



### Introduction to Electronics



#### Agenda

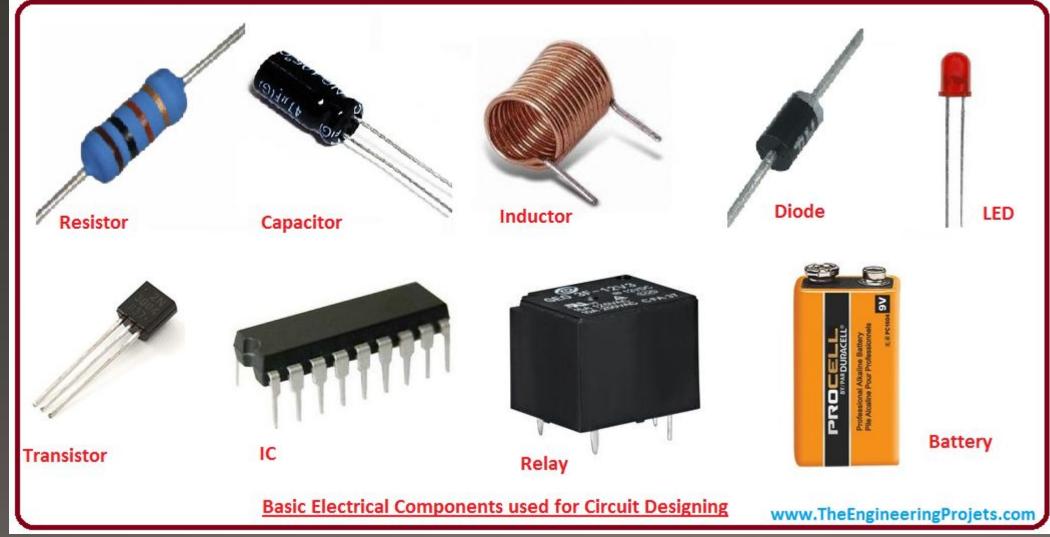
- Basic electronics Component
- Resistor
- ohm's law
- led
- Relay
- Measurement tools
- Measure Current in closed circuit
- Measure Voltage in closed circuit
- Bread board







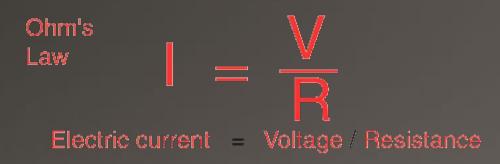
## Basic electronics component

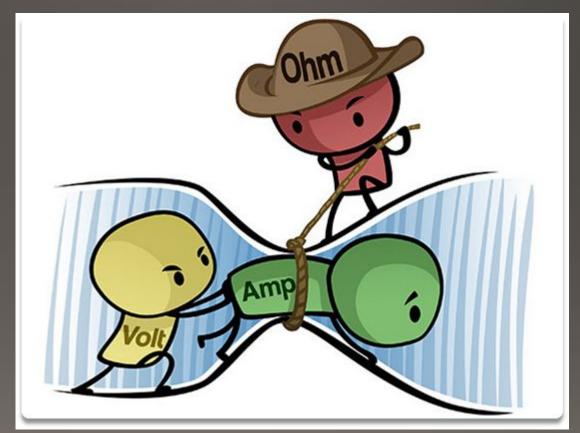






## ohm's law



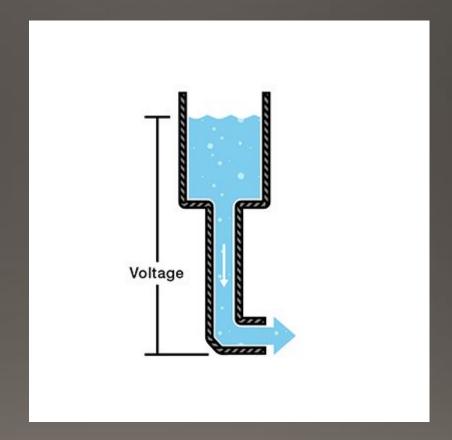






### Voltage

- Electric potential difference between two points.
- (V) Measured in Volts.



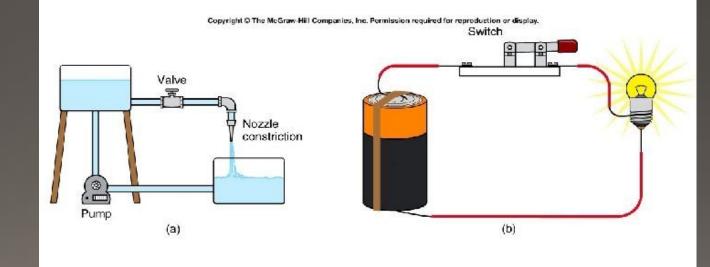




#### Current

- Charges (Electrons) moving through material.
- (I) Measured in Amps

#### Electric Current Is Analogous to Water Flow







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#### Resistance

- The ability of the material to slow/stop the flowing of the electrical current.
- (R) Measured in ohms  $(\Omega)$ .
- Application ...



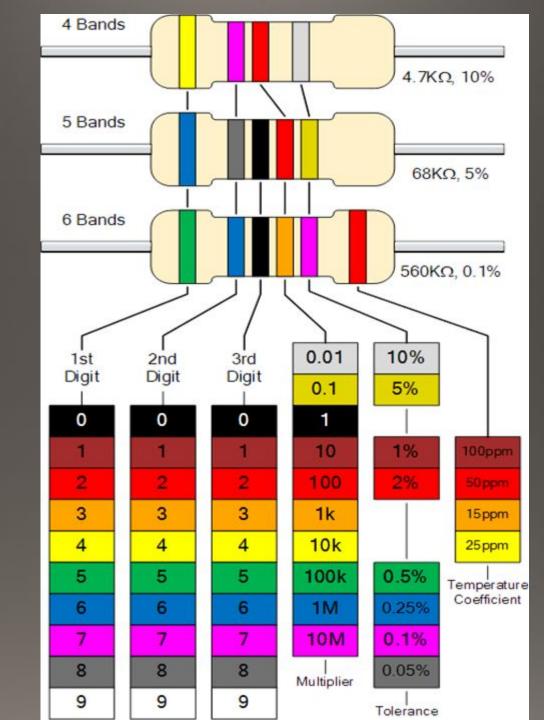








#### Resistor Color Code









### Variable Resistance







#### Batteries



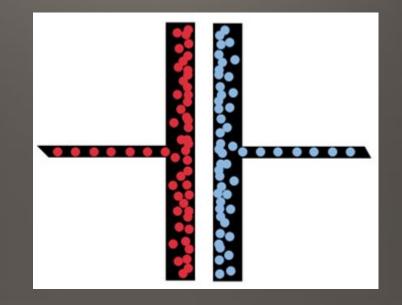


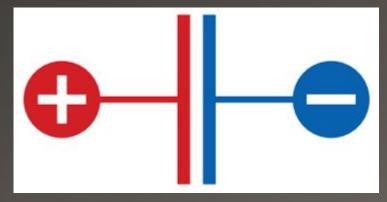


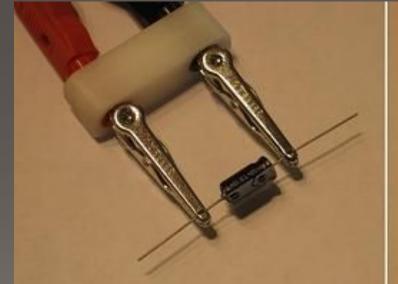




### Capacitors





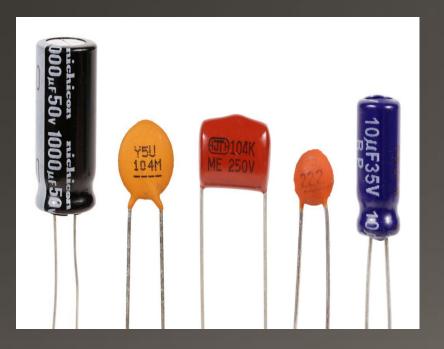


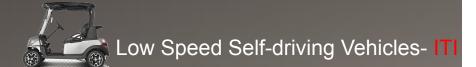




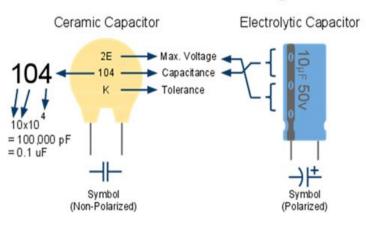


### Capacitors





#### **Capacitors**



#### **Capacitance Conversion Values**

Microfarads (µF)		Nanofarads (nF)		Picofarads (pF)
0.000001 µF	4+	0.001 nF	4+	1 pF
0.00001 µF	4+	0.01 nF	4+	10 pF
0.0001 µF	4+	0.1 nF	4+	100 pF
0.001 µF	4+	1 nF	4+	1,000 pF
0.01 µF	4+	10 nf	4+	10,000 pF
0.1 µF	4+	100 nF	4+	100,000 pF
1 µF	4+	1,000 nF	4+	1,000,000 pF
10 μF	4+	10,000 nF	4+	10,000,000 pF
100 μF	4+	100,000 nF	4+	100,000,000 pF

#### Max. Operating Voltage

Code	Max. Voltage
1H	50V
2A	100V
2T	150V
2D	200V
2E	250V
2G	400V
2J	630V

#### Tolerance

Code	Percentage
В	± 0.1 pF
С	±0.25 pF
D	±0.5 pF
F	±1%
G	±2%
н	±3%
J	±5%
K	±10%
M	±20%
Z	+80%, -20%



### **Switches**

Toggle switch

Pushbutton switch

Selector switch







Lever actuator limit switch









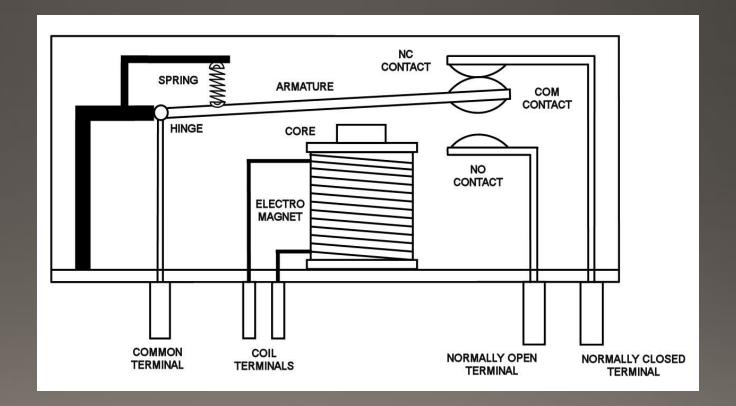




#### Electromechanical

- Electromagnet
- Armature that can be attracted by the electromagnet
- Spring
- Set of electrical contacts

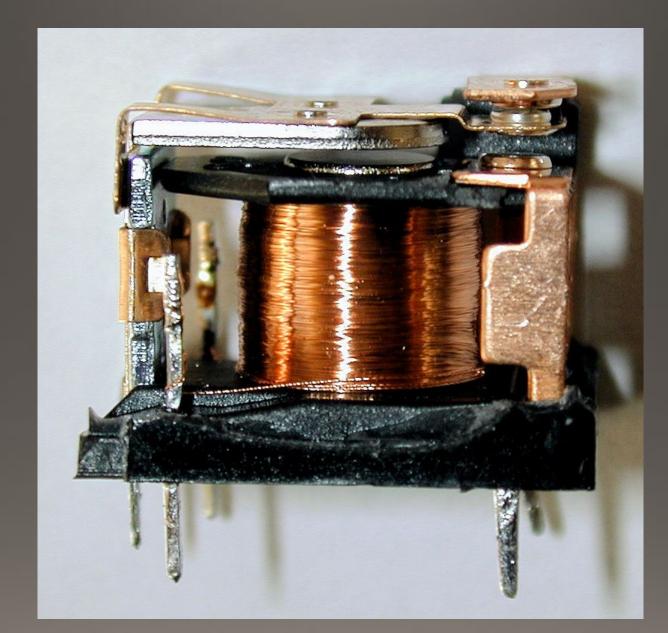






# M

# Relay body









## Multimeter (AVO Meter)



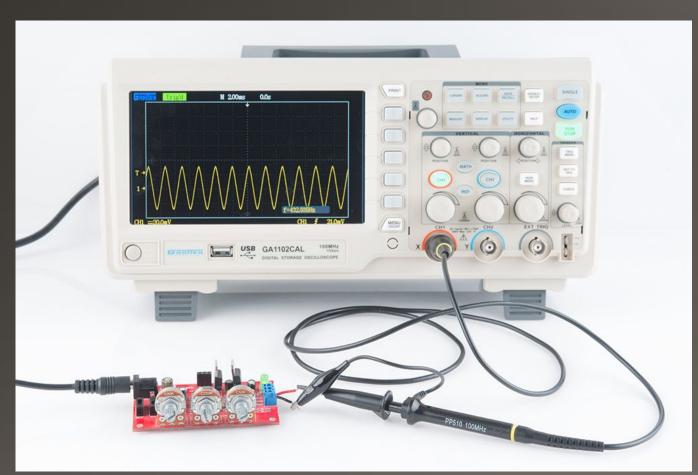






# M

## oscilloscope



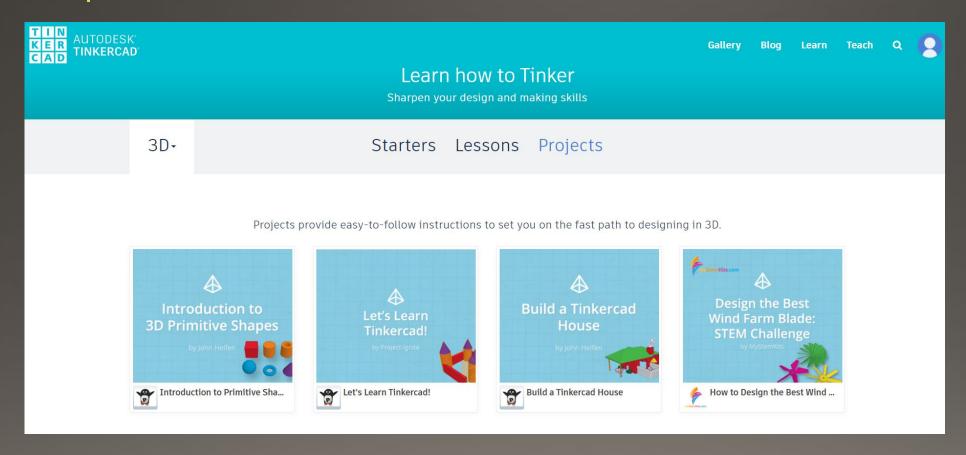






### Tinker cad

#### Dashboard | Tinkercad

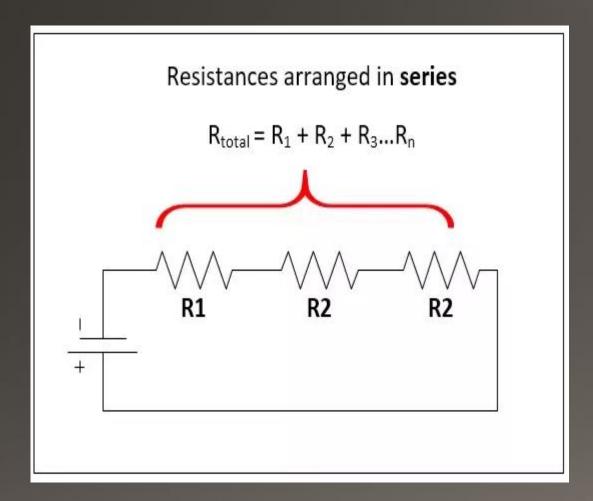


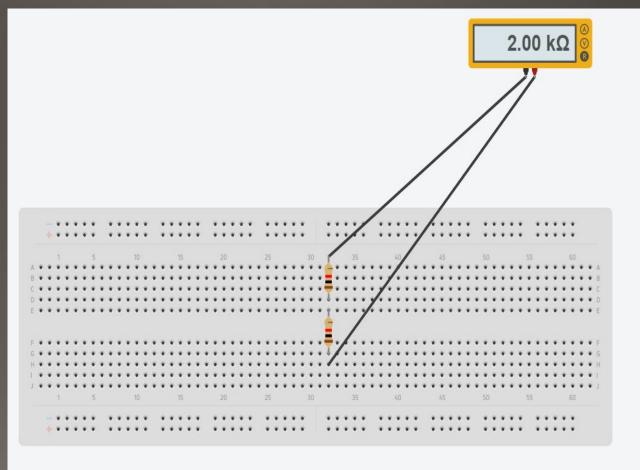






## Resistor in series









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## Task

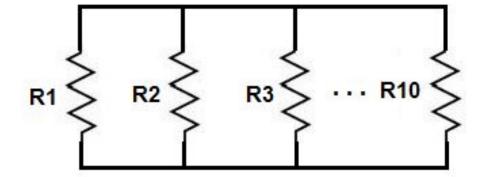
create a combined resistors of 4.5k ohm using 5 resistor.



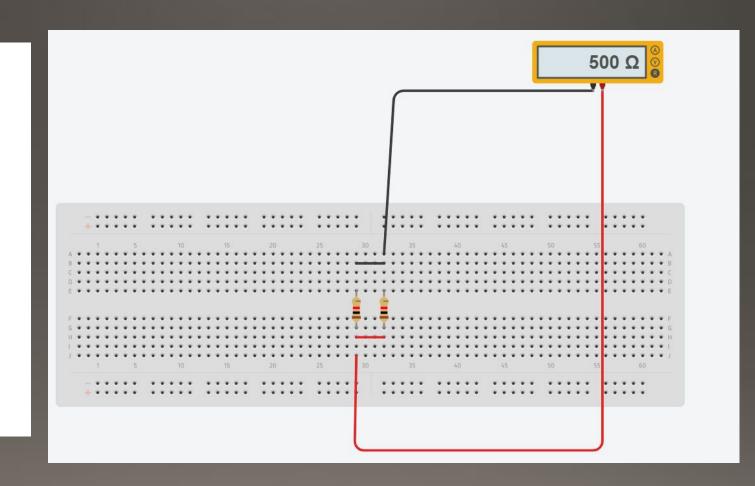


## Resistor in parallel





$$R_{T} = \frac{1}{\frac{1}{R_{1}} + \frac{1}{R_{2}} + \frac{1}{R_{3}} + \dots + \text{ etc.}}$$

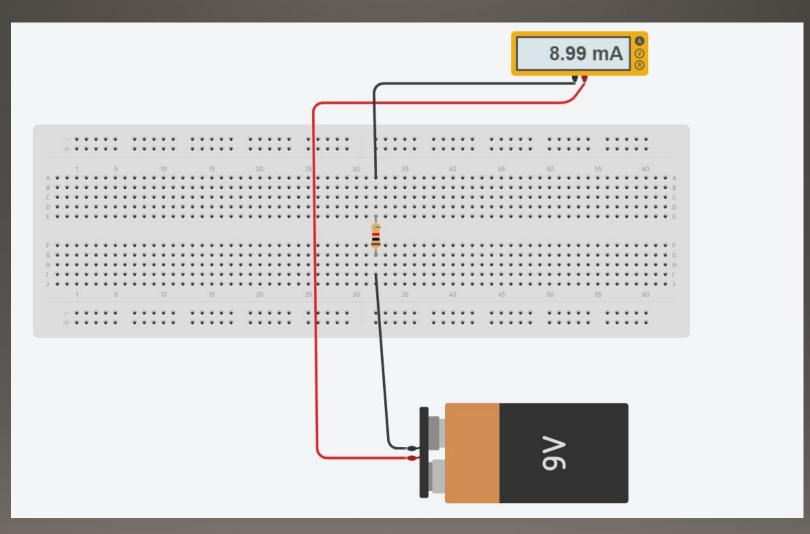






## ohm's law

 $\begin{array}{c|c} \text{Ohm's} \\ \text{Law} & = \frac{V}{R} \\ \text{Electric current} & = \text{Voltage / Resistance} \end{array}$ 







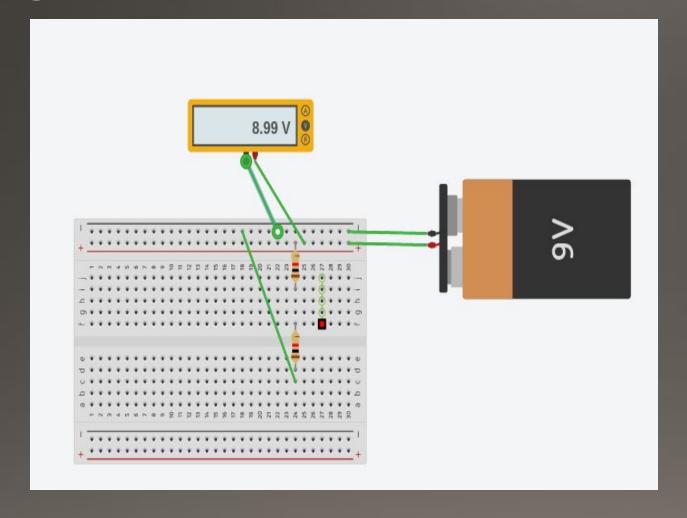
## Task

change the resistance value to create a current of 20m Amp.





## Voltage measurement

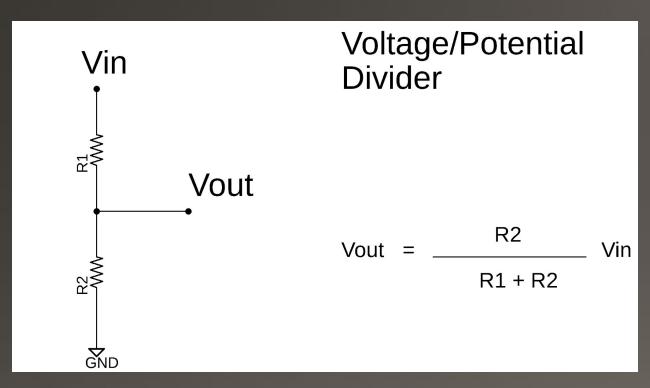


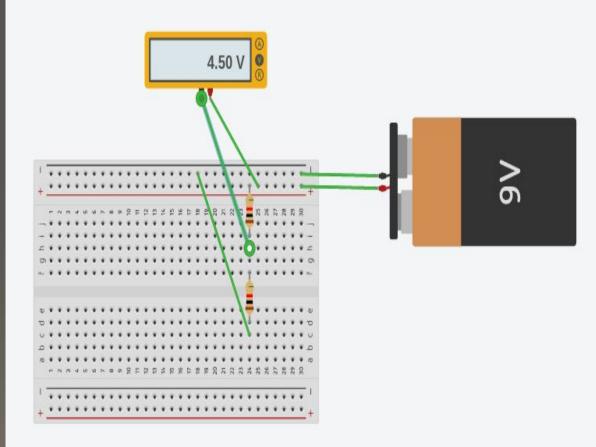






## Voltage divider



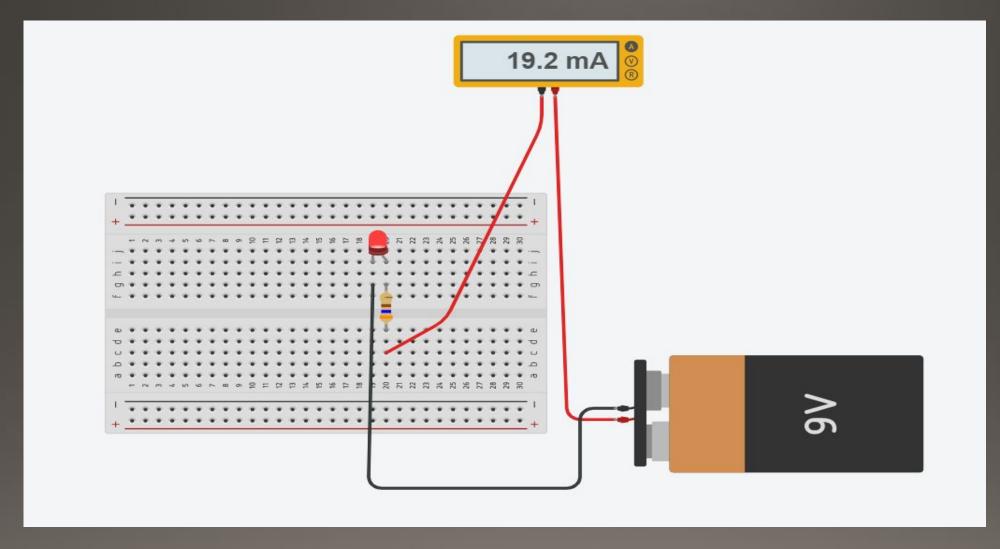








### current measurement

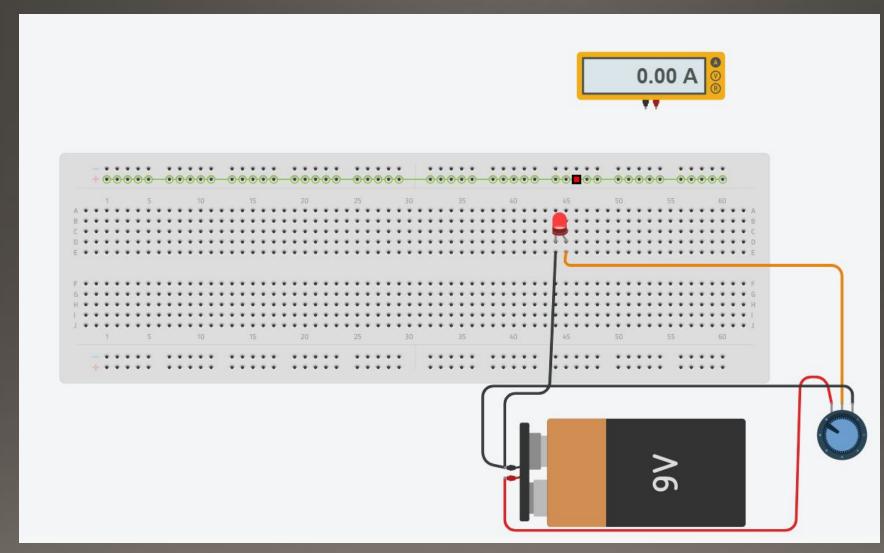








## variable resistor

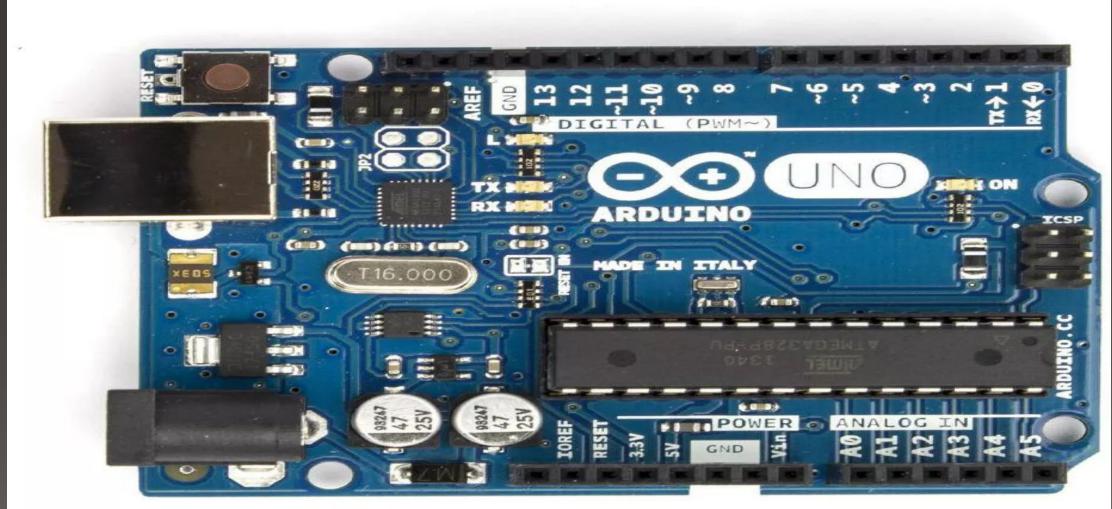






# M

## Arduino

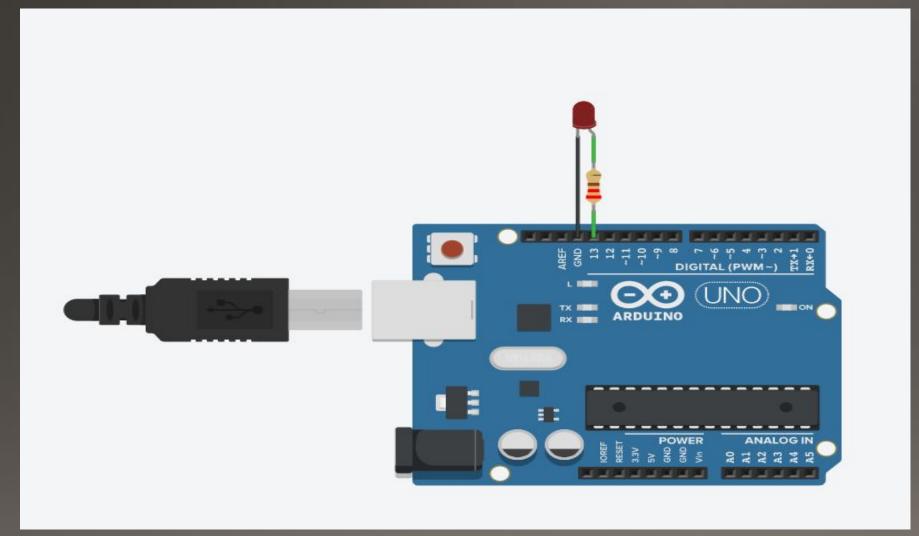






## blinking











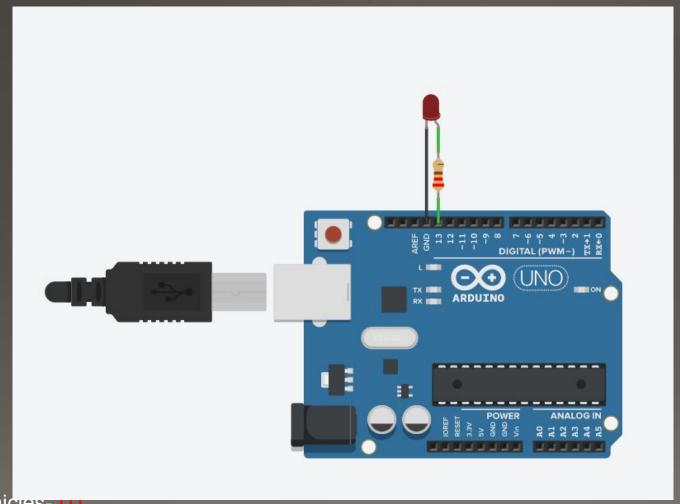
## Task blinking 2 led

add led to another digital pin to be blinking every 2 second





# Variable light (PWM)

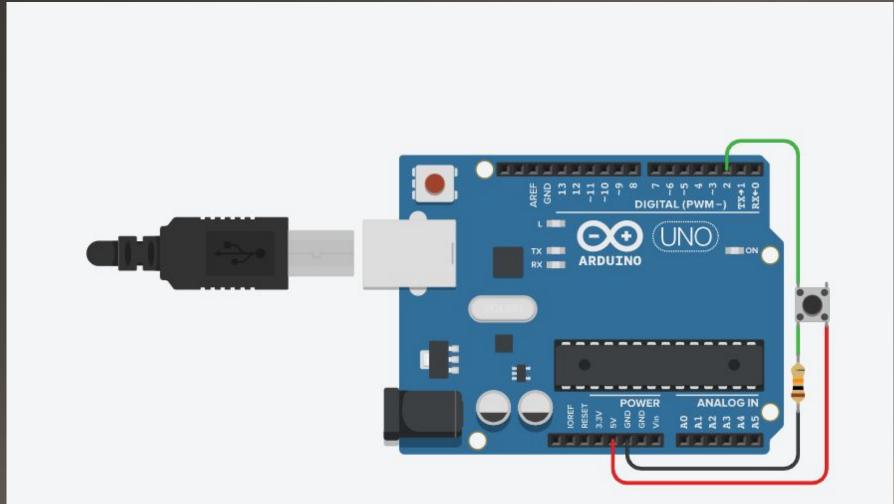


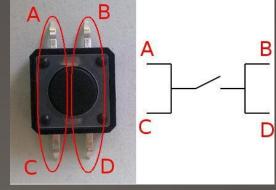






## Blinking with push button



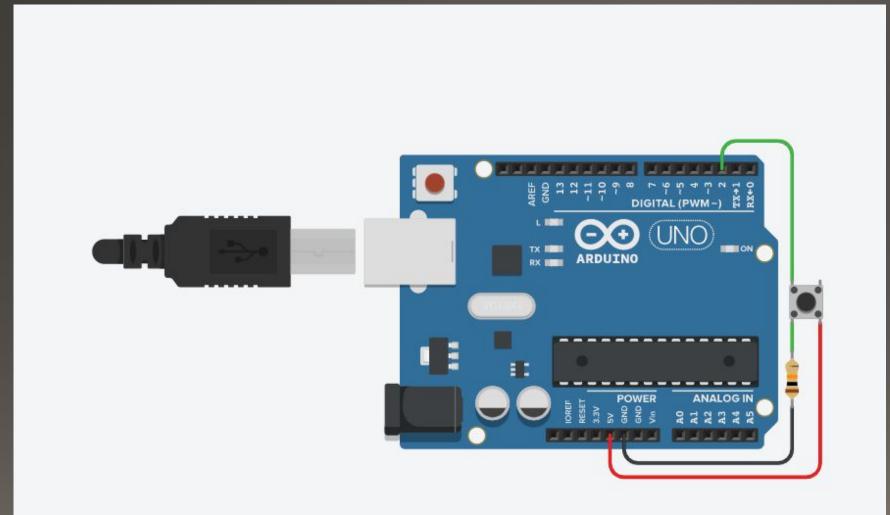








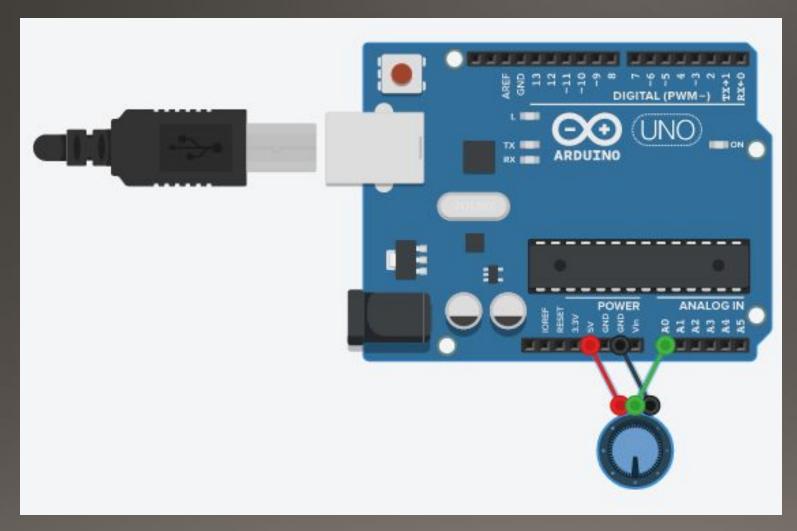
## Digital read serial







# Analog input

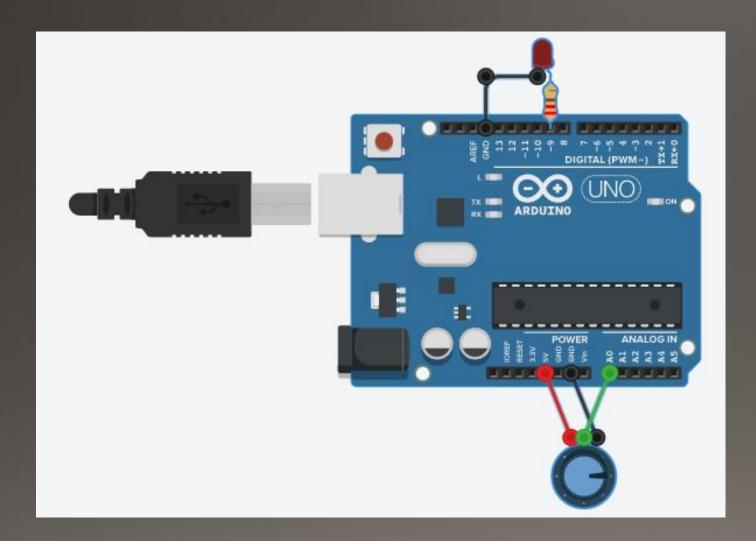






# M

## Dimmer

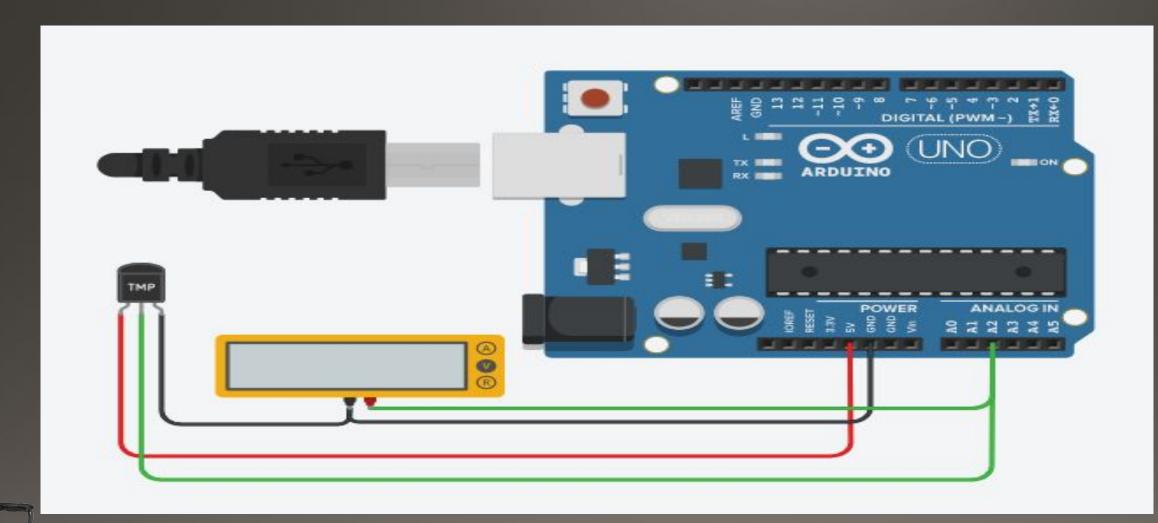








## Temperature Sensor







### Task 1

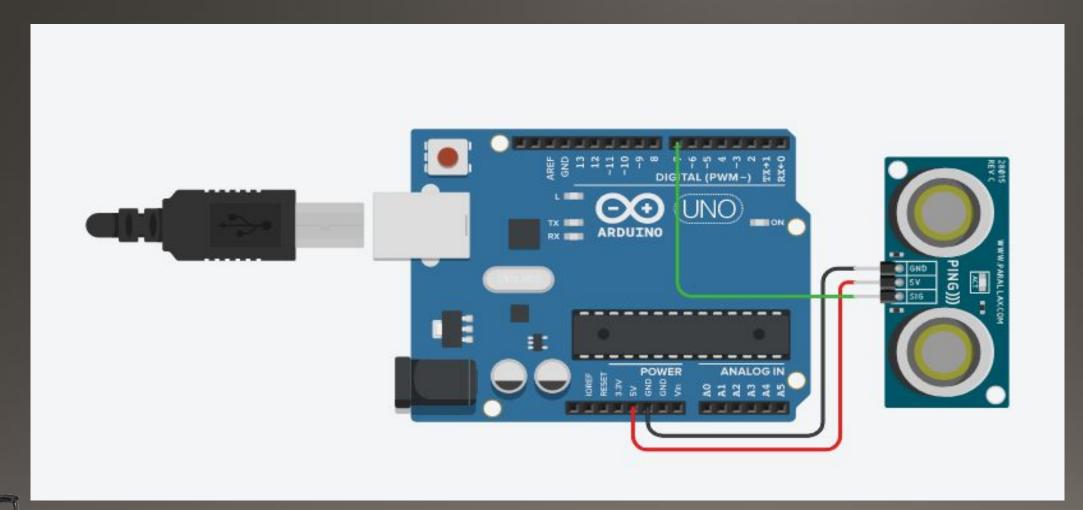
use the following formula to find the temperature.

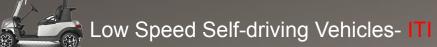
temperature=(Sensor\_voltage-0.5)\*100 print the output in Serial Monitor





## Ultrasonic Sensor









### Task 2

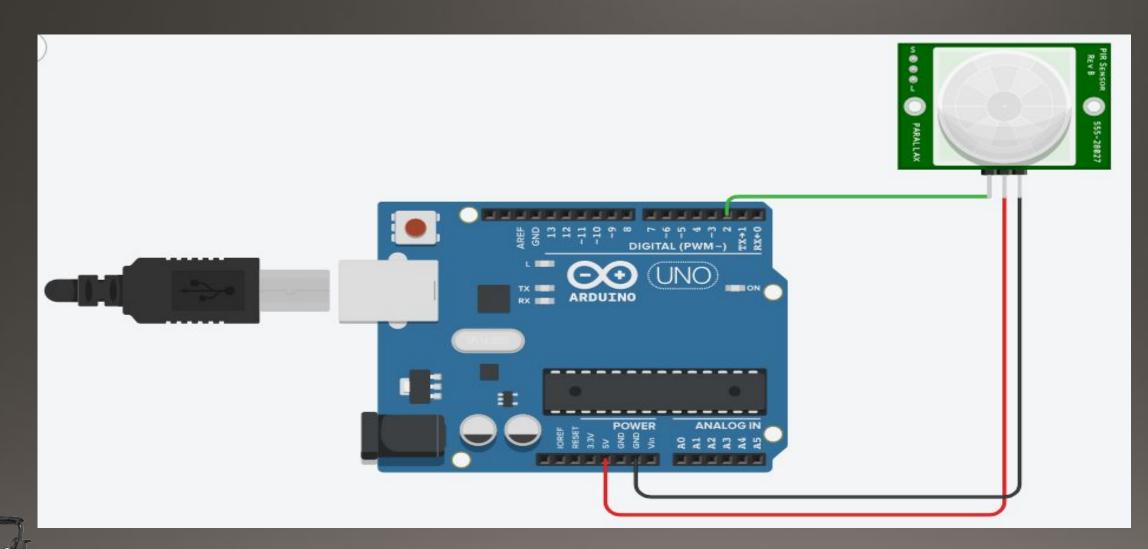
use ultrasonic sensor to get distance of the moving object. if the distance < 60 print "Warning -----"







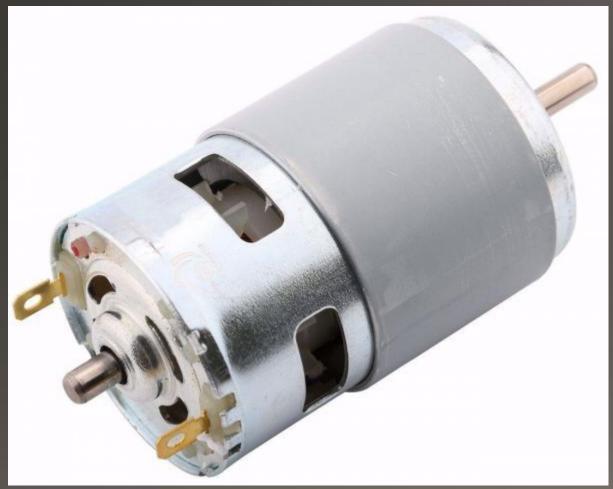
## PIR Sensor

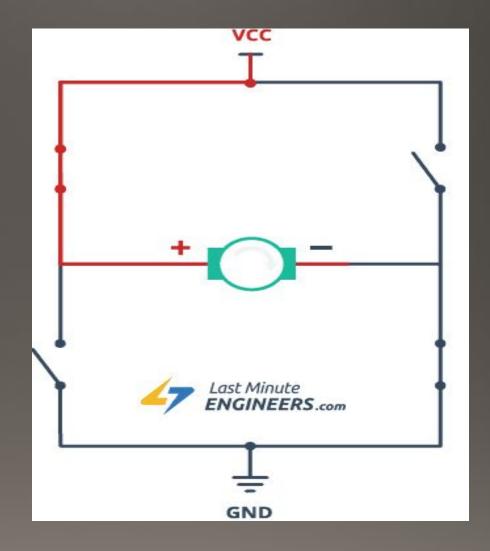






## DC Motor - H bridge



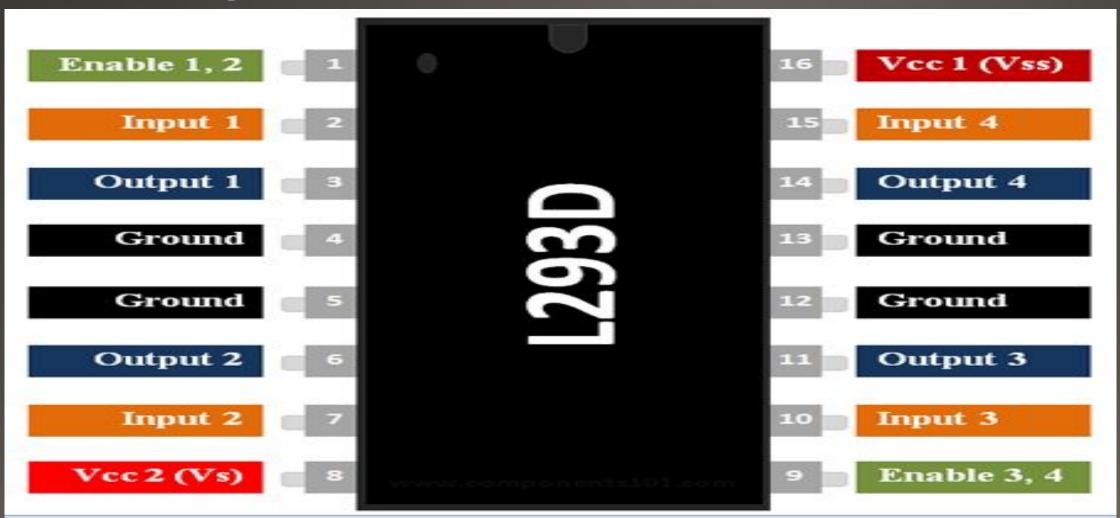








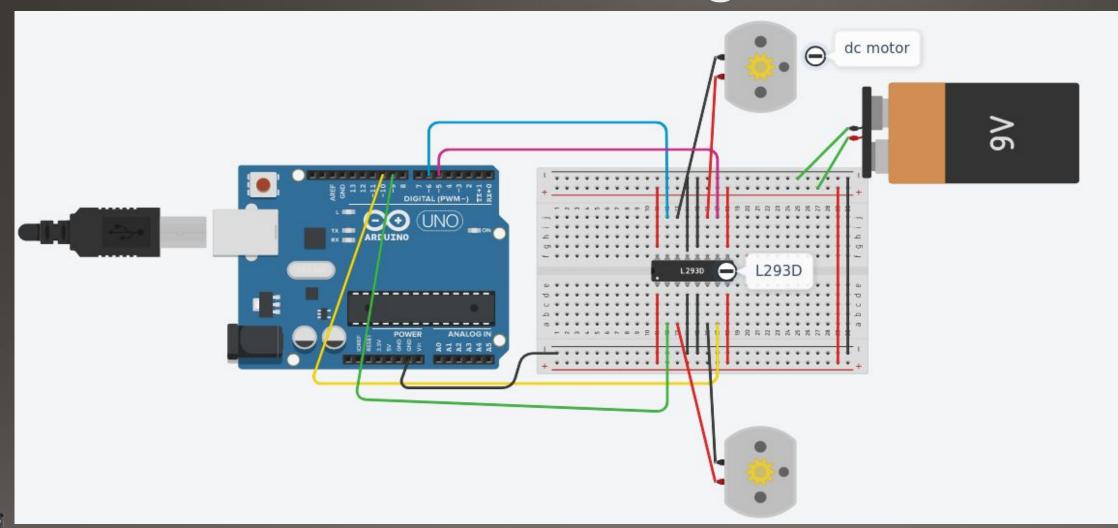
## H- bridge







## DC with L293D H bridge







### Task 3

add two push button to control dc motor direction, first one to rotate motor clockwise and other to rotate it counter clockwise.