

Inna Williams

#####

Check writtern homework

Section 10.1

1

a)

```
> with(DiscreteTransforms) : with(LinearAlgebra) : with(plots) :
```

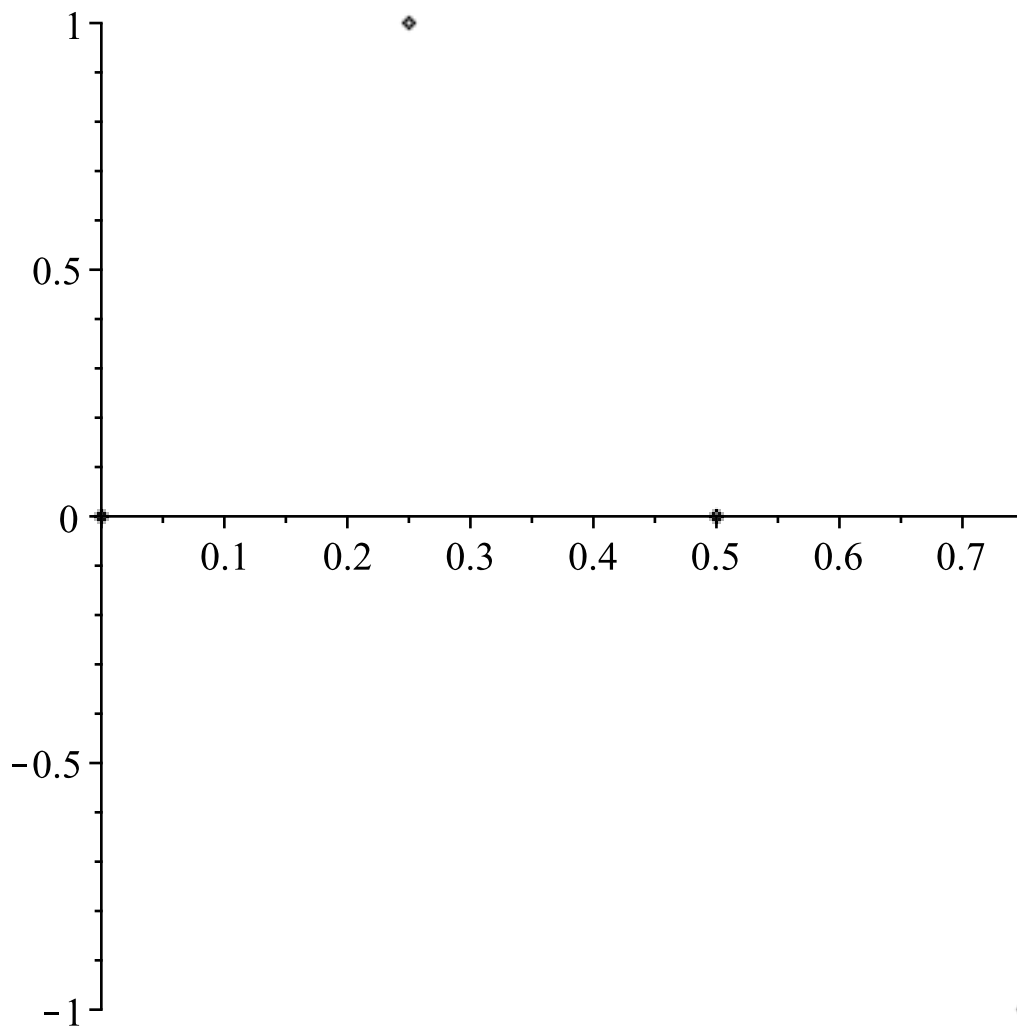
```
> V := Vector(4, [0, 1, 0, -1])
```

$$V := \begin{bmatrix} 0 \\ 1 \\ 0 \\ -1 \end{bmatrix}$$

(1)

```
> rule := i -> (i - 1) / 4 : T := Vector(4, rule) :
```

```
> dataplot1 := pointplot(T, V) : display(dataplot1)
```



```
> Z := FourierTransform(V)
```

$$Z := \begin{bmatrix} 0.1 \\ -1 \\ 0.1 \\ 1 \end{bmatrix}$$

(2)

```
*****
```

The answer is the same as in written homework

```
*****
```

3

b

```
*****
```

```
> V := Vector(4, [1, 1, -1, 1])
```

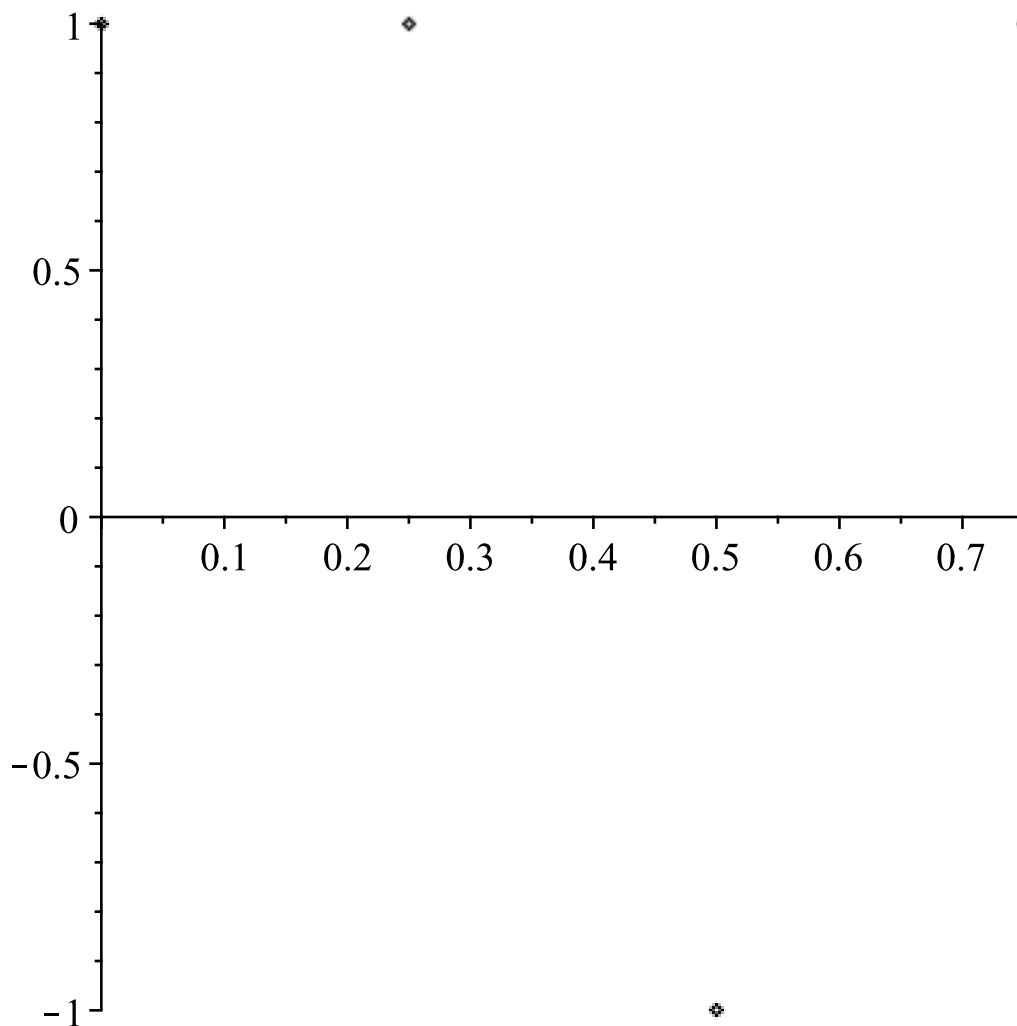
(3)

$$V := \begin{bmatrix} 1 \\ 1 \\ -1 \\ 1 \end{bmatrix}$$

(3)

```
> rule := i -> (i - 1) / 4 : T := Vector(4, rule) :
```

```
> dataplot1 := pointplot(T, V) : display(dataplot1)
```



```
> Z := InverseFourierTransform(V)
```

$$Z := \begin{bmatrix} 1. + 0. I \\ 1. + 0. I \\ -1. + 0. I \\ 1. + 0. I \end{bmatrix}$$

(4)

The answer is the same as in written homework

Section 10.2

Computer Problems

1

b

Find the order 8 trigonometric interpolating function $P_8(t)$ for the following data:

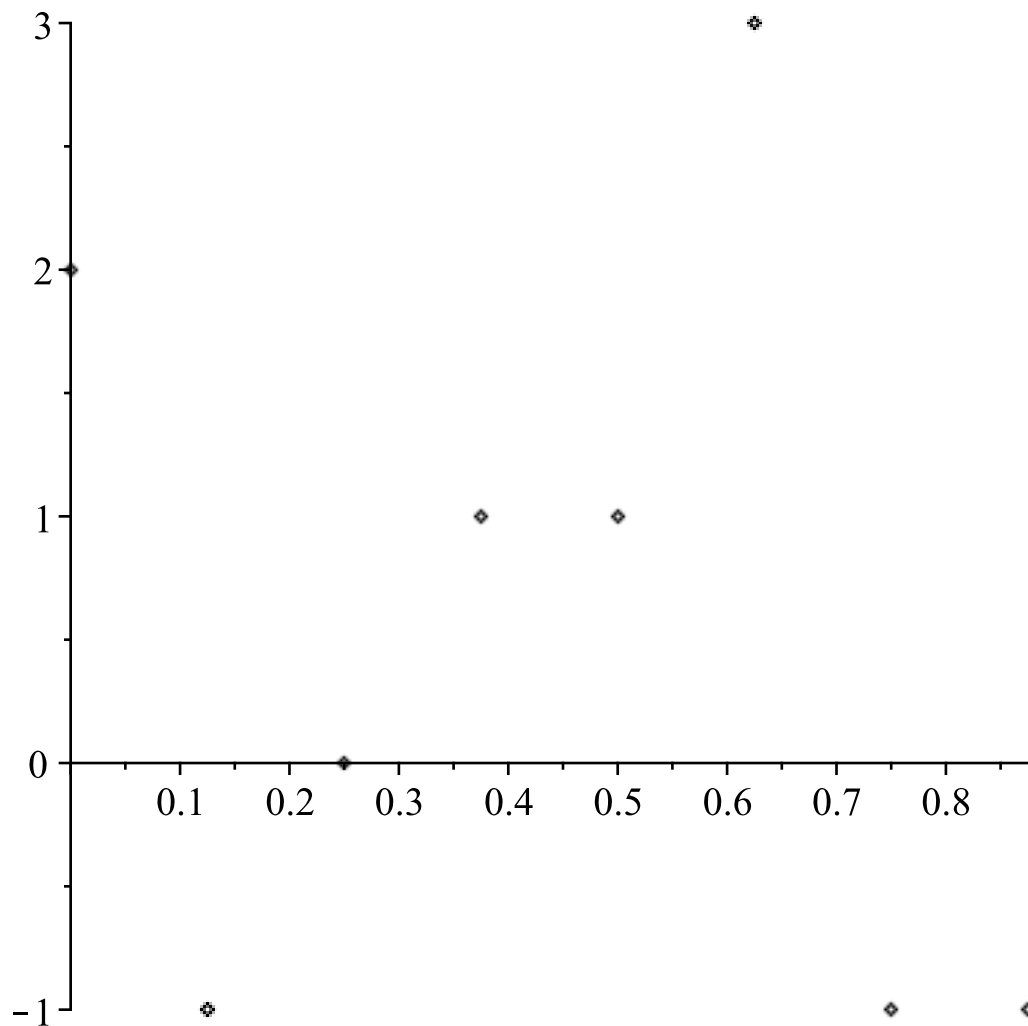
> $V := \text{Vector}(8, [2, -1, 0, 1, 1, 3, -1, -1])$

$$V := \begin{bmatrix} 2 \\ -1 \\ 0 \\ 1 \\ 1 \\ 3 \\ -1 \\ -1 \end{bmatrix}$$

(5)

> $rule := i \rightarrow \frac{(i-1)}{8} : T := \text{Vector}(8, rule) :$

> $dataplot1 := \text{pointplot}(T, V) : \text{display}(dataplot1)$



```
> Z := FourierTransform(V)
```

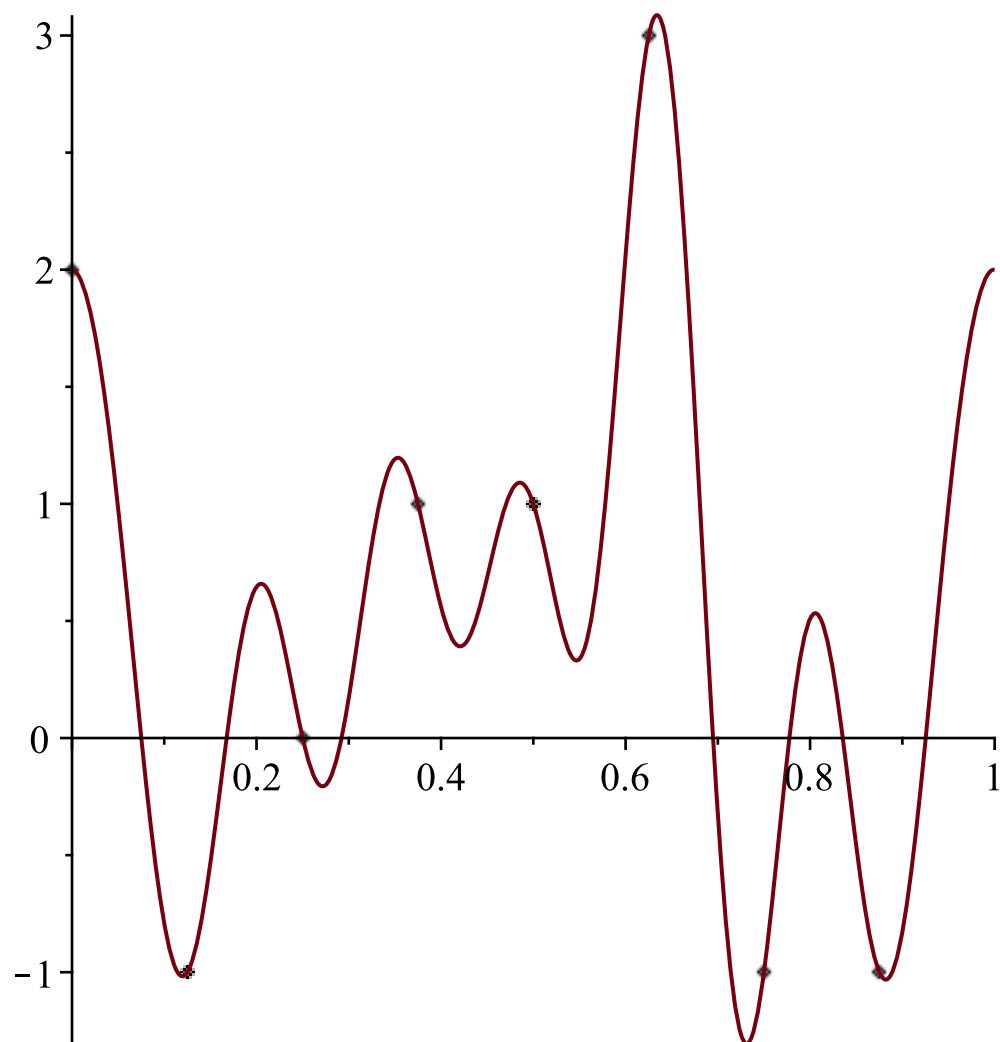
$$Z := \begin{bmatrix} 1.41421356237310 + 0. I \\ -1.14644660940673 + 0.146446609406726 I \\ 1.41421356237310 - 0.707106781186548 I \\ 1.85355339059327 + 0.853553390593274 I \\ 0. I \\ 1.85355339059327 - 0.853553390593274 I \\ 1.41421356237310 + 0.707106781186548 I \\ -1.14644660940673 - 0.146446609406726 I \end{bmatrix}$$

(6)

```
> P := t → evalf( ( 1 / sqrt(8) · add( Re( Z[ k ] ) · cos( 2 · ( k - 1 ) · π · t ) - Im( Z[ k ] ) · sin( 2 · ( k - 1 ) · π · t ) , k = 1 .. 8 ) ) :
```

```
>
```

```
> plot1 := plot(P, 0..1) : display(dataplot1, plot1)
```



```
>
```

```
> a := Re(Z); b := Im(Z)
```

$a :=$

1.41421356237310
-1.14644660940673
1.41421356237310
1.85355339059327
0.
1.85355339059327
1.41421356237310
-1.14644660940673

$$b := \begin{bmatrix} 0. \\ 0.146446609406726 \\ -0.707106781186548 \\ 0.853553390593274 \\ 0. \\ -0.853553390593274 \\ 0.707106781186548 \\ -0.146446609406726 \end{bmatrix} \quad (7)$$

$$\begin{aligned} & \text{> } c := 0; d := 1; n := 8; \quad a[1] := \text{evalf}\left(\frac{a[1]}{n^{\frac{1}{2}}}\right) : a[2..8] := \text{evalf}\left(\frac{2}{n^{\frac{1}{2}}} \cdot a[2..8]\right) : b[1] := \\ & \text{evalf}\left(\frac{b[1]}{n^{\frac{1}{2}}}\right) : b[2..8] := \text{evalf}\left(\frac{2}{n^{\frac{1}{2}}} \cdot b[2..8]\right) : a; b; \\ & \quad c := 0 \\ & \quad d := 1 \\ & \quad n := 8 \end{aligned}$$

$$\begin{bmatrix} 0.500000000044868 \\ -0.810660171852566 \\ 1.00000000008974 \\ 1.31066017189743 \\ 0. \\ 1.31066017189743 \\ 1.00000000008974 \\ -0.810660171852566 \end{bmatrix}$$

$$\begin{bmatrix} 0. \\ 0.103553390602566 \\ -0.500000000044868 \\ 0.603553390647434 \\ 0. \\ -0.603553390647434 \\ 0.500000000044868 \\ -0.103553390602566 \end{bmatrix} \quad (8)$$

$$\begin{aligned} & \text{> } P := (k) \rightarrow a[k] \cdot \cos(2 \cdot \pi \cdot (k-1) \cdot t) - b[k] \cdot \sin(2 \cdot \pi \cdot (k-1) \cdot t) \\ & \quad P := k \mapsto a_k \cos(2 \pi (k-1) t) - b_k \sin(2 \pi (k-1) t) \end{aligned} \quad (9)$$

$$\text{> } P8t := P(1) + P(2) + P(3) + P(4)$$

$$\begin{aligned}
 P8t := & 0.500000000044868 - 0.810660171852566 \cos(2 \pi t) \\
 & - 0.103553390602566 \sin(2 \pi t) + 1.00000000008974 \cos(4 \pi t) \\
 & + 0.500000000044868 \sin(4 \pi t) + 1.31066017189743 \cos(6 \pi t) \\
 & - 0.603553390647434 \sin(6 \pi t)
 \end{aligned}
 \tag{10}$$

#####

Section 10.3

#####

**2. nd 8 for the
following data points:**

b

**Find the least squares trigonometric approximating
functions of orders 4, 6, and 8 for the following data points**

> $V := \text{Vector}(8, [1, 0, -2, 1, 3, 0, -2, 1])$

$$V := \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \\ 3 \\ 0 \\ -2 \\ 1 \end{bmatrix}$$

(11)

>

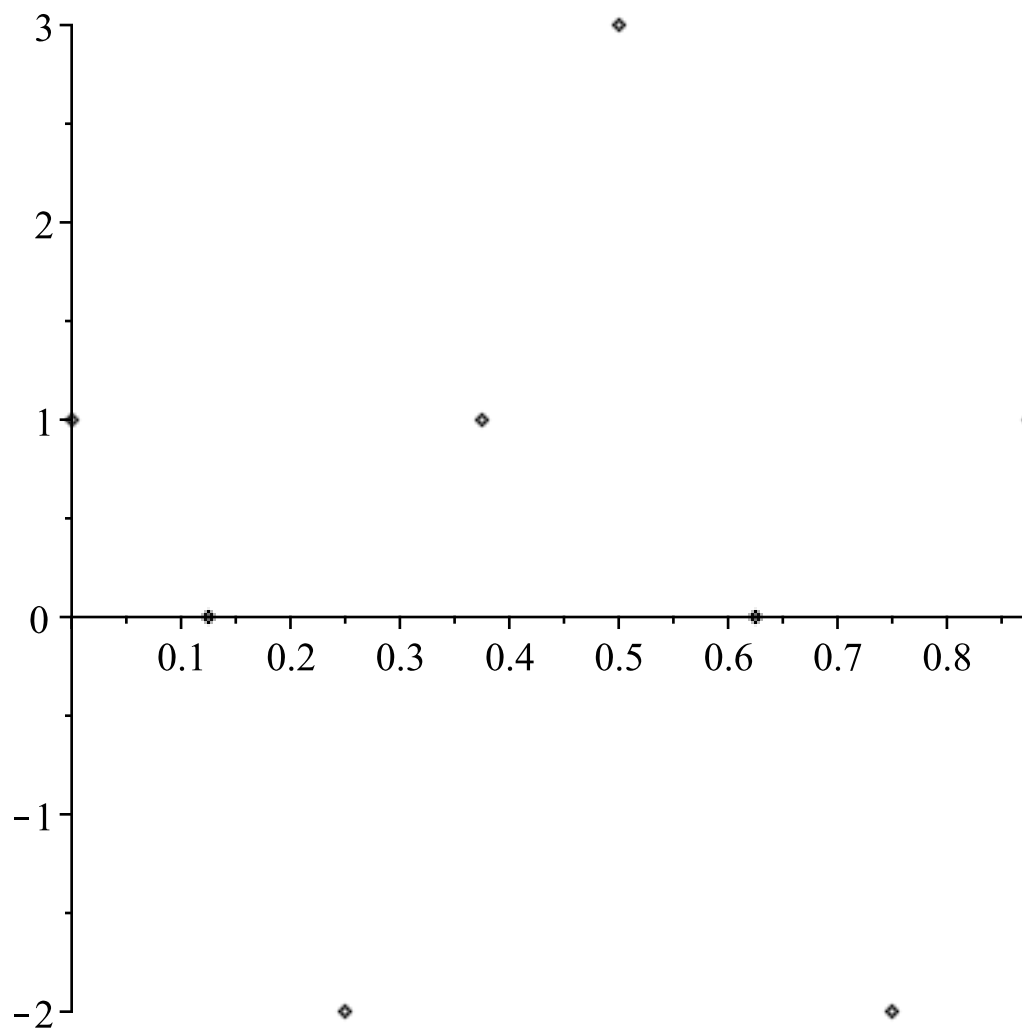
> $Z := \text{FourierTransform}(V)$

$$Z := \begin{bmatrix} 0.707106781186548 + 0. I \\ -0.707106781186548 + 0. I \\ 2.82842712474619 + 0.707106781186548 I \\ -0.707106781186548 + 0. I \\ -0.707106781186548 + 0. I \\ -0.707106781186548 + 0. I \\ 2.82842712474619 - 0.707106781186548 I \\ -0.707106781186548 + 0. I \end{bmatrix}$$

(12)

> $\text{rule} := i \rightarrow \frac{(i-1)}{8} : T := \text{Vector}(8, \text{rule}) :$

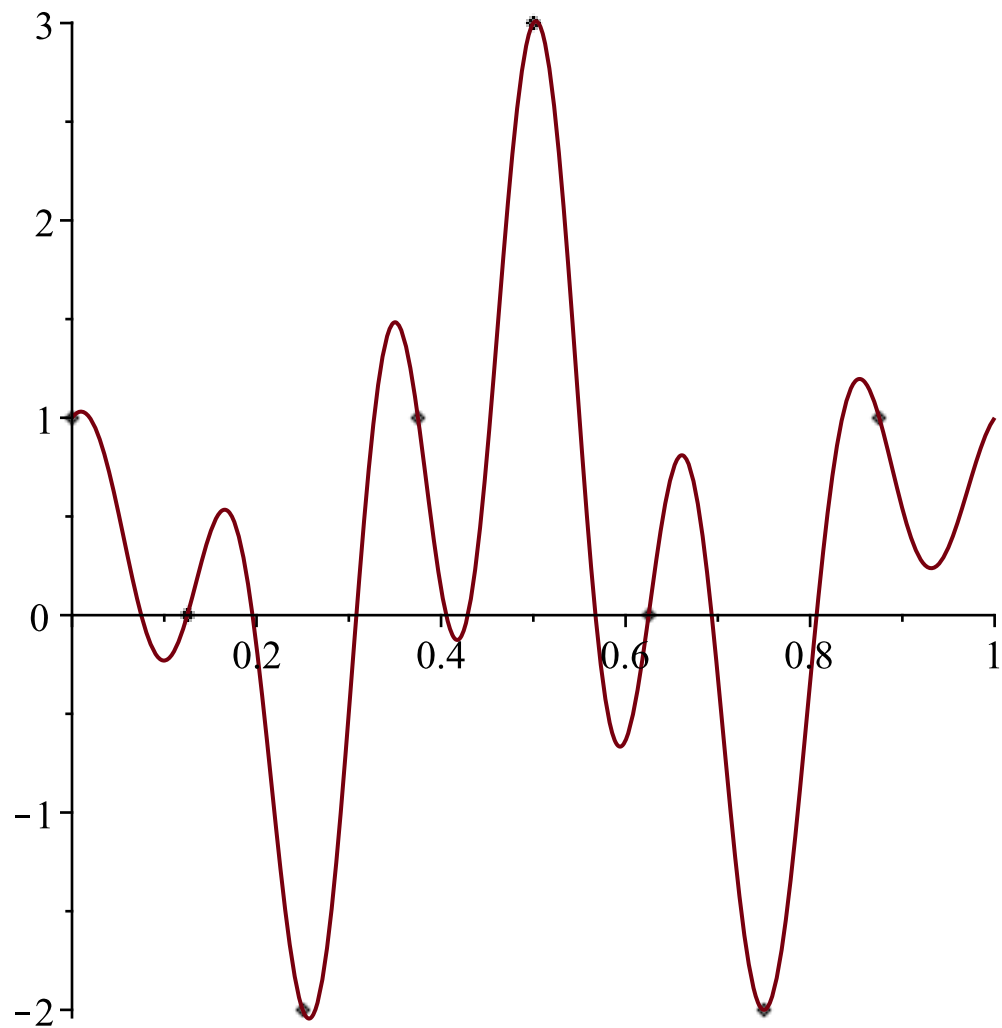
> $\text{dataplot1} := \text{pointplot}(T, V) : \text{display}(\text{dataplot1})$



```
> P := t → evalf(  $\frac{1}{\text{sqrt}(8)}$  · add( Re( Z[ k ] ) · cos( 2 · ( k − 1 ) · π · t ) − Im( Z[ k ] ) · sin( 2
```

```
· ( k − 1 ) · π · t ) , k = 1 .. 8 ) :
```

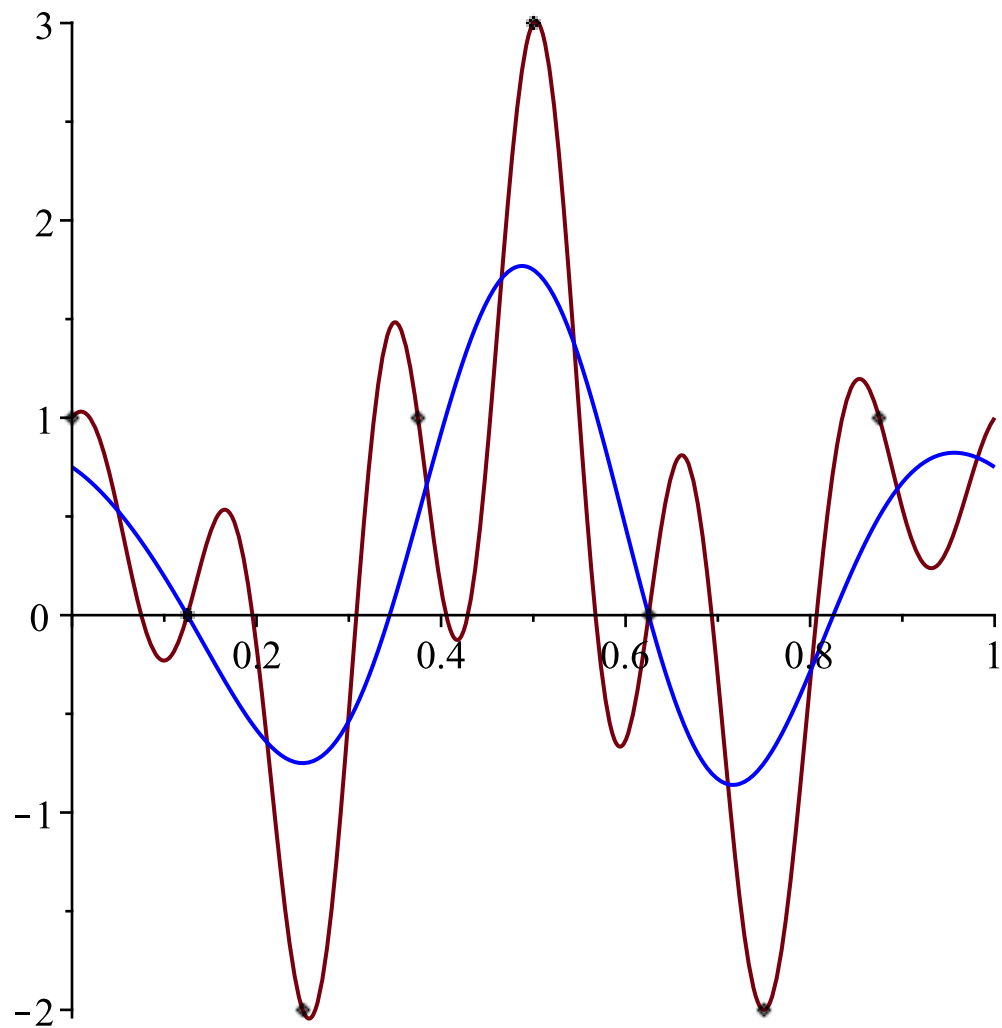
```
> plot1 := plot( P, 0 .. 1 ) : display( dataplot1, plot1 )
```



```

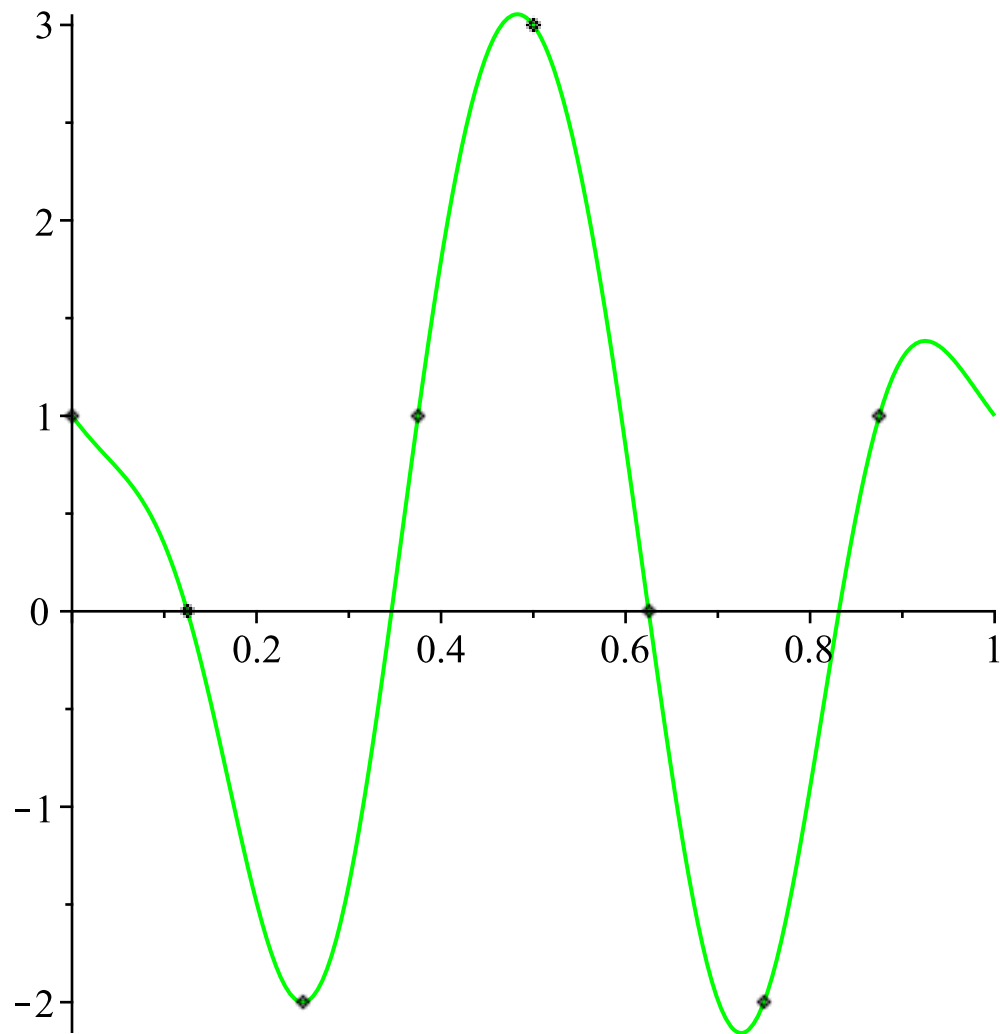
> Pdeg4 := t→evalf(  $\frac{1}{\text{sqrt}(8)}$  · add(Re(Z[k])·cos(2·(k-1)·π·t) - Im(Z[k])
    ·sin(2·(k-1)·π·t), k=1..4) ) :
> plot2 := plot(Pdeg4, 0..1, color=blue) : display(plot1, plot2, dataplot1)

```



```
> Peven := t→evalf(  $\frac{1}{\text{sqrt}(8)} \cdot \text{Re}(Z[1]) + \frac{2}{\text{sqrt}(8)} \cdot \text{add}(\text{Re}(Z[k]) \cdot \cos(2 \cdot (k - 1) \cdot \pi \cdot t) - \text{Im}(Z[k]) \cdot \sin(2 \cdot (k - 1) \cdot \pi \cdot t), k = 2 \dots 4) + \frac{1}{\text{sqrt}(8)} \cdot \text{Re}(Z[5]) \cdot \cos(8 \cdot \pi \cdot t)$  ) :
```

```
> plot3 := plot(Peven, 0..1, color = green) : display(plot3, dataplot1)
```



And we compute the reduced least-square trigonometric polynomial of order 4 (showed in brown)

```
> Pevendeg4 := t -> evalf(
  1/sqrt(8) * Re(Z[1]) + 2/sqrt(8) * add(Re(Z[k]) * cos(2
    * (k-1) * pi * t) - Im(Z[k]) * sin(2 * (k-1) * pi * t), k=2..2) + 2/sqrt(8) * Re(Z[3])
  * cos(4 * pi * t) ) :
> plot4 := plot(Pevendeg4, 0..1, color=brown) : display(plot3, plot4, dataplot1)
```

