<int, int> prev = { c[p[i-1]], c[(p[i-1] + (1 << k)) % n] };
          pair < int, int > now = \{ c[p[i]], c[(p[i] + (1 << k
                )) % n] };
          c_{new}[p[i]] = c_{new}[p[i - 1]] + (now != prev);
      c = c_new;
      k++:
   return p;
```

# 6 Dynamic Programming

# 6.1 Longest Increasing Subsequence

```
// Theme: Longest Increasing Subsequence
// Algorithm: LIS via binary search
// Complexity: O(N*log(N))
vector<int> lis(vector<int>& arr) {
   int n = arr.size(); 
vector<int> dp(n + 1, INF); dp[0] = -INF; 
vector<int> pos(n + 1, -1), previous(n, -1);
    int length = 0;
   for (int i = 0; i < n; ++i) {
       int j = lower_bound(dp.begin(), dp.end(), arr[i]) -
             dp.begin();
       if (dp[j - 1] < arr[i] && arr[i] < dp[j]) {
   dp[j] = arr[i];</pre>
           pos[j] = i;
           previous[i] = pos[j - 1];
           length = max(length, j);
       }
   }
   vector<int> res;
   int p = pos[length];
   while (p != -1) {
       res.push_back(arr[p]);
       p = previous[p];
   reverse(res.begin(), res.end());
   return res:
```

# 6.2 Longest Common Subsequence

```
// Theme: Longest Common Subsequence
// Algorithm: LCS via simple dynamic
// Complexity: O(n*m)
vector<int> lis(vector<int>& arr) {
    int n = arr.size();
    \label{eq:contint} \begin{array}{ll} \text{vector} < \text{int} > \text{dp(n + 1, INF); dp[0]} = -\text{INF;} \\ \text{vector} < \text{int} > \text{pos(n + 1, -1), previous(n, -1);} \end{array}
    int length = 0;
    for (int i = 0; i < n; ++i) {
         int j = lower_bound(dp.begin(), dp.end(), arr[i]) -
         dp.begin();
if (dp[j - 1] < arr[i] && arr[i] < dp[j]) {
  dp[j] = arr[i];</pre>
             pos[j] = i;
              previous[i] = pos[j - 1];
              length = max(length, j);
        }
    }
    vector<int> res;
    int p = pos[length];
while (p != -1) {
        res.push_back(arr[p]);
         p = previous[p];
    reverse(res.begin(), res.end());
    return res;
```

# 7 Graphs

# 7.1 Graph Implementation

```
// Theme: Graph Implementation
```

```
// Adjacency List (Unoriented)
vector<vector<int>> graph;
graph.assign(n, {});
for (int i = 0; i < n; i++) {
  int u, v; cin \rightarrow u \rightarrow v; --u --v;
  graph[u].push_back(v);
  graph[v].push_back(u);
// Adjacency List (Oriented)
vector<vector<int>> graph;
vector<vector<int>> rgraph;
graph.assign(n, {})
rgraph.assign(n, {});
for (int i = 0; i < n; i++) {
  int u, v; cin >> u >> v; --u --v; graph[u].push_back(v);
  rgraph[v].push_back(u);
vector<pair<int, int>> edges;
vector<vector<int>> graph;
graph.assign(n, {});
for (int i = 0; i < n; i++) {    int u, v; cin >> u >> v; --u; --v;    edges.push_back({ u, v });
  graph[u].push_back(i);
  graph[v].push_back(i);
struct edge {
  int u, v, w;
edge(int u, int v, int w = 0)
     : u(u), v(v), w(w) { }
};
vector<edge> edges;
vector<vector<int>> graph;
graph.assign(n, {});
for (int i = 0; i < n; i++) {
  int u, v, w; cin >> u >> v >> w; --u; --v;
  edges.push_back({ u, v, w });
  graph[u].push_back(i);
  graph[v].push_back(i);
struct edge {
  int res() {
    return cap - flow;
};
```

## 7.2 Graph Traversing

```
// Theme: Graph Traversing
vector<vector<int>> graph;
vector<int> used;
// Algorithm: Depth-First Search (Adjacency List)
// Complexity: O(N + M)
void dfs(int cur, int p = -1) {
   used[cur] = 1;
   for (auto &to : graph[cur]) {
   if (to == p || used[to]) continue;
       dfs(to, cur);
}
// Algorithm: Breadth-First Search (Adjacency List)
// Complexity: O(N + M)
void bfs(int u) {
   queue < int > q; q.push(u);
   while (q.size()) {
       int cur = q.front(); q.pop();
       for (auto &to : graph[cur]) {
   if (used[to]) continue;
           q.push(to);
   }
```

## 7.3 Topological Sort

```
// Theme: Topological Sort

vector<vector<int>> graph;
vector<int> used;

// Algorithm: Topological Sort
// Complexity: O(N + M)

vector<int> topsort;

void dfs_topsort(int cur, int p = -1) {
    used[cur] = 1;

for (auto &to : graph[cur]) {
    if (to == p || used[to]) continue;
    dfs(to, cur);
  }

topsort.push_back(cur);
```

```
for (int u = 0; u < n; u++)
    if (!used[u])
        dfs_topsort(u);
reverse(all(topsort));</pre>
```

# 7.4 Connected Components

```
// Theme: Connectivity Components
vector<vector<int>> graph;
vector<int> used;
 / Algorithm: Connected Components
// Complexity: O(N + M)
vector<vector<int>> cc:
void dfs_cc(int cur, int p = -1) {
   used[cur] = 1;
   cc.back().push_back(cur);
   for (auto &to : graph[cur]) {
   if (to == p || used[to]) continue;
      dfs_cc(to, cur);
}
for (int u = 0; u < n; i++)
   if (!used[u])
      dfs_cc(u);
// Algorithm: Strongly Connected Components
// Complexity: O(N + M)
vector<vector<int>> rgraph:
vector<vector<int>> topsort;
vector<vector<int>> scc;
void dfs_scc(int cur, int p = -1) {
   used[cur] = 1;
   scc.back().push_back(cur);
   for (auto &to : rgraph[cur]) {
      if (to == p || used[to]) continue;
      dfs_scc(to, cur);
}
for (auto &u: topsort)
   if (!used[u])
      dfs_scc(u);
```

#### 7.5 2 Sat

```
// Theme: 2-SAT
// Algorithm: Adding Edges To 2-SAT
vector<vector<int>> ts_graph;
vector<vector<int>> ts_rgraph;
vector<int>used;
vector<int>top_sort;
// Vertex By Var Number
int to_vert(int x) {
   if (x < 0)
      return ((abs(x) - 1) << 1) ^ 1;
   else {
      return (x - 1) \leftrightarrow 1;
}
// Adding Implication
void add_impl(int a, int b) {
   ts_graph[a].insert(b);
   ts_rgraph[b].insert(a);
```

```
}
// Adding Disjunction
void add_or(int a, int b) {
   add_impl(a ^ 1, b);
   add_impl(b ^ 1, a);
//topsort
void dfs(int v){
   used[v] = 1;
    for(auto to:ts_graph[v]){
       if(!used[to])dfs(to);
   top_sort.push_back(v);
}
//scc
vector<vector<long long int>> scc;
void dfs_scc(long long int cur, long long int p = -1) {
   used[cur] = 1;
    scc.back().push_back(cur);
   for (auto to : rgr[cur]) {
   if (to == p || used[to]) continue;
       dfs_scc(to, cur);
}
int main(){
   used.resize(n,0);
   for(i=0;i<n;i++){
       if(!used[i])dfs(i);
   reverse(top_sort.begin(), top_sort.end());
for(auto it:top_sort){
       if (!used[u]) {
           scc.push_back({});
           dfs_scc(u);
       }
   vector<long long int>v_scc;
   v_{scc.assign(2 * n, -1)}
    for (int i = 0; i < scc.size(); i++)
       for (auto& u : scc[i])
           v_scc[u] = i;
   vector<long long int> values(2 * n, -1);
    for (int i = 0; i < 2 * n; i += 2)
       if (v_scc[i] == v_scc[i ^ 1]) {
   cout << "NO\n";</pre>
           return 0;
       else {
           if (v_scc[i] < v_scc[i ^ 1]) {</pre>
               values[i] = 0;
values[i ^ 1] = 1;
           else {
               values[i] = 1;
values[i ^ 1] = 0;
       }
}
```

# 7.6 Bridges

```
// Theme: Bridges And ECC
vector<pair<int, int>> edges;
vector<vector<int>> graph;
vector<int> used;

vector<int> height;
vector<int> up;

// Algorithm: Bridges
// Complexity: O(N + M)
vector<int> bridges;

void dfs_bridges(int cur, int p = -1) {
    used[cur] = 1;
    up[cur] = height[cur];
```

```
for (auto &ind : g[cur]) {
   int to = cur ^ edges[ind].ff ^ edges[ind].ss;
       if (to == p) continue;
       if (used[to]) {
           up[cur] = min(up[cur], height[to]);
           height[to] = height[cur] + 1;
           dfs_bridges(to, cur);
up[cur] = min(up[cur], up[to]);
           if (up[to] > height[cur])
               bridges.push_back(ind);
   }
}
// Algorithm: ECC
// Complexity: O(N + M)
vector<int> st;
vector<int> add_comp(vector<int> &st, int sz) {
   vector<int> comp;
   while (st.size() > sz) {
       comp.push_back(st.back());
       st.pop_back();
   return comp;
}
vector<vector<int>> ecc;
void dfs_bridges_comps(int cur, int p = -1) {
   used[cur] = 1;
up[cur] = height[cur];
   for (auto &ind : g[cur]) {
   int to = cur ^ edges[ind].ff ^ edges[ind].ss;
       if (to == p) continue;
       if (used[to]) {
           up[cur] = min(up[cur], height[to]);
       else {
           int sz = st.size();
           st.push_back(to);
height[to] = height[cur] + 1;
           dfs_bridges_comps(to, cur);
           up[cur] = min(up[cur], up[to]);
           if (up[to] > height[cur])
               ecc.push_back(add_comp(st, sz));
       }
   }
```

#### 7.7 Articulation Points

```
// Theme: Articulation Points And VCC
vector<pair<int, int>> edges;
vector<vector<int>> graph;
vector<int> used;

vector<int> height;
vector<int> up;

// Algorithm: Articulation Points
// Complexity: O(N + M)

set<int> art_points;

void dfs_artics(int cur, int p = -1) {
    used[cur] = 1;
    up[cur] = height[cur];
    int desc_count = 0;

for (auto &ind : g[cur]) {
      int to = cur ^ edges[ind].ff ^ edges[ind].ss;
      if (to == p) continue;
      if (used[to]) {
          up[cur] = min(up[cur], height[to]);
      }
      else {
```

```
desc_count++;
height[to] = height[cur] + 1;
            dfs_artics(to, cur);
up[cur] = min(up[cur], up[to]);
             if (up[to] \rightarrow = height[cur] \&\& p != -1)
                 art_points.insert(cur);
    }
    if (p == -1 \&\& desc\_count > 1) {
        art_points.insert(cur);
// Algorithm: VCC
// Complexity: O(N + M)
vector<vector<int>> vcc:
void dfs_artics_comps(int cur, int p = -1) {
    used[cur] = 1;
    up[cur] = height[cur];
    for (auto &ind : g[cur]) {
  int to = cur ^ edges[ind].ff ^ edges[ind].ss;
         if (to == p) continue;
         if (used[to]) {
            up[cur] = min(up[cur], height[to]);
if (height[to] < height[cur]) st.push_back(ind);</pre>
        else {
             int sz = st.size();
             st.push_back(ind);
            height[to] = height[cur] + 1;
dfs_artics_comps(to, cur);
up[cur] = min(up[cur], up[to]);
             if (up[to] >= height[cur])
                 vcc.push_back(add_comp(st, sz));
    }
```

#### 7.8 Kuhn

```
// Maximum Matching
// Algorithm: Kuhn Algorithm
// Complexity: O(|Left Part|^3)
vector<vector<int>> bigraph;
vector<int> used;
vector<int> mt:
bool kuhn(int u) {
   if (used[u]) return false;
   used[u] = 1:
   for (auto &v : bigraph[u]) {
      if (mt[v] == -1 \mid \mid kuhn(mt[v])) {
          mt[v] = u;
          return true;
      }
   }
   return false;
int main() {
      ... чтениеграфа...
      mt.assign(k, -1);
      for (int v=0; v<n; ++v) {
             used.assign (n, false);
             try_kuhn (v);
      }
      for (int i=0; i < k; ++i)
             if (mt[i] != -1)
                    printf ("%d %d\n", mt[i]+1, i+1);
}
```

#### 7.9 Kruskal

```
#include <iostream>
#include <vector>
#include <algorithm>
using namespace std;
struct dsu {
   vector<int> p, size;
       p.assign(n, 0); size.assign(n, 0);
        for (int i = 0; i < n; i++) {
           p[i] = i;
            size[i] = 1;
    \begin{array}{ll} \text{int get(int } v) \ \{ \\ & \text{if } (p[v] \ != v) \ p[v] \ = \ \text{get(}p[v] \ ); \end{array} 
       return p[v];
   void unite(int u, int v) {
        auto x = get(u), y = get(v);
       if (x == y) return;
if (size[x] > size[y]) swap(x, y);
p[x] = y; size[y] += size[x];
};
int sz;
struct edge {
   long long int u, v, w;
   edge(long long int uu, long long int vv, long long int
          ww) :u(uu), v(vv), w(ww) {};
vector<edge> edges;
vector<vector<int>> graph;
// Algorithm: Kruskal Algorithm
// Complexity: O(M)
vector<edae> mst:
void kruskal() {
   dsu d(sz);
   auto tedges = edges;
sort(tedges.begin(), tedges.end(), [](edge& e1, edge& e2
     ) { return e1.w < e2.w; });</pre>
   for (auto& e : tedges) {
       if (d.get(e.u) != d.get(e.v)) {
            mst.push_back(e);
            d.unite(e.u, e.v);
       }
   }
}
int main() {
   long long int n, m, i, j, k,a,b,c;
   cin >> n >> m;
for (i = 0; i < m; i++) {
       cin >> a >> b >> c;
        a--; b--;
        edge e(a, b, c);
        edges.push_back(e);
   sz = n;
   kruskal();
    long long int ans = 0;
    for (auto it : mst)ans += it.w;
   cout << ans;
```

# 7.10 LCA (binary Lifting)

```
// Theme: Lowest Common Ancestor
// Algorithm: Binary Lifting
```

```
// Complextiry: Preprocessing O(N * log(N)) and request O(
      log(N))
vector<vector<int>> q;
vector<int> d;
vector<vector<int>> dp;
vector<int> used;
void dfs(int v, int p = -1) {
 if (p == -1) {
   p = v;
    d[v] = 0;
 } else {
   d[v] = d[p] + 1;
 dp[0][v] = p;
for (int i = 1; i < dp.size(); i++) {
   dp[i][v] = dp[i - 1][dp[i - 1][v]];
 for (int to : g[v]) {
  if (to != p) {
     dfs(to, v);
   }
\begin{array}{c} \text{int lca(int a, int b) } \{ \\ \text{if } (\texttt{d[a]} \, > \, \texttt{d[b]}) \, \, \{ \end{array}
   swap(a, b);
 for (int i = dp.size() - 1; i >= 0; i--) { if (d[dp[i][b]] >= d[a]) { }}
     b = dp[i][b];
   }
 if (a == b) {
   return a;
  for (int i = dp.size() - 1; i >= 0; i--) {
   if (dp[i][a] != dp[i][b]) {
     a = dp[i][a];
     b = dp[i][b];
 return dp[0][a];
signed main() {
 int n = 0, m = 0; // n - vertex count, m - requests
 q.resize(n);
 dp.resize(((int)log2(n) + 1));
 used.assign(n, 0);
for (int i = 0; i < dp.size(); i++) {
   dp[i].resize(n);
 // ...reading graph...
 dfs(0).
 // ...lca(u -1, v - 1) + 1
```

# 7.11 LCA RMQ (seqtree)

```
// Theme: Lowest Common Ancestor

// Algorithm: RMQ (seqtree)

// Complextiry: Preprocessing O(N) and request O(log(N))

typedef vector<vector<int>> graph;
typedef vector<int>::const_iterator const_graph_iter;

vector<int> lca_h, lca_dfs_list, lca_first, lca_tree;
vector<char> lca_dfs_used;

void lca_dfs(const graph &g, int v, int h = 1) {
    lca_dfs_used[v] = true;
    lca_h[v] = h;
}
```

```
{\tt lca\_dfs\_list.push\_back(v);}
 for (const\_graph\_iter\ i = g[v].begin();\ i != g[v].end();
        ++i)
   if (!lca_dfs_used[*i]) {
     lca_dfs(g, *i, h + 1);
lca_dfs_list.push_back(v);
}
void lca build tree(int i, int l, int r) {
 if (1 == r)
   lca_tree[i] = lca_dfs_list[l];
   int m = (l + r) \gg 1;
   lca_build_tree(i + i, 1, m);
lca_build_tree(i + i + 1, m + 1, r);
if (lca_h[lca_tree[i + i]] < lca_h[lca_tree[i + i + 1]])
     lca_tree[i] = lca_tree[i + i];
     lca_tree[i] = lca_tree[i + i + 1];
 }
}
void lca_prepare(const graph &g, int root) {
 int n = (int)g.size();
 lca_h.resize(n);
 lca\_dfs\_list.reserve(n * 2);
 lca_dfs_used.assign(n, 0);
 lca_dfs(g, root);
int m = (int)lca_dfs_list.size();
 lca_tree.assign(lca_dfs_list.size() * 4 + 1, -1);
 lca_build_tree(1, 0, m - 1);
lca_first.assign(n, -1);
 for (int i = 0; i < m; ++i) {
  int v = lca_dfs_list[i];</pre>
   if (lca_first[v] == -1)
     lca_first[v] = i;
}
int lca_tree_min(int i, int sl, int sr, int l, int r) {
 if (sl == 1 && sr == r)
   return lca_tree[i];
 int sm = (sl + sr) >> 1;
 if (r \leftarrow sm)
   return lca_tree_min(i + i, sl, sm, l, r);
 if (1 \rightarrow sm)
   return lca_tree_min(i + i + 1, sm + 1, sr, l, r);
 int ans1 = lca\_tree\_min(i + i, sl, sm, l, sm);
 int ans2 = lca\_tree\_min(i + i + 1, sm + 1, sr, sm + 1, r)
 \label{lem:condition} return \ lca\_h[ans1] \ < \ lca\_h[ans2] \ ? \ ans1 \ : \ ans2;
}
int lca(int a, int b) {
 int left = lca_first[a],
     right = lca_first[b];
 \quad \text{if (left > right)} \\
   swap(left, right);
 return lca_tree_min(1, 0, (int)lca_dfs_list.size() - 1,
        left, right);
}
signed main() {
 int n = 0, m = 0; // n - vertex count, m - requests graph g(n);
 // ...reading graph...
 lca_prepare(g, 0);
 // ...lca(u -1, v - 1) + 1
```

#### 7.12 Maximum Flow

```
// Theme: Maximum Flow
int s, t, sz;
vector<edge> edges;
vector<vector<int>> fgraph;
vector<int> used;
```

```
// Algorithm: Ford-Fulkerson Algorithm
// Complexity: O(MF)
int dfs_fordfulk(int u, int bound, int flow = INF) {
  if (used[u]) return 0;
   if (u == t) return flow;
   used[u] = 1;
   for (auto &ind : fgraph[u]) {
       auto &e = edges[ind],
           &_e = edges[ind ^ 1];
       int to = e.to, res = e.res();
       if (res < bound) continue;
       int pushed = dfs_fordfulk(to, bound, min(res, flow))
       if (pushed) {
           e.flow += pushed;
_e.flow -= pushed;
          return pushed;
       }
   }
   return 0;
}
// Algorithm: Edmonds-Karp Algorithm
// Complexity: O(N(M^2))
vector<int> p;
vector<int> pe;
void augment(int pushed) {
   int cur = t;
   while (cur != s) {
       auto &e = edges[pe[cur]],
   &_e = edges[pe[cur] ^ 1];
       e.flow += pushed;
       _e.flow -= pushed;
       cur = p[cur];
}
int bfs_edmskarp(int u, int bound) {
   p.assign(sz, -1);
pe.assign(sz, -1);
   int pushed = 0;
   queue<pair<int, int>> q;
q.push({ u, INF });
   used[u] = 1;
   while (q.size()) {
       auto [v, f] = q.front(); q.pop();
       for (auto &ind : fgraph[v]) {
           auto &e = edges[ind];
           int to = e.to, res = e.res();
           if (used[to] || res < bound) continue;
           p[to] = v;
           pe[to] = ind;
           used[to] = 1;
           if (to == t) {
              pushed = min(f, res);
              break:
           q.push({ to, min(f, res) });
       }
   }
   if (pushed)
       augment(pushed);
   return pushed;
}
// Algorithm: Dinic Algorithm
// Complexity: O((N^2)M)
```

```
vector<int> d;
bool bfs_dinic(int u, int bound) {
   d.assign(sz, INF); d[u] = 0;
   queue<int> q; q.push(u);
   while (q.size()) {
       int v = q.front(); q.pop();
       for (auto &ind : fgraph[v]) {
           auto &e = edges[ind];
           int to = e.to, res = e.res();
           if (d[v] + 1 \Rightarrow d[to] || res < bound) continue;
           d[to] = d[v] + 1;
           q.push(to);
   }
   return d[t] != INF;
}
vector<int> lst;
int dfs_dinic(int u, int mxf = INF) {
   if (u == t) return mxf;
    for (int i = lst[u]; i < fgraph[u].size(); i++) {
       int ind = fgraph[u][i];
       auto &e = edges[ind],
    &_e = edges[ind ^ 1];
       int to = e.to, res = e.res();
       if (d[to] == d[u] + 1 \&\& res) {
           int pushed = dfs_dinic(to, min(res, mxf - smf));
           if (pushed) {
               smf += pushed;
               e.flow += pushed;
               _e.flow -= pushed;
       }
       lst[u]++;
       if (smf == mxf)
           return smf;
   return smf;
}
int dinic(int u) {
   int pushed = 0;
   for (int bound = 111 \langle\langle 30; bound; bound \rangle\rangle = 1) {
       while (true) {
           bool bfs_ok = bfs_dinic(u, bound);
           if (!bfs_ok) break;
           lst.assign(sz, 0);
           while (true) {
               int dfs_pushed = dfs_dinic(u);
              if (!dfs_pushed) break;
              pushed += dfs_pushed;
          }
       }
   }
   return pushed;
}
// Algorithm: Maximum Flow Of Minimum Cost (SPFA)
// Complexity: ...
vector(int) d:
vector<int> p;
vector<int> pe;
void augment(int pushed) {
```

```
int cur = t;
   while (cur != s) {
      auto &e = edges[pe[cur]],
         &_e = edges[pe[cur] ^ 1];
      e.flow += pushed;
      _e.flow -= pushed;
      cur = p[cur];
   }
}
int bfs_spfa(int u, int flow = INF) {
   d.assign(sz, INF); d[u] = 0;
   p.assign(sz, -1);
   pe.assign(sz, -1);
   int pushed = 0;
   while (q.size()) {
      auto [v, f] = q.front(); q.pop();
      in_q[v] = 0;
      if (v == t) {
         pushed = f;
         break:
      for (auto &ind : fgraph[v]) {
         auto &e = edges[ind];
         int to = e.to, res = e.res(),
            w = e.weight;
         if (d[v] + w >= d[to] || !res) continue;
         d[to] = d[v] + w;
         p[to] = v;
         pe[to] = ind;
         if (!in_q[to]) {
            in_q[to] = 1;
q.push({ to, min(f, res) });
      }
   }
   if (pushed)
      augment(pushed);
   return pushed;
```

#### 7.13 Eulerian Path

```
// Theme: Eulerian Path
int sz;
vector<vector<int>> graph;
// Algorithm: Eulerian Path
// Complexity: O(M)
vector<int> eul;
// 0 - path not exist
// 1 - cycle exits
// 2 - path exists
int euler_path() {
   vector<int> deg(sz);
   int v1 = -1, v2 = -1;
for (int i = 0; i < sz; i++)
      if (deg[i] & 1)
         if (v1 == -1) v1 = i;
         else if (v2 == -1) v2 = i;
         else return 0;
   if (v1 != -1) {
```

```
if (v2 == -1)
   return 0;
graph[v1][v2]++;
   graph[v2][v1]++;
stack<int> st;
for (int i = 0; i < sz; i++) {
    if (deg[i]) {
        st.push(i);
        break;
}
while (st.size())
    int u = st.top();
    int ind = -1;
    for (int i = 0; i < sz; i++)
if (graph[u][i]) {
            ind = i;
            break;
        }
    if (ind == -1) {
        eul.push_back(u);
        st.pop():
    else {
        graph[u][ind]--;
        graph[ind][u]--;
        st.push(ind);
int res = 2;
if (v1 != -1) {
   res = 1:
    for (int i = 0; i < eul.size() - 1; i++)
        if (eul[i] == v1 && eul[i + 1] == v2 ||
eul[i] == v2 && eul[i + 1] == v1) {
            vector<int> teul;
            for (int j = i + 1; j < eul.size(); j++)
  teul.push_back(eul[j]);
for (int j = 0; j <= i; j++)</pre>
                teul.push_back(eul[j]);
            eul = teul;
            break;
        }
}
for (int i = 0; i < sz; i++)
    for (int j = 0; j < sz; j++)
if (graph[i][j])
            return 0;
return res;
```

#### 7.14 Eulerian Path Oriented

}

```
// Theme: Eulerian Path
// Algorithm: Eulerian Path
// Complexity: O(M)

// Algo doesn't validate the path to be correct.
// If the path exists, it will be found.
// Result way has to be reversed after execution.

struct Edge {
   int v, u;
   bool deleted = false;
};

vector<Edge> edges;

vector<deque<int>> graph;
vector<int> way;

void euler(int v, int last = -1) {
   while (!graph[v].empty()) {
```

#### 7.15 Shortest Paths

```
// Theme: Shortest Paths
vector<edge> edges;
vector<vector<int>> graph;
// Algorithm: Dijkstra Algorithm
// Complexity: O(M*log(N))
vector<int> d;
vector<int> p:
void dijkstra(int u) {
   d.assign(sz, INF); d[u] = 0;
   p.assign(sz, -1);
   priority_queue<pair<int, int>> q;
   q.push({ 0, u });
   while (q.size()) {
       int dist = -q.top().ff, v = q.top().ss; q.pop();
       if (dist > d[v]) continue;
       for (auto &ind : graph[v]) {
   int to = v ^ edges[ind].u ^ edges[ind].v,
               w = edges[ind].w;
           if (d[v] + w < d[to]) {
   d[to] = d[v] + w;</pre>
               p[to] = v;
               q.push({ -d[to], -to });
           }
      }
   }
// Algorithm: Shortest Path Faster Algorithm
// Complexity: ...
vector<int> d;
void bfs_spfa(int u) {
   d.assign(sz, INF); d[u] = 0;
   queue<int> q; q.push(u);
    vector(int) in_q(sz, 0); in_q[u] = 1;
   while (q.size()) {
       auto [v, f] = q.front(); q.pop();
       in_q[v] = 0;
       for (auto &ind : graph[v]) {
  int to = v ^ edges[ind].u ^ edges[ind].v,
     w = edges[ind].w;
}
           if (d[v] + w < d[to]) {
   d[to] = d[v] + w;
               if (!in_q[to]) {
                  in_q[to] = 1;
                  q.push( to );
              }
          }
      }
   }
// Algorithm: Belman-Ford Algorithm
// Complexity: (N*M)
vector<int> d:
void bfa(int u) {
```

```
d.assign(sz, INF); d[u] = 0;
   for (;;) {
       bool any = false;
       for (auto &e : edges) {
          if (d[e.u] != INF \&\& d[e.u] + e.w < d[e.v]) {
              d[e.v] = d[e.u] + e.w;
              any = true;
          if (d[e.v] != INF && d[e.v] + e.w < d[e.u]) {
              d[e.u] = d[e.v] + e.w;
              any = true;
          }
       }
       if (!any) break;
   }
// Algorithm: Floyd-Warshall Algorithm
// Complexity: O(N^3)
vector<vector<int>> d;
void fwa() {
   d.assign(sz, vector<int>(sz, INF));
   for (int i = 0; i < sz; i++)
       for (int j = 0; j < sz; j++)
for (int k = 0; k < sz; k++)
if (d[i][k] != INF && d[k][j] != INF)
                  d[i][j] = min(d[i][j], d[i][k] + d[k][j]);
}
```

## 8 Miscellaneous

# 8.1 Ternary Search

```
// Theme: Ternary Search
// Algorithm: Continuous Search With Golden Ratio
// Complexity: O(log(N))
// Golden Ratio
// Phi = 1.618...
double phi = (1 + sqrt(5)) / 2;
double cont_tern_srch(double 1, double r) {
 double m1 = 1 + (r - 1) / (1 + phi),

m2 = r - (r - 1) / (1 + phi);
 double f1 = f(m1), f2 = f(m2);
  int count = 200;
  while (count--) {
   if (f1 < f2) {
     r = m2;
     m2 = m1;
     f2 = f1;

m1 = 1 + (r - 1) / (1 + phi);
     f1 = f(m1);
   else {
     1 = m1;
     m1 = m2;
     f1 = f2;

m2 = r - (r - 1) / (1 + phi);
     f2 = f(m2);
 return f((l + r) / 2);
}
// Algorithm: Discrete Search
// Complexity: O(log(N))
if (f(m1) < f(m2))
```

```
r = m2;
else
    1 = m1;
}
return min(f(1), min(f(1 + 1), f(r)));
}
```