

12.3.5 Ion-atom scattering; general binary collision dynamics

A collision between two particles that have an interaction potential $V(r)$ and which collide with an *impact parameter* p is shown in Figure 12.6. It is desired to find the orbit of two particles in an elastic collision and to relate the interaction potential to the differential cross section $\sigma(E, \theta)$.

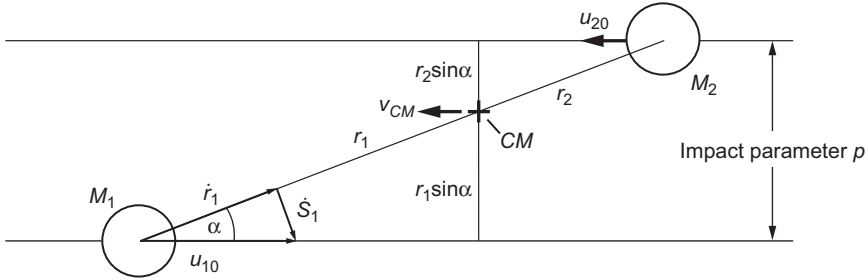


FIGURE 12.6: Geometry for derivation of elastic collision between an energetic ion and a stationary atom, interacting by a potential $V(r)$.

In the system considered, a particle mass M_1 is moving initially with kinetic energy E toward an initially stationary particle mass M_2 . The center of mass (CM) is located on the line joining the two masses at a distance

$$r_1 = \frac{M_2}{M_1 + M_2} r \quad \text{and} \quad r = r_1 + r_2 \quad (12.28)$$

from the mass M_1 . The initial velocity of particle 1 in the center-of-mass system, u_{10} , is decomposed into two perpendicular components \dot{r}_1 and \dot{S}_1 , such that $\vec{u}_{10} = \vec{\dot{S}}_1 + \vec{\dot{r}}_1$. The line between the particles makes an angle α with the initial direction of the particles in the CM system. Only the initial kinetic energy in the CM system is convertible to potential energy, and this is written

$$E_{CM} = \frac{1}{2} (M_1 + M_2) v_{CM}^2, \quad (12.29)$$

and using Equation (12.3):

$$E_{CM} = \frac{M_1}{M_1 + M_2} E = \frac{M_1}{M_1 + M_2} \left[\frac{M_1 v_{10}^2}{2} \right] \quad (12.30)$$

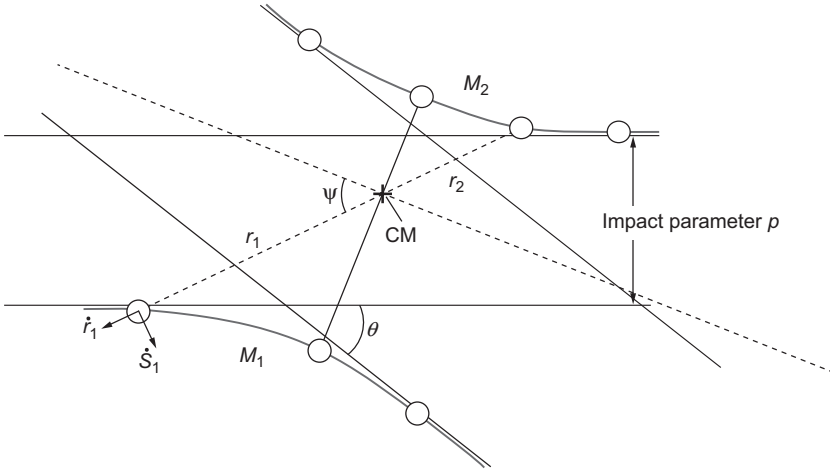


FIGURE 12.7: *Geometry during the collision in center-of-mass coordinates.*

where E is the initial kinetic energy of particle 1 in the laboratory frame. Now using conservation of energy and angular momentum during the collision, it is possible to derive a relationship between the scattering angle in the center of mass θ and the impact parameter p . The trajectory of the particles as they interact and are deflected by angle θ are shown in Figure 12.7.

Conservation of energy

As the two energetic particles approach each other, they convert kinetic energy into potential energy, $V(r)$, so that at the distance of closest approach, the kinetic energy is minimized. Conservation of energy for the system is

$$E_{CM} = V(r) + \frac{1}{2} M_1 u_{10}^2 + \frac{1}{2} M_2 u_{20}^2 = V(r) + \frac{1}{2} M_1 (\dot{r}_1^2 + \dot{S}_1^2) + \frac{1}{2} M_2 (\dot{r}_2^2 + \dot{S}_2^2) \quad (12.31)$$

The tangential speed \dot{S} is equal to $r\dot{\psi}$, so Equation (12.31) is

$$E_{CM} = V(r) + \frac{1}{2} M_1 (\dot{r}_1^2 + r_1^2 \dot{\psi}^2) + \frac{1}{2} M_2 (\dot{r}_2^2 + r_2^2 \dot{\psi}^2) \quad (12.32)$$

and using the definition of the energy of the center of mass,

$$E_{CM} = V(r) + \frac{1}{2} \left(\frac{M_1 M_2}{M_1 + M_2} \right) (\dot{r}^2 + r^2 \dot{\psi}^2) \quad (12.33)$$

along with
$$\dot{r}^2 = \left(\frac{dr}{d\psi} \frac{d\psi}{dt} \right)^2 = \left(\frac{dr}{d\psi} \right)^2 \dot{\psi}^2 \quad (12.34)$$

yields
$$E_{CM} = V(r) + \frac{1}{2} \left(\frac{M_1 M_2}{M_1 + M_2} \right) \left(\left[\frac{dr}{d\psi} \right]^2 + r^2 \right) \dot{\psi}^2 . \quad (12.35)$$

Conservation of angular momentum

The angular momentum of a mass M about an axis is $\vec{r} \times (M\vec{u}) = rMu \sin \alpha = rM\dot{S}$, where r is the distance between the particle and the axis, u is the velocity, and α is the angle between r and u . Then, the total angular momentum in the CM system is equal to

$$L = r_1 M_1 u_{10} \sin \alpha + r_2 M_2 v_{CM} \sin \alpha . \quad (12.36)$$

The tangential velocity \dot{S} is equal to $r\dot{\psi}$; thus,

$$L = L_1 + L_2 = M_1 \dot{S}_1 r_1 + M_2 \dot{S}_2 r_2 = M_1 r_1^2 \dot{\psi} + M_2 r_2^2 \dot{\psi} . \quad (12.37)$$

Using the definition of CM velocity in Equation (12.36) and equating to Equation (12.37)

$$\begin{aligned} L &= \frac{M_1 M_2}{M_1 + M_2} v_{10} (r_1 \sin \alpha + r_2 \sin \alpha) = \frac{M_1 M_2}{M_1 + M_2} v_{10} p \\ &= M_1 r_1^2 \dot{\psi} + M_2 r_2^2 \dot{\psi} \end{aligned} \quad (12.38)$$

where p is the impact parameter. Using Equations (12.28) in Equation (12.38), we obtain an equation for $\dot{\psi}$

$$\dot{\psi} = v_{10} p / r^2 , \quad (12.39)$$

which can be eliminated in Equation (12.38)

$$E_{CM} = V(r) + \frac{1}{2} \left(\frac{M_1 M_2}{M_1 + M_2} \right) \left(\left[\frac{dr}{d\psi} \right]^2 + r^2 \right) \left(\frac{v_{10} p}{r^2} \right)^2 . \quad (12.40)$$

Using Equation (12.30) to eliminate v_{10} ,

$$\frac{d\psi}{dr} = \frac{p}{r^2} \frac{1}{\left[1 - \frac{V(r)}{E_{CM}} - \frac{p^2}{r^2} \right]^{1/2}} . \quad (12.41)$$

When the particles are at their closest, $r = r_o$ and $\psi = \pi/2$, and when $r \rightarrow \infty$, $\psi \rightarrow \theta/2$. Integrating Equation (12.41) between these limits:

$$\int_{\theta/2}^{\pi/2} d\psi = \frac{\pi}{2} - \frac{\theta}{2} , \quad (12.42)$$

produces the *Classical Scattering Integral*

$$\theta = \pi - 2 \int_{r_o}^{\infty} \frac{p dr}{r^2 \left[1 - \frac{V(r)}{E_{CM}} - \frac{p^2}{r^2} \right]^{1/2}} . \quad (12.43)$$

Equation (12.43) relates the impact parameter p to the scattering angle in the center of mass θ . At the distance of closest approach, $dr/d\psi = 0$ and

$$1 - \frac{V(r_o)}{E_{CM}} - \frac{p^2}{r_o^2} = 0 . \quad (12.44)$$

Equation (12.44) can be solved for the distance of closest approach as a function of impact parameter. In a head-on collision, $p = 0$ and Equation (12.44) reduces to $V(r_o) = E_{CM}$, which, using Equation (12.27), yields the distance of closest approach in a head-on collision.