#### In [1]:

x = layers.BatchNormalization()(x)
x = layers.MaxPooling2D(pool size=2)(x)

x = layers.Dropout(0.25)(x)

```
from keras.utils import image dataset from directory
import tensorflow as tf
train dir 1 = 'trainning/train1'
train dir 2 = 'trainning/train2'
train dir 3 = 'trainning/train3'
validation dir = 'train4' # Validation
train dir \overline{5} = \frac{\text{trainning}}{\text{train5}}
test dir = 'test'
trainning = [train dir 1, train dir 2, train dir 3, train dir 5]
train dir = train dir 2
IMG SIZE = 32 \# 32x32
# image_dataset_from_directory with labels="inferred" for
# getting the images in the subdirectories and translating the subdirectory as a class
# of type categorical
#train dataset = image dataset from directory(train dir,image size=(IMG SIZE, IMG SIZE),b
atch size=32, labels="inferred", label mode="categorical")
test_dataset = image_dataset_from_directory(test_dir,image_size=(IMG_SIZE, IMG_SIZE), lab
els="inferred", label mode="categorical")
validation dataset = image dataset from directory(validation dir,image size=(IMG SIZE, IM
G SIZE), labels="inferred", label mode="categorical")
train dataset = tf.data.Dataset
for i in trainning:
    if i == trainning[0]:
        train dataset = image dataset from directory(i, image size=(IMG SIZE, IMG SIZE),
labels="inferred", label mode="categorical")
        continue
   train dataset = train dataset.concatenate( image dataset from directory(i, image size
=(IMG SIZE, IMG SIZE), labels="inferred", label mode="categorical"))
Found 10000 files belonging to 10 classes.
In [2]:
from keras.callbacks import ModelCheckpoint, EarlyStopping, ReduceLROnPlateau
import keras
from keras import layers
import numpy as np
IMG SIZE = 32
inputs = keras.Input(shape=(IMG SIZE, IMG SIZE, 3))
x = layers.Rescaling(1./255) (inputs)
x = layers.Conv2D(filters=32, kernel_size=3, activation="relu", padding='same', kernel_r
egularizer=keras.regularizers.12(0.001))(x)
x = layers.BatchNormalization()(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Dropout(0.25)(x)
x = layers.Conv2D(filters=64, kernel size=3, activation="relu", padding='same', kernel r
egularizer=keras.regularizers.12(0.001))(x)
```

x = layers.Conv2D(filters=128, kernel size=3, activation="relu", padding='same', kernel

```
regularizer=keras.regularizers.12(0.001))(x)
x = layers.BatchNormalization()(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Dropout(0.25)(x)
x = layers.Flatten()(x)
x = layers.Dense(256, activation="relu", kernel regularizer=keras.regularizers.12(0.001)
) (x)
x = layers.BatchNormalization()(x)
x = layers.Dropout(0.5)(x)
x = layers.Dense(128, activation="relu", kernel regularizer=keras.regularizers.12(0.001)
x = layers.BatchNormalization()(x)
x = layers.Dropout(0.5)(x)
# Output layer
outputs = layers.Dense(10, activation="softmax")(x)
model = keras.Model(inputs=inputs, outputs=outputs)
# Compile the model
model.compile(loss='categorical_crossentropy', optimizer='adam', metrics=['accuracy'])
# Callbacks
checkpoint = ModelCheckpoint(
    'models S/S without DA First.h5', monitor='val loss', verbose=0,
    save best only=True, mode='min'
early stopping = EarlyStopping(
   monitor='val loss', patience=5, verbose=1, mode='min',
   restore best weights=True
rl = ReduceLROnPlateau(
   monitor="val loss",
   factor=0.1,
   patience=4,
   verbose=0,
   mode="min",
# batch size 32
# Test loss: 0.6775595545768738
# Test accuracy: 0.8391000032424927
# batch size 64
# Test loss: 0.693570613861084
# Test accuracy: 0.8421000242233276
# batchsize 128
# Test loss: 0.7256516814231873
# Test accuracy: 0.8317000269889832
# sem BatchNormalization
#Test loss: 0.7569888234138489
# Test accuracy: 0.8009999990463257
# sem Droupout
#Test loss: 1.2996251583099365
#Test accuracy: 0.7465000152587891
#64 BATCH SIZE - pacience 10
# Epoch 102: early stopping
# 313/313 [============== ] - 1s 3ms/step - loss: 0.7004 - accuracy: 0.835
# Test loss: 0.7004380226135254
```

```
# Test accuracy: 0.8349999785423279

#128
# Test loss: 0.7256516814231873
# Test accuracy: 0.8317000269889832
```

#### In [4]:

```
history = model.fit(
 train dataset,
 epochs=200,
 batch size=128,
 validation data=validation dataset,
 callbacks=[checkpoint, early stopping, rl]
# Avaliar o modelo (com o teste)
test loss, test accuracy = model.evaluate(test dataset)
print(f'Test loss: {test loss}')
print(f'Test accuracy: {test accuracy}')
Epoch 1/200
3994 - val loss: 3.0313 - val accuracy: 0.3178 - lr: 0.0010
Epoch 2/200
286 - val loss: 1.7325 - val accuracy: 0.5480 - lr: 0.0010
Epoch 3/200
878 - val loss: 1.7617 - val accuracy: 0.5382 - lr: 0.0010
Epoch 4/200
197 - val loss: 1.6868 - val_accuracy: 0.5654 - lr: 0.0010
Epoch 5/200
341 - val loss: 1.4883 - val accuracy: 0.6629 - lr: 0.0010
Epoch 6/200
480 - val loss: 1.4054 - val accuracy: 0.6954 - lr: 0.0010
Epoch 7/200
582 - val loss: 1.4709 - val accuracy: 0.6735 - lr: 0.0010
Epoch 8/200
642 - val loss: 2.0779 - val accuracy: 0.4837 - lr: 0.0010
Epoch 9/200
737 - val loss: 1.3864 - val accuracy: 0.7057 - lr: 0.0010
Epoch 10/200
787 - val loss: 1.4003 - val accuracy: 0.7007 - lr: 0.0010
Epoch 11/200
821 - val loss: 1.6594 - val accuracy: 0.6134 - lr: 0.0010
Epoch 12/200
819 - val loss: 1.4633 - val accuracy: 0.6770 - lr: 0.0010
Epoch 13/200
842 - val loss: 1.5156 - val accuracy: 0.6592 - lr: 0.0010
Epoch 14/200
300 - val loss: 1.1259 - val accuracy: 0.7745 - lr: 1.0000e-04
Epoch 15/200
477 - val loss: 1.0401 - val accuracy: 0.7861 - lr: 1.0000e-04
Epoch 16/200
599 - val loss: 1.0010 - val accuracy: 0.7886 - lr: 1.0000e-04
Epoch 17/200
```

```
660 - val loss: 0.9698 - val accuracy: 0.7904 - lr: 1.0000e-04
Epoch 18/200
770 - val loss: 0.9261 - val accuracy: 0.7955 - lr: 1.0000e-04
Epoch 19/200
778 - val loss: 0.8985 - val accuracy: 0.7994 - lr: 1.0000e-04
Epoch 20/200
840 - val loss: 0.8773 - val accuracy: 0.8014 - lr: 1.0000e-04
Epoch 21/200
851 - val loss: 0.8573 - val accuracy: 0.8041 - lr: 1.0000e-04
Epoch 22/\overline{2}00
903 - val loss: 0.8501 - val accuracy: 0.8023 - lr: 1.0000e-04
Epoch 23/200
947 - val loss: 0.8245 - val accuracy: 0.8090 - lr: 1.0000e-04
Epoch 24/200
004 - val loss: 0.8263 - val accuracy: 0.8056 - lr: 1.0000e-04
Epoch 25/200
010 - val loss: 0.8209 - val accuracy: 0.8083 - lr: 1.0000e-04
Epoch 26/200
054 - val loss: 0.8155 - val accuracy: 0.8068 - lr: 1.0000e-04
Epoch 27/200
075 - val loss: 0.7864 - val accuracy: 0.8156 - lr: 1.0000e-04
Epoch 28/\overline{200}
072 - val loss: 0.8055 - val_accuracy: 0.8053 - 1r: 1.0000e-04
Epoch 29/200
099 - val loss: 0.7782 - val accuracy: 0.8168 - lr: 1.0000e-04
Epoch 30/\overline{200}
135 - val loss: 0.7685 - val accuracy: 0.8178 - lr: 1.0000e-04
Epoch 31/200
136 - val loss: 0.7654 - val accuracy: 0.8208 - lr: 1.0000e-04
Epoch 32/200
145 - val loss: 0.7630 - val accuracy: 0.8203 - lr: 1.0000e-04
Epoch 33/200
186 - val loss: 0.7838 - val accuracy: 0.8110 - lr: 1.0000e-04
Epoch 34/200
181 - val loss: 0.7768 - val accuracy: 0.8156 - lr: 1.0000e-04
Epoch 35/\overline{200}
216 - val loss: 0.7907 - val accuracy: 0.8090 - lr: 1.0000e-04
Epoch 36/200
250 - val loss: 0.7484 - val accuracy: 0.8176 - lr: 1.0000e-04
Epoch 37/200
238 - val loss: 0.7578 - val accuracy: 0.8178 - lr: 1.0000e-04
Epoch 38/200
254 - val loss: 0.7600 - val accuracy: 0.8126 - lr: 1.0000e-04
Epoch 39/200
248 - val loss: 0.7463 - val_accuracy: 0.8214 - lr: 1.0000e-04
Epoch 40/\overline{200}
270 - val loss: 0.7490 - val accuracy: 0.8201 - lr: 1.0000e-04
Epoch 41/200
```

```
299 - val loss: 0.7392 - val accuracy: 0.8241 - lr: 1.0000e-04
Epoch 42/200
306 - val loss: 0.7566 - val accuracy: 0.8180 - lr: 1.0000e-04
Epoch 43/200
320 - val loss: 0.7507 - val accuracy: 0.8212 - 1r: 1.0000e-04
Epoch 44/200
311 - val loss: 0.7530 - val accuracy: 0.8207 - lr: 1.0000e-04
Epoch 45/200
332 - val loss: 0.7345 - val accuracy: 0.8229 - lr: 1.0000e-04
Epoch 46/\overline{200}
355 - val loss: 0.7343 - val accuracy: 0.8243 - lr: 1.0000e-04
Epoch 47/200
350 - val loss: 0.7346 - val accuracy: 0.8239 - lr: 1.0000e-04
Epoch 48/200
358 - val loss: 0.7577 - val accuracy: 0.8200 - lr: 1.0000e-04
Epoch 49/200
397 - val loss: 0.7444 - val accuracy: 0.8222 - lr: 1.0000e-04
Epoch 50/200
371 - val loss: 0.7548 - val accuracy: 0.8166 - lr: 1.0000e-04
Epoch 51/200
496 - val loss: 0.7239 - val accuracy: 0.8275 - lr: 1.0000e-05
Epoch 52/\overline{200}
498 - val loss: 0.7178 - val accuracy: 0.8293 - 1r: 1.0000e-05
Epoch 53/\overline{200}
486 - val loss: 0.7131 - val accuracy: 0.8313 - lr: 1.0000e-05
Epoch 54/\overline{200}
503 - val_loss: 0.7156 - val_accuracy: 0.8294 - 1r: 1.0000e-05
Epoch 55/200
514 - val loss: 0.7137 - val accuracy: 0.8294 - lr: 1.0000e-05
Epoch 56/200
529 - val loss: 0.7124 - val accuracy: 0.8301 - lr: 1.0000e-05
Epoch 57/\overline{200}
539 - val loss: 0.7077 - val_accuracy: 0.8316 - lr: 1.0000e-05
Epoch 58/\overline{200}
592 - val loss: 0.7095 - val accuracy: 0.8315 - lr: 1.0000e-05
Epoch 59/200
571 - val loss: 0.7062 - val accuracy: 0.8330 - lr: 1.0000e-05
Epoch 60/200
561 - val loss: 0.7031 - val accuracy: 0.8318 - lr: 1.0000e-05
Epoch 61/200
604 - val loss: 0.7084 - val accuracy: 0.8308 - lr: 1.0000e-05
Epoch 62/200
612 - val loss: 0.7026 - val accuracy: 0.8336 - lr: 1.0000e-05
Epoch 63/200
593 - val loss: 0.7045 - val_accuracy: 0.8313 - lr: 1.0000e-05
Epoch 64/\overline{200}
640 - val loss: 0.6997 - val accuracy: 0.8339 - lr: 1.0000e-05
Epoch 65/200
```

```
615 - val loss: 0.7037 - val accuracy: 0.8312 - lr: 1.0000e-05
Epoch 66/200
601 - val loss: 0.6988 - val accuracy: 0.8343 - 1r: 1.0000e-05
Epoch 67/200
608 - val loss: 0.6999 - val accuracy: 0.8329 - 1r: 1.0000e-05
Epoch 68/200
629 - val loss: 0.6994 - val accuracy: 0.8332 - 1r: 1.0000e-05
Epoch 69/200
622 - val loss: 0.6990 - val accuracy: 0.8312 - lr: 1.0000e-05
Epoch 70/\overline{200}
662 - val loss: 0.6960 - val accuracy: 0.8334 - lr: 1.0000e-05
Epoch 71/200
632 - val loss: 0.6970 - val accuracy: 0.8329 - lr: 1.0000e-05
Epoch 72/200
643 - val loss: 0.6963 - val accuracy: 0.8344 - lr: 1.0000e-05
Epoch 73/200
637 - val loss: 0.6948 - val accuracy: 0.8347 - lr: 1.0000e-05
Epoch 74/200
662 - val loss: 0.6929 - val accuracy: 0.8348 - lr: 1.0000e-05
Epoch 75/200
654 - val loss: 0.6930 - val_accuracy: 0.8326 - lr: 1.0000e-05
Epoch 76/200
670 - val loss: 0.6886 - val accuracy: 0.8362 - lr: 1.0000e-05
Epoch 77/200
662 - val loss: 0.6928 - val accuracy: 0.8339 - lr: 1.0000e-05
Epoch 78/200
673 - val loss: 0.6903 - val accuracy: 0.8343 - lr: 1.0000e-05
Epoch 79/200
703 - val loss: 0.6892 - val accuracy: 0.8349 - lr: 1.0000e-05
Epoch 80/200
715 - val loss: 0.6952 - val accuracy: 0.8342 - lr: 1.0000e-05
Epoch 81/\overline{200}
toring model weights from the end of the best epoch: 76.
692 - val loss: 0.6932 - val_accuracy: 0.8346 - lr: 1.0000e-06
Epoch 81: early stopping
Test loss: 0.6837673187255859
Test accuracy: 0.8331000208854675
```

O modelo contém 3 camadas convolucionais para reconhecer padrões presentes nas imagens, e para analisar os dados espaciais. Adicionamos uma camada convolucional (layers.Conv2D) com x filtros, cada um com tamanho (janela de convolução) 3x3, utilizando a função de ativação ReLU. O padding='same' garante que a saída tenha o mesmo tamanho da entrada (uma vez que stride é 1). O kernel\_regularizer=keras.regularizers.l2(0.001) aplica a regularização L2 para evitar overfitting. A regularização L2 ajuda a reduzir a importância de variáveis correlacionadas, evitando que elas dominem o modelo e prejudiquem a generalização.

Com o objetivo de normalizar a ativação da camada anterior, acelerar o treino, e melhorar a estabilidade do modelo adiciona-mos o layer **layers.BatchNormalization**. Este aplica uma transformação que mantém a saída média próxima de 0 e o desvio padrão da saída próximo de 1.

Usamos layers.MaxPooling2D para reduzir a dimensão espacial da entrada pela metade ao utilizar uma janela

uu zaz.

Para evitar overfitting aplicamos uma camada de dropout ( layers.Dropout) com uma taxa de 0.25, esta desativa aleatoriamente 25% dos neurónios da camada durante o treino.

Este processo é repetido 3 vezes mas com um numero de filtros maior em cada layer (a dobrar), estas camadas convolucionais cada vez extraem características mais especificas. Depois de extrair as características através das camadas convolucionais, os dados são achatados (flatten) e passados para as camadas densas para classificação. Este modelo tem 2 camadas densas. Primeiro tranformamos a entrada 2D num vetor 1D usando layers.Flatten, uma vez que as camadas densas recebem um vetor de uma dimensão. Depois foi adicionada uma camada densa (totalmente conectada) com 256 neurónios e a função de ativação ReLU (layers.Dense). Esta inclui regularização L2. Normaliza-se a saída da camada densa (layers.BatchNormalization). E aplica-se dropout com uma taxa de 0.5 para evitar overfitting (layers.Dropout).

Depois na camada de saída temos uma uma camada densa ( layers.Dense) com 10 neurónios, um para cada classe, utilizando a função de ativação softmax para obter as probabilidades de classificação.

Após o modelo estar construido definimos o modelo com as entradas e saídas especificadas ( keras.Model). E compilamos o modelo (model.compile)utilizando a perda categorical\_crossentropy, o otimizador adam, e a métrica de accuracy. Usamos o categorical\_crossentropy uma vez que este é adequado para problemas multiclasse, ele mede a diferença entre a distribuição de probabilidade verdadeira das classes e a distribuição de probabilidade prevista, incentivando previsões de probabilidades que são mais próximas das distribuições reais das classes. Usamos o otimizador adam pois este proporciona uma taxa de aprendizagem adaptativa e é eficiente, funcionando bem com diferentes tipos de dados e problemas. A accuracy fornece uma métrica simples e intuitiva para avaliar o desempenho do modelo, é útil para verificar rapidamente se o modelo está a aprender corretamente. Para acabar usamos callbacks, primeiro salvamos o melhor modelo com base na métrica val\_loss (ModelCheckpoint). Usamos o EarlyStopping para parar o treino em caso que a val\_loss não melhor em 5 épocas consecutivas e restaura os melhores pesos do modelo. Durante o treino ajustamos a taxa de aprendizado (LearningRateScheduler). Esta mantém a taxa de aprendizado constante nas primeiras 10 épocas e a reduz exponencialmente depois disso.

Ao longo do processo de construção deste modelo, testámos várias camadas convolucionais com diferentes parâmetros e quantidades. Além disso, experimentámos diversas estratégias para combater o sobreajuste (overfitting). Este modelo final foi o que apresentou os melhores resultados.

Testou-se com diferentes valores de batch size e chegou-se à conclusão que não parece haver uma relação direta entre a accuracy e este valor, a nível de tempo com um batch size maior obviamente cada época demora mais tempo, mas depois vão ser precisas menos épocas para convergir. Consoante a seguinte tabela 128 para o batch size foi o que permitiu maior accuracy, mas uma vez que estou a usar o colab fica dificil fazer todos os testes que gostaria para tirar mais conclusões. Mas uma vez que por volta de uns 10 treinos a maior accuracy que tivemos foi com um batch size de 128, ficou esse. E no modeloS extra usámos o batch size de 128, uma vez que este é mais rápido e obtivemos melhores resultados.

Como se pode ver sem BatchNormalization a accuracy é bem mais baixa: Test loss: 0.75 Test accuracy: 0.80

E sem Droupout a accuracy nem chega aos 0.75 : Test loss: 1.29 Test accuracy: 0.74

Tendo o modelo final: Test loss: 0.693570613861084 Test accuracy: 0.8421000242233276

Após "finalizar" com uma boa accuracy o modelo S decidiu-se adaptar o modelo com data augmentation.

١

Batch size	Max. Test accuracy	At Epoch
32	70.41	13
64	71.79	14
128	73.02	<u>11</u>

256	71.76	13
512	71.98	15

layers.Conv2D: <a href="https://www.ibm.com/topics/convolutional-neural-networks">https://www.ibm.com/topics/convolutional-neural-networks</a> layers.BatchNormalization: <a href="https://medium.com/@ilyurek/demystifying-batch-normalization-a-practical-guide-with-python-24c58956d3e">https://medium.com/@ilyurek/demystifying-batch-normalization-a-practical-guide-with-python-24c58956d3e</a>

layers.MaxPooling2D: https://keras.io/api/layers/pooling\_layers/max\_pooling2d/

layers.Dropout:https://databasecamp.de/en/ml/dropout-layer-en

**L2 Regularization:** <a href="https://medium.com/@fernando.dijkinga/explaining-I1-and-I2-regularization-in-machine-learning-2356ee91c8e3">https://medium.com/@fernando.dijkinga/explaining-I1-and-I2-regularization-in-machine-learning-2356ee91c8e3</a>

#### **MODELO S COM DATA AUGMENTATION**

Com o objetivo de aumentar a quantidade e a diversidade dos dados de treino, o que ajuda a melhorar a generalização e a robustez do modelo. Adicionámos data augmentation.

#### In [6]:

```
from keras.callbacks import ModelCheckpoint, EarlyStopping,ReduceLROnPlateau
import keras
from keras import layers
data augmentation = keras. Sequential (
        [layers.RandomFlip("horizontal"),
        layers.RandomRotation(0.1),
        layers.RandomZoom(0.2),])
    # rotation range=20,
    # width shift range=0.1,
    # height shift range=0.1,
    # zoom range=0.2,
    # horizontal flip=True,
    # fill mode='nearest',
    # # shear range=0.2,
    # # zoom range=0.2,
    # # horizontal flip=True,
    # # fill mode='nearest',
    # # channel_shift_range=0.2,
inputs = keras.Input(shape=(IMG SIZE, IMG SIZE, 3))
x = data augmentation(inputs)
x = layers.Rescaling(1./255)(x)
x = layers.Conv2D(filters=32, kernel size=3, activation="relu", padding='same', kernel r
egularizer=keras.regularizers.12(0.001))(x)
x = layers.BatchNormalization()(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Dropout(0.25)(x)
x = layers.Conv2D(filters=64, kernel size=3, activation="relu", padding='same', kernel r
egularizer=keras.regularizers.12(0.001))(x)
x = layers.BatchNormalization()(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Dropout(0.25)(x)
x = layers.Conv2D(filters=128, kernel size=3, activation="relu", padding='same', kernel
regularizer=keras.regularizers.12(0.001))(x)
x = layers.BatchNormalization()(x)
x = layers.MaxPooling2D(pool size=2)(x)
x = layers.Dropout(0.25)(x)
x = layers.Flatten()(x)
```

```
) (x)
x = layers.BatchNormalization()(x)
x = layers.Dropout(0.5)(x)
x = layers.Dense(128, activation="relu", kernel regularizer=keras.regularizers.12(0.001)
) (x)
x = layers.BatchNormalization()(x)
x = layers.Dropout(0.5)(x)
# Output layer
outputs = layers.Dense(10, activation="softmax")(x)
model2 = keras.Model(inputs=inputs, outputs=outputs)
# compilar o modelo
model2.compile(loss='categorical crossentropy', optimizer='adam', metrics=['accuracy'])
# Callbacks
checkpoint = ModelCheckpoint(
   'models_S/S_with_DA_First.h5', monitor='val_loss', verbose=0,
   save best only=True, mode='min'
)
early stopping = EarlyStopping(
  monitor='val loss', patience=4, verbose=1, mode='min',
   restore best weights=True
learning rate = ReduceLROnPlateau(
  monitor="val loss",
  factor=0.1,
  patience=4,
  verbose=0,
  mode="min",
In [ ]:
history2 = model.fit(
  train dataset,
  epochs=200,
  batch size=128,
  validation data=validation dataset,
   callbacks=[checkpoint, early stopping, rl]
# Avaliar o modelo (com o teste)
test_loss, test_accuracy = model2.evaluate(test_dataset)
print(f'Test loss: {test loss}')
print(f'Test accuracy: {test accuracy}')
Epoch 1/200
Epoch 1: val loss improved from 1.59985 to 1.57618, saving model to best model3.h5
493 - val_loss: 1.5762 - val_accuracy: 0.6225 - lr: 0.0010
Epoch 2/200
Epoch 2: val loss improved from 1.57618 to 1.47002, saving model to best model3.h5
594 - val loss: 1.4700 - val accuracy: 0.6492 - lr: 0.0010
Epoch 3/200
Epoch 3: val loss did not improve from 1.47002
675 - val loss: 1.5922 - val accuracy: 0.5942 - lr: 0.0010
Epoch 4/200
Epoch 4: val loss improved from 1.47002 to 1.37626, saving model to best model3.h5
```

760 - val\_loss: 1.3763 - val\_accuracy: 0.6870 - lr: 0.0010

x = layers.Dense(256, activation="relu", kernel\_regularizer=keras.regularizers.12(0.001)

```
Epoch 5/200
Epoch 5: val loss did not improve from 1.37626
763 - val loss: 1.9492 - val accuracy: 0.5015 - lr: 0.0010
Epoch 6/200
Epoch 6: val loss did not improve from 1.37626
808 - val loss: 1.7475 - val accuracy: 0.5766 - lr: 0.0010
Epoch 7/200
Epoch 7: val loss did not improve from 1.37626
863 - val_loss: 1.5403 - val_accuracy: 0.6164 - lr: 0.0010
Epoch 8/200
Epoch 8: val loss did not improve from 1.37626
859 - val_loss: 1.7032 - val_accuracy: 0.5741 - lr: 0.0010
Epoch 9/200
Epoch 9: val loss did not improve from 1.37626
897 - val loss: 1.6398 - val accuracy: 0.5918 - lr: 0.0010
Epoch 10/200
Epoch 10: val loss did not improve from 1.37626
903 - val loss: 1.3978 - val accuracy: 0.6754 - lr: 0.0010
Epoch 11/\overline{200}
Epoch 11: val loss did not improve from 1.37626
948 - val loss: 1.5941 - val_accuracy: 0.5975 - lr: 9.0484e-04
Epoch 12/200
Epoch 12: val loss improved from 1.37626 to 1.27970, saving model to best model3.h5
099 - val loss: 1.2797 - val accuracy: 0.6996 - lr: 8.1873e-04
Epoch 13/200
Epoch 13: val loss did not improve from 1.27970
180 - val loss: 1.3611 - val accuracy: 0.6656 - lr: 7.4082e-04
Epoch 14/200
Epoch 14: val loss did not improve from 1.27970
261 - val loss: 1.3628 - val accuracy: 0.6625 - lr: 6.7032e-04
Epoch 15/200
Epoch 15: val loss improved from 1.27970 to 1.20225, saving model to best model3.h5
352 - val_loss: 1.2022 - val_accuracy: 0.7139 - lr: 6.0653e-04
Epoch 16/\overline{2}00
Epoch 16: val loss did not improve from 1.20225
380 - val loss: 1.2951 - val_accuracy: 0.6806 - lr: 5.4881e-04
Epoch 17/200
Epoch 17: val loss did not improve from 1.20225
428 - val_loss: 1.4012 - val_accuracy: 0.6443 - lr: 4.9659e-04
Epoch 18/200
Epoch 18: val loss improved from 1.20225 to 1.05067, saving model to best model3.h5
482 - val_loss: 1.0507 - val_accuracy: 0.7489 - lr: 4.4933e-04
Epoch 19/200
```

```
Epoch 19: val_loss did not improve from 1.05067
546 - val loss: 1.0600 - val accuracy: 0.7383 - lr: 4.0657e-04
Epoch 20/200
Epoch 20: val loss did not improve from 1.05067
647 - val loss: 1.0654 - val accuracy: 0.7355 - lr: 3.6788e-04
Epoch 21/200
Epoch 21: val loss did not improve from 1.05067
640 - val loss: 1.0940 - val accuracy: 0.7242 - 1r: 3.3287e-04
Epoch 22/\overline{2}00
Epoch 22: val loss improved from 1.05067 to 0.99854, saving model to best model3.h5
674 - val_loss: 0.9985 - val_accuracy: 0.7503 - lr: 3.0119e-04
Epoch 23/200
Epoch 23: val loss did not improve from 0.99854
741 - val_loss: 1.0481 - val_accuracy: 0.7249 - lr: 2.7253e-04
Epoch 24/200
Epoch 24: val loss improved from 0.99854 to 0.96532, saving model to best model3.h5
801 - val loss: 0.9653 - val accuracy: 0.7549 - lr: 2.4660e-04
Epoch 25/200
Epoch 25: val loss did not improve from 0.96532
842 - val loss: 0.9741 - val_accuracy: 0.7479 - lr: 2.2313e-04
Epoch 26/200
Epoch 26: val loss did not improve from 0.96532
912 - val_loss: 0.9684 - val_accuracy: 0.7436 - lr: 2.0190e-04
Epoch 27/200
Epoch 27: val loss improved from 0.96532 to 0.90483, saving model to best model3.h5
939 - val loss: 0.9048 - val accuracy: 0.7680 - lr: 1.8268e-04
Epoch 28/200
Epoch 28: val loss did not improve from 0.90483
944 - val loss: 0.9417 - val accuracy: 0.7496 - lr: 1.6530e-04
Epoch 29/\overline{200}
Epoch 29: val loss improved from 0.90483 to 0.86827, saving model to best model3.h5
948 - val loss: 0.8683 - val_accuracy: 0.7761 - lr: 1.4957e-04
Epoch 30/200
Epoch 30: val loss improved from 0.86827 to 0.84073, saving model to best model3.h5
020 - val loss: 0.8407 - val accuracy: 0.7792 - lr: 1.3534e-04
Epoch 31/200
Epoch 31: val loss improved from 0.84073 to 0.83603, saving model to best model3.h5
041 - val loss: 0.8360 - val accuracy: 0.7800 - lr: 1.2246e-04
Epoch 32/200
Epoch 32: val loss did not improve from 0.83603
070 - val loss: 0.8801 - val accuracy: 0.7643 - lr: 1.1080e-04
Epoch 33/\overline{200}
Epoch 33: val loss improved from 0.83603 to 0.82786, saving model to best model3.h5
```

```
064 - val_loss: 0.8279 - val_accuracy: 0.7802 - lr: 1.0026e-04
Epoch 34/200
Epoch 34: val loss did not improve from 0.82786
126 - val loss: 0.8291 - val accuracy: 0.7777 - 1r: 9.0718e-05
Epoch 35/200
Epoch 35: val loss improved from 0.82786 to 0.79306, saving model to best model3.h5
135 - val loss: 0.7931 - val accuracy: 0.7882 - lr: 8.2085e-05
Epoch 36/200
Epoch 36: val loss did not improve from 0.79306
148 - val loss: 0.8269 - val accuracy: 0.7743 - 1r: 7.4274e-05
Epoch 37/200
Epoch 37: val loss did not improve from 0.79306
163 - val loss: 0.8361 - val accuracy: 0.7749 - lr: 6.7206e-05
Epoch 38/200
Epoch 38: val loss did not improve from 0.79306
196 - val loss: 0.8652 - val accuracy: 0.7615 - lr: 6.0810e-05
Epoch 39/200
Epoch 39: val loss improved from 0.79306 to 0.79157, saving model to best model3.h5
192 - val loss: 0.7916 - val accuracy: 0.7858 - lr: 5.5023e-05
Epoch 40/\overline{200}
Epoch 40: val loss improved from 0.79157 to 0.75789, saving model to best model3.h5
241 - val_loss: 0.7579 - val_accuracy: 0.7979 - lr: 4.9787e-05
Epoch 41/200
Epoch 41: val_loss did not improve from 0.75789
208 - val loss: 0.7605 - val accuracy: 0.7964 - 1r: 4.5049e-05
Epoch 42/200
Epoch 42: val loss did not improve from 0.75789
214 - val loss: 0.7787 - val accuracy: 0.7873 - 1r: 4.0762e-05
Epoch 43/\overline{200}
Epoch 43: val loss improved from 0.75789 to 0.73982, saving model to best model3.h5
259 - val loss: 0.7398 - val accuracy: 0.8026 - lr: 3.6883e-05
Epoch 44/\overline{200}
Epoch 44: val loss did not improve from 0.73982
257 - val loss: 0.7530 - val accuracy: 0.7943 - 1r: 3.3373e-05
Epoch 45/200
Epoch 45: val loss did not improve from 0.73982
268 - val loss: 0.7564 - val accuracy: 0.7937 - 1r: 3.0197e-05
Epoch 46/200
Epoch 46: val loss did not improve from 0.73982
278 - val loss: 0.7872 - val accuracy: 0.7838 - 1r: 2.7324e-05
Epoch 47/\overline{2}00
Epoch 47: val loss did not improve from 0.73982
287 - val loss: 0.7637 - val_accuracy: 0.7906 - 1r: 2.4724e-05
Epoch 48/200
```

```
Epoch 48: val_loss did not improve from 0.73982
301 - val loss: 0.7448 - val accuracy: 0.7959 - 1r: 2.2371e-05
Epoch 49/200
Epoch 49: val loss did not improve from 0.73982
300 - val loss: 0.7599 - val accuracy: 0.7903 - 1r: 2.0242e-05
Epoch 50/200
Epoch 50: val loss did not improve from 0.73982
323 - val loss: 0.7488 - val accuracy: 0.7942 - lr: 1.8316e-05
Epoch 51/200
Epoch 51: val_loss did not improve from 0.73982
350 - val loss: 0.7478 - val accuracy: 0.7938 - lr: 1.6573e-05
Epoch 52/200
Epoch 52: val loss did not improve from 0.73982
311 - val loss: 0.7556 - val accuracy: 0.7919 - lr: 1.4996e-05
Epoch 53/200
347/1250 [======>.....] - ETA: 21s - loss: 0.9255 - accuracy: 0.7356
```

Começa-mos com estas transformações, mas chegamos à conclusão que era demasiada agressiva uma vez que piorou em muito a precisão do modelo... Algo que não estava à espera.

data\_augmentation = Sequential([ layers.RandomFlip("horizontal\_and\_vertical"), layers.RandomRotation(0.2), layers.RandomZoom(0.3), layers.RandomTranslation(0.1, 0.1), layers.RandomContrast(0.2), layers.RandomBrightness(0.2), ])

```
outras: dataAug = ImageDataGenerator( rotation_range=40, width_shift_range=0.2, height_shift_range=0.2, shear_range=0.2, zoom_range=0.2, horizontal_flip=True, fill_mode='nearest', brightness_range=[0.8, 1.2], channel_shift_range=0.2, )
```

Então decidimos diminuir a intensidade das alterações.

data\_augmentation = keras.Sequential([layers.RandomFlip("horizontal"), layers.RandomRotation(0.1), layers.RandomZoom(0.2),])

Test loss: 0.8087025117874146 Test accuracy: 0.7913000273704529

### ANALISE DE RESULTADOS sobre S sem data augmentation

```
In [2]:
```

```
from keras.models import load_model
model = load_model('/content/best_modelS_WITHOUT_64.h5')
```

```
In [10]:
```

```
import pandas as pd
import numpy as np
# usar para instalar...: pip install scikit-learn
```

```
from sklearn import metrics
from sklearn.model selection import train test split
import tensorflow as tf
from keras.models import Sequential
from keras.layers import Dense
from sklearn.preprocessing import LabelEncoder
# to install IPython, use: pip install ipython
from IPython.display import display
from sklearn.metrics import precision score
from sklearn.metrics import f1 score
from sklearn.metrics import recall score
from sklearn.metrics import accuracy score
import matplotlib.pyplot as plt
from sklearn.metrics import confusion matrix, classification report
import matplotlib.pyplot as plt
import seaborn as sns
```

Para avaliar o desempenho do modelo usamos a matriz de confusão, esta mostra o número de verdadeiros positivos, falsos positivos, verdadeiros negativos e falsos negativos para cada classe. E também apresentamos os valores para a accuracy, esta indica o desempenho geral do modelo que consiste na proporção de previsões corretas em relação ao total de previsões feitas. Dentre todas as classificações, quantas o modelo classificou corretamente. A precisão mede a exatidão das previsões positivas do modelo. A proporção de verdadeiros positivos (TP) em relação ao total de previsões positivas (TP + FP). Recall/Revocação/Sensibilidade: A proporção de verdadeiros positivos em relação ao total de exemplos reais positivos (TP + FN). Mede a capacidade do modelo de encontrar todos os exemplos positivos. E o F1-Scor é a média harmônica entre precisão e recall. É uma métrica balanceada que considera tanto falsos positivos quanto falsos negativos.

```
In [11]:
```

```
import numpy as np
import matplotlib.pyplot as plt
import seaborn as sns
from sklearn.metrics import confusion matrix, classification report
# Definir nomes das classes
class names = {
   0: "Airplane",
   1: "Automobile",
   2: "Bird",
   3: "Cat",
   4: "Deer",
   5: "Dog",
   6: "Frog"
   7: "Horse",
   8: "Ship",
   9: "Truck"
# Prever para todo o conjunto de teste
y pred = []
y true = []
for x, y in test dataset:
   predictions = model.predict(x)
   y pred.extend(np.argmax(predictions, axis=1))
   y true.extend(np.argmax(y, axis=1))
y_pred = np.array(y_pred)
y true = np.array(y true)
# Matriz de confusão
conf matrix = confusion matrix(y true, y pred)
```

```
# Plotar a matriz de confusão
plt.figure(figsize=(10, 8))
sns.heatmap(conf matrix, annot=True, fmt='d', cmap='Blues',
       xticklabels=class names.values(), yticklabels=class names.values())
plt.xlabel('Predicted')
plt.ylabel('True')
plt.title('Confusion Matrix')
plt.show()
# Relatório de classificação
class report = classification report(y true, y pred, target names=class names.values())
print("Classification Report:\n", class report)
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1/1	[======]	-	0s	53ms/step
1/1	[======]	-	0s	29ms/step
1/1	[======]	-	0s	39ms/step
1/1	[======]	-	0s	45ms/step
1/1	[======]	-	0s	33ms/step
1/1	[======]	-	0s	30ms/step
1/1	[======]	-	0s	34ms/step
1/1	[======]	-	0s	45ms/step
1/1	[======]	-	0s	44ms/step
1/1	[======]	-	0s	59ms/step
1/1	[======]	-	0s	40ms/step
1/1	[======]	-	0s	40ms/step
1/1	[======]	-	0s	33ms/step
1/1	[======]	-	0s	42ms/step
1/1	[======]	-	0s	232ms/step

# **Confusion Matrix**

- 800

- 600

- 400

- 200

	Airplane -	838	10	25	12	22	3	12	6	50	22
А	utomobile -	6	910	4	3	1	2	6	0	22	46
	Bird -	39	1	719	38	80	43	56	14	8	2
	Cat -	9	2	49	650	52	139	65	14	10	10
υ	Deer -	3	2	32	27	864	15	29	22	5	1
True	Dog -	7	1	31	121	46	756	15	19	1	3
	Frog -	1	1	31	24	17	7	910	4	4	1
	Horse -	6	1	21	26	41	34	4	859	2	6
	Ship -	23	8	3	4	5	1	5	4	938	9

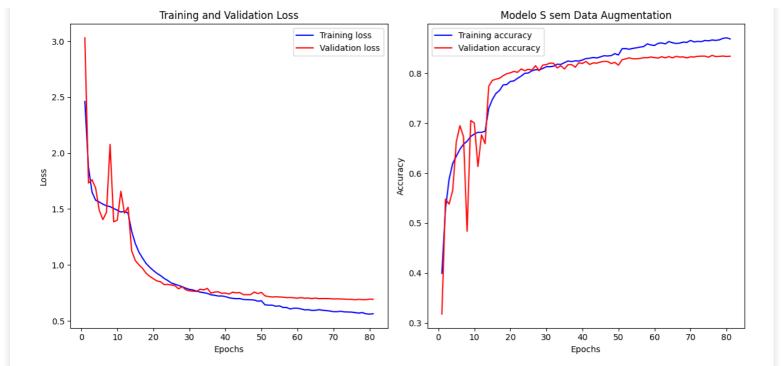


Classification	Report:			
	precision	recall	f1-score	support
2.1	0.00	0 0 1	0.06	1000
Airplane	0.88	0.84	0.86	1000
Automobile	0.92	0.91	0.92	1000
Bird	0.78	0.72	0.75	1000
Cat	0.72	0.65	0.68	1000
Deer	0.76	0.86	0.81	1000
Dog	0.75	0.76	0.76	1000
Frog	0.82	0.91	0.86	1000
Horse	0.90	0.86	0.88	1000
Ship	0.89	0.94	0.91	1000
Truck	0.90	0.89	0.89	1000
accuracy			0.83	10000
macro avg	0.83	0.83	0.83	10000
weighted avg	0.83	0.83	0.83	10000

Agora com o objetivo de mobnitorizar o processo de treino e verificar se o modelo está a aprender corretamente ao longo do tempo. Usamos as curvas de perda de treino (loss) e de validação (val\_loss) ao longo das épocas. E a curva de accuracy de treino (acc) e de validação (val\_acc) ao longo das épocas. Estas permitem por exemplo ao comparar as curvas de treino e validação, é possível identificar problemas de overfitting (onde a perda de validação aumenta enquanto a perda de treino diminui) ou underfitting (onde ambas as perdas são altas). Com base nas curvas, ajustes podem ser feitos aos hiperparâmetros do modelo, como a taxa de aprendizagem, o número de épocas, e outros.

```
In [12]:
```

```
def graph(history, title):
    acc = history.history['accuracy']
    val acc = history.history['val accuracy']
    loss = history.history['loss']
    val_loss = history.history['val loss']
    epochs = range(1, len(acc) + 1)
    plt.figure(figsize=(12, 6))
    plt.subplot(1, 2, 1)
    plt.plot(epochs, loss, 'b', label='Training loss')
plt.plot(epochs, val_loss, 'r', label='Validation loss')
    plt.title('Training and Validation Loss')
    plt.xlabel('Epochs')
    plt.ylabel('Loss')
    plt.legend()
    plt.subplot(1, 2, 2)
    plt.plot(epochs, acc, 'b', label='Training accuracy')
    plt.plot(epochs, val_acc, 'r', label='Validation accuracy')
    plt.title(title)
    plt.xlabel('Epochs')
    plt.ylabel('Accuracy')
    plt.legend()
    plt.tight layout()
    plt.show()
graph(history, "Modelo S sem Data Augmentation")
```



Para visualizar exemplos de imagens do conjunto de dados, juntamente com as previsões feitas pelo modelo. Com o objetivo de permitir uma análise visual rápida e intuitiva do desempenho do modelo.

```
In [13]:
```

```
import matplotlib.pyplot as plt
import numpy as np
# Assuming you have already trained your model and obtained predictions and true labels
# Example lists for demonstration
# Extract images and labels from test dataset
test images = []
test labels = []
for images, labels in test dataset:
    test images.append(images.numpy()) # Assuming you convert images to numpy arrays
    test labels.append(labels.numpy())
test_images = np.concatenate(test_images)
test_labels = np.concatenate(test_labels)
# Normalize the images to [0, 1]
test images = test images.astype(np.float32) / 255.0
# Display images with predictions and true labels
plt.figure(figsize=(12, 12))
for i in range (25):
   plt.subplot(5, 5, i + 1)
   plt.xticks([])
   plt.yticks([])
    plt.grid(False)
    plt.imshow(test_images[i], cmap=plt.cm.binary) # Display the ith image
    predicted_label = class_names[y_pred[i]]
    true_label = class_names[y_true[i]]
    if predicted_label == true_label:
        color = 'green'
    else:
        color = 'red'
    plt.xlabel(f'Pred: {predicted label} \n True: {true label}', color=color)
plt.show()
```

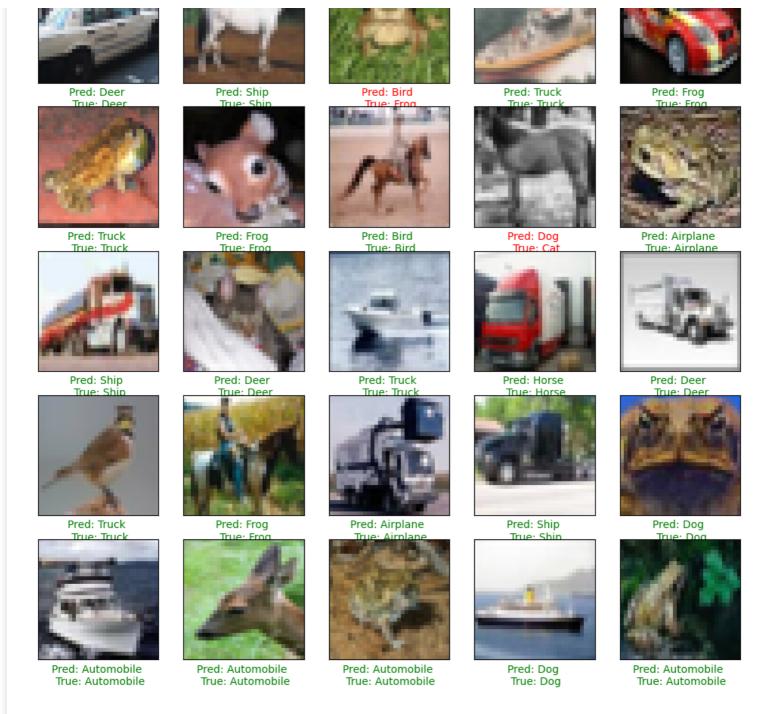












Com o objetivo de entender como as camadas convolucionais e de pooling do modelo de CNN processam e extraem as características das imagens de entrada ao longo da rede neural usámos a visualização de feature maps. É útil para " o modelo, verificar se as características esperadas estão a ser aprendidas e entender como as informações são transformadas e representadas nas diferentes camadas da rede.

#### In [16]:

```
import matplotlib.pyplot as plt
from keras.models import Model
from tensorflow.keras.utils import load_img, img_to_array
import numpy as np
import random

# Assuming you have defined your test_dataset and model somewhere

# Get the first image from test_dataset
first_batch = next(iter(test_dataset)) # Get the first batch from the dataset
first_image = first_batch[0][0] # Extract the first image from the batch

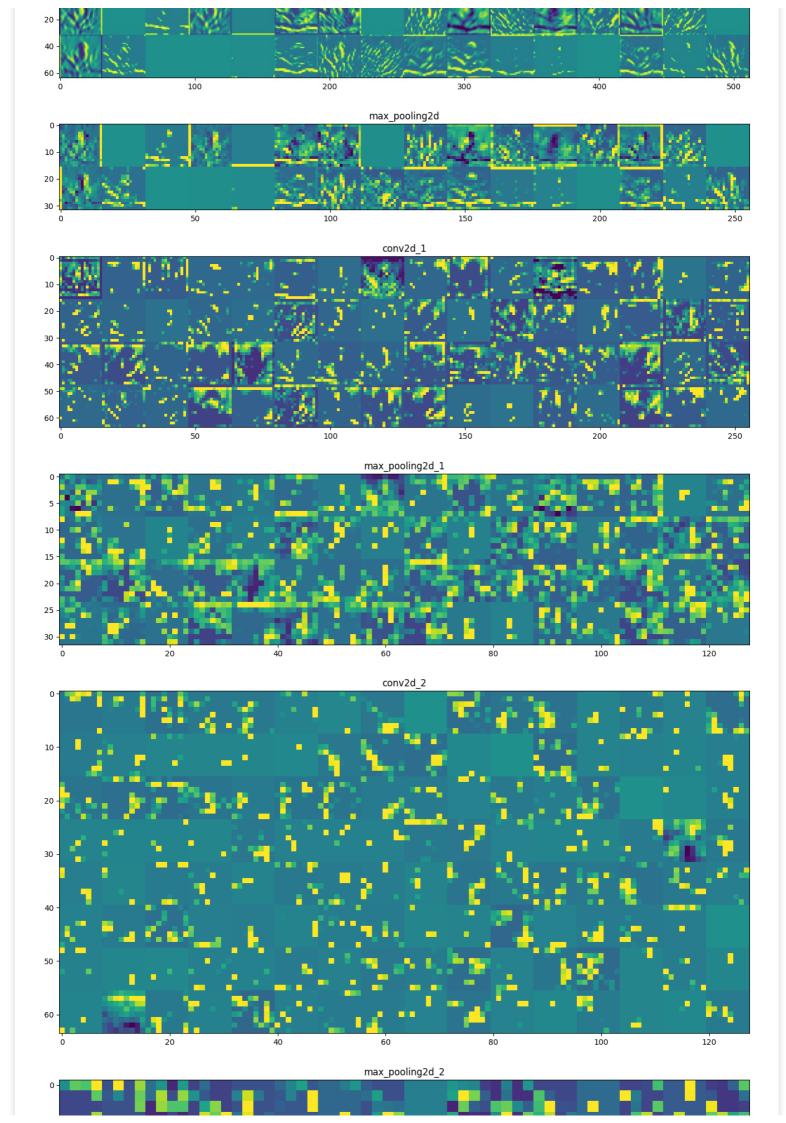
# Display the original image
plt.imshow(first_image.numpy().astype("uint8"))
plt.title('Original Image')
plt.axis('off')
plt.show()
```

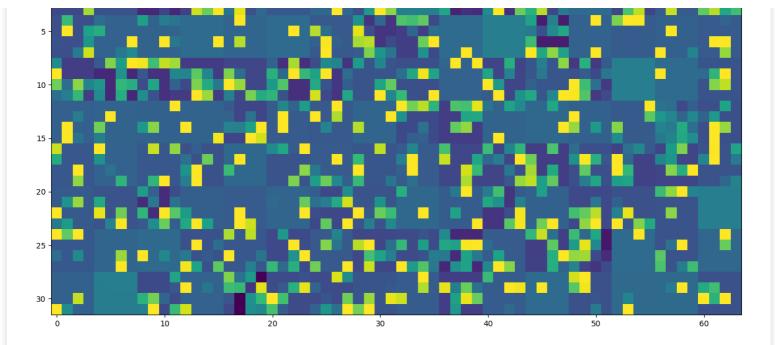
```
# Preprocess the image for visualization
img = first image.numpy()
img = np.expand dims(img, axis=0) # Now img has shape (1, 32, 32, 3)
def visualize filters(model, img):
    layer_outputs = [layer.output for layer in model.layers if 'conv' in layer.name or '
pool' in layer.name]
   activation model = Model(inputs=model.input, outputs=layer outputs)
   activations = activation model.predict(img)
    layer names = [layer.name for layer in model.layers if 'conv' in layer.name or 'pool
' in layer.name]
    for layer name, layer activation in zip(layer names, activations):
        n features = layer activation.shape[-1]
       size = layer activation.shape[1]
       n_cols = n_features // 16 # Number of columns in the grid
       display grid = np.zeros((size * n cols, size * 16))
       for col in range(n cols):
            for row in range(16):
                channel image = layer activation[0, :, :, col * 16 + row]
                channel image -= channel image.mean()
                channel image /= (channel image.std() + 1e-5)
                channel image *= 64
                channel image += 128
                channel image = np.clip(channel image, 0, 255).astype('uint8')
                display grid[col * size : (col + 1) * size, row * size : (row + 1) * siz
e] = channel image
       scale = 1. / size
       plt.figure(figsize=(scale * display grid.shape[1], scale * display grid.shape[0]
) )
       plt.title(layer name)
       plt.grid(False)
       plt.imshow(display_grid, aspect='auto', cmap='viridis')
# Visualize filters for the model and the first image
visualize filters (model, img)
```

## Original Image



1/1 [======] - 0s 195ms/step





Para complementar usamos heat maps (mapas de calor) para visualizar as regiões de uma imagem que são mais importantes para a decisão de classificação feita pelo modelo. Este mapa mostra visualmente onde o modelo está a "focar" mais para fazer uma decisão sobre a classe da imagem. Isto é útil para interpretar e entender quais características da imagem que estão a ser consideradas mais relevantes pelo modelo durante o processo de classificação.

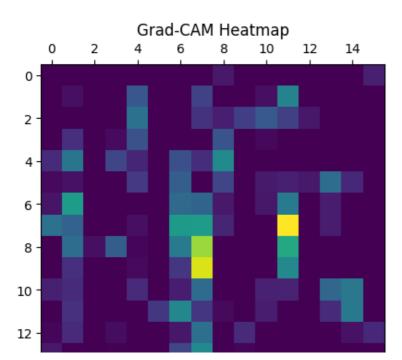
#### In [21]:

```
import tensorflow as tf
import numpy as np
import matplotlib.pyplot as plt
import random
import cv2
# Assuming test dataset and model are already defined
random index = random.randint(0, 500)
first batch = next(iter(test dataset)) # Get the first batch from the dataset
img = first batch[0][0] # Extract the first image from the batch
img array = img.numpy()
img_array = np.expand_dims(img_array, axis=0) # Now img_array has shape (1, 32, 32, 3)
plt.imshow(img_array[0].astype("uint8")) # Display the original image
plt.title('Original Image')
plt.axis('off')
plt.show()
def make gradcam heatmap(img array, model, last conv layer name, pred index=None):
    grad model = tf.keras.models.Model(
        [model.inputs], [model.get layer(last conv layer name).output, model.output]
    with tf.GradientTape() as tape:
       last conv layer output, preds = grad model(img array)
        if pred index is None:
            pred index = tf.argmax(preds[0])
        class channel = preds[:, pred index]
    grads = tape.gradient(class_channel, last_conv_layer_output)
    pooled_grads = tf.reduce_mean(grads, axis=(0, 1, 2))
    last_conv_layer_output = last_conv_layer_output[0]
    heatmap = last_conv_layer_output @ pooled_grads[..., tf.newaxis]
    heatmap = tf.squeeze(heatmap)
    heatmap = tf.maximum(heatmap, 0) / tf.math.reduce max(heatmap)
    return heatmap.numpy()
```

```
last_conv_layer_name = 'conv2d_1' # Replace with your actual last conv layer name
heatmap = make gradcam heatmap(img array, model, last conv layer name)
plt.matshow(heatmap)
plt.title('Grad-CAM Heatmap')
plt.show()
def superimpose heatmap(img, heatmap, alpha=0.4):
    heatmap = cv2.resize(heatmap, (img.shape[1], img.shape[0]))
    heatmap = np.uint8(255 * heatmap)
   heatmap = cv2.applyColorMap(heatmap, cv2.COLORMAP JET)
   superimposed_img = heatmap * alpha + img
   return np.uint8(superimposed img)
# Convert img array to (32, 32, 3) for superimpose heatmap function
img for superimpose = img array[0].astype("uint8")
superimposed img = superimpose heatmap(img for superimpose, heatmap)
plt.imshow(superimposed img)
plt.title('Image with Grad-CAM Heatmap')
plt.axis('off')
plt.show()
```

# Original Image





# Image with Grad-CAM Heatmap



O Feature Space ajuda a verificar como as características são distribuídas no espaço, ao revelar padrões ou agrupamentos que podem indicar a capacidade do modelo de discriminar entre as diferentes classes. Ao comparar os gráficos entre as camadas, podemos ver como estas (por exemplo, camadas convolucionais, em comparação com as camadas densas) aprendem e representam as características das imagens.

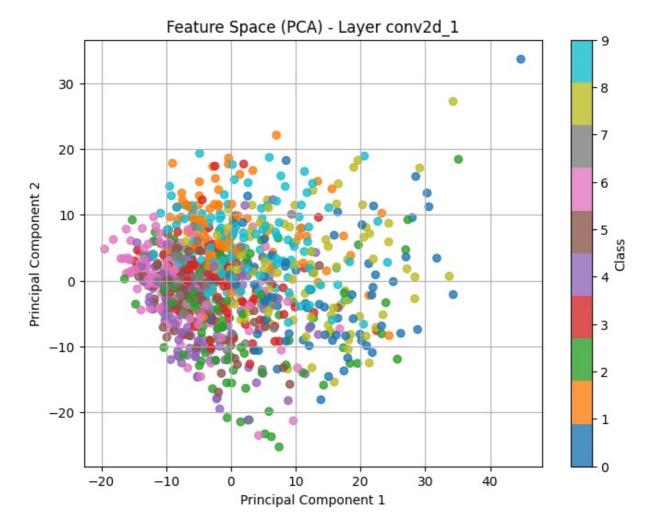
## In [19]:

```
# Function to extract images and labels from a tf.data.Dataset
from sklearn.decomposition import PCA
def get images and labels(dataset, num samples):
   dataset = dataset.unbatch().take(num samples)
   images = []
   labels = []
    for img, label in dataset:
       images.append(img.numpy())
        labels.append(label.numpy())
    return np.array(images), np.array(labels)
# Extract images and labels from the test dataset
x test, y test = get images and labels(test dataset, num samples=1000)
# Visualization function
def visualize feature space(layer name, x data, y data):
    feature extractor = tf.keras.models.Model(inputs=model.input, outputs=model.get laye
r(layer name).output)
    num samples = len(x_data)
    sample_indices = np.random.choice(len(x_data), num samples, replace=False)
    sample images = x data[sample indices]
    features = feature extractor.predict(sample images)
    pca = PCA(n components=2)
    features reduced = pca.fit transform(features.reshape(num samples, -1))
    plt.figure(figsize=(8, 6))
    plt.scatter(features_reduced[:, 0], features_reduced[:, 1], c=np.argmax(y_data[sampl
e indices], axis=1), cmap='tab10', marker='o', alpha=0.8)
```

```
plt.colorbar(label='Class')
  plt.title(f'Feature Space (PCA) - Layer {layer_name}')
  plt.xlabel('Principal Component 1')
  plt.ylabel('Principal Component 2')
  plt.grid(True)
  plt.show()

# Assuming you have x_test and y_test as your test dataset
layer_name = 'conv2d_1'
  visualize_feature_space(layer_name, x_test, y_test)
```

32/32 [=======] - Os 4ms/step



### Para mostrar a arquitetura do modelo

# In [17]:

```
model.summary()
```

Model: "model"

Layer (type)	Output Shape	Param #
input_1 (InputLayer)	[(None, 32, 32, 3)]	0
rescaling (Rescaling)	(None, 32, 32, 3)	0
conv2d (Conv2D)	(None, 32, 32, 32)	896
<pre>batch_normalization (BatchN ormalization)</pre>	(None, 32, 32, 32)	128
<pre>max_pooling2d (MaxPooling2D )</pre>	(None, 16, 16, 32)	0
dropout (Dropout)	(None, 16, 16, 32)	0
conv2d_1 (Conv2D)	(None, 16, 16, 64)	18496

<pre>batch_normalization_1 (Batc hNormalization)</pre>	(None, 16, 16, 64)	256
<pre>max_pooling2d_1 (MaxPooling 2D)</pre>	(None, 8, 8, 64)	0
dropout_1 (Dropout)	(None, 8, 8, 64)	0
conv2d_2 (Conv2D)	(None, 8, 8, 128)	73856
<pre>batch_normalization_2 (Batc hNormalization)</pre>	(None, 8, 8, 128)	512
<pre>max_pooling2d_2 (MaxPooling 2D)</pre>	(None, 4, 4, 128)	0
dropout_2 (Dropout)	(None, 4, 4, 128)	0
flatten (Flatten)	(None, 2048)	0
dense (Dense)	(None, 256)	524544
<pre>batch_normalization_3 (Batc hNormalization)</pre>	(None, 256)	1024
dropout_3 (Dropout)	(None, 256)	0
dense_1 (Dense)	(None, 128)	32896
<pre>batch_normalization_4 (Batc hNormalization)</pre>	(None, 128)	512
dropout_4 (Dropout)	(None, 128)	0
dense_2 (Dense)	(None, 10)	1290

-----

Total params: 654,410
Trainable params: 653,194
Non-trainable params: 1,216