

# TIME-VARYING TRANSITION PROBABILITY MATRIX

## APPLICATION TO BRAND SHARE ANALYSIS

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## Introduction

- motivated examples

- stationary distribution of Google matrix

## Problem Formulation

- time-varying graph and transition matrix

- graph estimation problem

## Numerical Examples

- real-world data analysis

## Conclusion

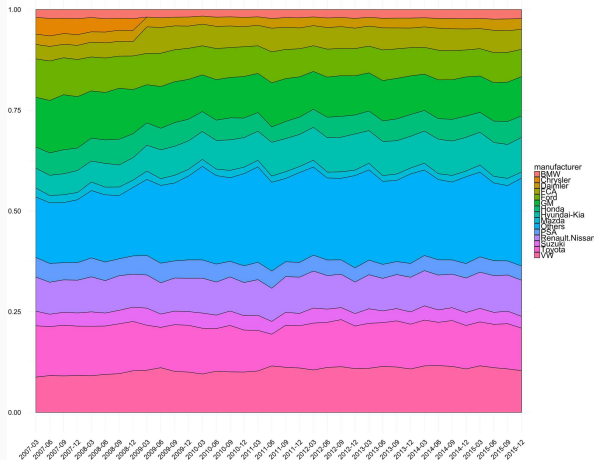
# INTRODUCTION

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two problems in graph inference:

- **direct problem (deductive):**  
induce properties from known graph structure
  - shortest path, traveling salesman, graph coloring %problem
  - maximum flow, minimum cut %problem
  - Google search (stationary distribution of Google matrix)
- **inverse problem (inductive):**  
estimate graph structure from partially observed properties
  - path analysis, graphical model estimation
  - sparse estimation of accuracy matrix
  - structure estimation via graph Laplacian

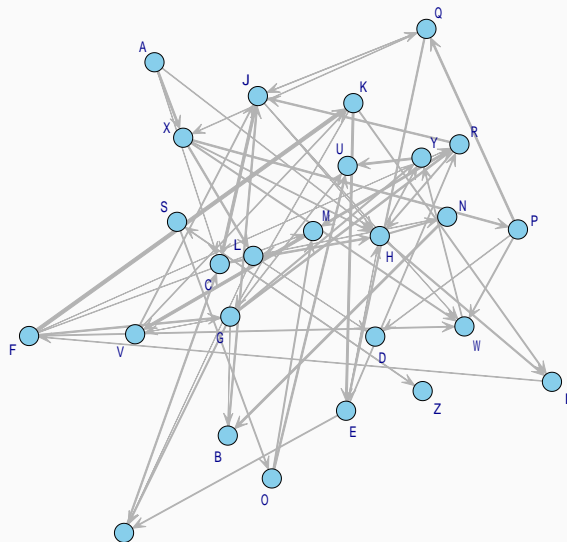
automobile sales data of manufacturers



## Questions

- why sales shares vary?
- what happens in customer preferences?

weighted graph



directed graph

- number of node: 26
- edge exist.: 0.1
- weight:  
uniform on  $[0, 1]$

- adjacency matrix  $W$

$(W)_{ij}$  = strength of connection from  $i$  to  $j$

- indicate vector of sink node  $\mathbf{a}$

$$(\mathbf{a})_i = \begin{cases} 1, & \text{if } (W\mathbf{e})_i = 0 \\ 0, & \text{otherwise} \end{cases}$$

where  $\mathbf{e}$  is a vector of all 1

- normalized adjacency matrix (transition matrix)  $H$

$$H = \text{diag}(W\mathbf{e} + \mathbf{a})^{-1}W$$

$(H\mathbf{e})_i = 1$  holds except for sink nodes

- transition matrix with sink node adjustment  $S$

$$S = H + \mathbf{a}\mathbf{e}^T/n$$

= (probabilistic transition)  
+ (escape from sink nodes)

probability matrix:  $S\mathbf{e} = \mathbf{e}$

- Google matrix  $G$

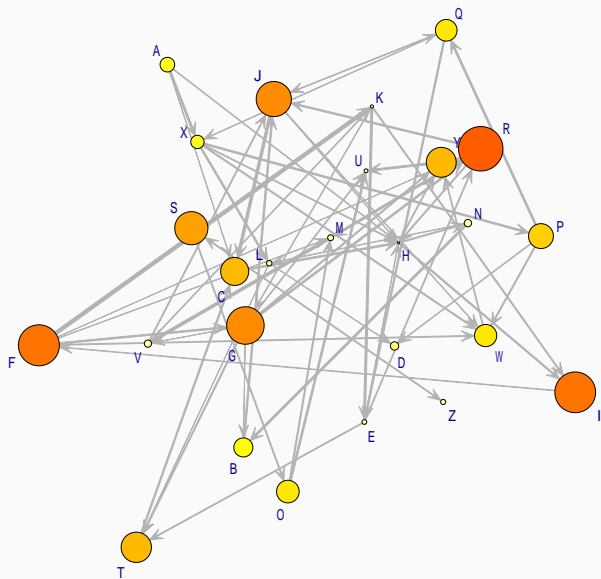
$$G = \alpha S + (1 - \alpha)\mathbf{e}\mathbf{e}^T/n$$

= (transition along edges) + (random transition)

probability matrix:  $G\mathbf{e} = \mathbf{e}$

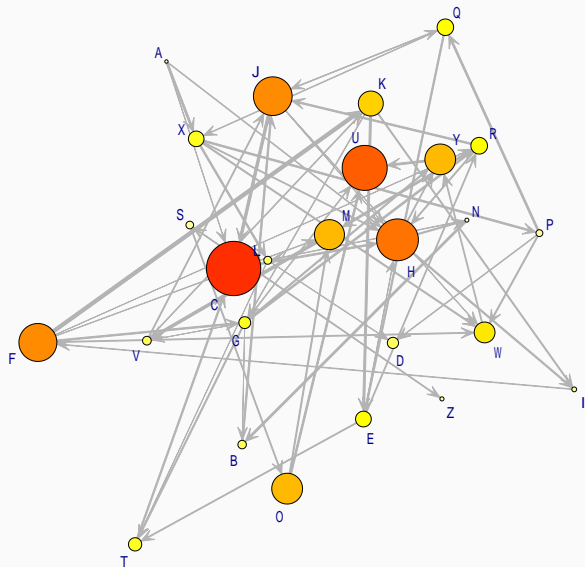


$t = 1$



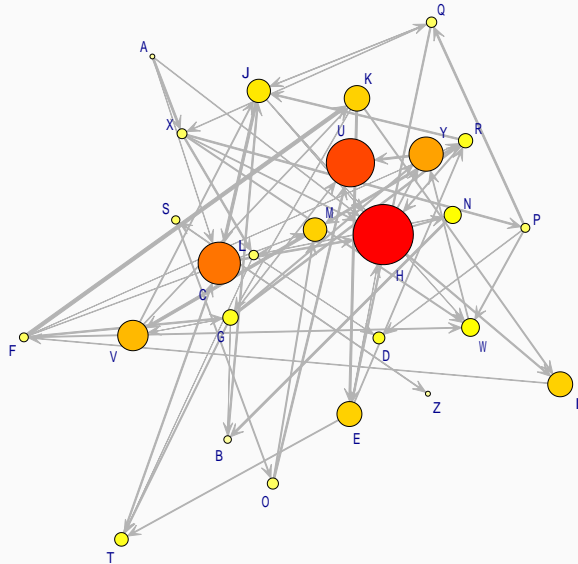
- $\alpha = 0.85$
- initial: \ uniform dist.

$t = 2$



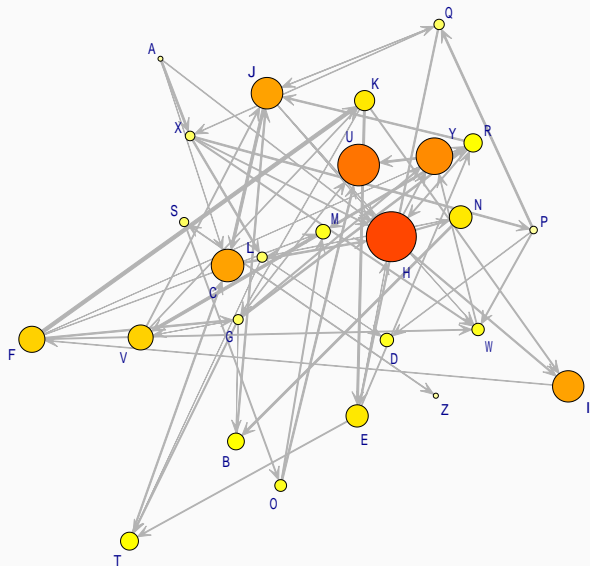
- $\alpha = 0.85$
- initial: \ uniform dist.

$t = 3$



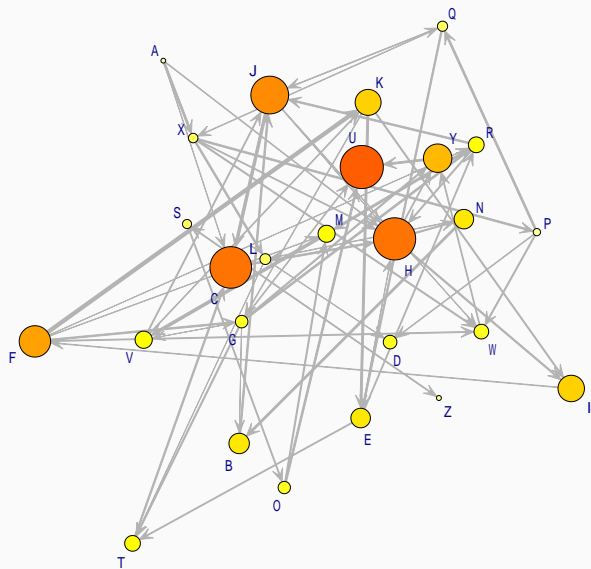
- $\alpha = 0.85$
- initial: \ uniform dist.

t = 4



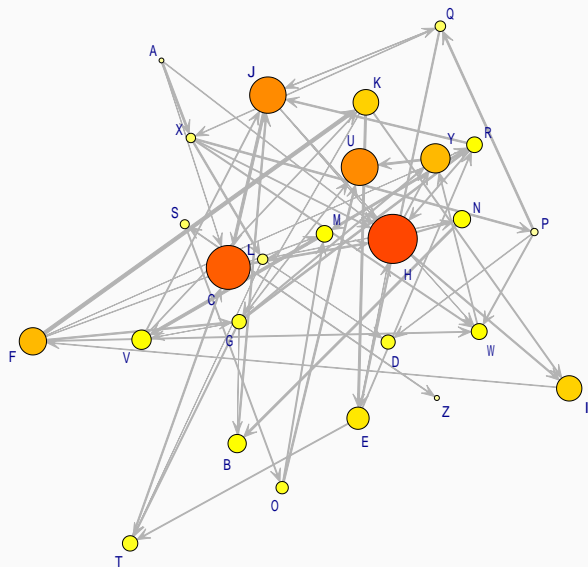
- $\alpha = 0.85$
- initial: \ uniform dist.

t = 5



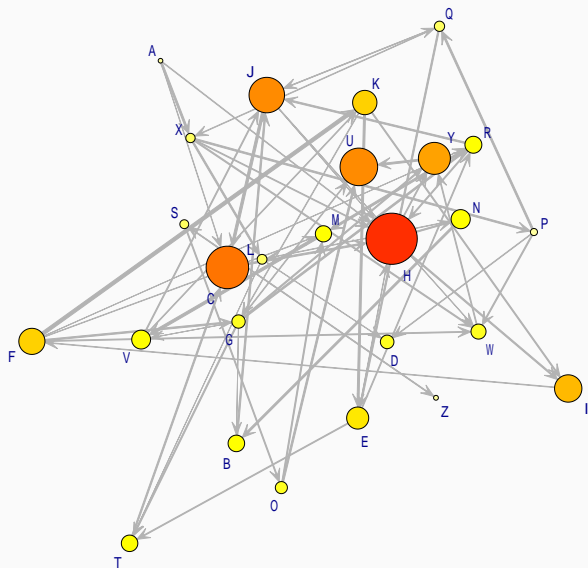
- $\alpha = 0.85$
- initial: \ uniform dist.

t = 6



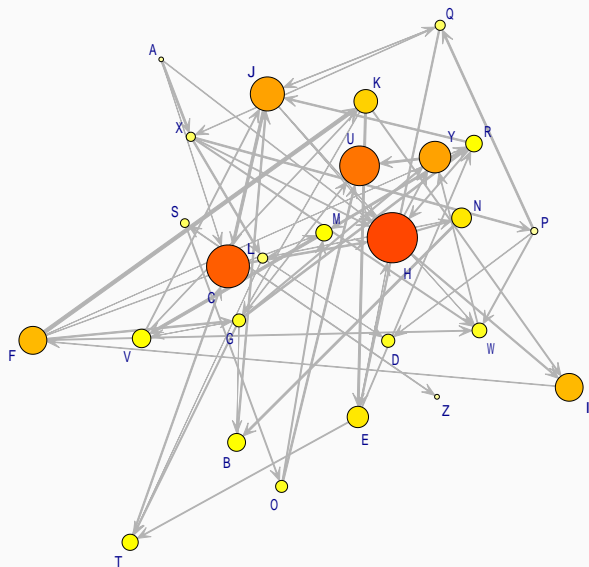
- $\alpha = 0.85$
- initial: \ uniform dist.

$t = 7$



- $\alpha = 0.85$
- initial: \ uniform dist.

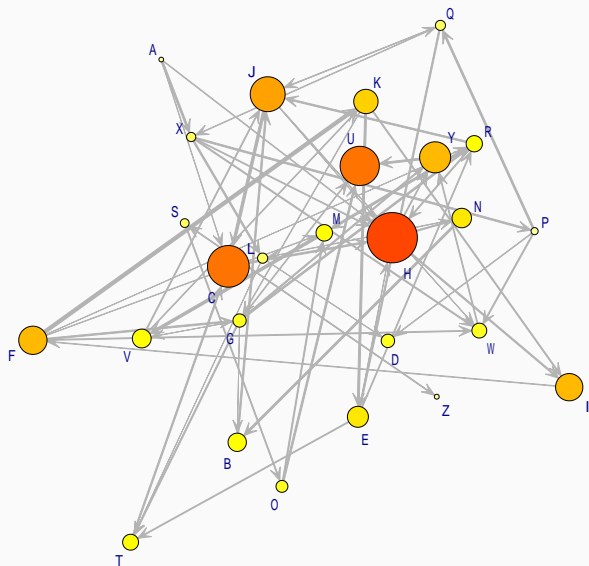
$t = 8$



- $\alpha = 0.85$
- initial: \ uniform dist.

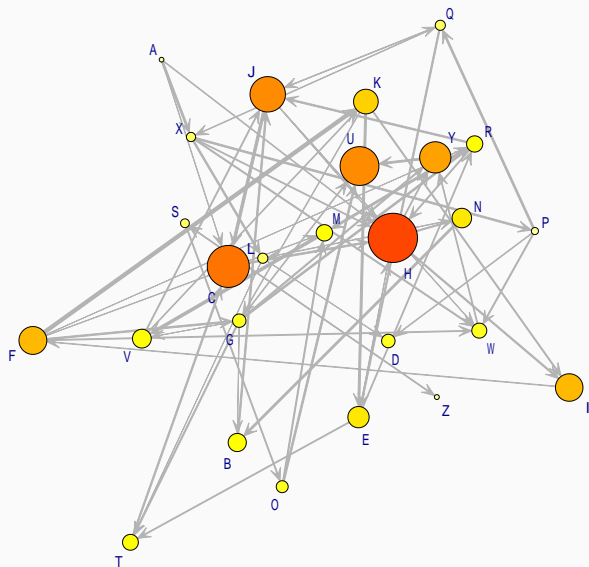


$t = 9$



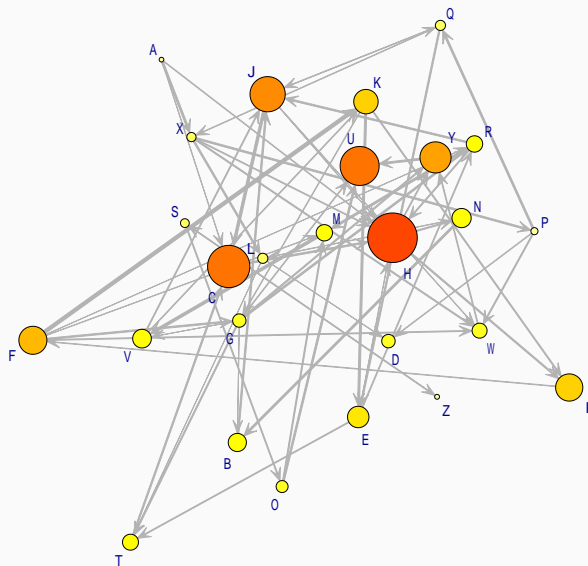
- $\alpha = 0.85$
- initial: \ uniform dist.

$t = 10$



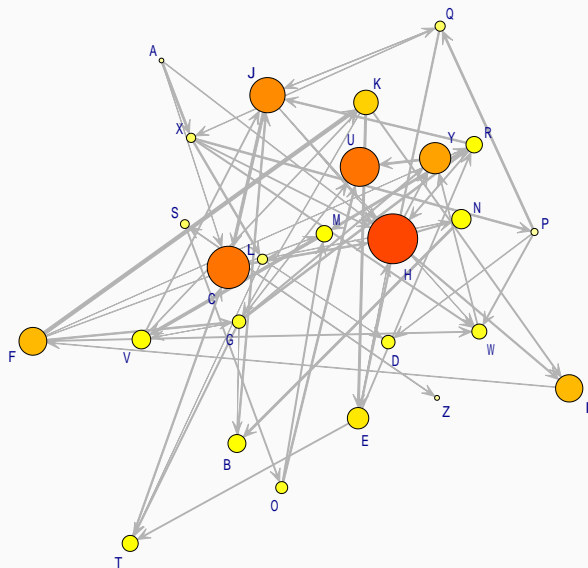
- $\alpha = 0.85$
- initial: \ uniform dist.

t = 11



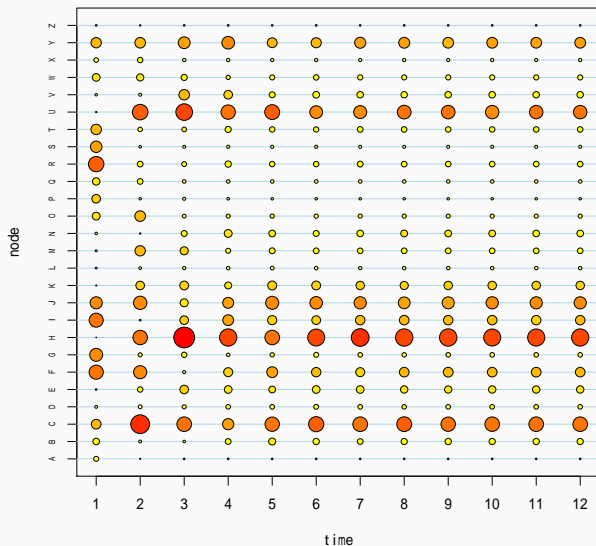
- $\alpha = 0.85$
- initial: \ uniform dist.

$t = 12$



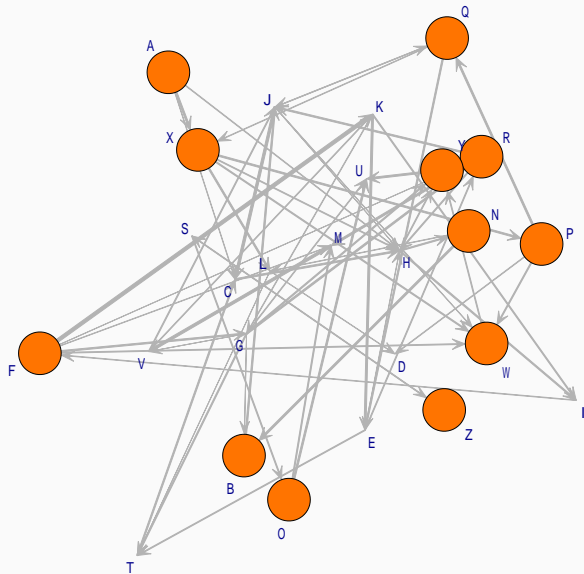
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# transient process



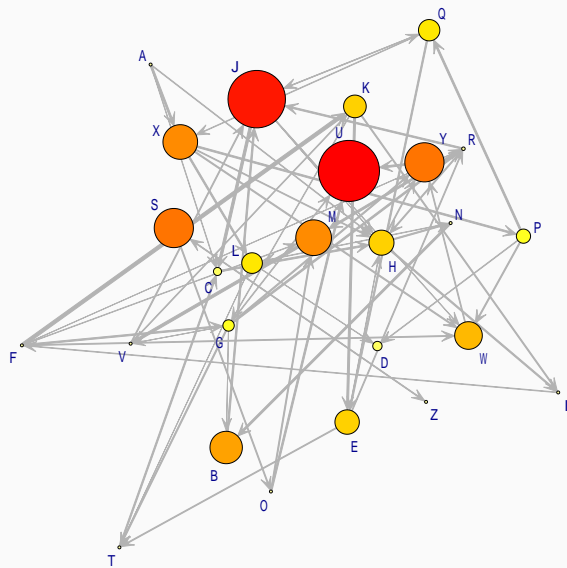
- $\alpha = 0.85$
- initial: \ uniform dist.

$t = 1$



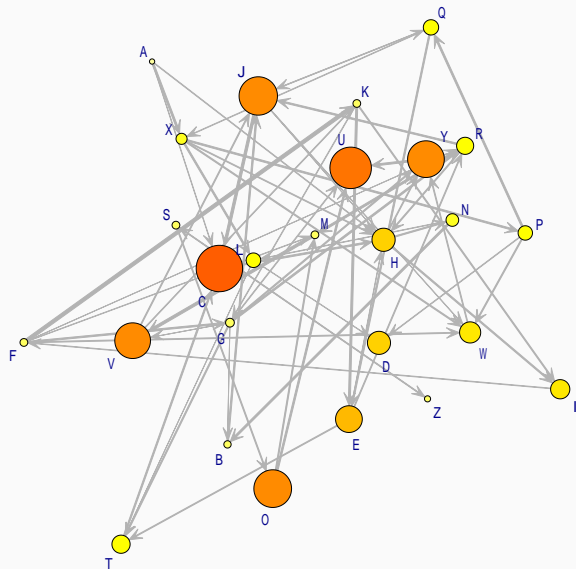
- $\alpha = 0.85$
- initial:  
12 nodes

t = 2



- $\alpha = 0.85$
- initial:  
12 nodes

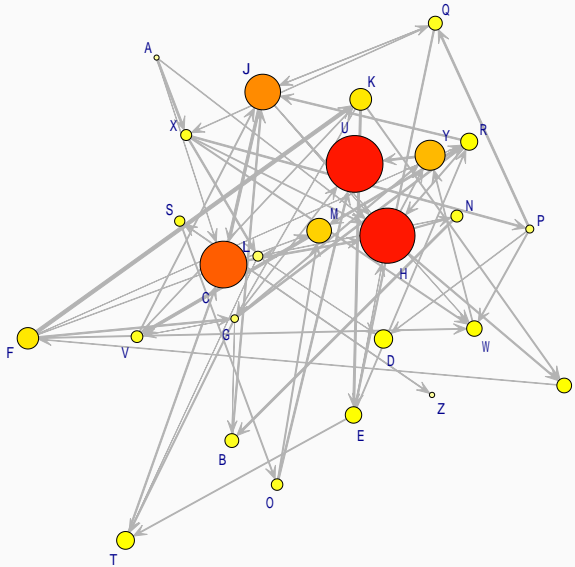
t = 3



- $\alpha = 0.85$
- initial:  
12 nodes

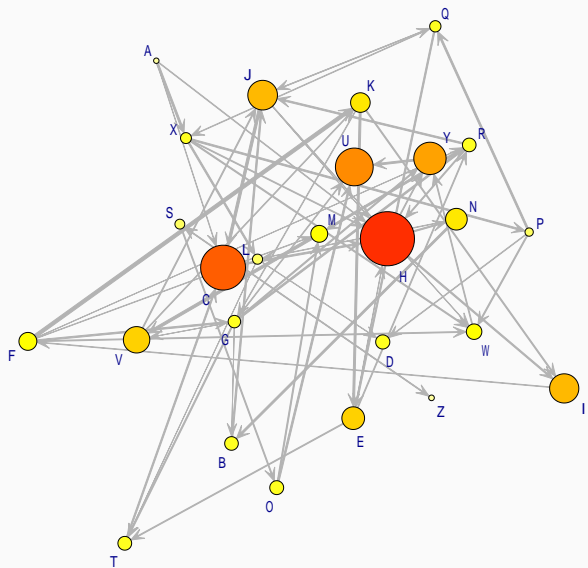


$t = 4$



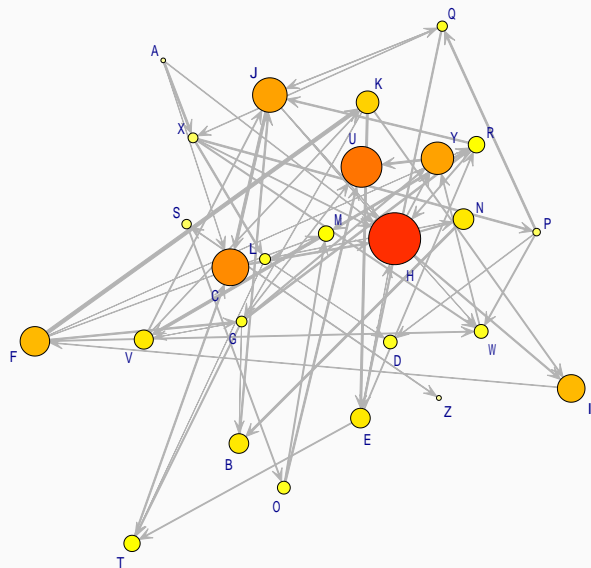
- $\alpha = 0.85$
- initial:  
12 nodes

t = 5



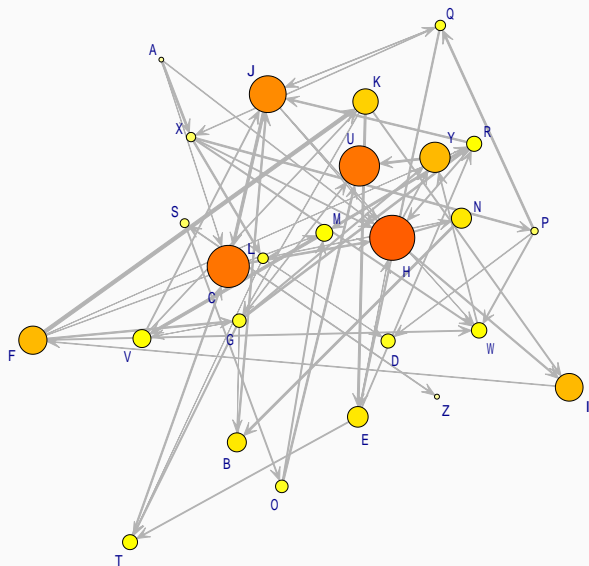
- $\alpha = 0.85$
- initial:  
12 nodes

t = 6



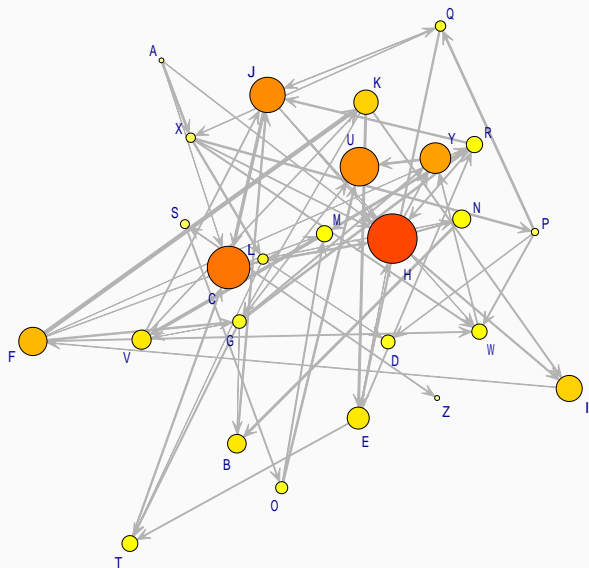
- $\alpha = 0.85$
- initial:  
12 nodes

t = 7



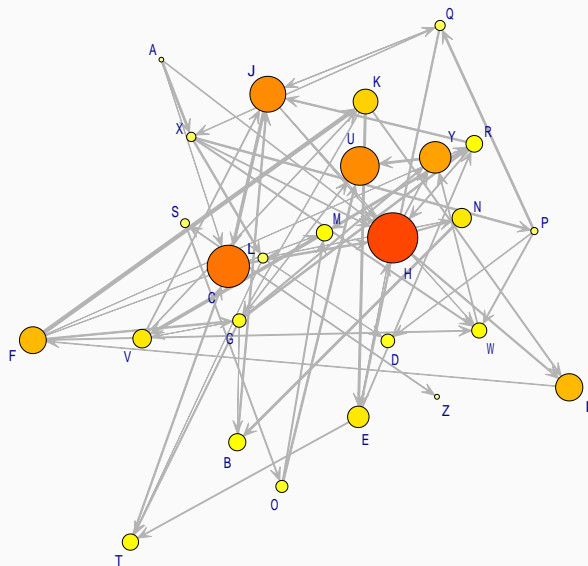
- $\alpha = 0.85$
- initial:  
12 nodes

t = 8



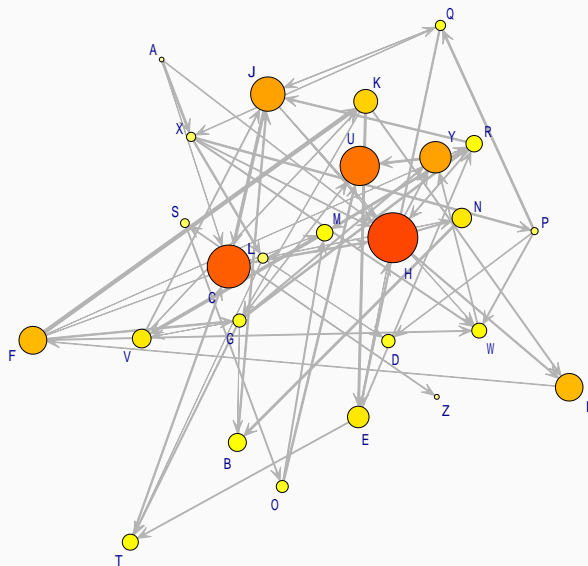
- $\alpha = 0.85$
- initial:  
12 nodes

t = 9



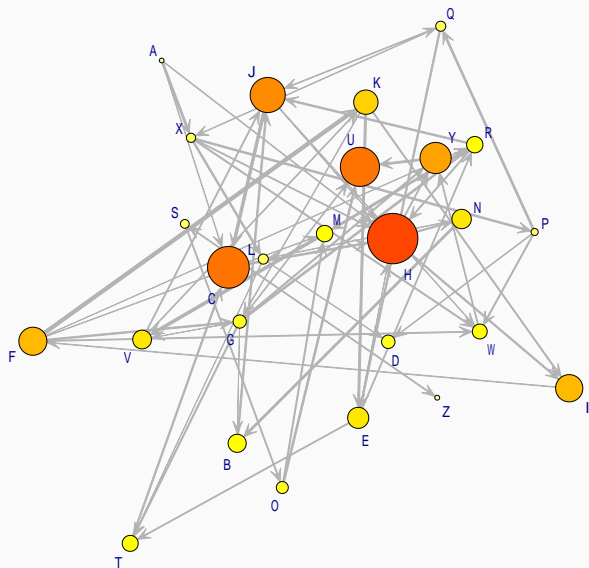
- $\alpha = 0.85$
- initial:  
12 nodes

t = 10



- $\alpha = 0.85$
- initial:  
12 nodes

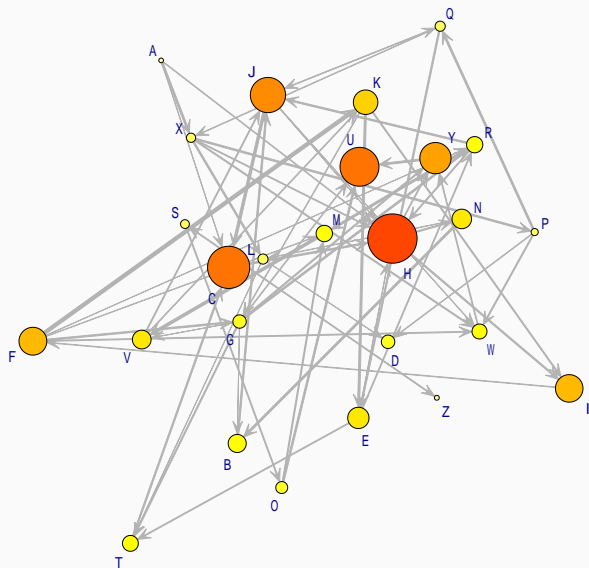
t = 11



- $\alpha = 0.85$
- initial:  
12 nodes

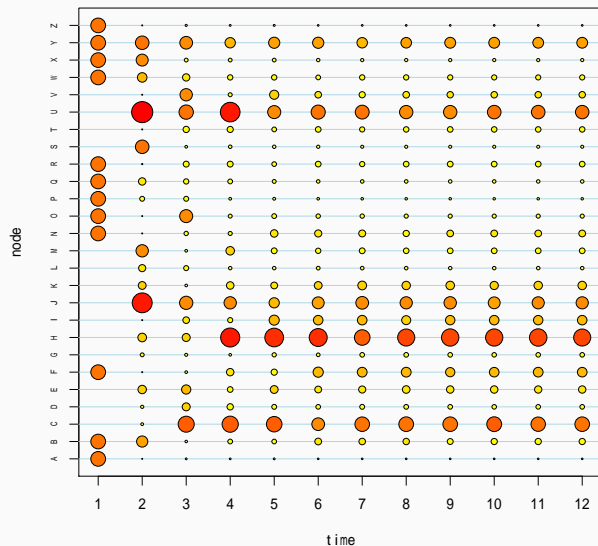


t = 12



- $\alpha = 0.85$
- initial:  
12 nodes

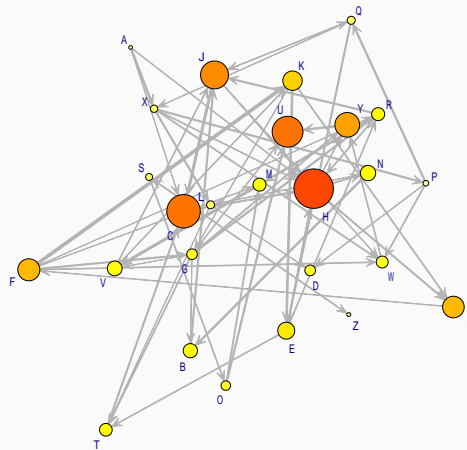
transient process



- $\alpha = 0.85$
- initial:  
12 nodes

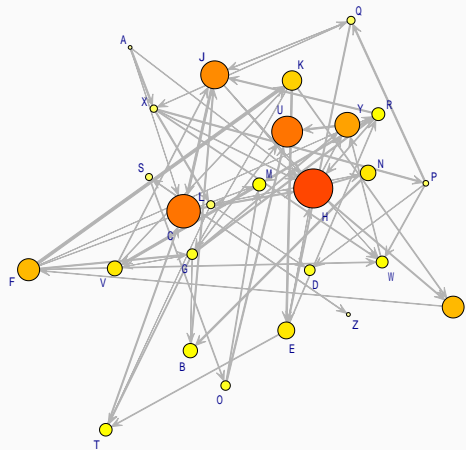
initial condition 1

$t = 12$



initial condition 2

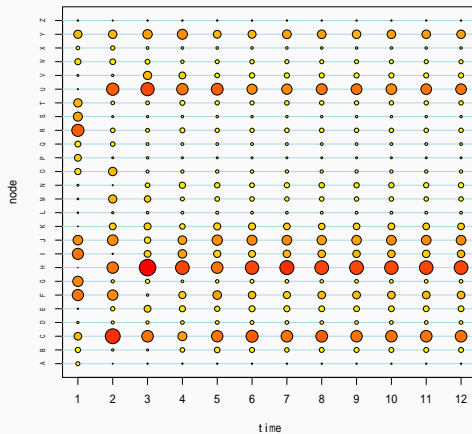
$t = 12$



fast convergence to the same stationary distribution

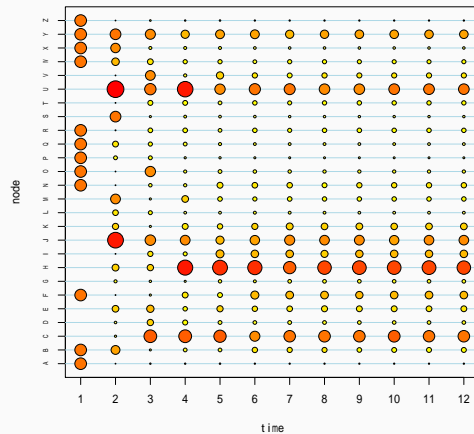
initial condition 1

transient process



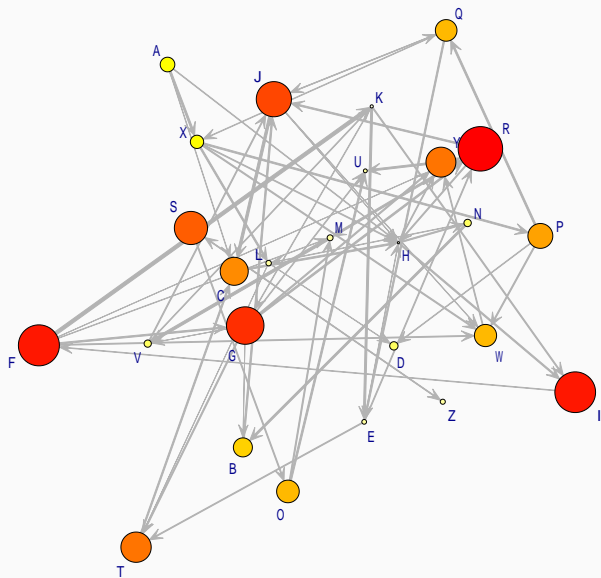
initial condition 2

transient process



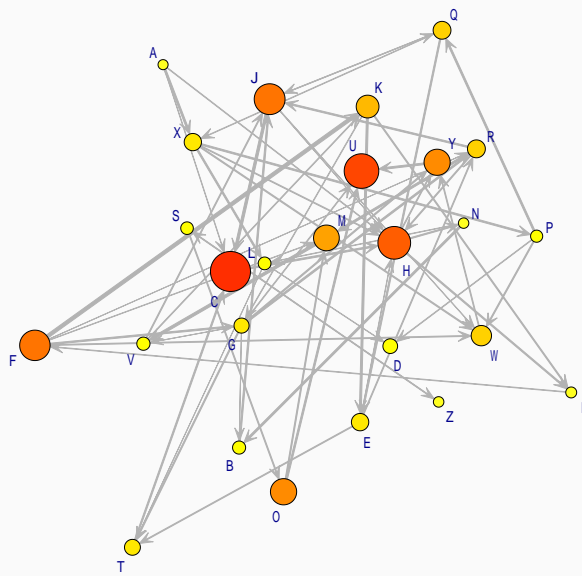
fast convergence to the same stationary distribution

$t = 1$



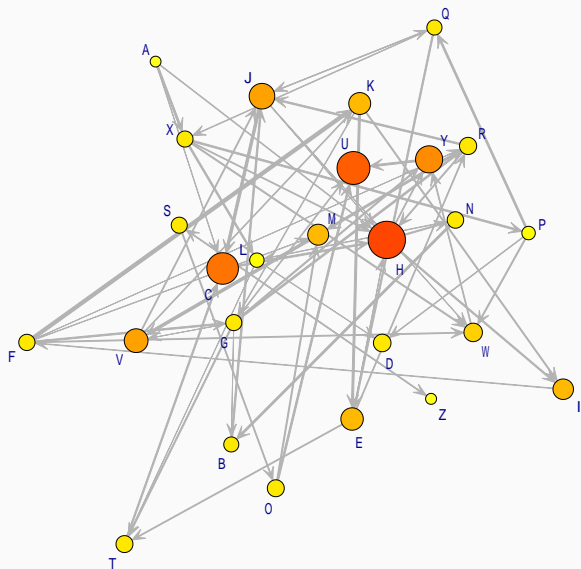
- $\alpha = 0.5$
- initial:  
uniform dist.

t = 2



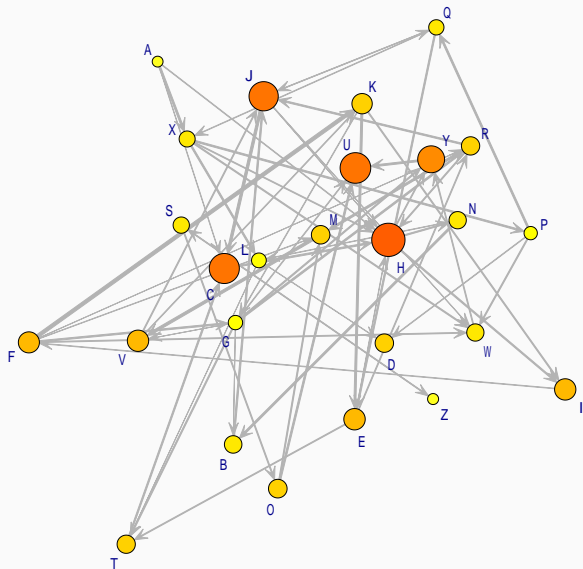
- $\alpha = 0.5$
- initial:  
uniform dist.

t = 3



- $\alpha = 0.5$
- initial:  
uniform dist.

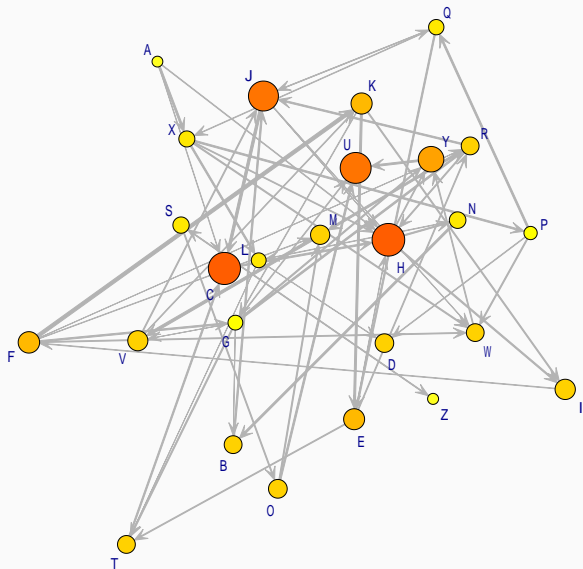
t = 4



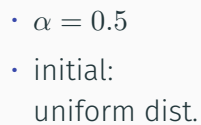
- $\alpha = 0.5$
- initial:  
uniform dist.



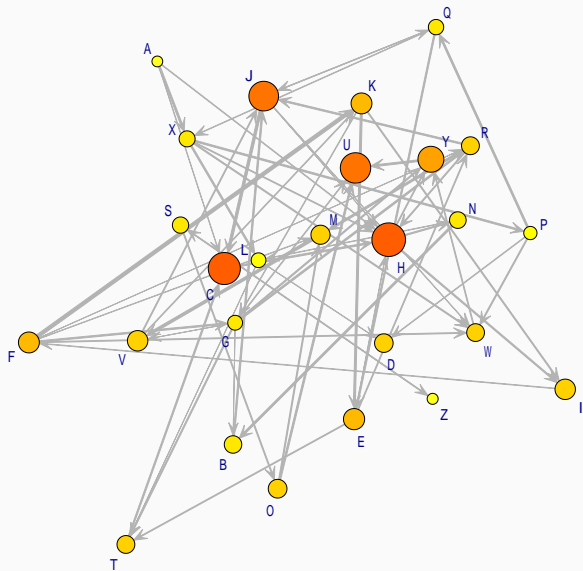
t = 5



- $\alpha = 0.5$
- initial:  
uniform dist.

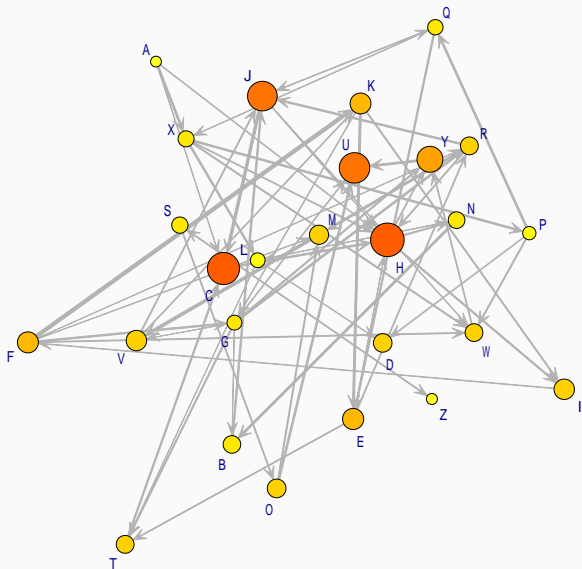


$t = 7$



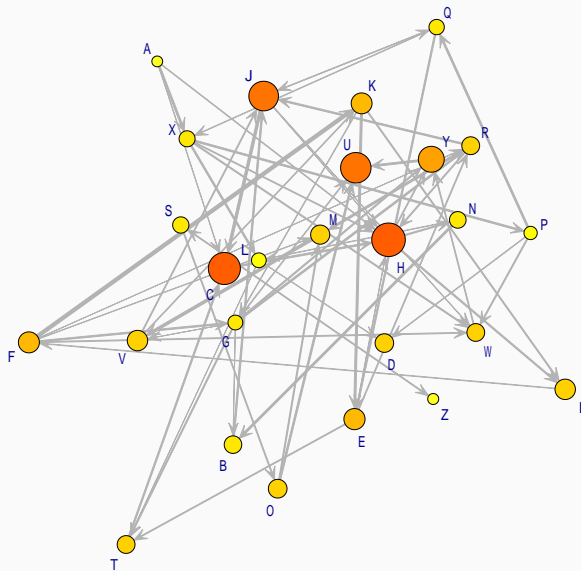
- $\alpha = 0.5$
- initial:  
uniform dist.

$t = 8$



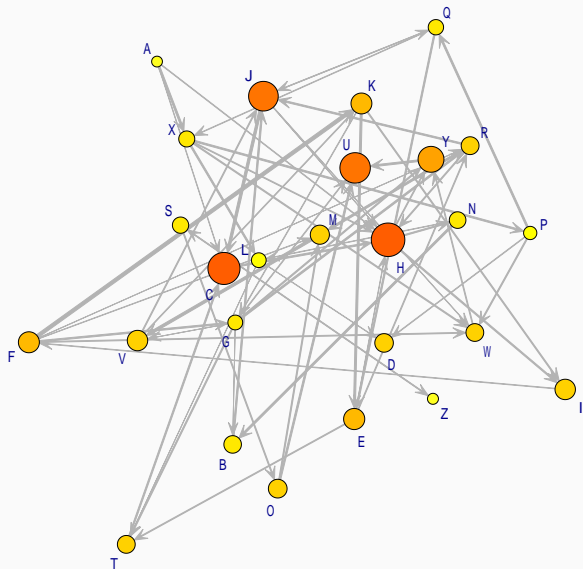
- $\alpha = 0.5$
- initial:  
uniform dist.

$t = 9$



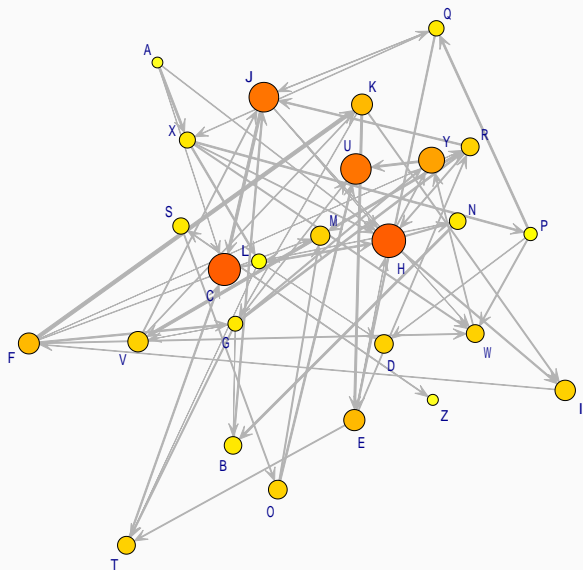
- $\alpha = 0.5$
- initial:  
uniform dist.

$t = 10$



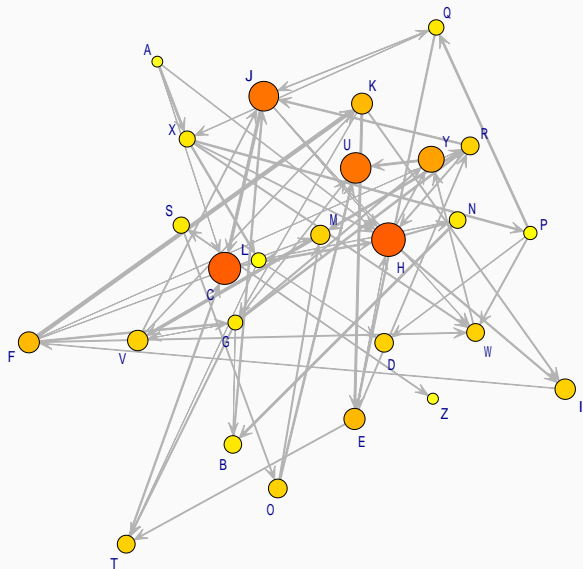
- $\alpha = 0.5$
- initial:  
uniform dist.

t = 11



- $\alpha = 0.5$
- initial:  
uniform dist.

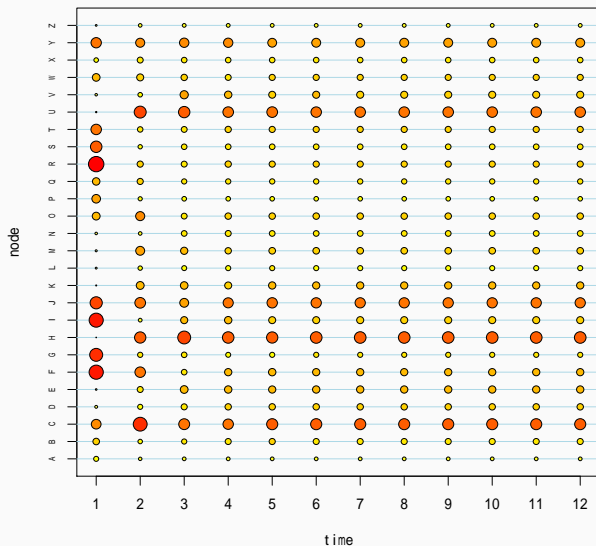
$t = 12$



- $\alpha = 0.5$
- initial:  
uniform dist.

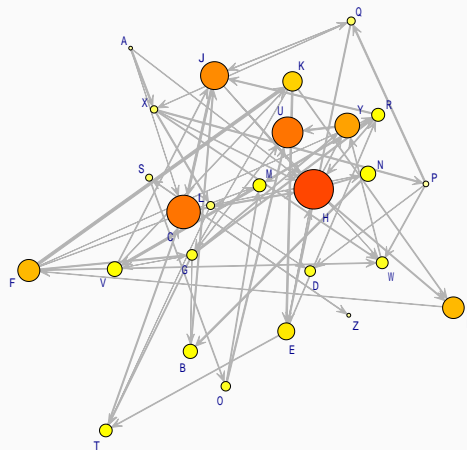


# transient process

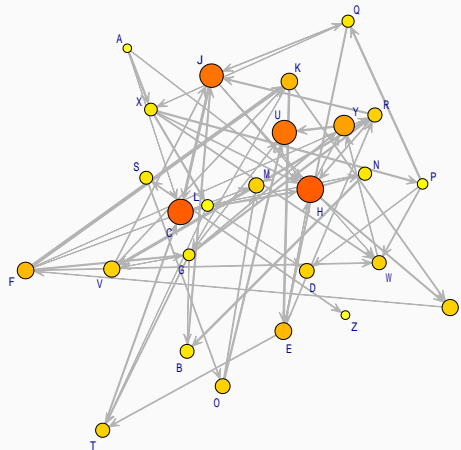


- $\alpha = 0.5$
- initial:  
uniform dist.

$\alpha = 0.85$   
t = 12



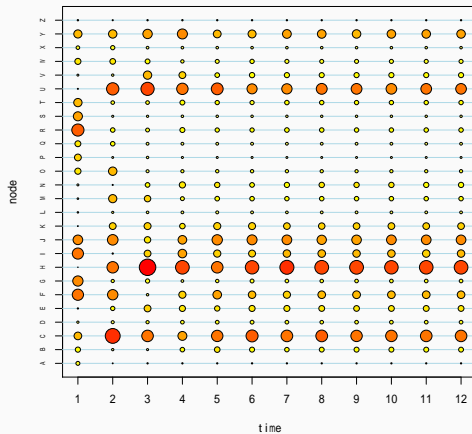
$\alpha = 0.5$   
t = 12



random diffusion with smaller scaling

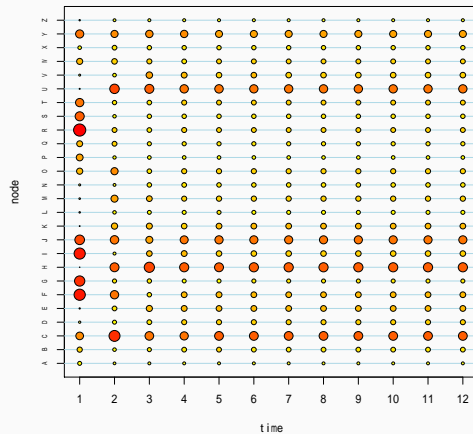
$$\alpha = 0.85$$

transient process



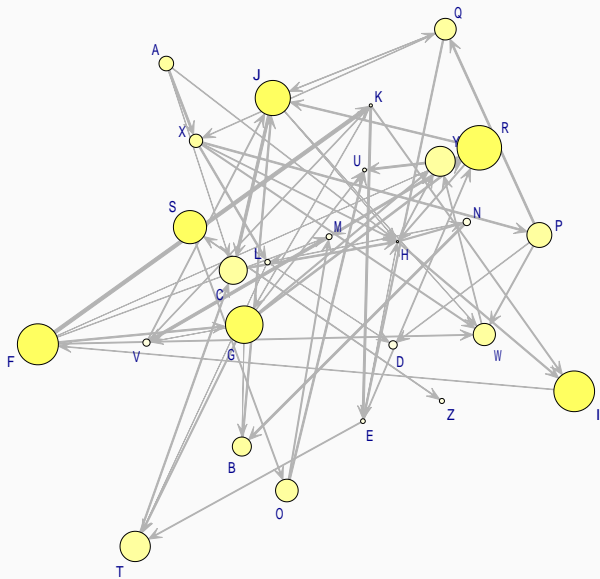
$$\alpha = 0.5$$

transient process



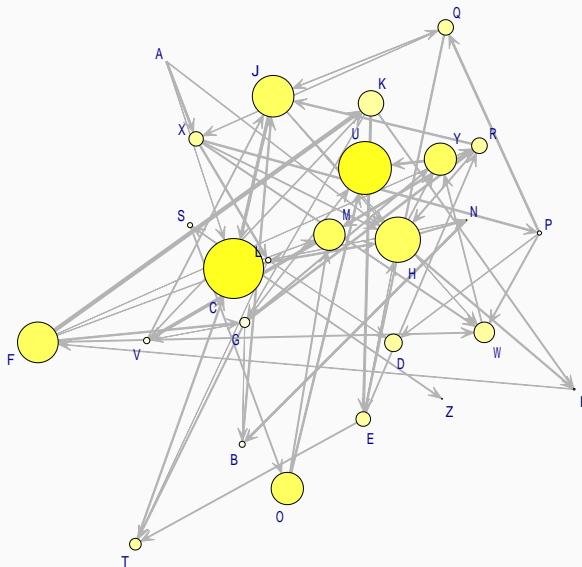
random diffusion with smaller scaling

$t = 1$



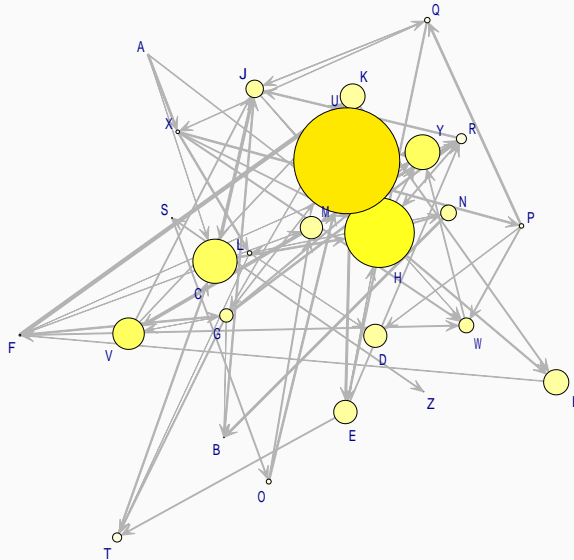
- without sink node escape
- initial:  
uniform dist.

$t = 2$



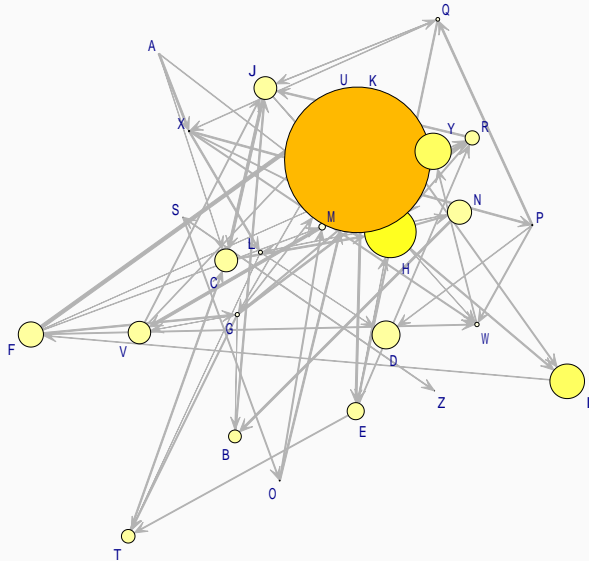
- without sink node escape
- initial:  
uniform dist.

$t = 3$



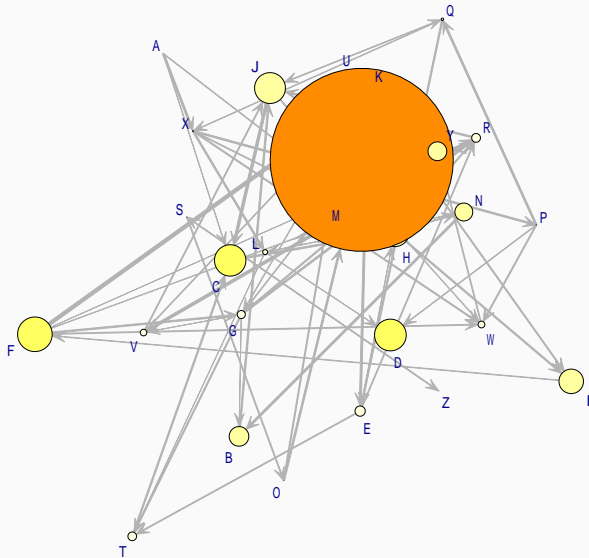
- without sink node escape
- initial:  
uniform dist.

$t = 4$



- without sink node escape
- initial:  
uniform dist.

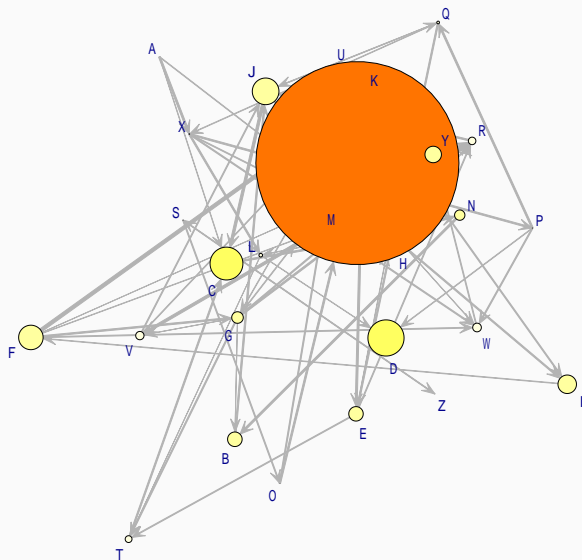
$t = 5$



- without sink node escape
- initial:  
uniform dist.

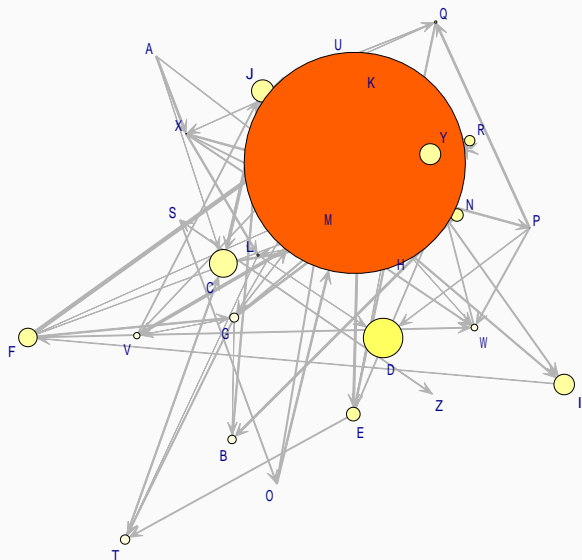


$t = 6$



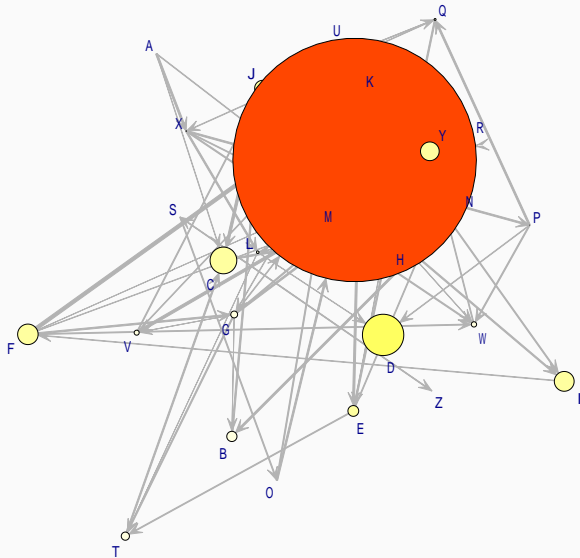
- without sink node escape
- initial:  
uniform dist.

$t = 7$



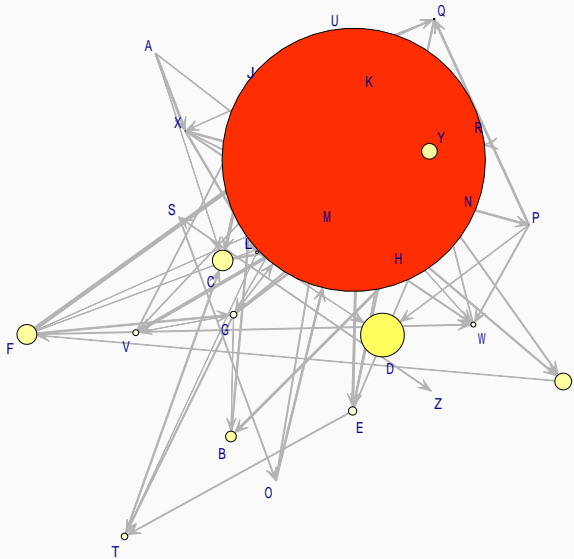
- without sink node escape
- initial:  
uniform dist.

$t = 8$



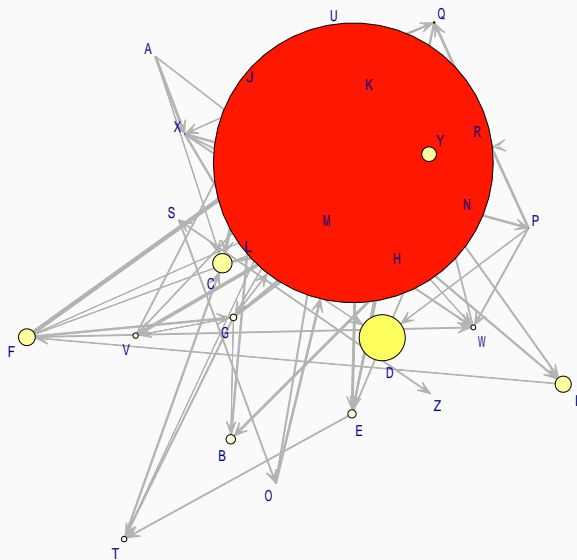
- without sink node escape
- initial:  
uniform dist.

$t = 9$



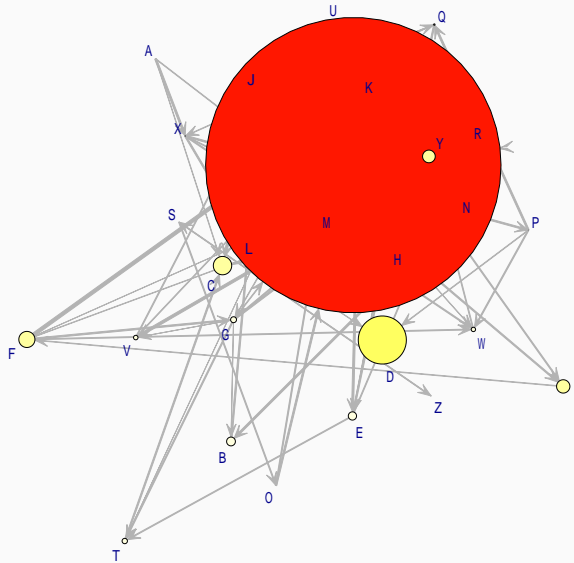
- without sink node escape
- initial:  
uniform dist.

$t = 10$



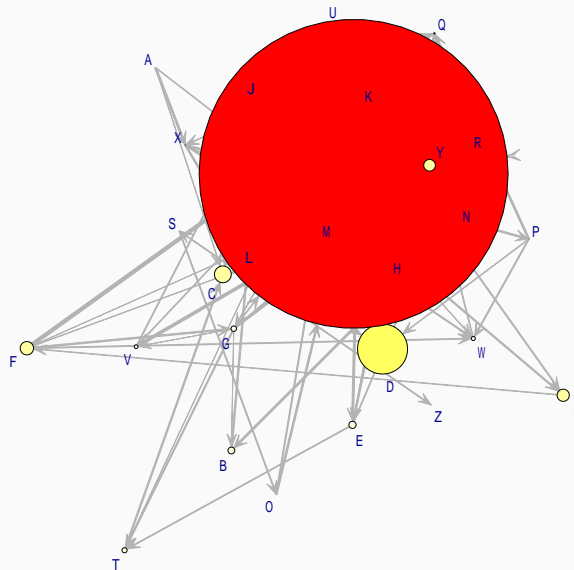
- without sink node escape
- initial:  
uniform dist.

$t = 11$



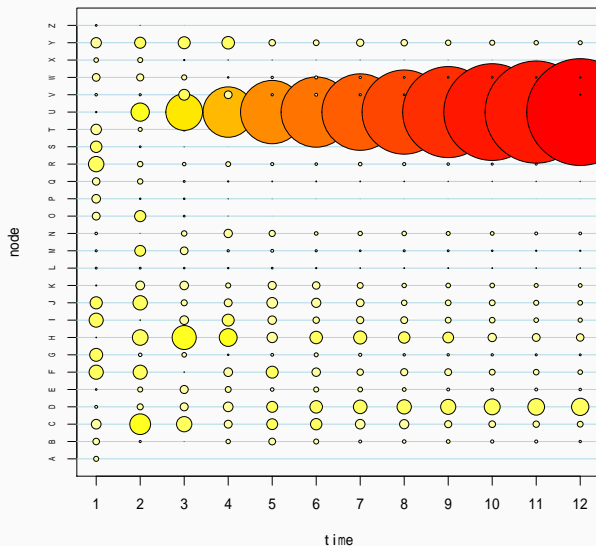
- without sink node escape
- initial:  
uniform dist.

$t = 12$



- without sink node escape
- initial:  
uniform dist.

# transient process

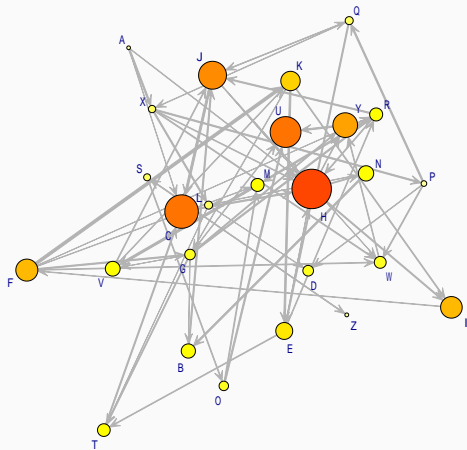


- without sink node escape
- initial:  
uniform dist.



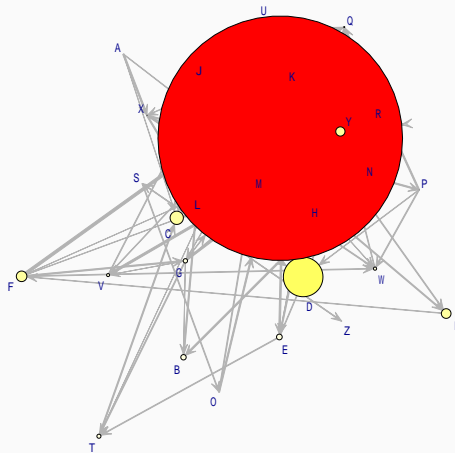
with sink node adjustment

$t = 12$

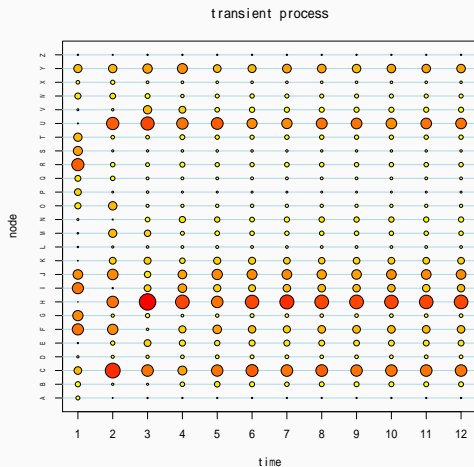


without sink node adjustment

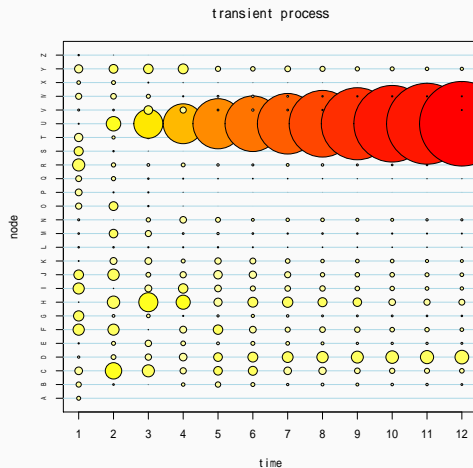
$t = 12$



with sink node adjustment



without sink node adjustment



a simple and strong model of movements on directed graph:

- behavior model of selection from finite options
  - web surf model
  - purchase model of certain genres
  - transition model of audience ratings
  - customer share model of restaurants/coffee shops
- adjustment of transition matrix (sink node/ $\alpha$ )
  - out of stock or service
  - capricious or adventurous attempts
  - introduction from others

## PROBLEM FORMULATION

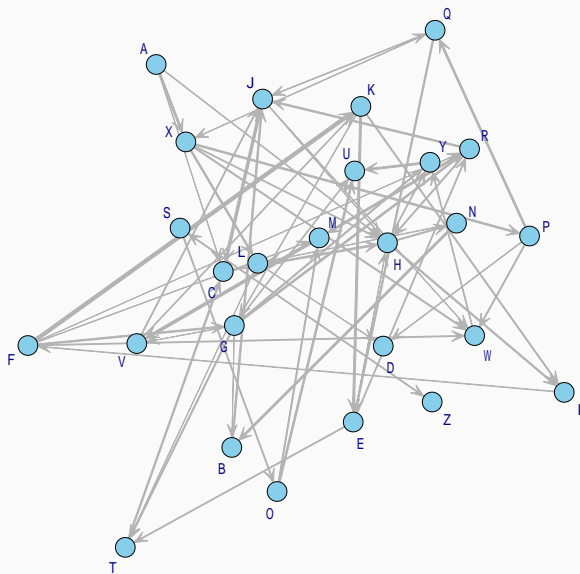
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non-stationary data on directed graphs:

- strength of edges slowly change in time
  - change of structure
  - change of stationary distribution
- model assumption:
  - frequent update (fast time scale;  $t$ )  
e.g.: purchase every day
  - sparse observation (slow time scale;  $T$ )  
e.g.: aggregate every week

observations are supposed to be on stationary distribution at current point

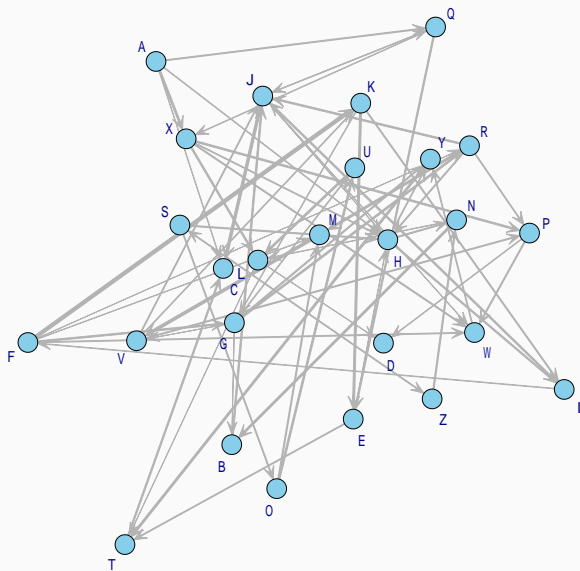
$T = 1$



change of structure

- 10% edges at random
- relatively small

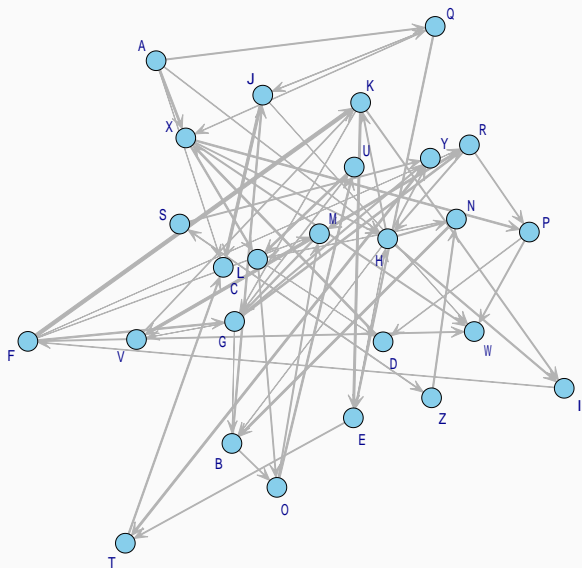
$T = 2$



change of structure

- 10% edges at random
- relatively small

$T = 3$

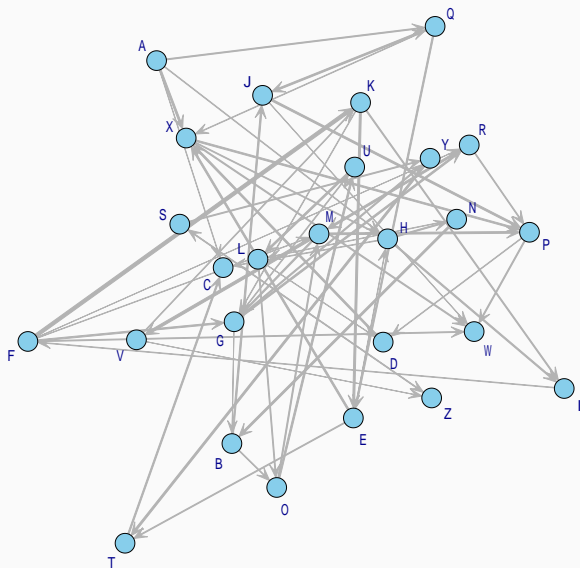


change of structure

- 10% edges at random
- relatively small



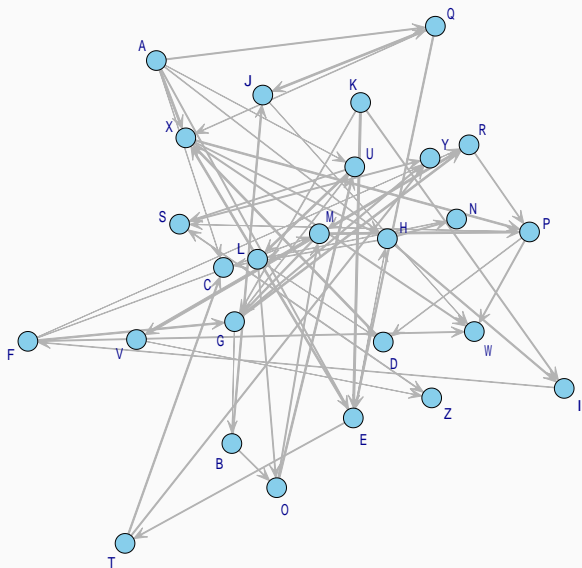
$T = 4$



change of structure

- 10% edges at random
- relatively small

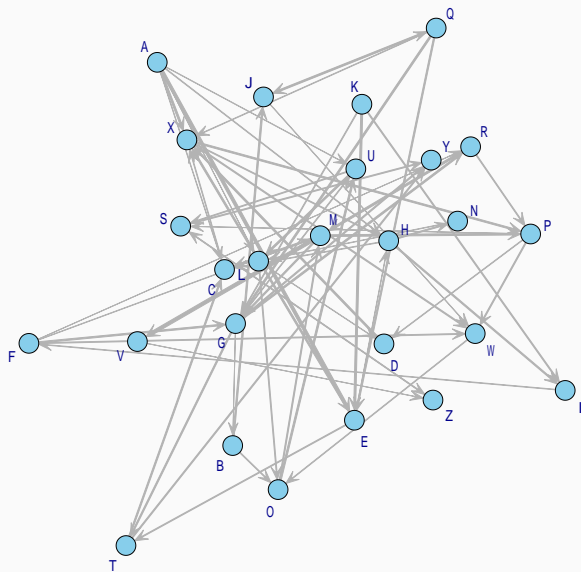
$T = 5$



change of structure

- 10% edges at random
- relatively small

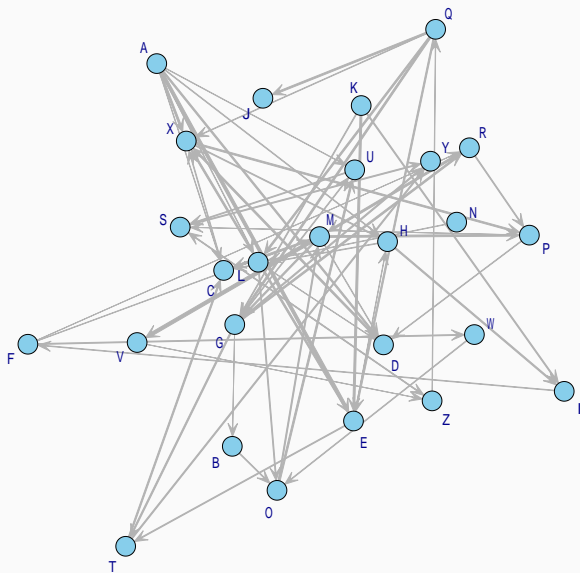
$T = 6$



change of structure

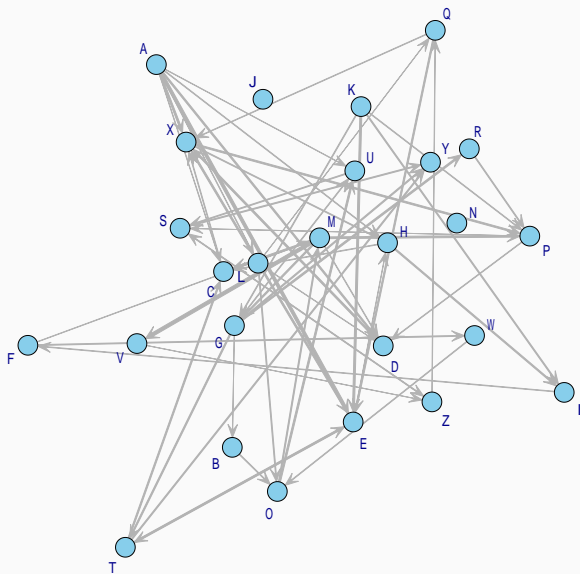
- 10% edges at random
- relatively small

$T = 7$



change of structure

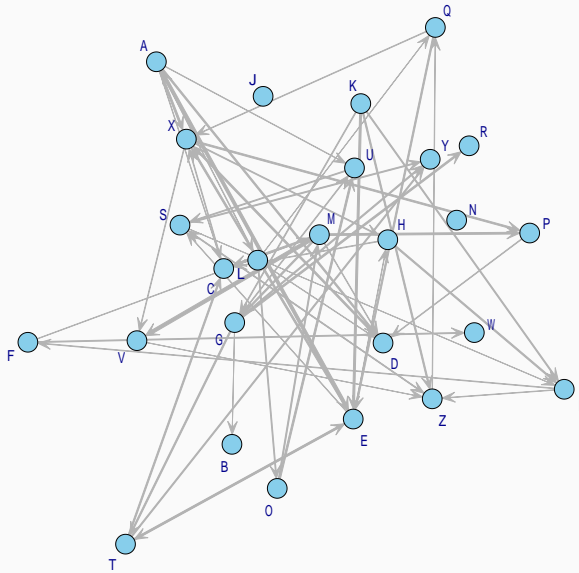
- 10% edges at random
- relatively small

$$T = 8$$


change of structure

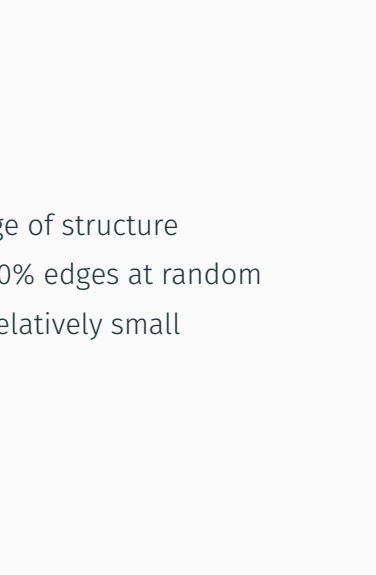
- 10% edges at random
- relatively small

$T = 9$



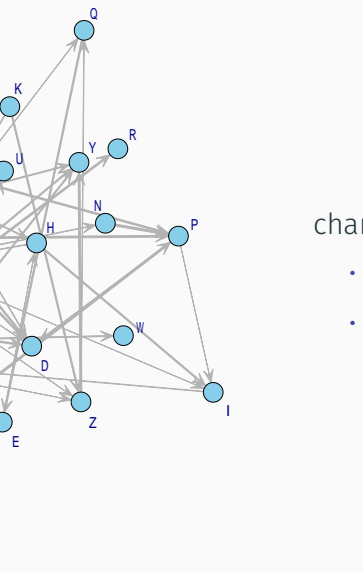
change of structure

- 10% edges at random
- relatively small



ge of structure

- 0% edges at random  
relatively small

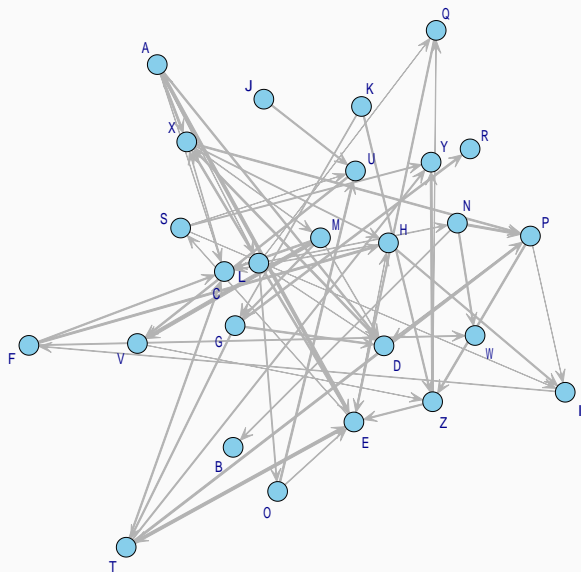


change of structure

- 10% edges at random
- relatively small



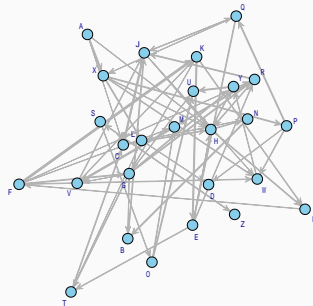
$T = 12$



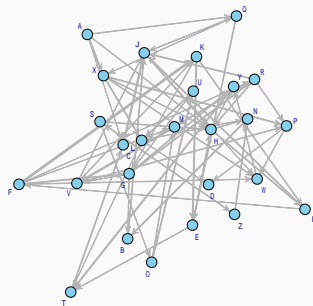
change of structure

- 10% edges at random
- relatively small

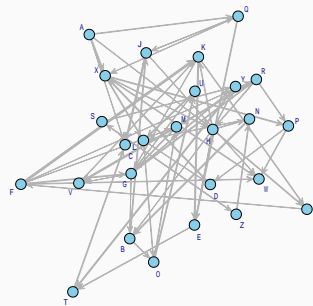
T = 1



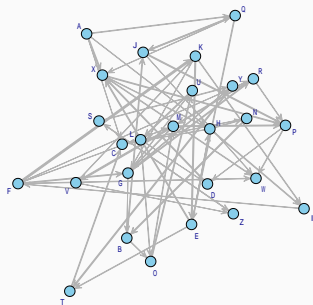
T = 2



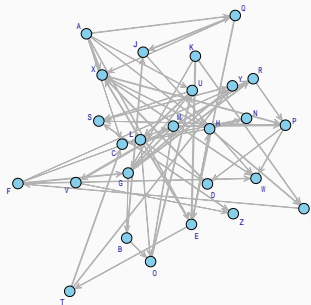
T = 3



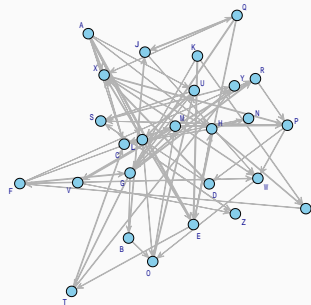
T = 4



T = 5

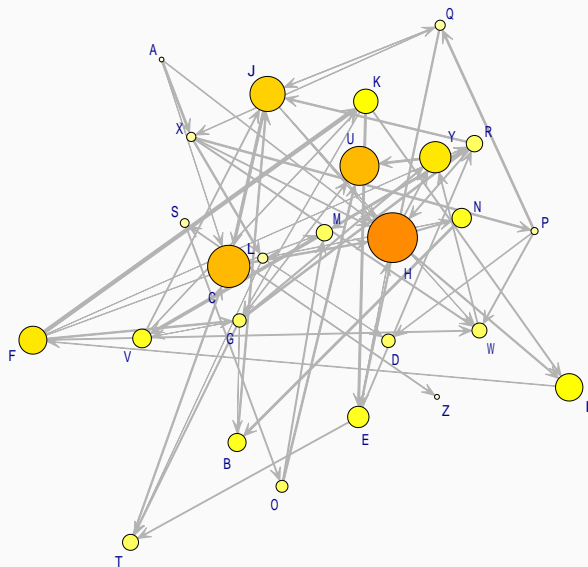


T = 6





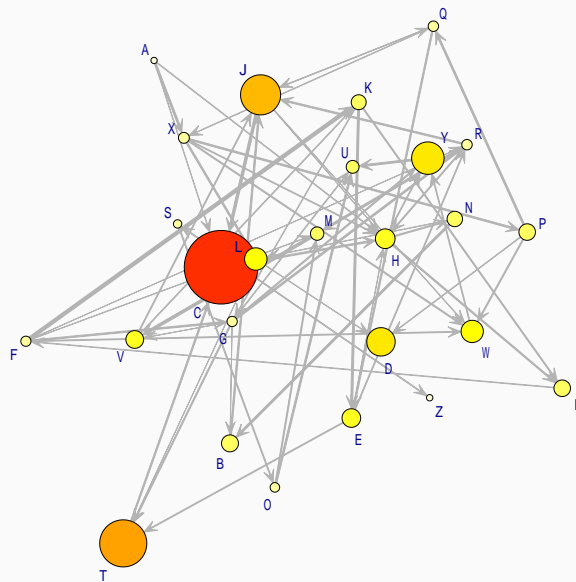
$T = 1$



change of stationary  
distribution

- 10% edges at random
- large effect

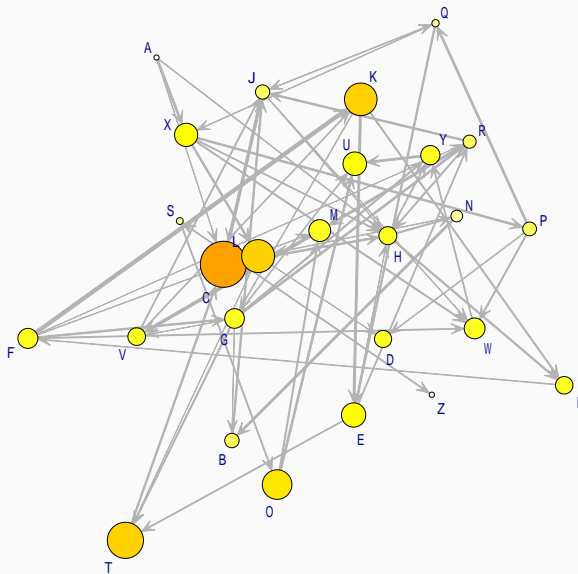
$T = 2$



change of stationary  
distribution

- 10% edges at random
- large effect

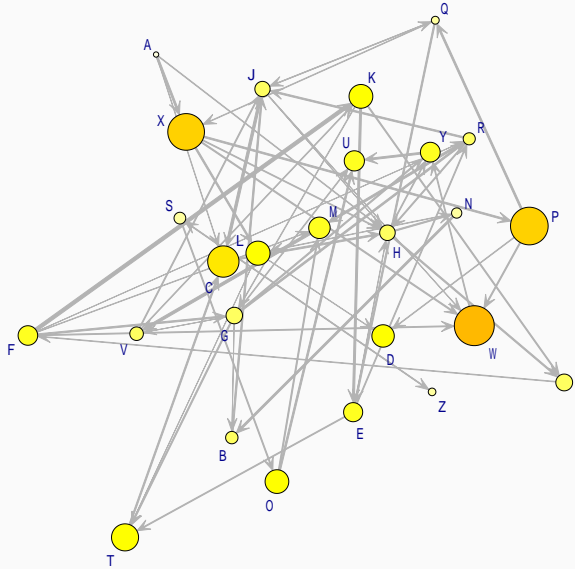
$T = 3$



change of stationary  
distribution

- 10% edges at random
- large effect

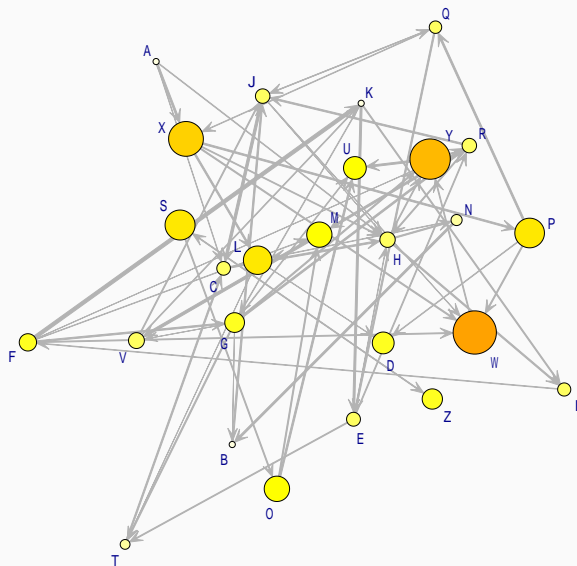
$T = 4$



change of stationary  
distribution

- 10% edges at random
- large effect

$T = 5$

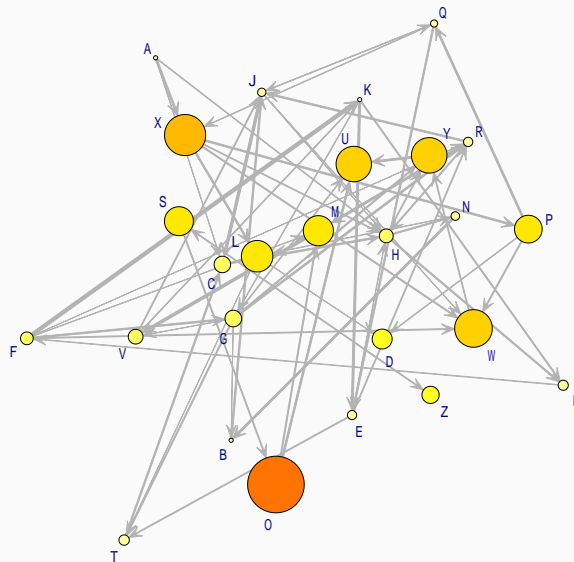


change of stationary  
distribution

- 10% edges at random
- large effect



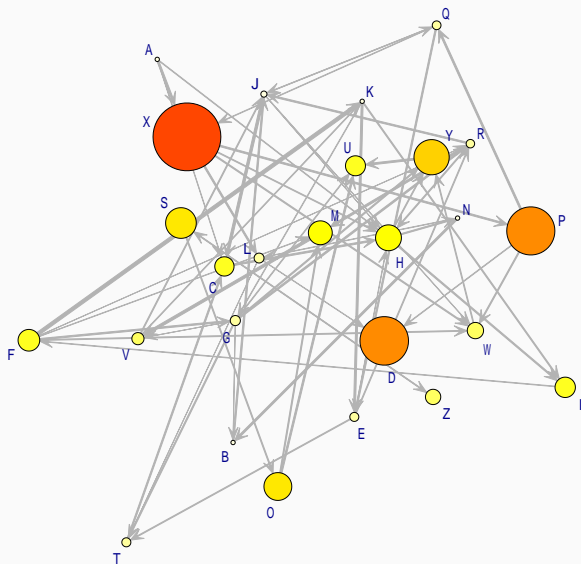
$T = 6$



change of stationary  
distribution

- 10% edges at random
- large effect

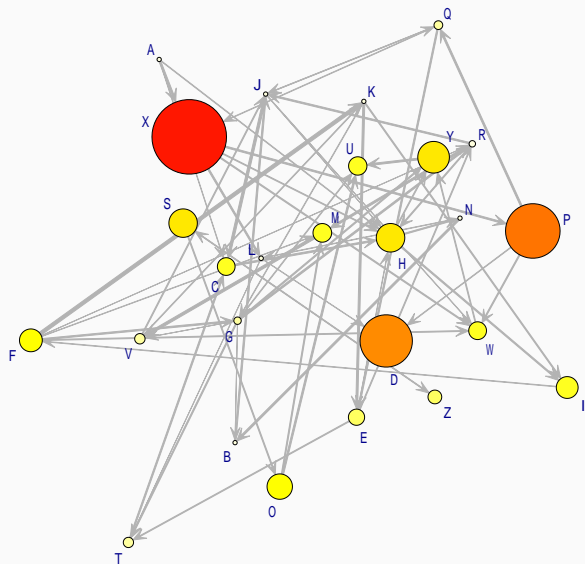
$T = 7$



change of stationary  
distribution

- 10% edges at random
- large effect

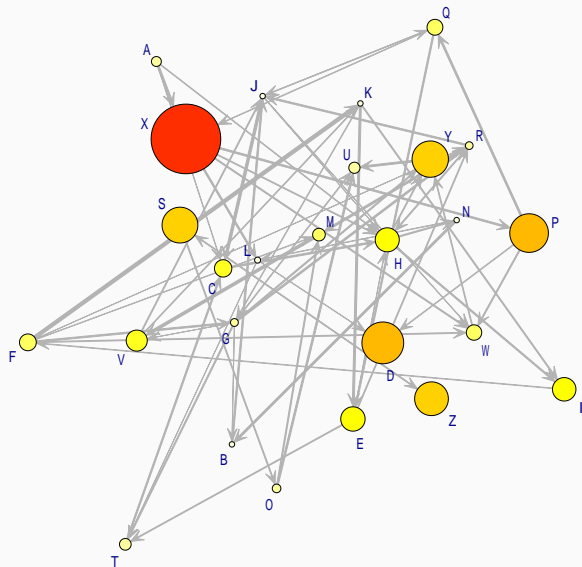
$T = 8$



change of stationary  
distribution

- 10% edges at random
- large effect

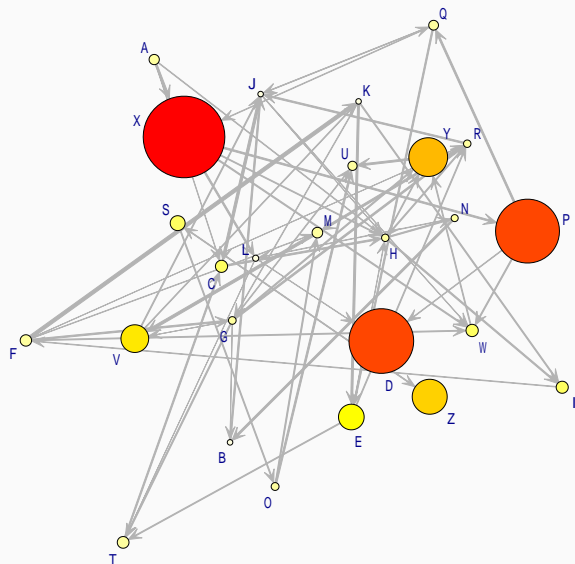
$T = 9$



change of stationary  
distribution

- 10% edges at random
- large effect

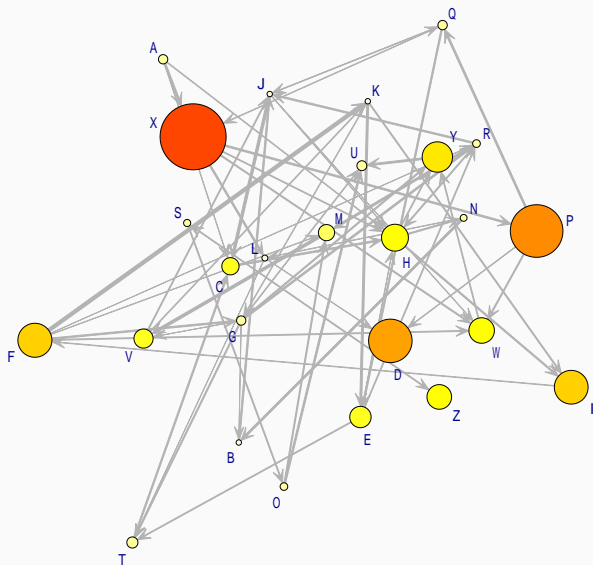
$T = 10$



change of stationary  
distribution

- 10% edges at random
- large effect

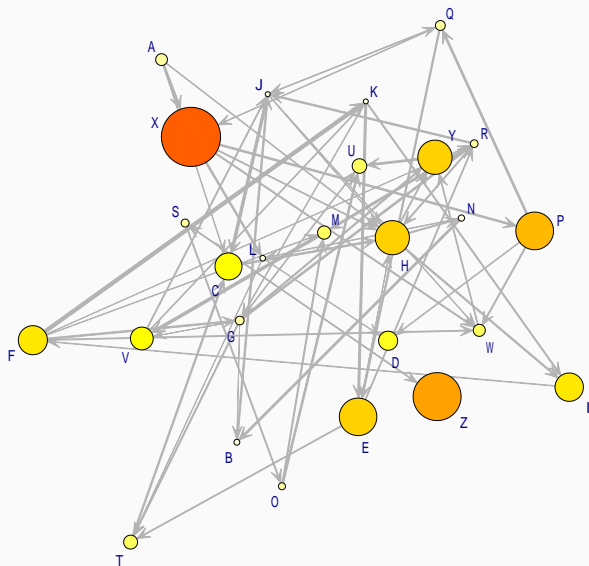
T = 11



change of stationary  
distribution

- 10% edges at random
- large effect

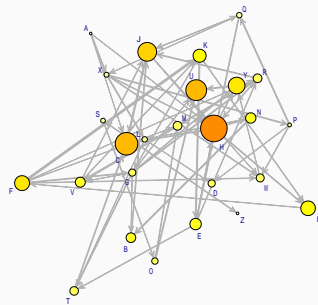
T = 12



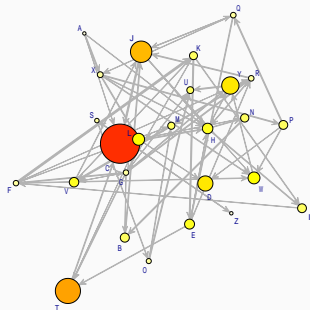
change of stationary  
distribution

- 10% edges at random
- large effect

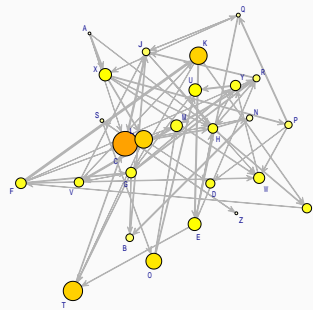
T = 1



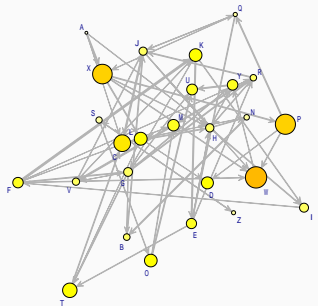
T = 2



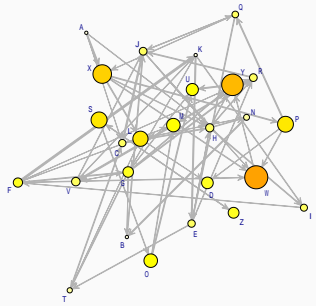
T = 3



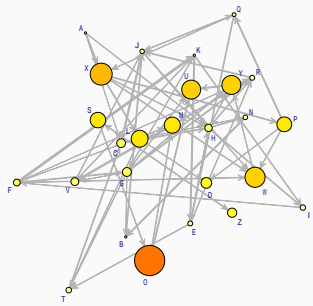
T = 4



T = 5

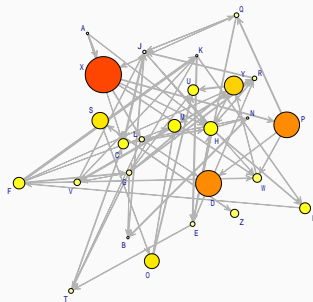


T = 6

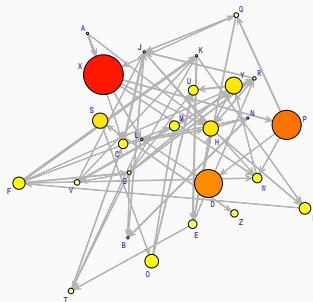




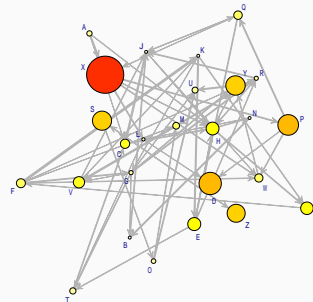
T = 7



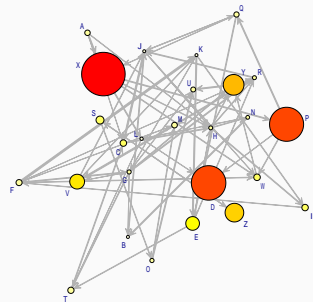
T = 8



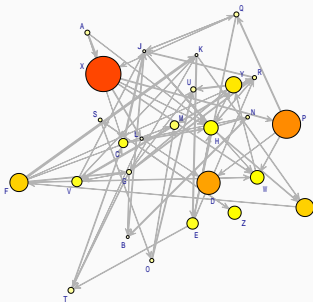
T = 9



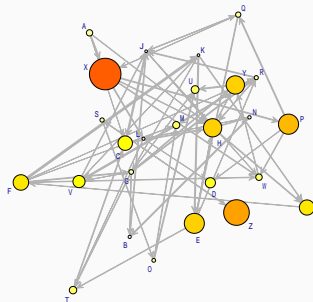
T = 10



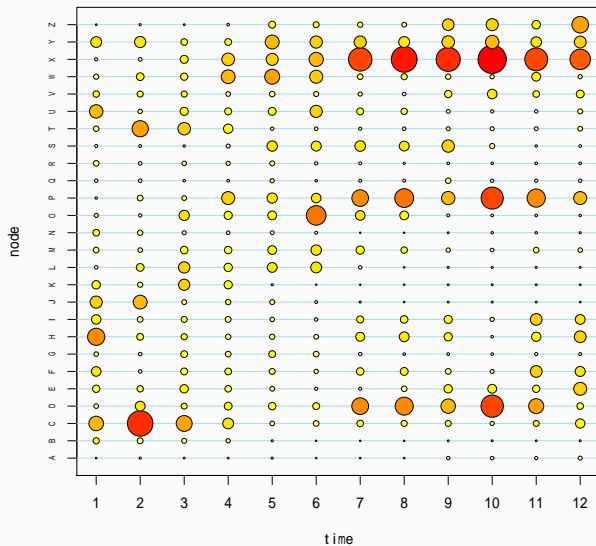
T = 11



T = 12



change of stationary states



change of stationary  
distribution

- 10% edges at random
- large effect

for given series of stationary distributions  $\{\pi_t\}$ , estimate series of graph structures  $\{G_t\}$ .

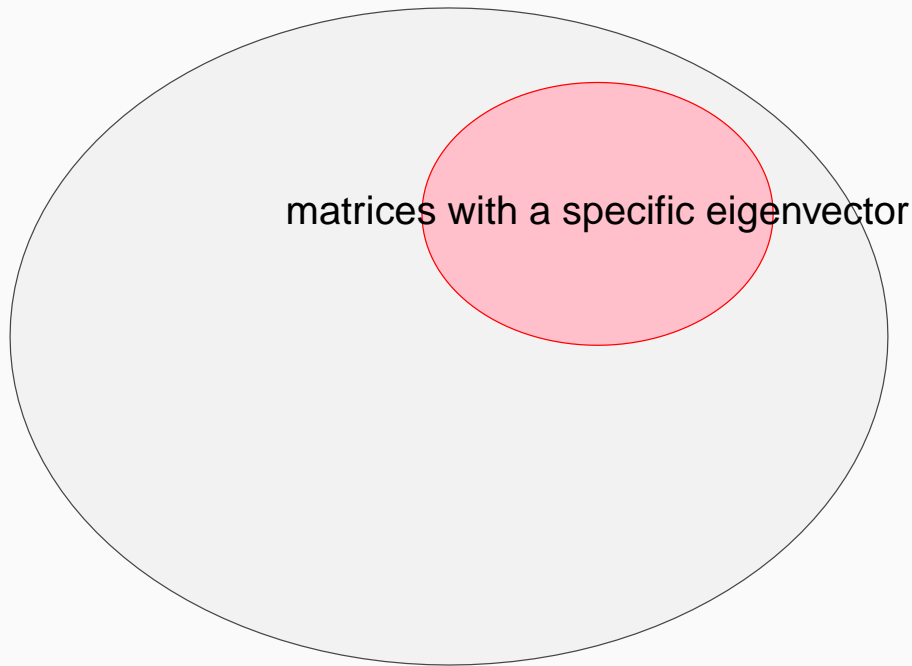
$$\text{minimize } L(\{G_t\}) \quad \text{subject to } \forall t, \pi_t^T G_t = \pi_t^T$$

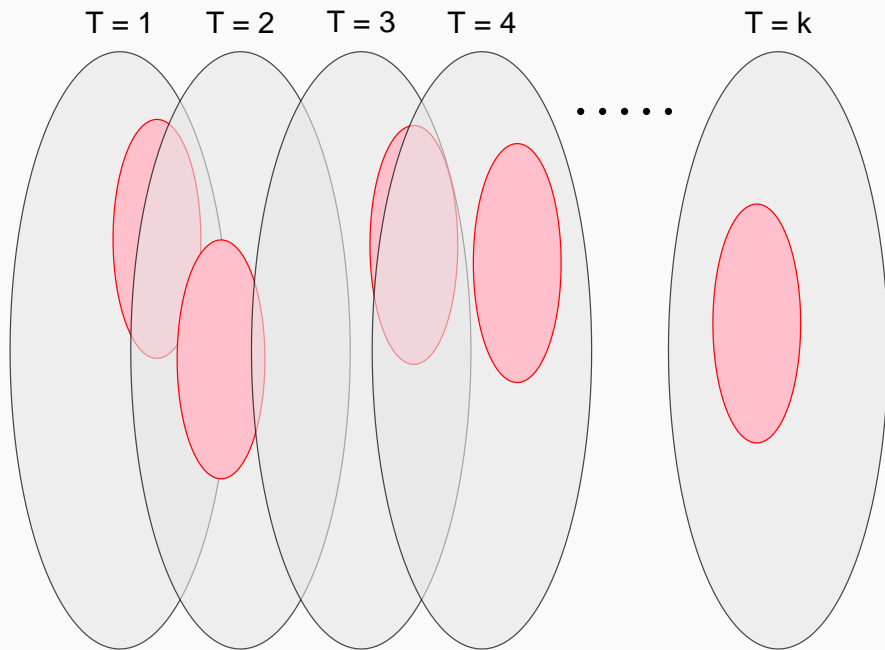
- infinitely many matrices have the same eigenvector
- the followings are needed:
  - assumptions on graph structures
  - assumptions of graph changes

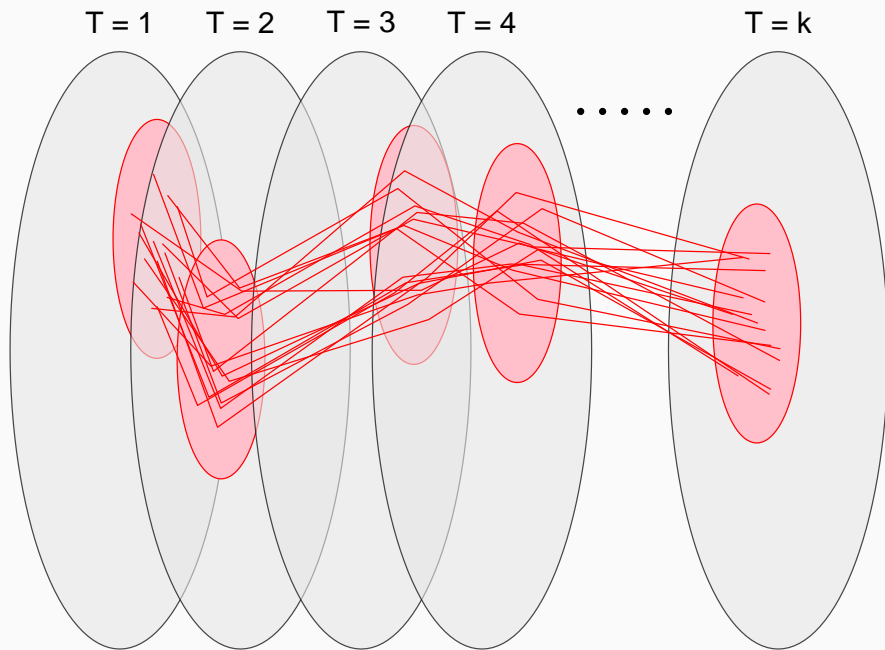
e.g. (fused lasso): for a certain sparse norm of matrix,  $\|\cdot\|_S$ ,

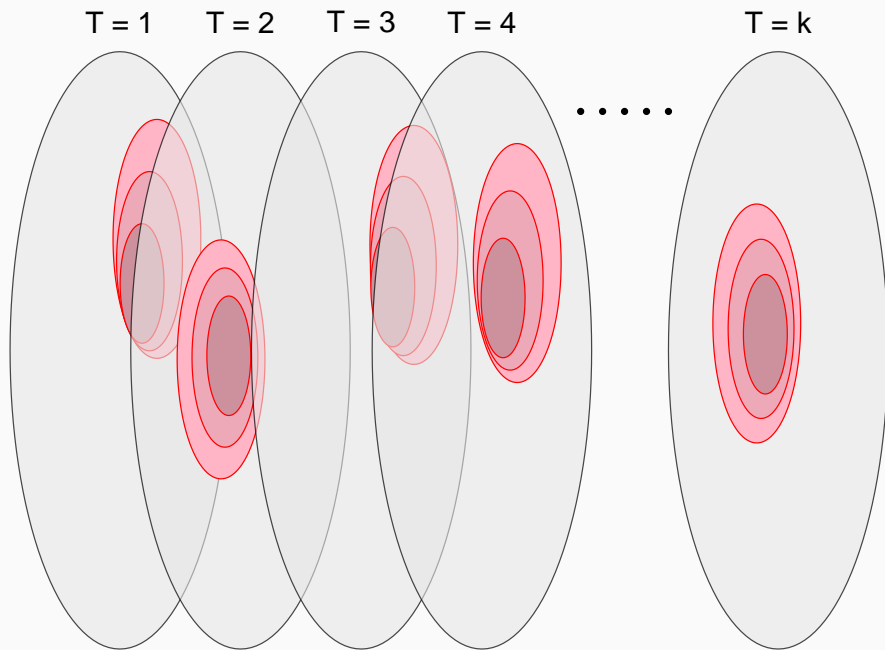
$$L(\{G_t\}) = \sum_t \|G_t\|_s + \sum_t \|G_{t+1} - G_t\|_s$$

space of probability matrices

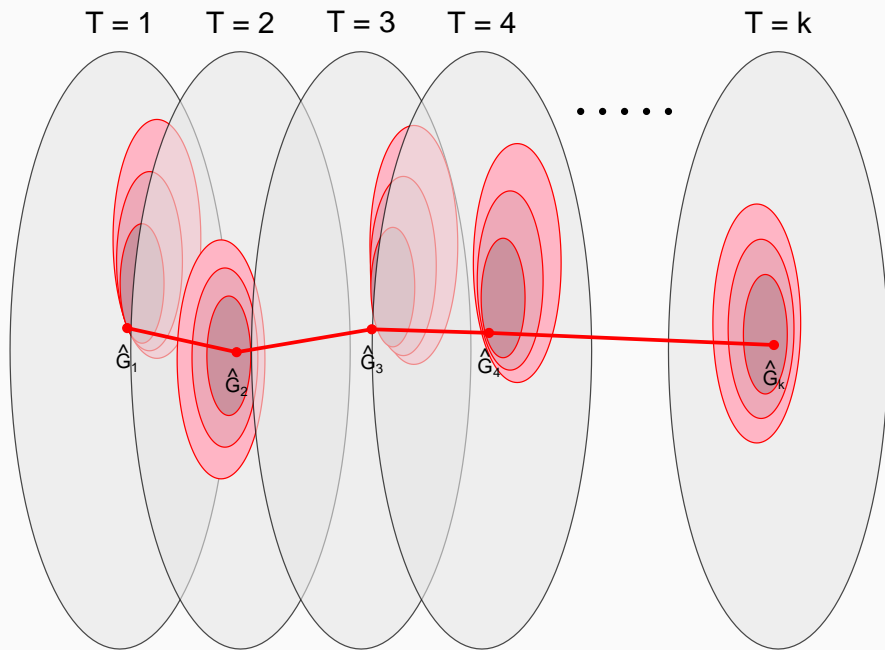












make matrices keep in a restricted subspace:

- eigenvector of matrix  $A$  to be  $\mathbf{a}$  (unit vector):

$$Aa = \lambda a + b \Rightarrow A - ba^T \rightarrow A$$

- eigenvalue of eigenvector  $\mathbf{a}$  to be  $\mu$ :

$$Aa = \lambda a \Rightarrow A + (\mu - \lambda)aa^T \rightarrow A$$

- A to be a probability matrix:

$$A\mathbf{e} = \mathbf{d} \Rightarrow \text{diag}(\mathbf{d})^{-1}A \rightarrow A$$

## NUMERICAL EXAMPLES

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## Reference

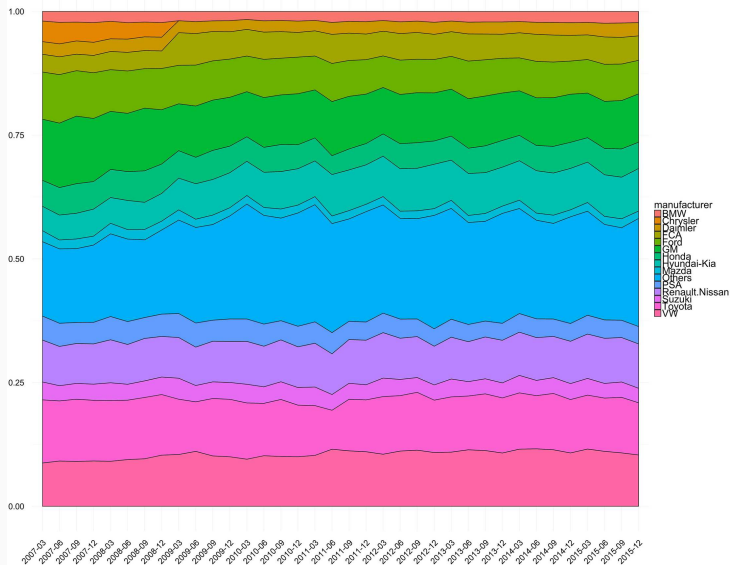
Chiba et al. "Time-Varying Transition Probability Matrix Estimation and Its Application to Brand Share Analysis"

- quarterly unit automobile sales data of manufacturers from 2007-1Q to 2015-4Q
- estimate transition paths and discuss the relation between social events and estimated results
- objective:

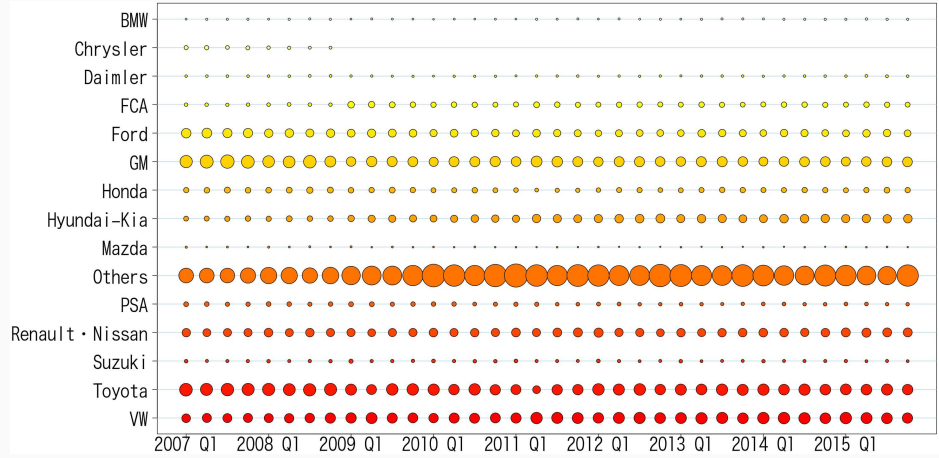
$$L(\{G_t\}) = \sum_t \|G_{t+1} - G_t\|_1$$

- optimization: simplex method with slack variables

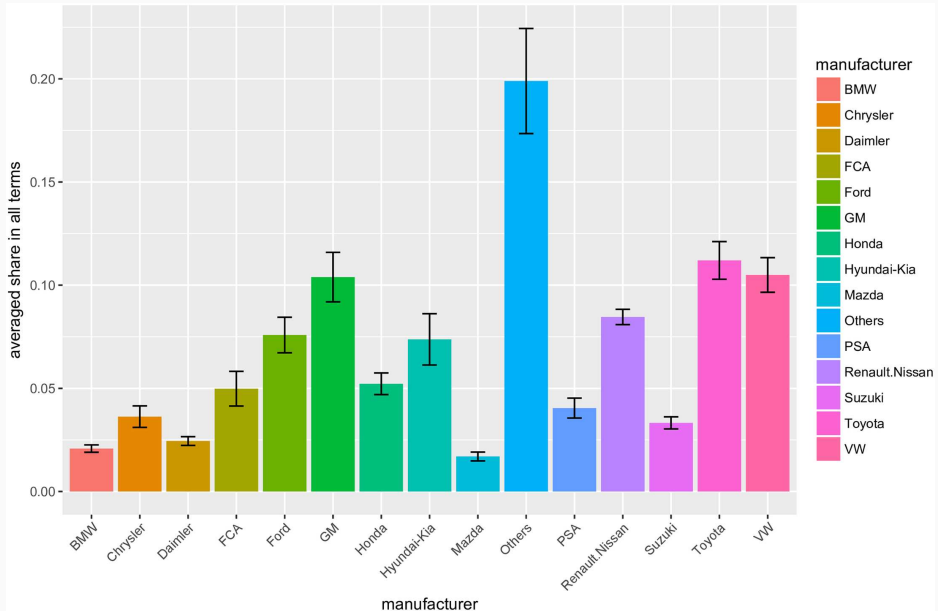
## automobile sales for different manufactures

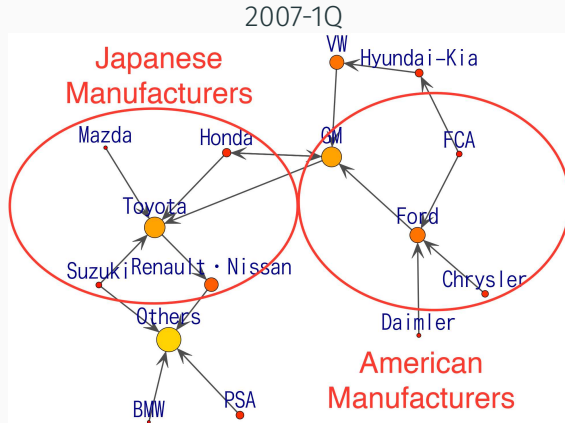


# market share transition



## averages and standard deviations of sales shares

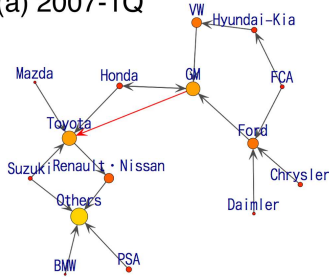




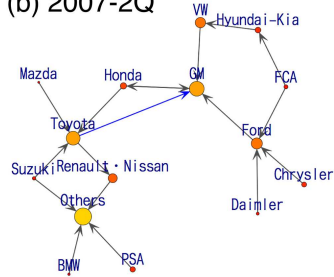
- remove minor edge below 0.24
- show market share with node size
- cf. GM and Honda are allied



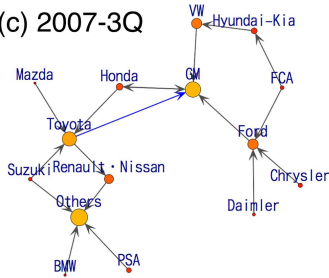
(a) 2007-1Q



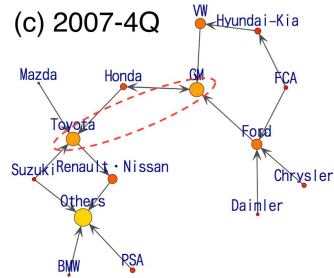
(b) 2007-2Q



(c) 2007-3Q

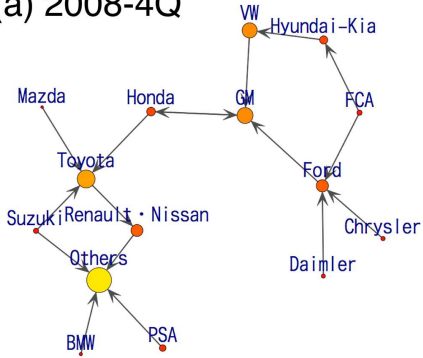


(c) 2007-4Q

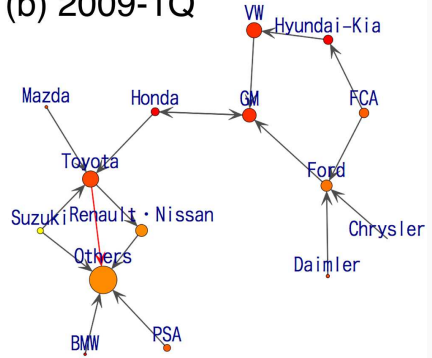


In March 2008, TOYOTA has become the world's top seller by beating GM

(a) 2008-4Q

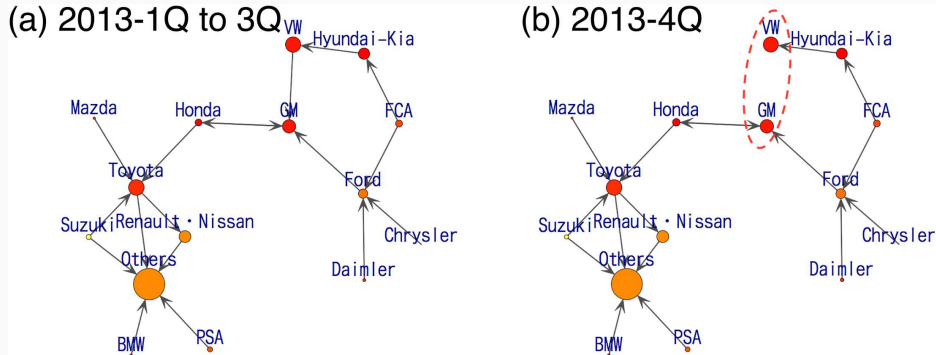


(b) 2009-1Q

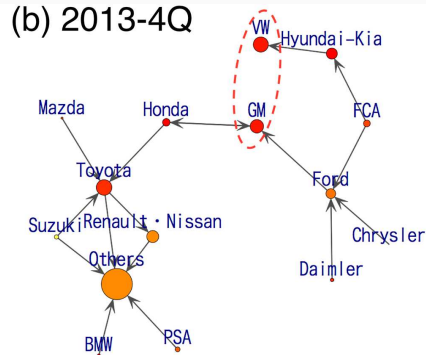


In 2009, TOYOTA launched a massive recall

(a) 2013-1Q to 3Q



(b) 2013-4Q



In 2013, VW beats GM in total sales amount to claim second position in the automobile industry

## CONCLUSION


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we presented the followings

- a model of transitions and stationary distributions
- a simple method for estimating transition matrices from a sequence of stationary distributions
- analysis of consumer transitions for sales share data without detailed recording of consumer transitions

further investigation would be devoted to

- other objectives and constraints to improve the accuracy of estimation and interpretability
- other probabilistic models for estimating changes in transitions

-  Chiba, Tomoaki et al. (Jan. 11, 2017). "Time-Varying Transition Probability Matrix Estimation and Its Application to Brand Share Analysis." In: *PLoS ONE* 12.1, e0169981. DOI: [10.1371/journal.pone.0169981](https://doi.org/10.1371/journal.pone.0169981).