



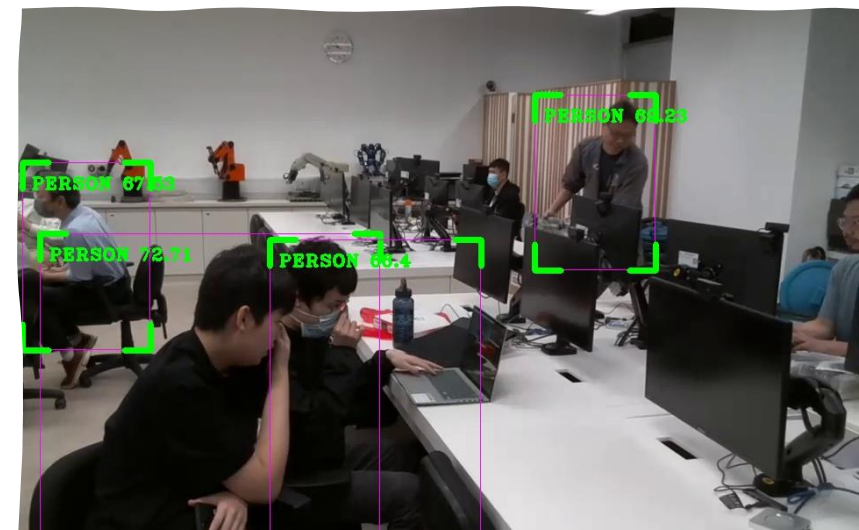
DRONE HUMAN DETECTION

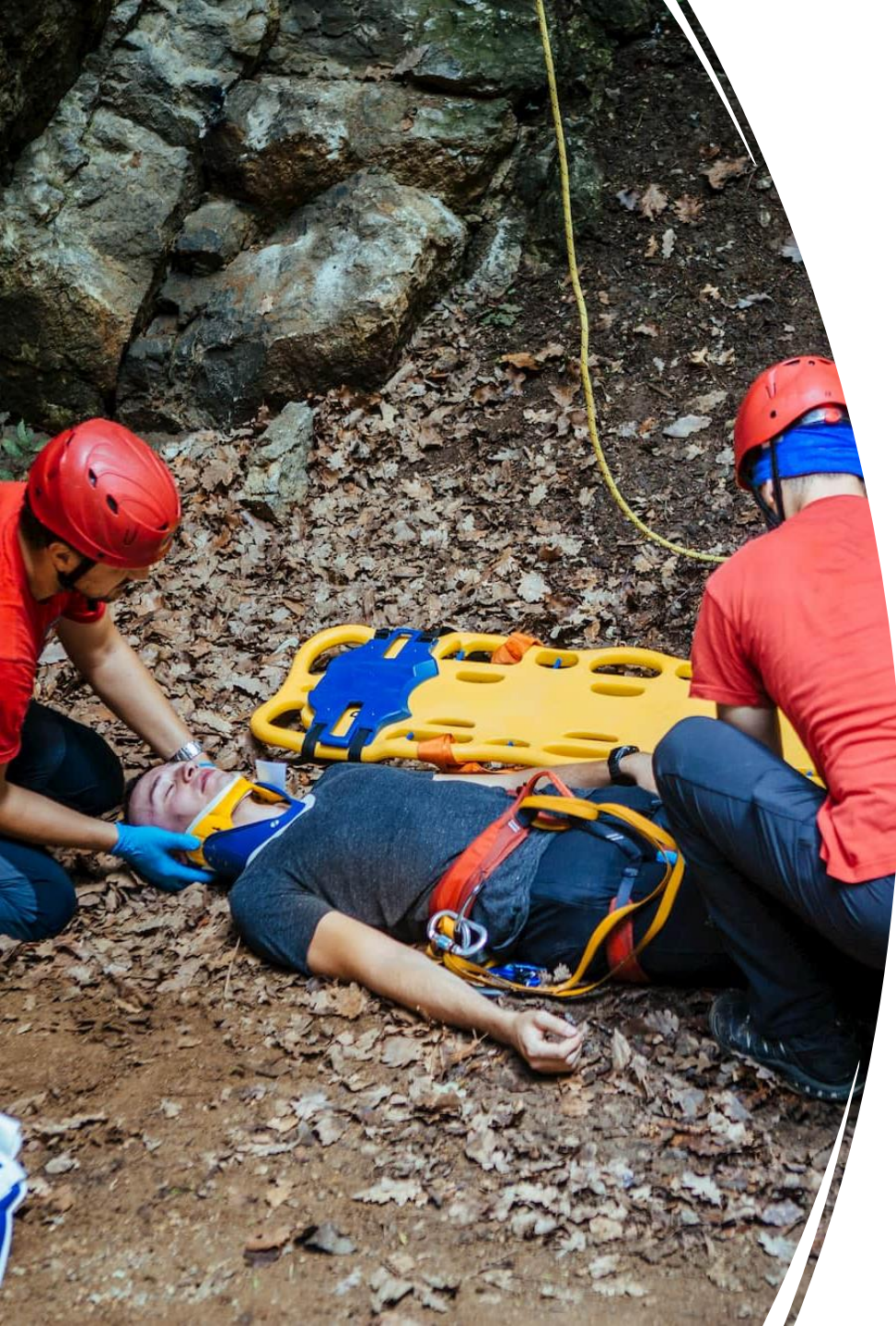
With Using Keyboard Control

220171174

By Cheung Tsz Chun Noddy

- CLEARLY SHOW
THE OBJECTIVE OF
YOUR PROJECT
-





TARGET USERS

-SEARCH AND RESCUE TEAMS

- Fire Services Department (FSD)
- Hong Kong St. John Ambulance Brigade (SJA)
- National Search and Rescue Agency (NASRA)
- United States Coast Guard Search and Rescue

SPECIAL FEATURES

Real-time video streaming

Highlight the detected humans, create a beep sound if humans are detected

Keyboard control of the drone

Mapping and finding out the distance in meters

Take photos with the drone and send them back to the computer

can be easily customized to detect specific objects (including dogs and cats)





APPLICATIONS

Search
and
rescue

locate missing persons in remote or inaccessible areas

Monitor

monitor large areas

Others

detecting missing animals (like dogs and cats)

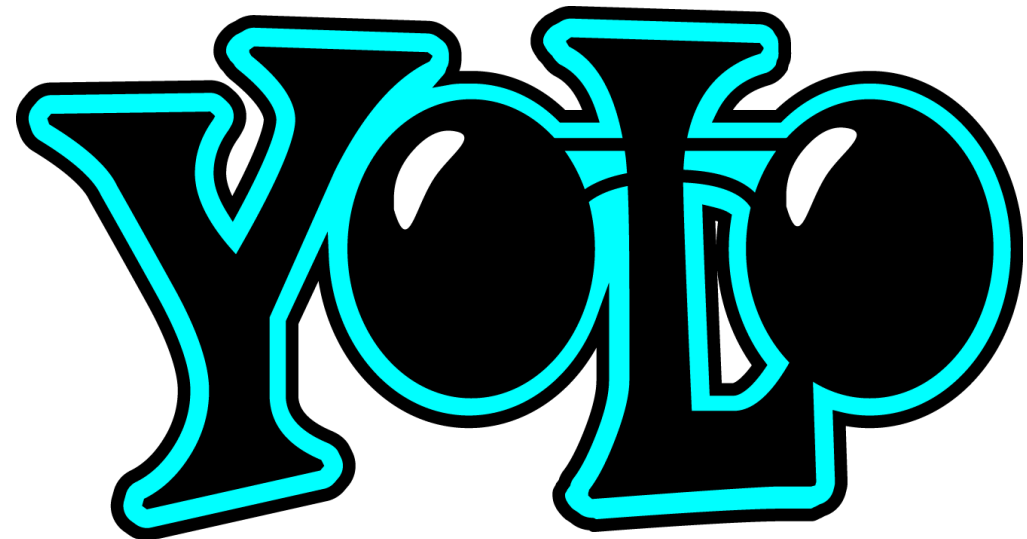
THE METHOD USED

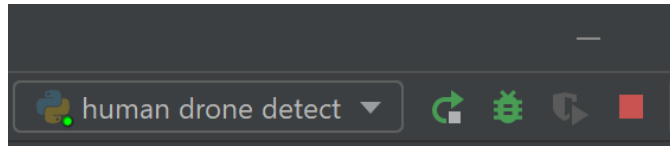
- utilize the 'pygame' library to initialize the keyboard controls, fly the drone and take pictures with code, and implement YOLOV3 for detection
- used Python math and OpenCV for mapping
- Use 'winsound' to generate a beep sound if any humans are detected



WHY SUCH METHOD IS SELECTED

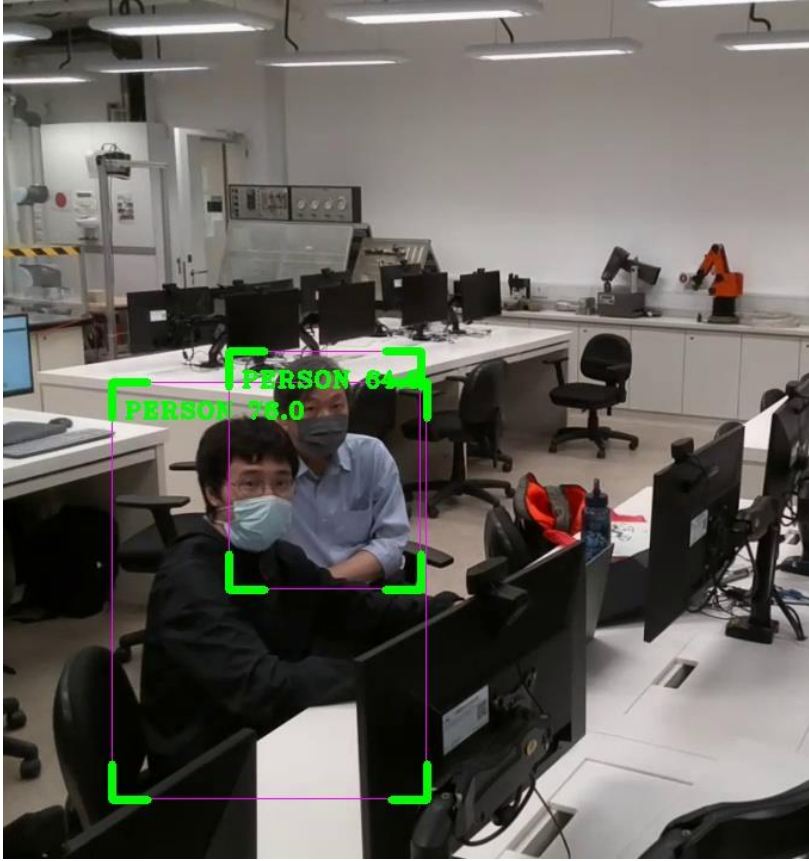
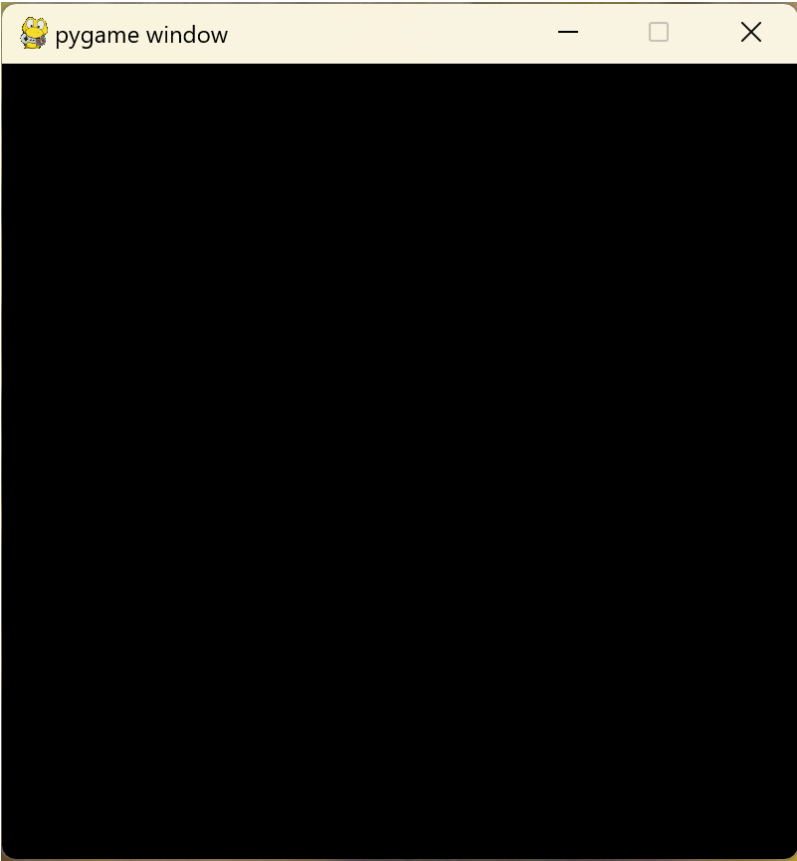
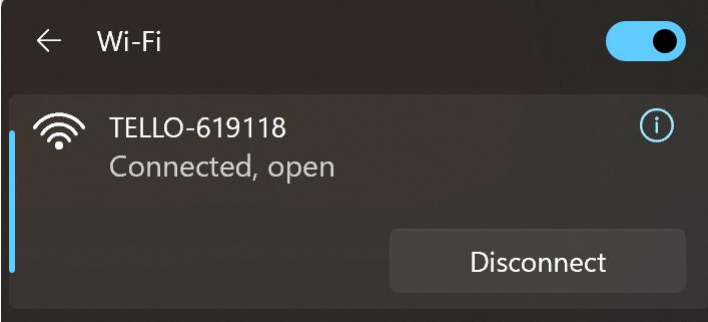
- Speed: YOLO can process images and video frames at very high speeds
- Accuracy: high accuracy in detecting objects, including people
- Reliability: YOLO has been extensively tested and validated on large datasets, making it a reliable and trustworthy tool for object detection
- Flexibility: YOLO can be easily customized to detect specific objects (including dogs and cats)





HOW TO CONTROL

- 1. Connect to Drone Wi-Fi
- 2. Click the pygame window
- 3. press keyboard button to control
- 4. press the stop button to stop the program

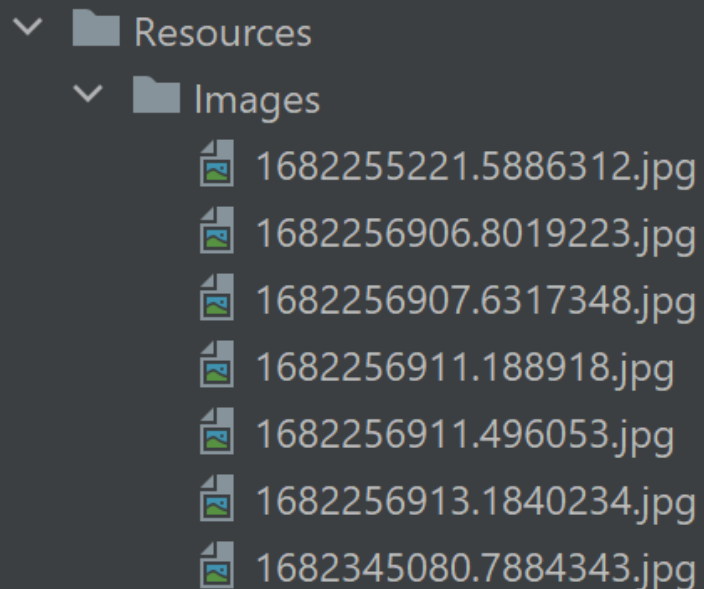


Command	Drone Movement
LEFT, RIGHT	left-right
Up, Down	forward-backward
“w”, “s”	up-down
“a”, “d”	yaw (rotation) movement
“q”, “e”	Land, Takeoff
“z”	Take Pictures



TAKE PHOTOS WITH THE DRONE AND SEND THEM BACK TO THE COMPUTER

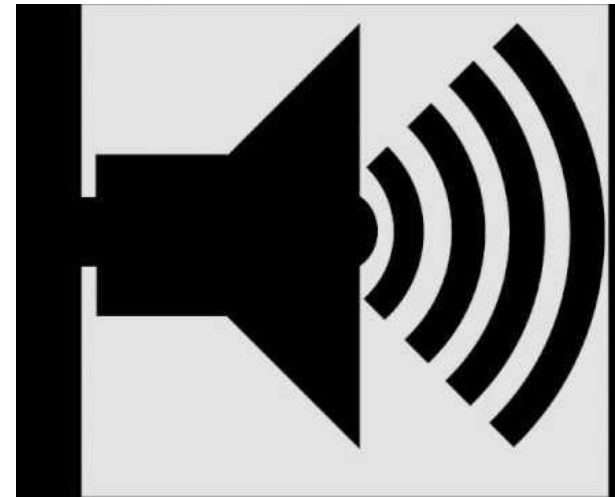
- Taken photos will be sent back to your PC in the Images folder inside the Resources folder
- The photos are named by time, so the name won't get duplicated
- 0.25s per photo for the interval, preventing too many pictures taken at the same time



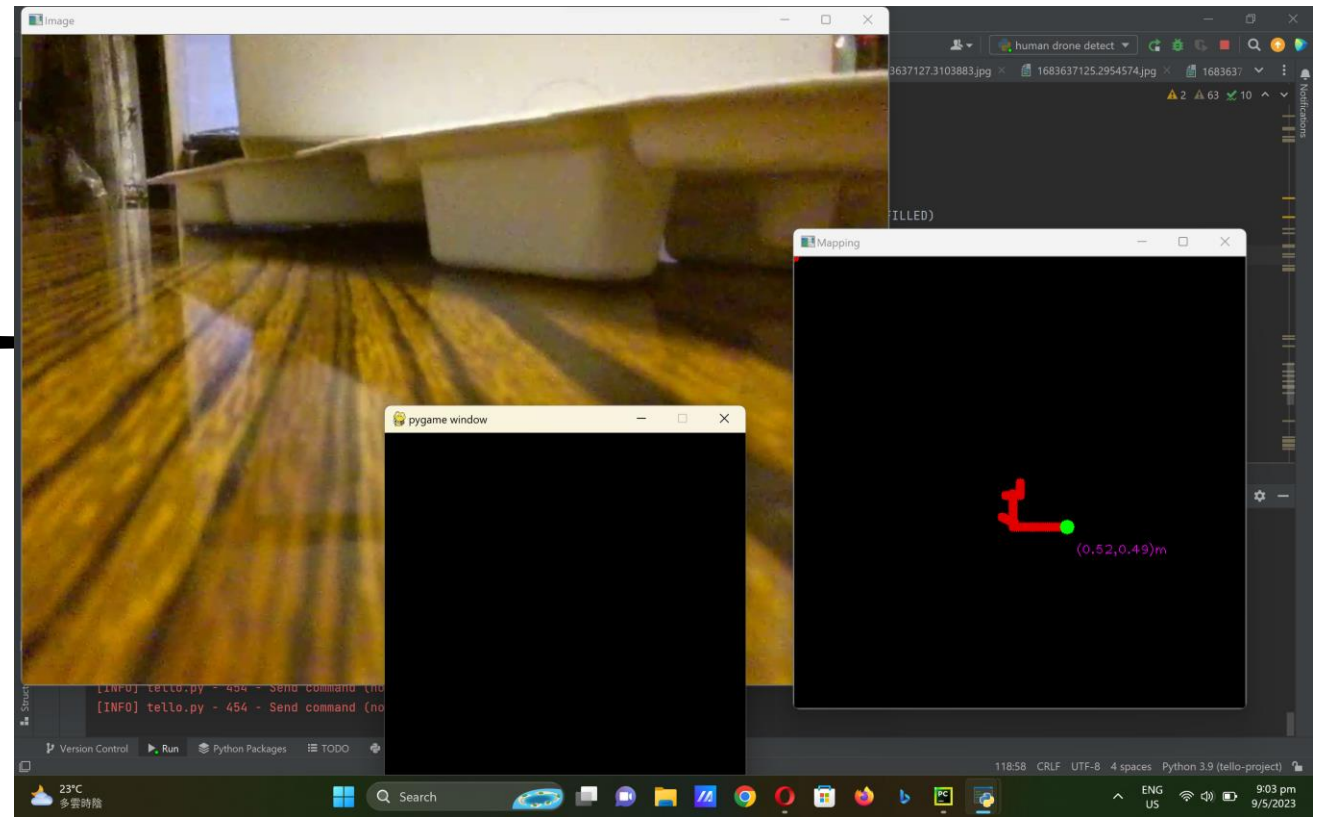
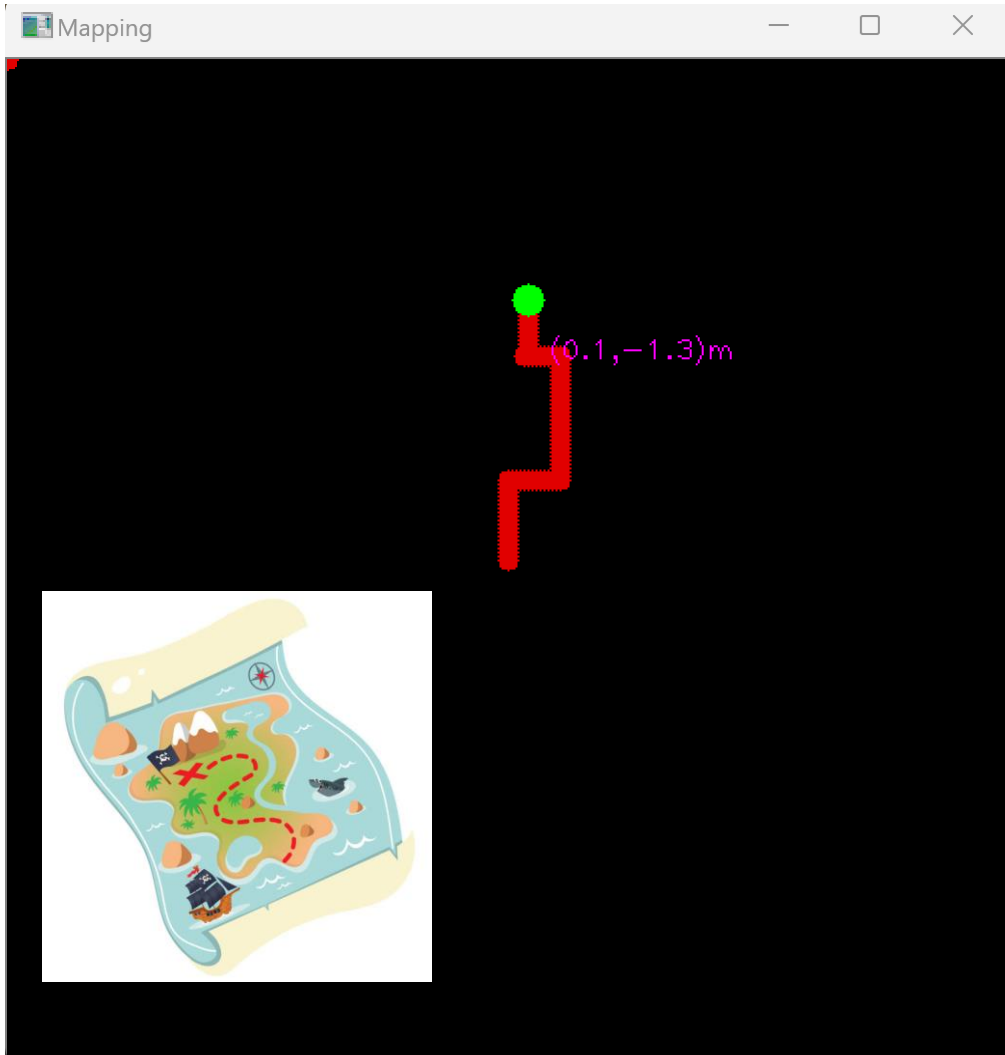
GENERATE A BEEP NOISE

```
10 freq=1000  
11 dur=50
```

- The code will alarm the rescue team every time the drone finds a person
- The frequency is 1000 HZ and the duration is 50 milliseconds
- It's useful for searching for multiple people over a large area, as it can be difficult for rescue teams to keep track of all the search results



MAPPING



- Knowing the (X, Y) axis in meters by calculating the drone speed (15 cm/s)
- Record the drone search history
- Help to locate missing persons

DETECT OTHER OBJECTS(LIKE DOGS AND CATS)

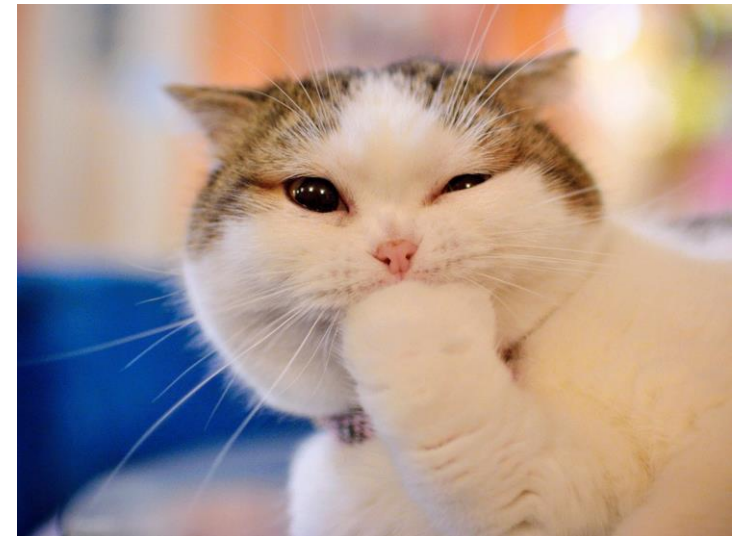
42

```
class_of_interest = classNames.index('person') + 1
```

- We can select other objects to detect by simply changing `classNames.index('Person')` in line 42
- It can help the rescue team search for missing pets in emergency situations



!!!?





LIMITATIONS

LIMITATIONS OF MY DESIGN

→ impact long-range surveillance or monitoring



Battery life: ~
13 minutes



Environmental factors: lighting conditions, weather, and obstacles




Wi-Fi range:
~ 100m

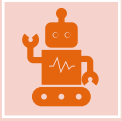



YOLOv3 resolution:
416x416

IMPROVEMENT THAT CAN BE DONE IN FUTURE



Set up Wi-Fi range extender: coverage area 



Hardware upgrades: drone or computer 



Environmental monitoring: install extra sensors to monitor (GPS and weather)



Battery life extension: external battery packs



ETHICAL ISSUE

- Privacy concerns
- Data security: may collect and store sensitive data (video footage and personal information)
- Safety risks: particularly if the drone is flown in crowded or restricted areas



TIMELINE OF THE PROJECT

Easter Holiday: Project planning and research

17/4: Hardware setup. Ask school and teacher to borrow the drone

24-25/4: coding the keyboard part

29-30/4, 1/5: coding the YOLO part to detect human and write the PowerPoint

9-10/5: coding the Mapping part and final testing

SCHOOL TIMETABLE					
	8:00-8:50	9:00-9:50	10:00-10:50	11:30-12:20	1:30-2:20
IE	1	1	1	1	1
ON					
E					
ED					
U					
I					

REFERENCE LINK

- <https://youtu.be/5dh9abXqMok>
- <https://youtu.be/LmEcyQnfpDA>

The GitHub URL for my code:

<https://github.com/noddycheung/cv2/blob/03e5f72156c6ec88f823be5a69f80dacd20bc814/dronemap%2Bcam%2Bnoise>

<https://github.com/noddycheung/cv2/blob/bfb04e090110f04e3ee33516714a286696f2f35a/KeyPressModule>