```
In [1]: ▶ import cv2
            import sys
            # Load video, 0 for webcam, str for path to video
            video = cv2.VideoCapture(0)
            # video = cv2.VideoCapture('test_clip.mp4')
            # Exit if video not opened.
            if not video.isOpened():
                print('Could not open video!')
                sys.exit()
            # Tracker Variables
            tracker = None
            roi = (0, 0, 0, 0)
            # -1 for not tracking, 0 for init tracking, 1 for update tracking
            tracking flag = -1
            # Loop simulate Camera Preview Callback
            while True:
                # Capture user Key Press to simulate App Control
                key = cv2.waitKey(1) & 0xff
                # User Press Enter
                if key == 13:
                    # Not tracking
                    if tracking flag == -1:
                        # Pause and let user select ROI
                        roi = cv2.selectROI(frame, False)
                        # Init tracking
                        tracking flag = 0
                    # Is tracking
                    if tracking flag == 1:
                        # Reset ROI
                        roi = (0, 0, 0, 0)
                        # Clear Tracker
                        tracker.clear()
                        # Stop tracking
                        tracking flag = -1
                # User Press ESC
                elif key == 27:
                    break
                # Start timer
```

```
start = cv2.getTickCount()
# Read Next frame.
read_success, frame = video.read()
if not read success:
    print('Cannot read video file!')
    sys.exit()
if tracking_flag == -1:
    # Display Text
    cv2.putText(frame, "Press ENTER to select ROI!", (10, 30), cv2.FONT_HERSHEY_SIMPLEX, 0.75, (0, 0, 255), 2)
elif tracking flag == 0:
    # Initialize KCF Tracker and Start Tracking
    # 1. Create a KCF Tracker
    # 2. Initialize KCF Tracker with grayscale image and ROI
    # 3. Modify tracking flag to start tracking
    # Your code starts here
    KCF tracker = cv2.TrackerKCF create()
    ready = KCF_tracker.init(frame,roi)
    tracking_flag = 1
else:
    # Update tracking result is succeed
    # If failed, print text "Tracking failure occurred!" at top left corner of the frame
    # Calculate and display "FPS@fps value" at top right corner of the frame
    # Your code starts here
    ready, roi = KCF_tracker.update(frame)
    if(ready == False):
        cv2.putText(frame, "Tracking failure occured!", (10,40), cv2.FONT_HERSHEY_SIMPLEX, 0.75, (0, 0, 255), 2)
    FPS = cv2.getTickFrequency()/(cv2.getTickCount() - start)
    cv2.putText(frame, "FPS@" + str(FPS), (400,100), cv2.FONT HERSHEY SIMPLEX, 0.75, (0, 0, 255), 2)
# Draw ROI Rectangle
p1 = (int(roi[0]), int(roi[1]))
p2 = (int(roi[0] + roi[2]), int(roi[1] + roi[3]))
cv2.rectangle(frame, p1, p2, (255, 0, 0), 2, 1)
# Display result
cv2.imshow("ECE420 Lab7", frame)
```