

## FLOW NETWORK

A flow network is a diagraph  $G=(V,E)$  with a source and sink and non negative integer capacity  $c(e)$  for each  $e$  in  $E$

NO PARALLEL EDGES NO EDGE ENTERS S NO EDGE LEAVES T

A s-t cut is a partition  $(A,B)$  of the vertices with  $s$  and  $t$  in  $A$  and  $B$

The capacity of an s-t cut is the sum of the capacities of the edges from  $A$  to  $B$

An s-t flow is a function from the edges to the integers satisfying the following:

Every edge  $e$  in  $E$  has a flow less than or equal to capacity

Every vertex  $v$  is not part of  $s,t$

Flow from  $s$  is same as flow into  $t$

BiPartite Matching:

Given an undirected graph  $G=(V,E)$  of a subset of edges  $M$  from  $E$  is a matching if each node appears in at most one edge in  $E$

SOLVE:

1. Consider a flow network  $G'$  where all edges are directed from  $L$  to  $R$  and match the edges in  $G$
2. There are edges from  $s$  to every vertex in  $L$
3. There are edges to  $t$  from every vertex in  $R$
4.  $C(e) = 1$  for every  $e$  in  $E'$

## FORD FULKERSON ALGORITHM

Input: Directed Graph  $G=(V,E)$  with capacity  $c$  in  $E \rightarrow \mathbb{N}^+$

Source  $s$  and sink  $t$

Output is the max flow

ALGO:

PICK A PATH from  $s$  to  $t$ , flow on it as much as possible

Update network

Create a residual network – if there is a simple path, flow more!

Every iteration takes linear time in the size of the graph.

Maximality of flow: why does getting stuck mean we found max flow?

Flow value lemma: Let  $f$  be a flow : Let  $f$  be a flow:  $(C, V-C)$  be an s-t cut, sin  $C < t$  in  $V-C$

Min Cut – Max Flow Theorem

Value of max flow = capacity of Min cut

In fact: The following are equivalent

1. There is an st cut whose capacity is the value of  $f$ .
2.  $f$  is a max flow
3. There are no augmenting paths in respect to  $f$

## EDIT DISTANCE:

Given an alignment of two strings:

It's cost is the sum of the number of gaps and number of mismatches. The edit distance between two strings is the min cost of an alignment between them.

1. Align  $x$  and  $y$ ; Cost: possible mismatch between  $x_i + y_j$  plus cost of aligning  $x_1..x_{i-1}$  &  $y_1..y_{j-1}$
2. Align  $x_1..x_{i-1}$  and  $y_1..y_j$  leave  $x_i$  unmatched cost: 1 for gap + cost of aligning  $x_1..x_{i-1}$ ,  $y_1..y_j$
3. Similarly but when  $y_j$  is unmatched

$OPT(i,0) = i$   $OPT(0,j) = j$

$OPT(i,j) = \min\{ (0 \text{ if } x_i = y_j, 1 \text{ if } x_i \neq y_j) + OPT(i-1, j-1), 1+OPT(i-1,j), 1+OPT(i,j-1) \}$

Algorithm:

For  $i = 0..m$

$Opt[i,0] = i$

For  $j = 0..n$

$OPT(0,j) = j$

For  $i = 1..m$

For  $j = 1..n$ ;  $b = (x_i = y_j)$   $OPT[i,j] = \min\{b+OPT[i-1,j-1], 1+OPT[i-1,j], 1+OPT[i,j-1]\}$

### Knapsack

Input: Items 1..n where each have value  $v_i$  and weight  $w_i$  greater than 0. Capacity of W.

Output: Fill the knapsack with the max value where you don't exceed the capacity.

$OPT(i, w)$  – max profit for object 1..i and weight  $\leq w$

$OPT(0, w) = 0$

$OPT(i, w) = \max \{$   
     $OPT(i-1, w)$   
     $v_i + OPT(i-1, w-w_i)$

Algorithm:

For  $w = 0..W$

$OPT[0, w] = 0$

For  $i = 1..n$

    For  $w = 1..W$

        If  $(w_i > w)$

$OPT[i, w] = OPT[i-1, w]$

        ELSE

    (ABOVE CONDITIONAL)

Runtime is  $O(n \times W)$

### Interval Scheduling:

Input: Tasks with weight  $w_i$

Output: Non overlapping tasks with total max weight.

Sort jobs by finish time and

$OPT[j]$  has value of optimal solution up to  $f_j$ .

Therefore: algo is

$OPT[j] = \max (w_j + OPT[p(j)],$

$OPT[j-1])$  where  $OPT[0] = 0$ .

You either choose to do the task or not.

$O(n \lg n)$  to sort by finish time.

$O(n \lg n)$  to compute p)

Overall:  $O(n \lg n)$

Algorithm:

1. Sort  $f_1..f_n$

2. Compute  $p(1)..p(n)$

3.  $OPT[0] = 0$

4. For  $j=1..n$

$Opt[j] = \max\{w_j +$

$OPT(p(j)), OPT[j-1]$

Elements of Dynamic

Programming:

- Order/Time
- Polynomilaity

### ShortestPaths

Input: Weighted directed graph  $G=(V,E)$ . there are negative weights but no negative cycles

Output: length of shortest path from s to t

$OPT(l, v)$  = length of shortest v-t path using  $\leq l$  edges

$OPT(l, v) = \min \{ OPT(i-1, v), OPT(i-1, u) + W(v, u) \}$

$OPT(0, v) = \text{infinity}$   $OPT(0, t) = 0$

NOTE: Length of shortest path  $\leq n-1$ , otherwise there's a cycle.

Algorithm:

For each v in V

$OPT[0, v] = \text{infinity}$

$OPT[0, t] = 0$

For  $l = 1 .. n-1$

    For each v in V

$OPT[l, v] = OPT[i-1, 1]$

    For each (v,u) in E

$OPT[l, v] = \text{ABOVE ALGO}$

TIME:  $O(V \times E) + V^2$

SPACE:  $O(V \times E)$

BELLMAN FORD:

For each v in V

$OPT[v] = \text{infinity}$

$OPT[t] = 0$

For  $l = 1..n-1$

    For each (u,v) in E

        If  $OPT[v] + W(u, v) < OPT[u]$

$OPT[u] = OPT[v] + W(u, v)$

TIME:  $O(V \times E)$  SPACE:  $O(V)$

Check if BF has neg cycles by adding this to end

For each (u,v) in E

    If  $OPT[v] = w(u, v) < OPT[u]$

        Then announce negative cycle

### Dynamic Programming:

Idea: Store  $OPT[j]$  in an array.

Update tasks takes  $O(1)$  time,

having computed  $OPT[i]$  for

every  $i < j$  already. This is

memorization.