

loop



```
graph LR; loop[loop] --> SensorManager[SensorManager::isDataAvailable];
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow. The first box on the left is white with a black border and contains the text 'loop'. The second box on the right is gray with a black border and contains the text 'SensorManager::isDataAvailable'. The arrow points from the right side of the first box to the left side of the second box.

SensorManager::isDataAvailable