# Zero Shot Domain Adaption

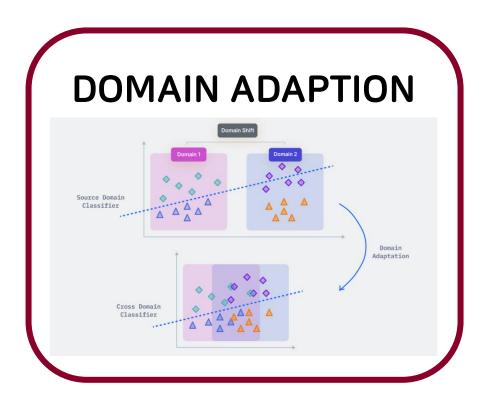
POSIDA-Prompt Driven Synthesis Image for Zero-shot Domain Adaption



# ABSTRACT - Problem

How to train the model in unrealistic, rare event in real situation?

- 1. Data Dependency issue
- 2. Technical limitation



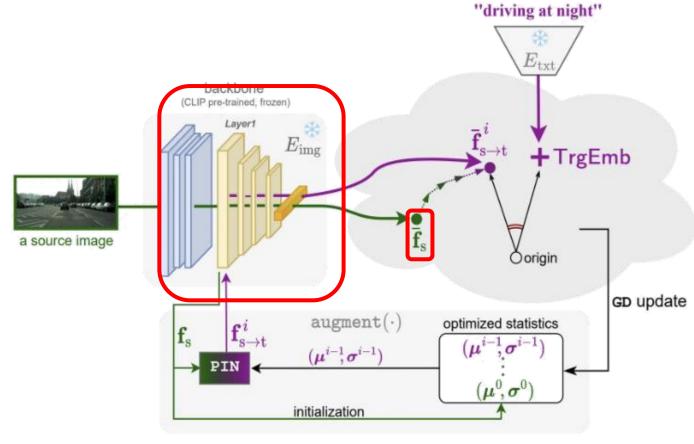
# 1 ABSTRACT

#### Zero shot domain adaption

- Technology that utilizes knowledge from the learned source domain to generalize to the untrained target domain
- Improve the safety and efficiency of autonomous vehicles
- Contributes to the successful application of autonomous driving in a wider range of real-world environments

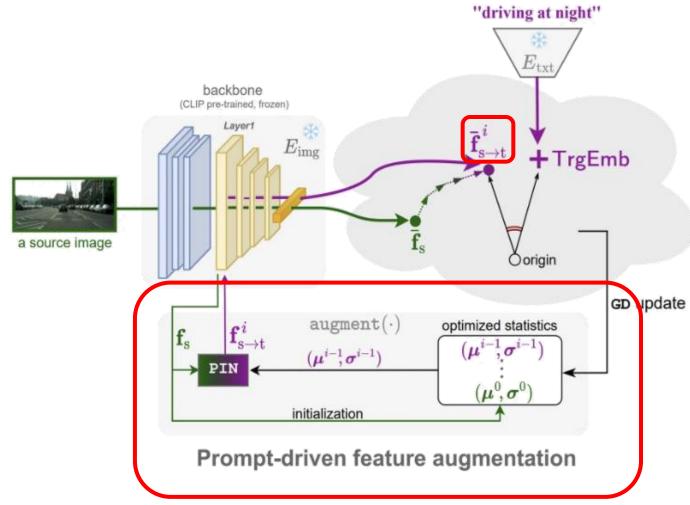


### base model

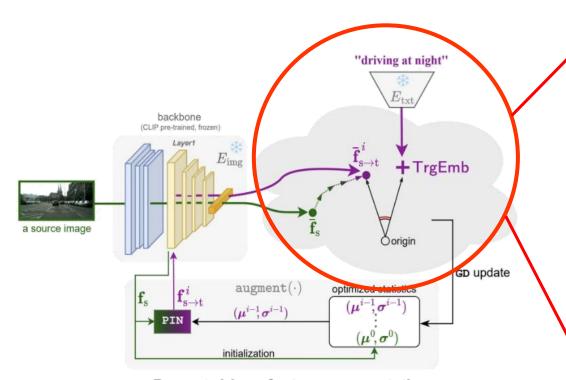


Prompt-driven feature augmentation

### base model



### base model - problem



Prompt-driven feature augmentation

#### Limitation embedding text

- Performance depending on prompt
- Only text prompt has limitation



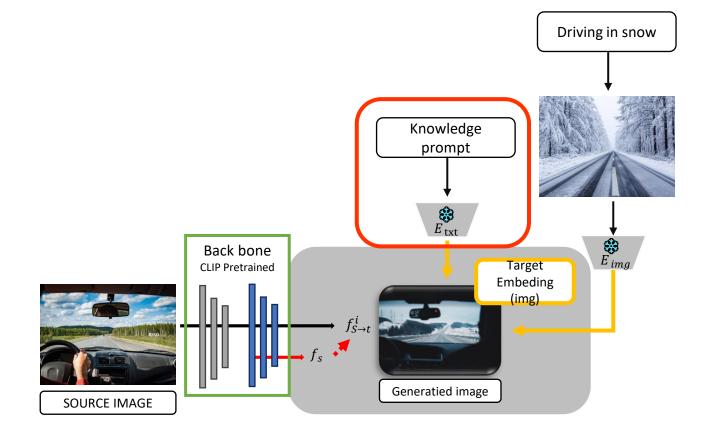
Domain gap exist



So add Knowledge based prompt & Synthesis image

### POSIDA

### Prompt Driven Synthesis Image for Zero-shot Domain Adaption



#### Knowledge based prompt

 Weather-specific and driving situation-specific prompts for optimal model performance

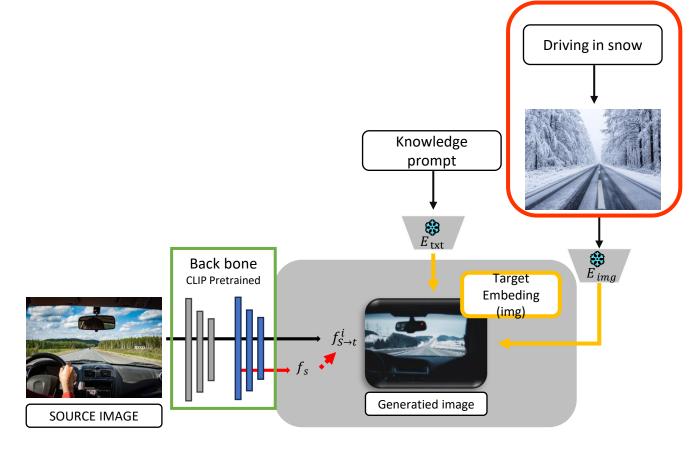
Ex: a photo of {SNOW}



an open highway with {SNOW}

### POSIDA

### Prompt Driven Synthesis Image for Zero-shot Domain Adaption



#### **Use Synthesized image**

- In embedding space information of prompt is not enough
- Use Synthesized image information to increase overall performance

# Data set

#### Source domain: Cityscapes



#### 30 classes

(road, sidewalk, rail track, car, trailer building, building...etc)

50 cities

Several season

Daytime

Good weather condition

**11GB** 

# 4 Data set

#### Target domain: ACDC



#### 19 classes

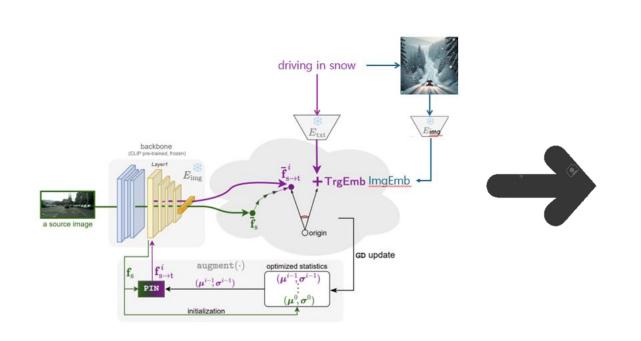
(road, sidewalk, rail track, car, trailer building, building...etc)

#### Data split

1000foggy, 1006 nighttime, 1000 rainy and 1000 snowy

17GB

### Evaluation metric - MIOU



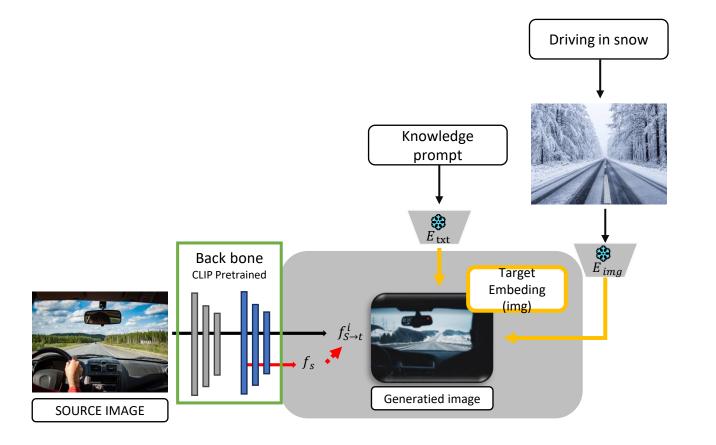


$$IOU = \frac{Correct \ AREA}{Whole \ AREA}$$

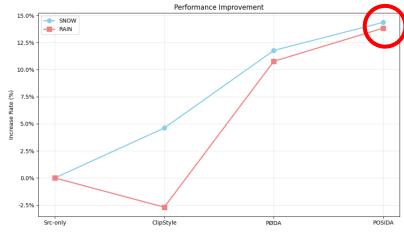
$$\approx MIOU = \frac{1}{n} \sum_{k=1}^{n} \frac{Correct \ AREA}{Whole \ AREA}$$

### Experience result 1

Table 1. Model Performance



Condition	SNOW	RAIN
Src-only	39.28	38.2
clipstyle	41.09	37.17
PODA	43.9	42.31
POSIDA	44.92	43.48



## Ablation study

#### **About LOSS function**

#### Table 2. Loss

Condition	$\alpha = 0.3$	$\alpha = 0.5$	$\alpha = 0.8$
SNOW	44.24	44.77	44.53
RAIN	42.51	43.48	42.85

 $\text{Combined Loss} = \alpha \cdot \text{Loss}_{\text{IMAGE}} + (1 - \alpha) \cdot \text{Loss}_{\text{TEXT}}$ 

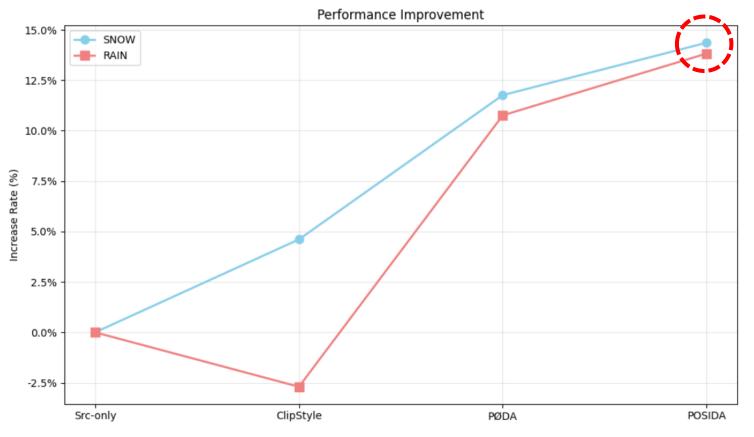
#### About Knowledge prompt

#### Table 3. Knowledge prompt

Condition	w/o knowledge prompt	with knowledge prompt
SNOW	44.23	44.36
RAIN	42.02	42.42

# 6 Conclusion

#### 1. Overall performance increased



# 6 Conclusion

#### 2. Although the model added generated images

inference time & model size unchanged

PODA: 1sec -> 5.98 img / POSIDA: 1sec -> 5.82 img

model size & num of hyper parameter is remained

#### 3. Limitation

- lack of time & resources limitation on various condition experiment

#### 4. Discussion

- POSIDA method can extended to various domains
- In future research can aim to improve performance through optimizing prompts

### Thank you

**Q&A** 

# 7 Appendix

#### 1. CLIP style

- Use clip embedding space
- Use text prompt to change image style

