

Dijkstra's Algorithm

UT Austin CS prof 84-99
Turing award in 1972
one of the founding fathers of CS.

Single Source Shortest Path

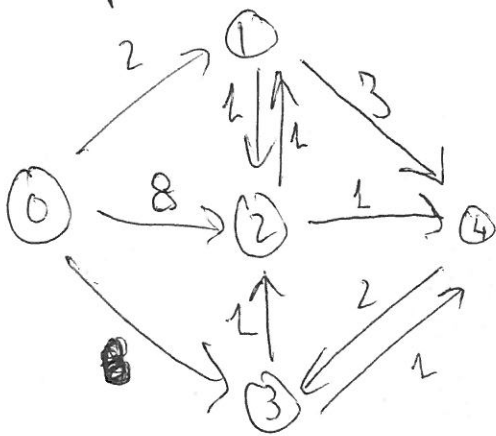
Input: Graph $G = (V, E)$
vertex $s \in V$

Output: For every vertex $v \in V$
shortest path from s to v .

We saw how to solve this problem for
unweighted G (using BFS).

Today: Weighted case, where all weights are non-negative.

Example



| | length |
|-------------------|--------|
| $0 \rightarrow 1$ | 2 |
| $0 \rightarrow 2$ | 3 |
| $0 \rightarrow 3$ | 6 |
| $0 \rightarrow 4$ | 4 |

Algorithm

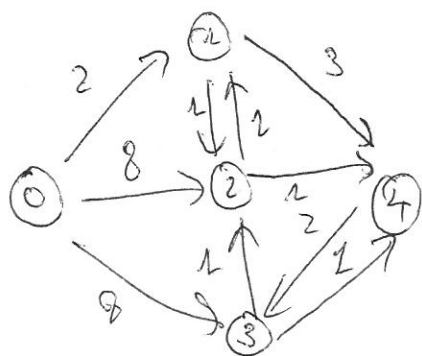
- ① Maintain $S \subseteq V$ = vertices for which we already found shortest paths.

Initially $S = \{s\}$.
 $d(s) = 0$.

- ② Repeat: pick $v \in V - S$ that minimizes $\min_{u \in S} d(u) + w(u, v)$
 $S \leftarrow S \cup \{v\}$
 $d(v) \leftarrow d(u) + w(u, v)$.



Run the algo on previous example: $s = 0$



$$S = \{0\} \quad d(0) = 0$$

$$S = \{0, 1\} \quad d(1) = 2$$

$$S = \{0, 1, 2\} \quad d(2) = 3$$

$$S = \{0, 1, 2, 4\} \quad d(4) = 4$$

$$S = \{0, 1, 2, 4, 3\} \quad d(3) = 6$$

Correctness of Algorithm

2.5

Lemma Every time a vertex is extracted from V and added to S its $d(v)$ is the ^{length of the} shortest path from s to v .

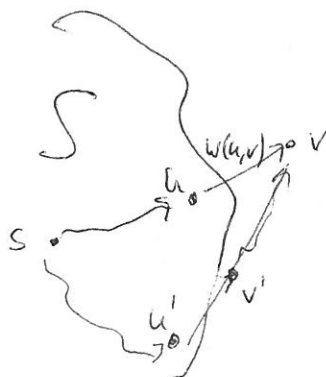
Pf By induction.

Base When s is added $d(s)=0$ which is indeed the length.

Hypothesis Suppose this is true for S so far,

Step now we add v to S .

- (a) There is a path $S \rightsquigarrow v$ of length $d(u) + w(u, v)$ because there's a path $S \rightsquigarrow u$ of length $d(u)$.



- (b) Suppose ^{on way of contradiction} there's a path $S \rightsquigarrow v$ that is shorter than $d(u) + w(u, v)$.

$s \in S$ and $v \notin S$ so there must be an edge (u', v') on the path so $u' \in S, v' \notin S$.

$$d(u') + w(u', v') < d(u) + w(u, v)$$

part of a path
that is shorter than
 $d(u) + w(u, v)$.

\Rightarrow Dijkstra would have picked v'
& set $d(v') \leq d(u') + w(u', v') < d(u) + w(u, v)$

← Chapter 2.5 in the book

Priority Queue: maintain a set Q of elements where each element has a value "key".

The following operations are supported:

- $\text{Insert}(Q, x)$: insert element x with value $\text{key}(x)$ to Q .
- $\text{Minimum}(Q)$: returns a pointer to element in Q with min key.
report if $Q = \emptyset$.
- $\text{Extract-Min}(Q)$: returns an element with min key & extracts it from Q
(i.e. deletes).
- $\text{Decrease-key}(Q, x, k)$: given a pointer to element x in S change $\text{key}(x)$ to k if $\text{key}(x) > k$.

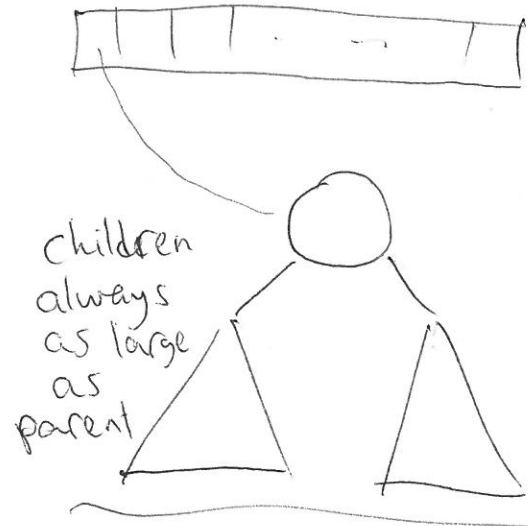
Dijkstra (G, s)

1. For each $v \in V$ do $d[v] \leftarrow \infty$.
2. $d[s] \leftarrow 0$
3. Q - a binary heap with all $v \in V$, each with key $d[v]$.
4. While $Q \neq \emptyset$ do
5. $u \leftarrow \text{Extract-Min}(Q)$
6. For each neighbor v of u do
7. If $v \in Q$ then $\text{Decrease-key}(Q, v, d[u] + w(u, v))$.

Run-time

Binary heap implementation:

- Insert $O(\lg n)$ time.
- Min $O(1)$ time.
- Extract-Min $O(\lg n)$ time.
- Decrease-key $O(\lg n)$ time.



Note A priority queue allows sorting so n inserts + n extract-min must take $\Omega(n \lg n)$ time

Steps 1-3 $O(n \lg n)$.

Step 5 $O(n \lg n)$

Steps 6-7 $O(m \lg n)$

$n = |V|$.

Overall: $O((m+n) \lg n)$.