Run2 HRP2 Ros SW examples

Start HRP2 SW on Raspberry PI

Make sure that the Raspberry Pi is connected to the Mower via Can Dongle

ssh into the Raspberry Pi and run:

```
source  /opt/ros/galactic/setup.bash
source  install/local_setup.bash
sudo ip link set can0 up type can bitrate 1000000
sudo ifconfig can0 txqueuelen 5000
```

sudo nano /proc/sys/fs/mqueue/msg_max

set to 300

ros2 launch hrp_pkg hrp_keepalive.launch.py

Remote control using keyboard

source /opt/ros/galactic/setup.bash
source install/local_setup.bash

python3 ./install/lib/python3.8/site-packages/hqv_keyboard_remote_drive/keyboard_remote_drive_node.py

Record sensor data

source /opt/ros/galactic/setup.bash
source install/local_setup.bash

ros2 bag record -a