QM March 8

Recap:

We realize that when the change in Hamiltonian H over time \dot{H} is small when compared with the equivalent time energy difference between instantaneous eigenstates E_n-E_m , which means $\left|\sum_{n\neq m} \frac{\langle \psi_m | \dot{H} | \psi_n \rangle}{E_n-E_m}\right| \ll 1$, we can use the adiabatic approximation. We obtain our final coefficient relation that

$$\dot{c}_m(t) = -c_m(t)\langle \psi_m | | \dot{\psi}_m \rangle \tag{1}$$

Geometric phase:

The solution for (1) is that

$$c_m(t) = c_m(0)e^{i\delta_m(t)} \tag{2}$$

where we obtain geometric phase

$$\delta_m(t) = i \int_0^t \left\langle \psi_m(t') \middle| rac{\partial}{\partial t} \middle| \psi_m(t') \right
angle \, dt'$$
 (3)

so that we can write our wave function with the coefficient values in (2) and get

$$\Psi(t) = \sum_{n} c_m(0)\psi_n(t)e^{i\theta_n(t)}e^{i\delta_m(t)}$$
(4)

If we have the special case where

$$egin{aligned} c_n(0) &= 1 \ c_m(0) &= 0 orall m
eq n \end{aligned}$$

We then get the case where the total wave function (4) gets reduced to a stationary state ψ_n with the dynamic phase and the geometric phase:

$$\Psi(t) = \psi_n(t)e^{i\theta_n(t)}e^{i\delta_n(t)} \tag{5}$$

We note that δ_m is real, because

$$egin{aligned} \langle \psi_m(t)|\psi_m(t)
angle &=1\ rac{\partial}{\partial t}\langle \psi_m(t)|\psi_m(t)
angle &=0\ \langle \dot{\psi}_m|\psi_m
angle + \langle \dot{\psi}_m|\psi_m
angle &=0\ 2\mathrm{Re}\,\langle \psi_m|\dot{\psi}_m
angle &=0 \end{aligned}$$

and combine the i in front of (3) gives that $\delta_m \in \mathbb{R}$.

Closed Contour

If ψ has $ec{R}(t)$ dependence, we can write that

$$rac{\partial}{\partial t}\psi_m(ec{R}(t)) = rac{\partial \psi_m}{\partial R_1}rac{\partial R_1}{\partial t} + rac{\partial \psi_m}{\partial R_2}rac{\partial R_2}{\partial t} + rac{\partial \psi_m}{\partial R_3}rac{\partial R_3}{\partial t} =
abla_R\psi_m\cdotrac{\partial R_1}{\partial t}$$

Using this formulation with (3) will result in

$$\delta_n(t) = i \int_0^t raket{\psi_m|\dot{\psi}_m} dt' = i \int_0^t raket{\psi_n|
abla_R\psi_m} rac{dec{R}}{dt} \ dt := \int_{R_i}^{R_f} ec{A}_n(ec{R}) \ dec{R}$$

However, "phases" are not real physical observable. Therefore, we consider the gauge dependence of $\delta_n(t)$ so that:

$$\psi_n(\vec{R}(t)) o \psi_n'(\vec{R}(t)) = \psi_n(\vec{R}(t))e^{i\zeta_n(\vec{R}(t))}$$
 (6)

This gauge transformation gives:

$$ec{A}_n
ightarrow ec{A}_n' = ec{A}_n -
abla_R \zeta_n(ec{R})$$

$$\delta_n(t)
ightarrow \delta_n'(t) = \delta_n(t) - \zeta(ec{R}_f) + \zeta(ec{R}_i)$$

and we if have a closed contour, we have $ec{R}_i = ec{R}_f$, and therefore

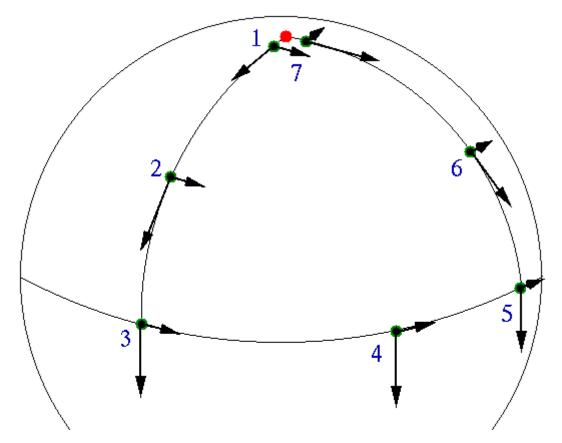
$$e^{i\zeta_n(ec{R}_i)}=e^{i\zeta_n(ec{R}_f)}$$

Therefore, we must have that

$$\zeta_n(ec{R}_f) - \zeta_n(ec{R}_i) = 2\pi n ext{ for } n \in \mathbb{Z}$$

Therefore, for a closed contour, $\delta_n(t)$ is actually a physical phase as a gauge transformation **cannot** cancel $\delta_n(t)$. Therefore, $\delta_n(t)$ is physical.

A classical example:



Note that any rotator starting from 1, and go through a closed contour as the diagram indicated, we realize the plane of the rotation changes.

This process is called a Non-holonomic transport, or paralled transformation in differential geometry.

On the example above, I claim that the shift in the plane of rotation $\theta=\Omega$, the solid angle of the surface. This is because

$$A=rac{2\pi R^2}{2\pi/ heta} o heta=rac{A}{R^2}=\Omega$$

This happens because the surface of a sphere has intrinsic curvature (not homeomorphic to \mathbb{R}^2).

Measurement of Berry Phase

We know our wave function have a total phase (dynamic + Berry)

$$\Psi_n(t)=\psi_n(t)e^{i heta_n(t)}e^{i\delta_n(t)}$$

and Berry phase is nothing but a T period angle change of $\vec{R}(t)$, so $\delta_n(T)=$ Berry phase. But note that after T, our dynamic phase becomes 1. Therefore

$$\Psi=\psi_0+e^{i\delta_n}
ightarrow |\Psi|^2=|\psi_0|^2(1+\cos\delta_n)$$

Example: Spin in a rotating magnetic field.

Let's consider we have a rotating spin $\frac{1}{2}$ particle under a uniform magnetic field. If we express the strength of \vec{B} over time, we have:

$$ec{B} = B_0(\sinlpha\cos(\omega t),\sinlpha\sin(\omega t),\coslpha)$$

in polar coordinates with angle α and our spin $\frac{1}{2}$ particle is rotating with a frequency ω in the uniform magnetic field, with our Hamiltonian

$$H(t) = \frac{e}{m}\vec{S} \cdot \vec{B}$$

and $\omega_1=\frac{eB_0}{m}$ which is called the cyclotron frequency. Note that the adiabatic condition is when $\omega_1\gg\omega$.

Just diagonalize H(t) gives our instantaneous eigenstates

$$\chi_+(t) = egin{pmatrix} \cosrac{lpha}{2} \ e^{i\omega t \sinlpha/2} \end{pmatrix} \quad E_+ = rac{\hbar\omega_1}{2}$$

$$\chi_-(t) = egin{pmatrix} e^{-i\omega t} \sinrac{lpha}{2} \ -\cosrac{lpha}{2} \end{pmatrix} \quad E_- = rac{-\hbar\omega_1}{2}$$