Barrier synchronization

Other synchronization (flag checks and return integers, etc)

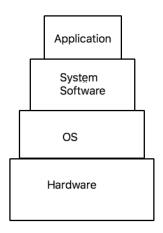
You have to provide it will not work: mutual exclusion, progress, bounded waiting → no deadlock if all 3 are there

Mutual exclusion: no process will have exclusive access to a resource

Bounded waiting: how long (quantitative measure) process/thread has been waiting.

Starvation

Review throughput assignment and excel file might be in midterm Non preemptive system = let all process go through If we make it a preemptive system= what would be changed.



User mode vs system mode:

**Why do we need a system mode?** To avoid programs using hardware resources. **What could happen?** You could write one program that could erase everything. To

 $make\ sure\ access\ to\ hardware\ resource\ is\ privileged.$ 

Application wants to display on a monitor (hardware resource)

sys.out.println (system call)

That generates a software trap

That generates a hardware interrupt

 $\ensuremath{\mathsf{OS}}$  comes in and transmit the command to Monitor

How do we implement this interrupt hardware mechanism?

Mode Bit: switch between 0 and 1.

App

sys.out.println (sys call)

trap

HW interrupt

Monitor

OS Architecture

<u>Batch</u>

→ 0 → 0 →

<u>Microkernel</u>

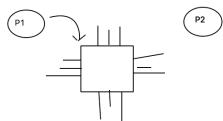
We take core OS piece .

user space

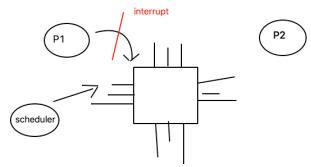
system space kernel

## *Multitasking*: You can load multiple programs to memory

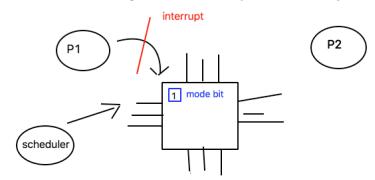
## **Context Switching**



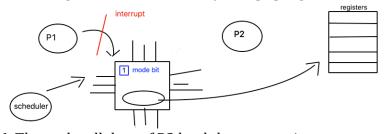
- 1. P1 is running and hit timeslice
- 2. Hardware Interrupt



- 3. OS Scheduler loaded on CPU
- 4. Scheduler Change the Mode bit (to 1, to be in syst mode) to access resources



5. Save register value in memory except program counter (PC)



- 6. Then take all data of P2 load them on register except program counter (PC)
- 7. Change back the Mode bit, Stop the scheduler.

