

Assignment 12 - Search Trees and Hashing

Q1.

```
static class Node {
    private int data;
    private Node left;
    private Node right;

    Node(int data) {
        this.data = data;
        this.left = this.right = null;
    }
}

static Node findLeftMost(Node root) {
    // helper function to traverse

    if (root == null) {
        return null;
    }

    while (root.left != null) {
        root = root.left;
    }

    return root;
}

static Node deleteNode(Node root) {
    // node with only one child or none
    if (root.left == null) {
        Node child = root.right;
        root = null;
        return child;
    } else if (root.right == null) {
        Node child = root.left;
        root = null;
        return child;
    }
}
```

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        // Node with two children, get inorder successor in the right sub-tree
        Node next = findLeftMost(root.right);
        root.data = next.data;
        root.right = deleteNode(root.right);

        // return root pointer
        return root;
    }

    static Node delete(Node root, int key1, int key2){
        // base
        if (root == null){
            return null;
        }

        // traverse BST
        root.left = delete(root.left, key1, key2);
        root.right = delete(root.right, key1, key2);

        // once root's data is in the range, call deletenode
        if (root.data >= key1 && root.data <= key2){
            return deleteNode(root);
        }

        return root;
    }
}

```

Q2:

```
public class Q2 {  
    static class BNode{  
        private int cnt;  
        private int[] keys;  
        private BNode[] children;  
        private boolean leaf;  
  
        BNode(int n, BNode parent){  
            this.cnt = 0; // count of keys  
            this.keys = new int[n-1]; // array list of keys  
            this.children = new BNode[n]; // array list of children (BNode)  
            this.leaf = true; // boolean for leaf node or not  
            this.parent = parent; // a pointer to parent node  
        }  
    }  
  
    static class BTree{  
  
        private int order; // order of BTree  
        private BNode head; // a pointer for BNode head  
  
        BTree(int order){  
            this.order = order;  
            this.head = new BNode(order, null);  
        }  
    }  
  
    public BNode search(BNode root, int key){  
        int i = 0;  
        while (i < root.cnt && root.keys[i] < key ){  
            i++;  
        }  
  
        if (i<= root.cnt && root.keys[i] == key){  
            return root;  
        }  
  
        if (root.leaf){
```

```

        return null;
    } else {
        return search(root.children[i], key);
    }
}

public void deleteKey(BTree root, int key){
    BNode tmp = search(root.head, key);

    // deletion occurs at leaf node
    if (tmp.leaf) {
        int i = 0;

        // searching through keys
        while (tmp.keys[i] < key){
            i++;
        }

        while (i < tmp.cnt){
            tmp.keys[i] = tmp.keys[i+1];
            i++;
        }
        tmp.cnt--;
    } else {
        // deletion at non-leaf BNode
    }
}
}

```

Q3:

For a hash table having tablesize positions and n records already occupied, the $lf = n/tablesize$. Since new keys are uniformly distributed to the hash table, the possibility that n+1th element's insertion causes collision would be $n/table\ size = lf$, like a table below:

Key ID	P(Collision)
1	$0/tablesize$
2	$1/tablesize$
3	$2/tablesize$
...	
n	$(n-1)/tablesize$

Therefore, an expected number of collisions would be the sum of each independent possibility of collision for n keys:

$$\begin{aligned}
 E(\text{ \# of collisions }) &= \sum_{i=1}^{n-1} \frac{i}{tablesize} = \frac{1}{tablesize} + \frac{2}{tablesize} + \dots + \frac{n-1}{tablesize} \\
 &= \frac{1}{tablesize} \cdot \frac{(n-1+1)(n-1)}{2} = \frac{n}{tablesize} \cdot \frac{n-1}{2} = \frac{lf \cdot (n-1)}{2}
 \end{aligned}$$

Q4:

The number of occupied slots in the tablesize-sized hash table is n.

If start by counting the number of insertions for each item, the numbers of comparisons would be:

For the first element, n = 0 is occupied, # of comparison is exactly one = $(tablesize+1)/(tablesize-0+1)$.

For the second element, n = 1, so # of comparisons is: $(tablesize+1)/tablesize = 1 + 1/tablesize = 1 + 1/P(\text{insertion collides for } n=1)$

If the hash table is full, so n = tablesize, # of comparisons = $(tablesize+1)/1 = tablesize+1$.

So that the average number of comparisons needed to insert a new element = $(tablesize+1)/(tablesize-n+1)$.

On the other hand, linear probing will not satisfy this condition since it always requires more sequential comparisons, and the number will be over the average number.